Numerical Aspects of nonequilibrium dynamics Institut Henri Poincaré, Paris April 25, 2017

Courant 🦞 NYU

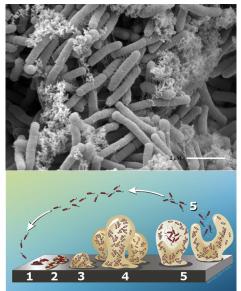
Non-equilibrium self-organization of motile bacteria with fluctuating population and speed

Tobias Grafke, M. Cates, E. Vanden-Eijnden

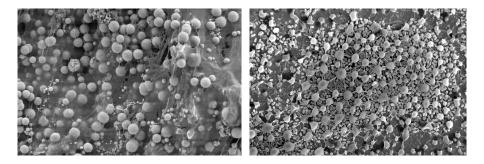
Collective behavior of bacteria

Bacteria show complex collective behavior

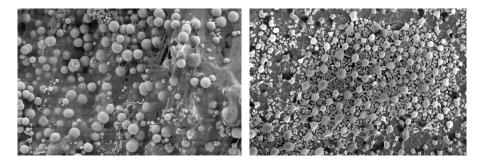
- For example, bacteria such as E. Coli are capable of active propulsion, i.e. have a free-swimming (planktonic) stage.
- They are capable of sensing their environment through quorum sensing, density-dependent gene regulation.
- They stick to surface to form biofilms, high density colonies.
- They exhibit cyclic/time-periodic behavior: Biofilm formation, maturation, dispersion, planktonic stage.
- All these are controlled by highly complex bio-chemical processes.



Collective behavior of bacteria



Collective behavior of bacteria



Statistical mechanics of active matter

Stepping away from the biological complexity: Is it possible to describe similarly complex life-cycles as **emergent behavior** of a large number of simple **individual agents** subject to a small number of collective rules?

Intrinsically out-of-equilibrium system: Statistical mechanics of active matter

Tobias Grafke Non-equilibrium self-organization of motile bacteria

Self-propelled bacteria modeled as active Brownian motion:

For position $X \in \Omega \subset \mathbb{R}^d$, direction $\hat{n} \in S^{d-1}$, and location dependent swim speed $v(X) \in \mathbb{R}$

 $\dot{X} = v(X)\hat{n},$ $d\hat{n} = \tau^{-1/2} P \circ dW, \qquad P = \mathrm{Id} - \hat{n}\hat{n}^{T}$

Direction diffuses on S^{d-1} with tumbling rate $\tau^{-1}.$



active Brownian motion[†]

• Limit $\tau \rightarrow 0$ yields Brownian motion

 $dX = \sqrt{2D(X)} \circ dW$ with diffusivity $D(x) = \tau v^2(x)$

[†] M. Cates, J. Tailleur (2015)

Cates & Tailleur

Now consider N such particles with position $X_i, i \in \{1, ..., N\}$.

To model **quorum sensing**, introduce scale δ over which particles feel each other's influence,

$$dX_i = \sqrt{2D(\rho_{N,\delta}(t, X_i))} \circ dW_i$$

with

$$\rho_{N,\delta}(t,x) = \int_{\Omega} \phi_{\delta}(x-y)\rho_{N}(t,y) \, dy, \qquad \rho_{N}(t,x) = \frac{1}{N} \sum_{j=1}^{N} \delta(x-X_{j}(t))$$

ъ. т.

Cates & Tailleur

Now consider N such particles with position $X_i, i \in \{1, ..., N\}$.

To model **quorum sensing**, introduce scale δ over which particles feel each other's influence,

$$dX_i = \sqrt{2D(\rho_{N,\delta}(t, X_i))} \circ dW_i$$

with

$$\rho_{N,\delta}(t,x) = \int_{\Omega} \phi_{\delta}(x-y)\rho_N(t,y)\,dy, \qquad \rho_N(t,x) = \frac{1}{N}\sum_{j=1}^N \delta(x-X_j(t))$$

In the limit $N \to \infty$, yields closed integro-differential equation for $\rho_N \to \rho$,

$$\partial_t \rho = \nabla \cdot (D(\rho_\delta) \nabla \rho + \frac{1}{2} D'(\rho_\delta) \nabla \rho_\delta), \qquad \rho_\delta(t, x) = \int_{\Omega} \phi_\delta(x - y) \rho(t, x) \, dy$$

in the sense that

$$\forall \epsilon, T > 0: \quad \lim_{N \to \infty} \mathbb{P}\Big(\sup_{0 \le t \le T} \Big| \frac{1}{N} \sum_{j=1}^{N} f(X_j(t)) - \int_{\Omega} \rho(t, x) f(x) \, dx \Big| > \epsilon \Big) = 0$$

ъ. т.

