

On some p -adic differential equations

(with separation of variables)

Pierre Lairez, **Tristan Vaccon**

TU Berlin, 立教大学 (Rikkyo University)–JSPS Post-Doctoral Fellow

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RIKKYO UNIVERSITY

- 1 p -adic precision: direct approach and differential precision
 - Direct analysis
 - Application in linear algebra
 - The main lemma

- 2 p -adic differential equations with separation of variables
 - Isogeny computation
 - The original scheme

- 3 Application of differential precision
 - Applying the lemma
 - A more subtle approach

Why should one work with p -adic numbers ?

p -adic methods

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My personal (long-term) motivation

Computing (some) moduli spaces of p -adic Galois representations.

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Definition of the precision

Finite-precision p -adics

Elements of \mathbb{Q}_p can be written $\sum_{i=k}^{+\infty} a_i p^i$, with $a_i \in \llbracket 0, p-1 \rrbracket$, $k \in \mathbb{Z}$ and p a prime number.

While working with a computer, we usually only can consider the beginning of this power series expansion: we only consider elements of the following form $\sum_{i=l}^{d-1} a_i p^i + O(p^d)$, with $l \in \mathbb{Z}$.

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Example

The order of $3 * 7^{-1} + 4 * 7^0 + 5 * 7^1 + 6 * 7^2 + O(7^3)$ is 3.

p -adic precision vs real precision

The quintessential idea of the step-by-step analysis is the following :

Proposition (p -adic errors don't add)

Indeed,

$$(a + O(p^k)) + (b + O(p^k)) = a + b + O(p^k).$$

That is to say, if a and b are known up to precision $O(p^k)$, then so is $a + b$.

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Remark

It is quite the opposite to when dealing with real numbers, because of **Round-off error** :

$$(1 + 5 * 10^{-2}) + (2 + 6 * 10^{-2}) = 3 + 1 * 10^{-1} + 1 * 10^{-2}.$$

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Precision formulae

Proposition (addition)

$$(x_0 + O(p^{k_0})) + (x_1 + O(p^{k_1})) = x_0 + x_1 + O(p^{\min(k_0, k_1)})$$

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Proposition (division)

$$\frac{xp^a + O(p^b)}{yp^c + O(p^d)} = x * y^{-1} p^{a-c} + O(p^{\min(d+a-2c, b-c)})$$

In particular,

$$\frac{1}{p^c y + O(p^d)} = y^{-1} p^{-c} + O(p^{d-2c})$$

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A little warm-up on computing determinants : expansion

An example of determinant computation

$$\begin{bmatrix} p^5 + O(p^{10}) & 1 + O(p^{10}) & 1 + p^3 + O(p^{10}) \\ O(p^{10}) & 1 + O(p^{10}) & 1 + O(p^{10}) \\ 2p^6 + O(p^{10}) & 2p + O(p^{10}) & 2p + p^5 + O(p^{10}) \end{bmatrix}$$

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If we expand directly using the expression of the determinant in terms of the coefficients, we get:

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Direct expansion

If we expand directly using the expression of the determinant in terms of the coefficients, we get:

$$-2p^9 + O(p^{10}),$$

because of $1 \times 1 \times O(p^{10})$.

A little warm-up on computing determinants : row-echelon form computation

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Summary: precision and p -adic computations

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Direct method for precision

- Has often been enough to get a first view of the problem.
- Depends heavily on the algorithm chosen for the computation
- No idea on what is **optimal**.

