

Long Time Approximation of Ergodic SDEs and Multi-Level Monte Carlo

K. C. Zygalakis

School of Mathematics, University of Edinburgh

Numerical schemes for SDEs and SPDEs

Université Lille 1

01 June 2016



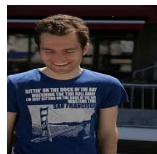
Collaborators



Mike Giles (Oxford)



Lukasz Szpruch
(Edinburgh)



Sebastian Vollmer
(Oxford)

Preprint can be found on ArXiv ([arXiv:1605.01384](https://arxiv.org/abs/1605.01384))



Overview

- 1 Introduction
 - Ergodic SDEs
 - Multi-level Monte Carlo
- 2 Coupling of SDEs
- 3 New MLMC framework
 - General Numerical Analysis
 - Examples of numerical methods
- 4 Stochastic Gradient Langevin Algorithm
- 5 Numerical Investigations



Overview

1 Introduction

- Ergodic SDEs
- Multi-level Monte Carlo

2 Coupling of SDEs

3 New MLMC framework

- General Numerical Analysis
- Examples of numerical methods

4 Stochastic Gradient Langevin Algorithm

5 Numerical Investigations



Ergodic SDEs



Ergodic SDEs I

Consider the stochastic differential equation

$$dX_t = \nabla \log \pi(X_t) dt + \sqrt{2} dW_t.$$

Under appropriate assumptions on $\nabla \log \pi(x)$ one can show that its dynamics are **ergodic** with respect to $\pi(x) : \mathbb{R}^d \mapsto \mathbb{R}$ i.e

$$\lim_{T \rightarrow \infty} \frac{1}{T} \int_0^T \phi(X_s) ds = \int_{\mathbb{R}^d} \phi(x) \pi(x) dx.$$

$\pi(x)$ also satisfies the equation

$$\mathcal{L}^* \pi(x) = 0$$

\mathcal{L}^* is the adjoint of

$$\mathcal{L} := \nabla \log \pi(x) \cdot \nabla_x + \Delta_x$$

Ergodic SDEs II

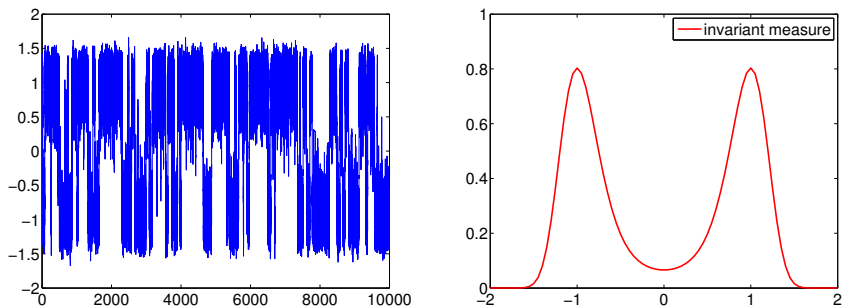


Figure: Long trajectory and invariant measure

Example problem

Standard Bayesian Model with i.i.d. data

- 1 prior distribution $p_0(x)$ on $x \in \mathbb{R}^{\dim}$
- 2 $d_i \stackrel{\text{i.i.d.}}{\sim} p(d|x_0)$ for $i := 1, \dots, N$
- 3 posterior $\pi(x) := p(x | \{d_i\}_{i=1}^N) \propto p_0(x) \prod_{i=1}^N p(d_i|x)$.



How to sample from $\pi(x)$?

- 1 Solve the underlying SDE with a numerical method for large times

$$x_{n+1} = x_n - h\nabla \log \pi(x_n) + \sqrt{2h}\xi_n$$

- 2 Use a Metropolis-Hastings type of algorithm

Use (1) as proposal within MCMC framework ($y_n = x_n$)

$$y_{n+1} = \begin{cases} x_{n+1} & \text{with probability } \alpha(y_n, x_{n+1}) \\ y_n & \text{with probability } 1 - \alpha(y_n, x_{n+1}) \end{cases}$$

where

$$\alpha(y_n, x_{n+1}) = \min \left(1, \frac{\pi(x_{n+1})q(x_{n+1}, y_n)}{\pi(y_n)q(y_n, x_{n+1})} \right)$$

Things to consider when making a choice

- 1 The first approach (numerical analysis) introduces bias in the calculation of $\pi(x)$
- 2 The second approach (computational statistics) removes the bias from the calculation of $\pi(x)$

However

- Computational Statistics approach might be expensive in the presence of big data.