To make this closed in $\rho(t, x)$, consider $D(\rho) = D_0 e^{-\rho}$, and expand in $\delta \ll 1$,

 $\rho_{\delta}(x) \approx \rho(x) + \frac{1}{2} \delta^2 \partial_x^2 \rho(x).$

Then we obtain an effective diffusion equation

$$\partial_t \rho = \nabla \cdot \left(D_e(\rho) \nabla \rho - \delta^2 \rho D(\rho) \nabla \Delta \rho \right)$$

with diffusivity

 $D_e(\rho) = D(\rho) + \frac{1}{2}D'(\rho)\rho.$

To make this closed in $\rho(t, x)$, consider $D(\rho) = D_0 e^{-\rho}$, and expand in $\delta \ll 1$,

 $\rho_{\delta}(x) \approx \rho(x) + \frac{1}{2} \delta^2 \partial_x^2 \rho(x).$

Then we obtain an effective diffusion equation

$$\partial_t \rho = \nabla \cdot \left(D_e(\rho) \nabla \rho - \delta^2 \rho D(\rho) \nabla \Delta \rho \right)$$

with diffusivity

$$D_e(\rho) = D(\rho) + \frac{1}{2}D'(\rho)\rho.$$

Despite non-equilibrium microscopic model, continuum model restores detailed balance

$$\partial_t \rho = \nabla \cdot \left(\rho D(\rho) \nabla (\delta E / \delta \rho)\right)$$

with

$$E(\rho) = \int_{\Omega} (\rho \log \rho - \rho + f(\rho) + \frac{1}{2}\delta^2 |\nabla \rho|^2) \, dx \,, \quad f'(\rho) = \frac{1}{2} \log D(\rho) \quad \text{(free energy)}$$

("Thermodynamic mapping" depends on regularization, not preserved by original Cates & Tailleur)

$$\partial_t \rho = \nabla \cdot \left(D_e(\rho) \nabla \rho - \delta^2 \rho D(\rho) \nabla \Delta \rho \right),$$
$$D_e(\rho) = D(\rho) + \frac{1}{2} D'(\rho) \rho$$

 $D(\rho) > 0$ diffusivity, but $D_e(\rho) < 0$ possible!

For $D(\rho) = D_0 e^{-\rho}$

effective diffusivity

 $D_e(\rho) = D_0(1 - \frac{1}{2}\rho)e^{-\rho}$

Homogeneous configuration stable if

$$\bar{\rho} = \frac{1}{|\Omega|} \int\limits_{\Omega} \rho(x) \, dx < 2$$

$$\begin{split} \partial_t \rho &= \nabla \cdot \left(D_e(\rho) \nabla \rho - \delta^2 \rho D(\rho) \nabla \Delta \rho \right), \\ D_e(\rho) &= D(\rho) + \frac{1}{2} D'(\rho) \rho \end{split}$$

 $D(\rho) > 0$ diffusivity, but $D_e(\rho) < 0$ possible!

For $D(\rho) = D_0 e^{-\rho}$

effective diffusivity

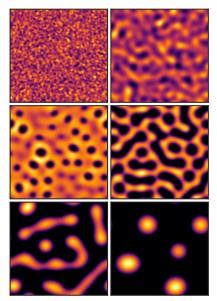
 $D_e(\rho) = D_0(1 - \frac{1}{2}\rho)e^{-\rho}$

Homogeneous configuration stable if

$$\bar{\rho} = \frac{1}{|\Omega|} \int\limits_{\Omega} \rho(x) \, dx < 2$$

If p
 2, then phase separation occurs

 Feedback loop: Accumulation induced slowdown + slowdown induced accumulation



Up to now, single behavioral rule:

Active Brownian motion with density dependent diffusivity

Introduce second behavioral rule: Population dynamics

Up to now, single behavioral rule:

Active Brownian motion with density dependent diffusivity

Introduce second behavioral rule: Population dynamics

$$A \xrightarrow{\lambda_r} A + A \qquad \qquad \lambda_r = \alpha \qquad (reproduction)$$
$$A + A \xrightarrow{\lambda_c} A \qquad \qquad \lambda_c = \alpha/\rho_0 \qquad (competition)$$

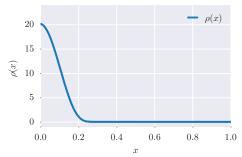
with carrying capacity ρ_0 and timescale α , leads to logistic growth.

 $\partial_t \rho = \nabla \cdot (D_e(\rho) \nabla \rho - \delta^2 \rho D(\rho) \nabla \Delta \rho) + \alpha \rho (1 - \rho / \rho_0)$

Phase separation eventually if

 $D_e(\rho_0) < 0$

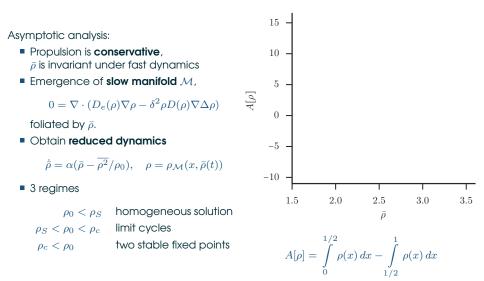
- System will drive itself into instability
- Coarsening stopped by growth, arrested phase separation[†]