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The Main lemma of p -adic differential precision

Lemma (CRV14)

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Geometrical meaning

Interpretation

$x +$

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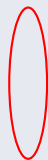
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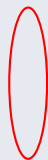
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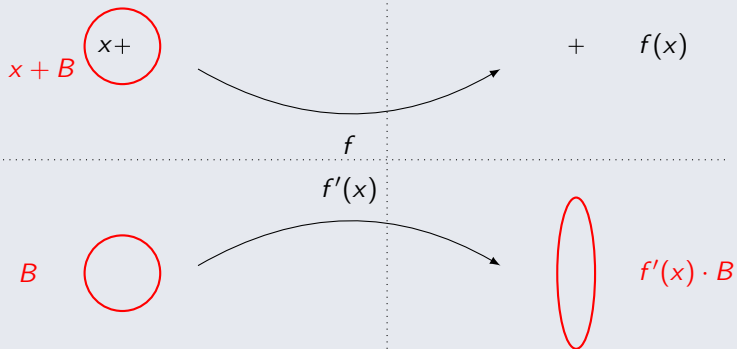
$$x + B \quad \text{with } x \text{ circled}$$

$$+ \quad f(x)$$

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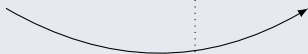
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 f

$$\text{○} \quad + \quad f(x) \\ f(x) + f'(x) \cdot B$$

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Remark

Our framework can be extended to **(complete) ultrametric K -vector spaces** (e.g. being $\mathbb{F}_p((X))^n$, $\mathbb{Q}((X))^m$, $\mathbb{R}((\varepsilon))^s$).

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When f is locally analytic, it essentially corresponds to

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This can be determined with **Newton-polygon** techniques.

Looking back to the case of the determinant

Differential of the determinant

It is well known:

$$\det'(M) : dM \mapsto \text{Tr}(\text{Com}(M) \cdot dM).$$

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- **Approximate SNF is optimal.**

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On some p -adic differential equations

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An example of p -adic algorithm

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Isogeny and Differential equations (*cf* Schoof-Elkies-Atkin algorithm, Bostan-Morain-Salvy-Schost 08, Lercier-Sirvent 08, ...)

Let E and \tilde{E} be two elliptic curves over $\mathbb{Z}/p\mathbb{Z}$:

$$E : y^2 = x^3 + Ax + B,$$

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Let us assume that there exists some normalized isogeny I between E and \tilde{E} . Then, for some rational fraction U ,

$$I(x, y) = (U(x), yU'(x)),$$

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Writing $U = \frac{1}{S(\frac{1}{\sqrt{x}})^2}$, we get :

$$(Bx^6 + Ax^4 + 1)S'^2 = 1 + \tilde{A}S^4 + \tilde{B}S^6.$$

Change of variable and the differential equation

The differential equation

Let S be such that

$$U = \frac{1}{S\left(\frac{1}{\sqrt{x}}\right)^2}.$$

Then if $A, B, \tilde{A}, \tilde{B}$ are in \mathbb{Z}_p ,

$$S \in \mathbb{Z}_p[[t]]$$

We have the following differential equation for S :

$$(Bx^6 + Ax^4 + 1)S'^2 = 1 + \tilde{A}S^4 + \tilde{B}S^6.$$

A p -adic computation of a solution

Computing the isogeny

Given E and \tilde{E} , the goal is to compute the isogeny I via the differential equation:

$$\begin{cases} S(0) = 0, \\ (Bx^6 + Ax^4 + 1)S'^2 = 1 + \tilde{A}S^4 + \tilde{B}S^6. \end{cases}$$

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- 3 Reduce mod p to get the solution in $\mathbb{Z}/p\mathbb{Z}$.

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Change of equation

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To compute $y \pmod{x^{2^N+1}}$, we need an initial precision of $O(N^2)$ digits.

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Differential and differential equation

Theorem

Let $\Phi : (g, h) \mapsto y$ such that $y(0) = 0$ and $y' = gh(y)$. Then,

$$\Phi'(g, h) \cdot (\delta g, \delta h) = h(y) \int \delta g + \frac{g \delta h(y)}{h(y)}.$$

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$$\Phi'(y) \cdot (\delta g, \delta h) \pmod{x^{2^N+1}} \in \frac{O(p^k)}{p^N} \mathbb{Z}_p[[x]].$$

First conclusion on the application of the lemma

Proposition

$\Phi(g, h) \bmod (p, t^{2^n})$ is determined by $g, h \bmod (p^{1+\log_p 2^n}, t^{2^n})$. In other words, we have a logarithmic loss in precision.