Computational Complexity

The quantity of interest is

$$\pi(g) = \int_{\mathbb{R}^d} g(x)\pi(x)dx = \lim_{T \rightarrow \infty} \mathbb{E}(g(X_T))$$

We are measuring accuracy in terms of the mean square error

$$\text{MSE} := \mathbb{E}(\pi(g) - \hat{g})^2$$

where \hat{g} is the approximation obtain from the algorithm of choice (numerical analysis, computational statistics).

For MSE to be of $\mathcal{O}(\epsilon^2)$ we have the following computational complexity

- numerical analysis approach: $\mathcal{O}(\epsilon^{-3})$
- computational statistics approach: $\mathcal{O}(\epsilon^{-2})$

Multi-level Monte Carlo

Generic approach for finite time

$$dX_t = \nabla \log \pi(X_t) dt + \sqrt{2} dW_t, \quad P = g(X_T).$$

The simplest estimator for $\mathbb{E}(P)$ is an average of N path simulations

$$\hat{Y} = N^{-1} \sum_{i=1}^N \hat{P}^{(i)}$$

with $\hat{P}^{(i)} = g(X_T^i)$.

Decomposition of MSE

$$\begin{aligned}\mathbb{E} \left[\left(\hat{Y} - \mathbb{E}(P) \right)^2 \right] &= \mathbb{E} \left[\left(\hat{Y} - \mathbb{E}(\hat{P}) + \mathbb{E}(\hat{P}) - \mathbb{E}(P) \right)^2 \right] \\ &= N^{-1} \mathbb{V}[\hat{P}] + \left(\mathbb{E}(\hat{P}) - \mathbb{E}(P) \right)^2\end{aligned}$$

- first term is due to the variance of the estimator
- second term is due to bias (finite time steps)-weak convergence

For the Euler method the combined MSE error is $\mathcal{O}(N^{-1} + h^2)$. To make this equal to $\mathcal{O}(\epsilon^2)$ we need

$$N = \mathcal{O}(\epsilon^{-2}), \quad h = \mathcal{O}(\epsilon) \implies \text{cost} = \mathcal{O}(N^{-1}h) = \mathcal{O}(\epsilon^{-3})$$

Multi-level Monte Carlo

To estimate $\mathbb{E}[P]$ where P can be approximated by \widehat{P}_l using $h_l = 2^{-l}T$ uniform time steps, we use

$$\mathbb{E}[\widehat{P}_L] = \mathbb{E}[\widehat{P}_0] + \sum_{\ell=1}^L \mathbb{E}[\widehat{P}_\ell - \widehat{P}_{\ell-1}]$$

$\mathbb{E}[\widehat{P}_\ell - \widehat{P}_{\ell-1}]$ is estimated using N_ℓ simulations with the same **Brownian path** $W(t)$ for both \widehat{P}_ℓ and $\widehat{P}_{\ell-1}$,

$$\widehat{Y}_\ell = \frac{1}{N_\ell} \sum_{i=1}^{N_\ell} (\widehat{P}_\ell^{(i)} - \widehat{P}_{\ell-1}^{(i)})$$

Because of the **strong convergence**, on finer levels $\mathbb{V}[\widehat{P}_\ell - \widehat{P}_{\ell-1}]$ is small and so few paths are required.

Same Brownian path $W(t) \implies$ strong convergence \implies small variance

Complexity theorem

$$|\mathbb{E}[\widehat{P}_\ell - \widehat{P}_{\ell-1}]| \leq c_1 h_\ell^\alpha, \quad \mathbb{V}[\widehat{P}_\ell - \widehat{P}_{\ell-1}] \leq c_2 h_\ell^\beta,$$

for some $\alpha \geq 1/2$, $\beta > 0$, $c_1 > 0$ and $c_2 > 0$, the computational complexity of the resulting multilevel estimate needed to achieve the accuracy ε is proportional to

$$C = \begin{cases} \varepsilon^{-2}, & \beta > \gamma, \\ \varepsilon^{-2} \log^2(\varepsilon), & \beta = \gamma, \\ \varepsilon^{-2-(1-\beta)/\alpha}, & 0 < \beta < \gamma \end{cases}$$

where the cost of the algorithm is of order $h^{-\gamma}$.