What happens in practice ?

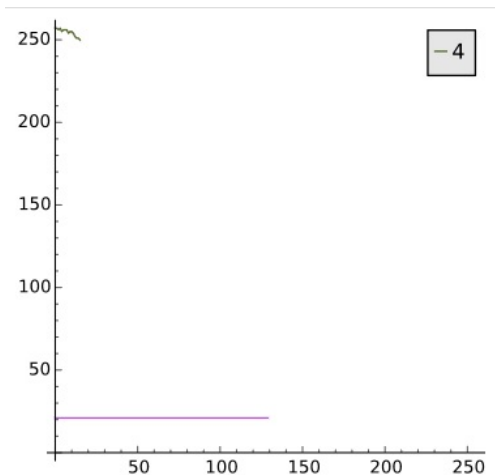


Figure: Precision over the output

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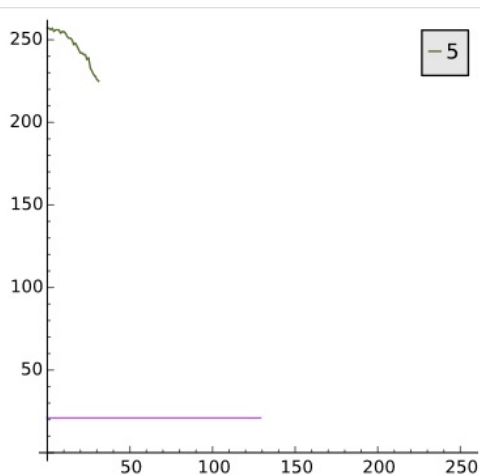


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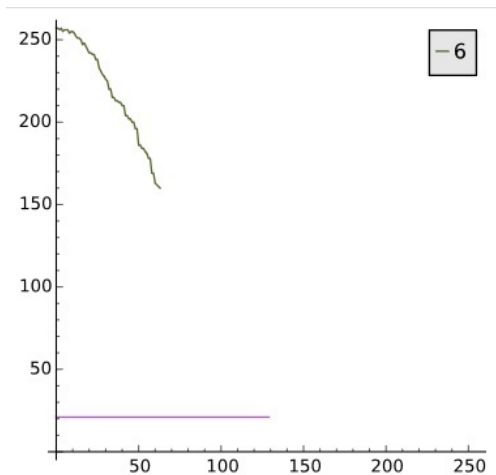


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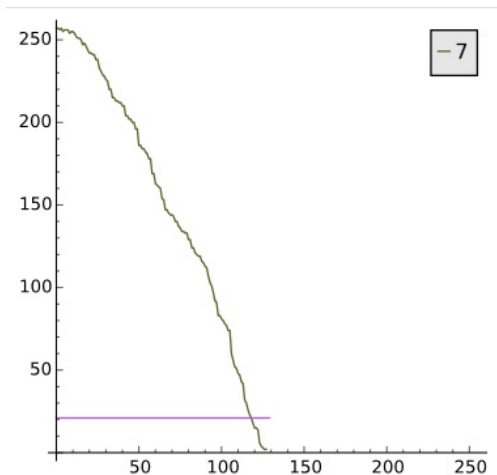


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- In the previous computation, we start with some given approximations of g, h, u_0 and try **to follow** the algorithm for the exact counterparts of g, h, u_0 . This is somehow **much stronger** than our desire: computing a good approximate solution.
- Another way is then to modify the current g, h, u_0 **at each step**, in a consistent way, so as to keep on getting better approximate solutions.
- A third way here will be to work entirely in $\mathbb{Z}/p^k\mathbb{Z}$.

New framework

In this new computation, we consider h as given, and not varying for the lemma.