Modified Multilevel approach

- Note that \widehat{P}_ℓ appears twice, in $\mathbb{E}[\widehat{P}_{\ell+1} - \widehat{P}_\ell^c]$ and $\mathbb{E}[\widehat{P}_\ell^f - \widehat{P}_{\ell-1}]$, and $\widehat{P}_\ell^f = \widehat{P}_\ell^c$ naturally leads to cancellation and the telescoping sum.
- It may be better to use a different approximation for \widehat{P}_ℓ^f and $\widehat{P}_{\ell-1}^c$ in $\mathbb{E}[\widehat{P}_\ell^f - \widehat{P}_{\ell-1}^c]$, provided $\mathbb{E}[\widehat{P}_\ell^f] = \mathbb{E}[\widehat{P}_\ell^c]$.

A new MLMC:

$$\mathbb{E}[\widehat{P}_L^f] = \mathbb{E}[\widehat{P}_0^f] + \sum_{l=1}^L \mathbb{E}[\widehat{P}_l^f - \widehat{P}_{l-1}^c]$$

The complexity theorem is still valid.

Main Challenge

We want to extend the MLMC framework for $T \rightarrow \infty$. However for a typical SDE the constants c_1, c_2 will grow exponential with time T .

Approach:

- Restrict ourselves to a certain class of ergodic SDEs with log-concave invariant densities.
- These SDEs have exponentially contracting properties when driven by the same Brownian motion
- Exploit the exponentially contracting property of the SDE on the level of the numerical discretization by appropriately coupling of the fine and the coarse level. These will yield **uniform in time estimates** for the appropriate differences between the fine and the coarse paths.

Overview

- 1 Introduction
 - Ergodic SDEs
 - Multi-level Monte Carlo
- 2 Coupling of SDEs
- 3 New MLMC framework
 - General Numerical Analysis
 - Examples of numerical methods
- 4 Stochastic Gradient Langevin Algorithm
- 5 Numerical Investigations



Contracting properties

For the simplicity of notation take $U(x) = \log \pi(x)$ and assume that there exists $m \geq 0$ such that

$$U(y) \leq U(x) + \langle \nabla U(x), y - x \rangle - \frac{m}{2} \|x - y\|^2$$

We define

$$\psi_{s,t,W}(x) := x + \int_s^t \nabla U(X_r) dr + \int_s^t \sqrt{2} dW_r, \quad x \in \mathbb{R}^d.$$

and $X_T = \psi_{0,T,W}(X_0)$ and $Y_T = \psi_{0,T,W}(Y_0)$. Then

$$\mathbb{E} \|X_T - Y_T\|^2 \leq \mathbb{E} \|X_0 - Y_0\|^2 e^{-2mT}$$

MLMC in time

$$\lim_{T \rightarrow \infty} \mathbb{E}(g(X_T)) = \pi(g),$$

Now consider $(0 = T_0 < T_1 < T_2, \dots, T_i < \dots)$ and a sequence of random variables $(\Delta_i)_{i \geq 0}$ satisfying

$$\mathbb{E}\Delta_i = \begin{cases} \mathbb{E}g(X_{T_i}) - \mathbb{E}g(X_{T_{i-1}}) & i \geq 1 \\ \mathbb{E}g(X_{T_i}) & i = 0 \end{cases}$$

$$\pi(g) = \sum_{i=1}^{\infty} \mathbb{E}(\Delta_i).$$

Properties of the paths at different levels

We will construct the fine $X^{(f,i)}$ and the coarse $X^{(c,i)}$ paths in a way to satisfy

$$\mathcal{L}(X^{(f,i)}) = \mathcal{L}(X_{T_i}), \quad \mathcal{L}(X^{(c,i)}) = \mathcal{L}(X_{T_{i-1}}), \quad \forall i \geq 0,$$

and

$$\mathbb{E}\|X^{(f,i)} - X^{(c,i)}\|^2 \leq \mathbb{E}\|X_{T_i} - X_{T_{i-1}}\|^2.$$

Construction:

- Take $X^{(f,i)}(0) = \psi_{0, (T_i - T_{i-1}), \tilde{W}}(X(0))$
- Set $X^{(f,i)}(T_{i-1}) = \psi_{0, T_{i-1}, W}(X^{(f,i)}(0)), \quad X^{(c,i)}(T_{i-1}) = \psi_{0, T_{i-1}, W}(X(0)).$

Illustrations of couplings

We have

$$\mathbb{E} \|X^{(f,i)}(T_{i-1}) - X^{(c,i)}(T_{i-1})\|^2 \leq \mathbb{E} \|X^{(f,i)}(0) - X(0)\|^2 e^{-2mT_{i-1}}.$$

which leads to **small variance** for the choice of $T_i := \frac{\log 2}{2m} \beta(i+1)$

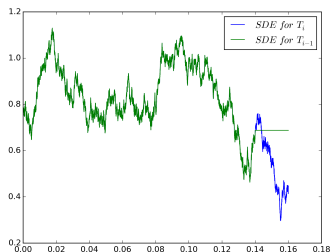
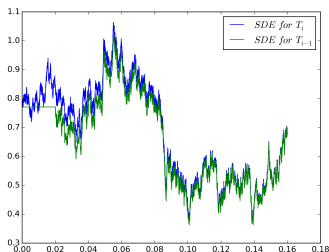


Figure: Shifted Couplings

Overview

- 1 Introduction
 - Ergodic SDEs
 - Multi-level Monte Carlo
- 2 Coupling of SDEs
- 3 New MLMC framework**
 - General Numerical Analysis
 - Examples of numerical methods
- 4 Stochastic Gradient Langevin Algorithm
- 5 Numerical Investigations



Coupling Numerical solutions

Consider

$$x_{k+1}^h = S_{h,\xi_k}^f(x_k^h), \quad y_{k+1}^h = S_{h,\tilde{\xi}_k}^c(y_k^h), \quad P_h(x, \cdot) = \mathcal{L}(S_{h,\xi}^f(x))$$

The coupling arises by evolving both fine and course paths jointly, over a time interval of length $T_i - T_{i-1}$, by doing two steps for the finer level (with the time step h_i) and one on the coarser level (with the time step h_{i-1}) using the discretization of the same Brownian path.

Numerical Algorithm

- 1 Set $x_0^{(f,i)} = x_0$, then simulate according to P_{h_i} up to $x_{\frac{t_i - t_{i-1}}{h_i}}^{(f,i)}$;
- 2 set $x_0^{(c,i)} = x_0$ and $x_0^{(f,i)} = x_{\frac{t_i - t_{i-1}}{h_i}}^{(f,i)}$, then simulate $(x^{(f,i)}, x^{(c,i)})$ jointly according to

$$\left(x_{k+1}^{(f,i)}, x_{k+1}^{(c,i)} \right) = \left(S_{h_i, \xi_{k,2}}^f \circ S_{h_i, \xi_{k,1}}^f \left(x_k^{(f,i)} \right), S_{h_{i-1}, \frac{1}{\sqrt{2}}(\xi_{k,1} + \xi_{k,2})}^c \left(x_k^{(c,i)} \right) \right).$$

- 3 set

$$\Delta_i := g \left(x_{\frac{t_i - 1}{h_{i-1}}}^{(f,i)} \right) - g \left(x_{\frac{t_i - 1}{h_{i-1}}}^{(c,i)} \right)$$

General Numerical Analysis

Definition of L^2 -regularity

We will say a process $(x_k^h)_{k \in \mathbb{N}}$ is L^2 -regular **uniformly in time** if it can be written as

$$S_{h,\xi_k}(x_k) - S_{h,\xi_k}(y_k) = x_{k+1,x_k}^h - x_{k+1,y_k}^h = x_k - y_k + Z_{k+1}, \quad \forall k \geq 0,$$

and for all $k \geq 0$ there exists constants $K > 0$ and random variables \mathcal{R}_k and \mathcal{H}_{k+1} such that

$$\begin{aligned} \mathbb{E}_k[|x_{k+1,x_k}^h - x_{k+1,y_k}^h|^2] &\leq (1 - Kh)|x_k - y_k|^2 + \mathcal{R}_k \\ \mathbb{E}_k[|Z_{k+1}|^2] &\leq \mathbb{E}_k(\mathcal{H}_{k+1})|x_k - y_k|^2 h. \end{aligned}$$

Moreover we assume that there exists constants $C_{\mathcal{R}}$, $C_{\mathcal{H}}$ and β s.t

$$\begin{aligned} \sup_{n \geq 1} \mathbb{E} \left[\sum_{i=1}^n \mathcal{R}_i \right] &\leq C_{\mathcal{R}} h^{2\beta} \\ \sup_{n \geq 1} \mathbb{E} [\mathcal{H}_n^2] &\leq C_{\mathcal{H}}. \end{aligned}$$