Lemma

Let $Y : g \mapsto y$ such that $y(0) = 0$ and $y' = gh(y)$. Then,

$$Y'(g) \cdot (\delta g) = h(y) \int \delta g.$$

A consequence of the lemma

Corollary

Let $n > 0$ and $\kappa > 1$ be integers, and let $g \in \mathbb{Z}_p[[t]]$ such that $Y(g) \pmod{t^{n+1}}$ has integer coefficients. For any $y \in \mathbb{Q}_p[[t]]$ the following are equivalent:

- 1 $y = Y(\bar{g}) \pmod{t^{n+1}}$ for some power series $\bar{g} \in \mathbb{Z}_p[[t]]$ such that $\int(\bar{g} - g) = 0 \pmod{p^\kappa}$;
- 2 $y = Y(g) \pmod{p^\kappa, t^{n+1}}$.

Final take on the Newton scheme

As a consequence, we can prove that it is harmless to work in $\mathbb{Z}/p^k\mathbb{Z}$ for our computation.

Proposition

We can obtain the solution $\Phi(g, h) \pmod{(p, t^{n+1})}$ knowing $g, h \pmod{(p^{[\log_p n]+1}, t^{n+1})}$ and applying the following iteration:

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modulo $p^{[\log_p n]+1}$ and growing order of truncation.

Timings

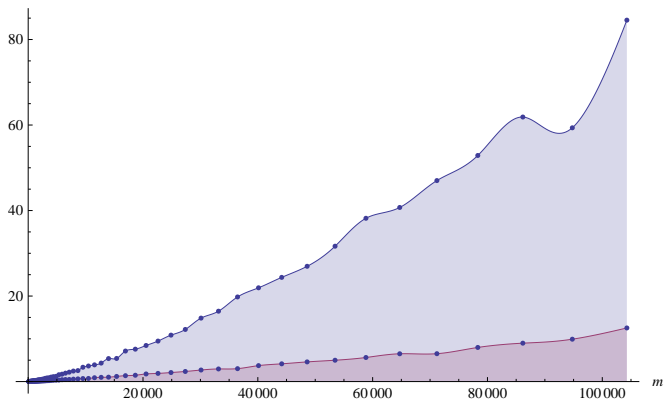


Figure: Timings in seconds, measured on a laptop, of our Algorithm run at precision λ_{old} (upper curve) and λ_{new} (lower curve) in order to compute an approximation modulo $(5, t^{4m+1})$ of some given m -isogenies.

Speedup

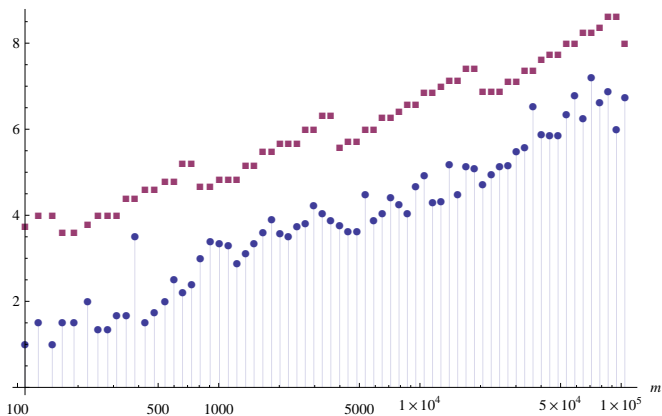


Figure: Practical speedup obtained with the new precision analysis compared with the theoretical improvement (m -axis in logarithmic scale). (■) is the ratio on precisions, (●) is the actual speedup.

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References

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Linear Algebra

- XAVIER CARUSO, DAVID ROE AND TRISTAN VACCON p -adic stability in linear algebra, ISSAC 2015.

Differential equations

- PIERRE LAIREZ AND TRISTAN VACCON On p -adic differential equations with separation of variables, arXiv:1602.00244.

Thank you for your attention

Thanks

$$x + O(p^{N'})$$

$$y + O(p^{M'}) \subset f(x) + O(p^N)$$