Assumptions for the numerical method

Consider two process $(x_k^f)_{2k \in \mathbb{N}}$ and $(x_k^c)_{k \in \mathbb{N}}$ and assume that

H0 For $q > 1$ there exist functions $H_k^f := H(k, f, q)$ and $H_k^c := H(k, c, q)$

$$\mathbb{E}|x_k^f|^q \leq H_k^f \quad \text{and} \quad \sup_{k \geq 0} \mathbb{E}|x_k^c|^q \leq H_k^f,$$

with $\sup_{k \geq 0} H_k^f < \infty$ and $\sup_{k \geq 0} H_k^c < \infty$

H1

$$\mathcal{L}(S_{h,\xi}^f(x)) = \mathcal{L}(S_{h,\tilde{\xi}}^c(x))$$

H2 The process $(x_k^f)_{2k \in \mathbb{N}}$ is L^2 regular uniformly in time.



Exponential contraction of numerical trajectories

Theorem

Take $(x_n^f)_{2n \in \mathbb{N}}$ and $(x_n^c)_{n \in \mathbb{N}}$ with $h \in (0, 1]$ and assume that **H0-H2** hold. Moreover, assume that there exists constants $c_s > 0$, $c_w > 0$ and $\alpha \geq \frac{1}{2}$, $\beta \geq 0$ with $\alpha \geq \frac{\beta}{2} + 1$ such that for all $n \geq 1$

$$|\mathbb{E}_{n-1}(x_{n,x_{n-1}^c}^c - x_{n,x_{n-1}^c}^f)| \leq c_w(1 + |x_{n-1}^c|^p)h^\alpha,$$

and

$$\mathbb{E}_{n-1}[|x_{n,x_{n-1}^c}^c - x_{n,x_{n-1}^c}^f|^2] \leq c_s(1 + |x_{n-1}^c|^{2p})h^{\beta+1},$$

where $p \geq 1$. Fix $\zeta \in (0, 1)$. Then the global error is given by

$$\begin{aligned} \mathbb{E}[|(x_{T/h, y_0}^c - x_{T/h, x_0}^f)|^2] &\leq |x_0 - y_0|^2 e^{-K\zeta T} + \sum_{j=1}^n e^{(j-(n-1))K\zeta h} \mathbb{E}(\mathcal{R}_{n-1}) \\ &\quad + h^{\beta+1} \sum_{j=1}^n C_j(\zeta) e^{(j-(n-1))K\zeta h}, \end{aligned}$$

where $C_n(\zeta) := \left(c_s H_{1,n} + \frac{(4c_w+2)[4c_w H_{1,n} + c_s(H_{3,n} + 2H_{2,n})]}{4(1-\zeta)K} \right)$ with $H_{1,n} := (1 + \mathbb{E}[|x_{n-1}^c|^{2p}])$, $H_{2,n} := (1 + \mathbb{E}[|x_{n-1}^c|^{4p}])$, $H_{3,n} := \mathbb{E}[\mathcal{H}_{n-1}]$.

Decay of MLMC variance

Let $g(\cdot)$ be a Lipschitz function. Define

$$h_i = 2^{-i}, \quad T_i \sim -\frac{\beta}{K\zeta} (\log h_0 + i \log 2), \quad \forall i \geq 0.$$

Then the resulting MLMC variance is given by.

$$\mathbb{V}[\Delta_i] \leq C2^{-\beta i}, \quad \Delta_i = g\left(x_{\frac{t_{i-1}}{h_{i-1}}}^{(f,i)}\right) - g\left(x_{\frac{t_{i-1}}{h_{i-1}}}^{(c,i)}\right)$$

Hence we can apply the complexity theorem

Examples of Numerical Methods

Euler-Maryama method

When the Euler method is used both for the fine and the coarse paths, if we assume that $U(x)$ is Lipschitz we have

$$\begin{aligned}\mathbb{E}_{n-1}[|x_{n,x_{n-1}} - x_{n,y_{n-1}}|^2] &\leq (1 - (2m - L^2h)h)|x_{n-1} - y_{n-1}|^2 \\ \mathbb{E}_k[|Z_n|^2] &\leq h^2 L^2 |x_{n-1} - y_{n-1}|^2\end{aligned}$$

while in addition we have the following one-step error estimates

$$\|\mathbb{E}[x_{1,x}^f - x_{1,x}^c]\| \leq \frac{h^{3/2}}{2} L \left(\mathbb{E} \left[\frac{\sqrt{h}}{2} (L\|x\| + \|\nabla U(0)\|) \right] + \frac{2}{\pi} \right). \quad (1)$$

$$\mathbb{E} \|x_{1,x}^f - x_{1,x}^c\|^2 \leq h^3 \frac{L^2}{4} \left(\frac{h}{2} (\|x\|^2 + \|\nabla U(0)\|^2) + d \right) \quad (2)$$

Implying that $\alpha = 3/2$ (with additional regularity assumptions $\alpha = 2$), $\beta = 2$ hence giving computational complexity of $\mathcal{O}(\epsilon^{-2})$

Beyond Lipschitz $U(x)$

One can alleviate the assumption about $U(x)$ being Lipschitz by using for example the implicit-Euler method, which can be verified that it satisfies the necessary conditions that yield computational complexity of $\mathcal{O}(\epsilon^{-2})$.

Overview

- 1 Introduction
 - Ergodic SDEs
 - Multi-level Monte Carlo
- 2 Coupling of SDEs
- 3 New MLMC framework
 - General Numerical Analysis
 - Examples of numerical methods
- 4 Stochastic Gradient Langevin Algorithm
- 5 Numerical Investigations



Revisiting Big Data problem

We are interested in sampling with respect to

$$\pi(x) = p(\theta | \{d_i\}_{i=1}^N) \propto p_0(x) \prod_{i=1}^N p(d_i | x)$$

Here

$$\nabla \log \pi(x) = \nabla \log p_0(x) + \sum_{i=1}^N \nabla \log p(d_i | x)$$

Numerical discretization

Problem: When $N \gg 1$ standard approaches might be computationally infeasible

Stochastic Gradient Langevin Dynamics

$$x_{k+1} = S_{h, \xi_k, \tau_k}(x_k).$$

where

$$S_{h, \xi, \tau}(x) = x + h\hat{f}(x) + \sqrt{2h}\xi, \quad \hat{f}(x) = \left(\nabla \log p_0(x) + \frac{N}{n} \sum_{i=1}^n \nabla \log p(d_{\tau_i} | x) \right)$$

and

$$\mathbb{E}_{\tau} \hat{f}(x) = \nabla \log p(x), \quad \forall n \leq N.$$

- 1 Set $x_0^{(f,i)} = x_0$, then simulate according to $S_{h_i, \xi, \tau}(x)$ for $\frac{t_i - t_{i-1}}{h_i}$ steps with independent random input;
- 2 set $x_0^{(c,i)} = x_0$ and $x_0^{(f,i)} = x_{\frac{t_i - t_{i-1}}{h_i}}^{h_i}$, then simulate $(x^{(f,i)}, x^{(c,i)})$ jointly according to

$$\left(x_{k+1}^{(f,i)}, x_{k+1}^{(c,i)} \right) = \left(S_{h_i, \xi_{k,2}, \tau_k^{\mathcal{F},2}} \circ S_{h_i, \xi_{k,1}, \tau_k^{\mathcal{F},1}}(x_k^{(f,i)}), S_{h_{i-1}, \frac{1}{\sqrt{2}}(\xi_{k,1} + \xi_{k,2}), \tau_k^C}(x_k^{(c,i)}) \right).$$

- 3 set

$$\Delta_i := g \left(x_{\frac{t_i - 1}{h_{i-1}}}^{(f,i)} \right) - g \left(x_{\frac{t_i - 1}{h_{i-1}}}^{(c,i)} \right)$$

Possible choices of coupling

We need

$$\mathcal{L}(\tau^{\mathcal{F},1}) = \mathcal{L}(\tau^{\mathcal{F},2}) = \mathcal{L}(\tau^{\mathcal{C}}).$$

This is satisfied when

- an independent sample of $\{1, \dots, N\}$ without replacement denoted as $\tau_{\text{ind}}^{\mathcal{C}}$ called independent coupling;
- a draw of s samples without replacement from $(\tau^{\mathcal{F},1}, \tau^{\mathcal{F},2})$ denoted as $\tau_{\text{union}}^{\mathcal{C}}$ called union coupling;
- the concatenation of a draw of $\frac{n}{2}$ samples without replacement from $\tau^{\mathcal{F},1}$ and a draw of $\frac{n}{2}$ samples without replacement from $\tau^{\mathcal{F},2}$ (provided that n is even) $\tau_{\text{strat}}^{\mathcal{C}}$ called stratified coupling.

One-step error

Nothing changes in terms of the exponent α however for all the different data coupling choices we have

$$\mathbb{E} \left\| S_{\frac{h}{2}, \xi, 2, \tau^{\mathcal{F}, 2}} \circ S_{\frac{h}{2}, \xi_1, \tau^{\mathcal{F}, 1}}(x) - S_{h, \frac{1}{\sqrt{2}}(\xi_1 + \xi_2), \tau^c}(x) \right\|^2 \leq Ch^2$$

implying that $\beta = 1$, and hence the computational complexity is of $\mathcal{O}(\epsilon^{-2} \log \epsilon^3)$.

Overview

- 1 Introduction
 - Ergodic SDEs
 - Multi-level Monte Carlo
- 2 Coupling of SDEs
- 3 New MLMC framework
 - General Numerical Analysis
 - Examples of numerical methods
- 4 Stochastic Gradient Langevin Algorithm
- 5 Numerical Investigations



Ornstein Uhlenbeck process

$$dX_t = -\kappa X_t dt + \sqrt{2} dW_t,$$

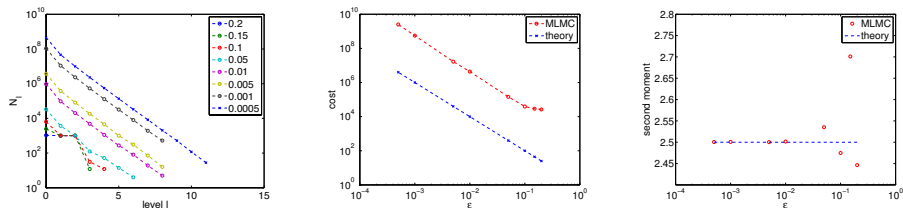


Figure: MLMC results for the OU process for $g(x) = x^2$ and $\kappa = 0.4$

Logistic Regression

Data $d_i \in \{-1, 1\}$ are modelled by

$$p(d_i | l_i, x) = f(d_i x^T l_i)$$

where $f(z) = \frac{1}{1 + \exp(-z)} \in [0, 1]$ and $l_i \in \mathbb{R}^d$ are fixed covariates. We put a Gaussian prior $\mathcal{N}(0, C_0)$ on x , for simplicity we use $C_0 = I$ subsequently. By Bayes' rule the posterior π satisfies

$$\pi(x) \propto \exp\left(-\frac{1}{2} \|x\|_{C_0}^2\right) \prod_{i=1}^N f(y_i x^T l_i).$$

We consider $d = 3$ and $N = 100$ data points and choose the covariate to be

$$l = \begin{pmatrix} l_{1,1} & l_{1,2} & 1 \\ l_{2,1} & l_{2,2} & 1 \\ \vdots & \vdots & \vdots \\ l_{100,1} & l_{100,2} & 1 \end{pmatrix}$$

for a fixed sample of $l_{i,j} \stackrel{\text{i.i.d.}}{\sim} \mathcal{N}(0, 1)$ for $i = 1, \dots, 100$ and we take $n = 10$.

Numerical experiment

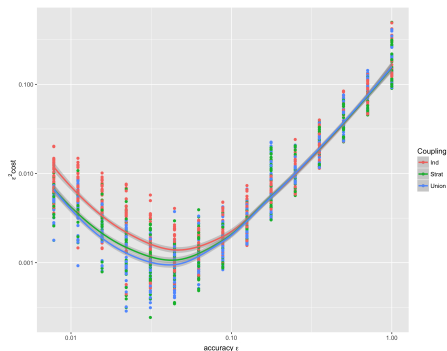


Figure: Cost of MLMC (sequential CPU time) SGLD for Bayesian Logistic Regression for decreasing accuracy parameter ϵ and different couplings

Conclusions and future work

- We have extended the MLMC framework to infinite time for a class of ergodic SDEs
 - We have achieved the computational complexity as for MCMC methods without the need of accept reject (we can make our samples unbiased)
- 1 Study tamed methods
 - 2 Investigate different couplings for SGLD to bring computational complexity down to $\mathcal{O}(\epsilon^{-2})$

Thank you for your attention!