[†] Cates, M. E. and Marenduzzo, D. and Pagonabarraga, I. and Tallleur, J. (2010) Tobias Grafke Non-equilibrium self-organization of motile bacteria

Consider large **timescale separation**, $\alpha \ll 1$, i.e. fast propulsion, slow reproduction

 $\partial_t \rho = \nabla \cdot \left(D_e(\rho) \nabla \rho - \delta^2 \rho D(\rho) \nabla \Delta \rho \right) + \alpha \rho (1 - \rho/\rho_0)$



Consider large **timescale separation**, $\alpha \ll 1$, i.e. fast propulsion, slow reproduction

 $\partial_t \rho = \nabla \cdot (D_e(\rho)\nabla\rho - \delta^2 \rho D(\rho)\nabla\Delta\rho) + \alpha \rho (1 - \rho/\rho_0)$

Asymptotic analysis:

- Propulsion is **conservative**, $\bar{\rho}$ is invariant under fast dynamics
- Emergence of **slow manifold** \mathcal{M} ,

 $0 = \nabla \cdot (D_e(\rho)\nabla\rho - \delta^2 \rho D(\rho)\nabla\Delta\rho)$

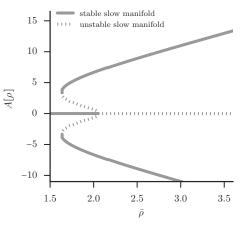
foliated by $\bar{\rho}$.

Obtain reduced dynamics

 $\dot{\bar{\rho}} = \alpha(\bar{\rho} - \overline{\rho^2}/\rho_0), \quad \rho = \rho_{\mathcal{M}}(x, \bar{\rho}(t))$

3 regimes

 $\begin{array}{ll} \rho_0 < \rho_S & \mbox{homogeneous solution} \\ \rho_S < \rho_0 < \rho_c & \mbox{limit cycles} \\ \rho_c < \rho_0 & \mbox{two stable fixed points} \end{array}$



$$A[\rho] = \int_{0}^{1/2} \rho(x) \, dx - \int_{1/2}^{1} \rho(x) \, dx$$

Consider large **timescale separation**, $\alpha \ll 1$, i.e. fast propulsion, slow reproduction

 $\partial_t \rho = \nabla \cdot (D_e(\rho)\nabla\rho - \delta^2 \rho D(\rho)\nabla\Delta\rho) + \alpha \rho (1 - \rho/\rho_0)$

Asymptotic analysis:

- Propulsion is **conservative**, $\bar{\rho}$ is invariant under fast dynamics
- Emergence of **slow manifold** \mathcal{M} ,

 $0 = \nabla \cdot (D_e(\rho)\nabla\rho - \delta^2 \rho D(\rho)\nabla\Delta\rho)$

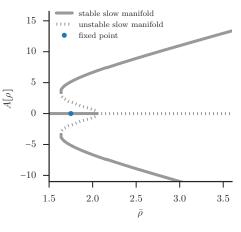
foliated by $\bar{\rho}$.

Obtain reduced dynamics

 $\dot{\bar{\rho}} = \alpha(\bar{\rho} - \overline{\rho^2}/\rho_0), \quad \rho = \rho_{\mathcal{M}}(x, \bar{\rho}(t))$

3 regimes

 $\begin{array}{ll} \rho_0 < \rho_S & \mbox{homogeneous solution} \\ \rho_S < \rho_0 < \rho_c & \mbox{limit cycles} \\ \rho_c < \rho_0 & \mbox{two stable fixed points} \end{array}$



$$A[\rho] = \int_{0}^{1/2} \rho(x) \, dx - \int_{1/2}^{1} \rho(x) \, dx$$

Consider large **timescale separation**, $\alpha \ll 1$, i.e. fast propulsion, slow reproduction

 $\partial_t \rho = \nabla \cdot (D_e(\rho)\nabla\rho - \delta^2 \rho D(\rho)\nabla\Delta\rho) + \alpha \rho (1 - \rho/\rho_0)$

Asymptotic analysis:

- Propulsion is **conservative**, $\bar{\rho}$ is invariant under fast dynamics
- Emergence of **slow manifold** \mathcal{M} ,

 $0 = \nabla \cdot (D_e(\rho)\nabla\rho - \delta^2 \rho D(\rho)\nabla\Delta\rho)$

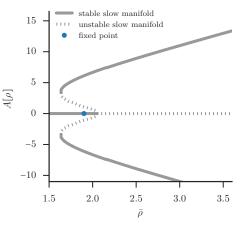
foliated by $\bar{\rho}$.

Obtain reduced dynamics

 $\dot{\bar{\rho}} = \alpha(\bar{\rho} - \overline{\rho^2}/\rho_0), \quad \rho = \rho_{\mathcal{M}}(x, \bar{\rho}(t))$

3 regimes

 $\begin{array}{ll} \rho_0 < \rho_S & \mbox{homogeneous solution} \\ \rho_S < \rho_0 < \rho_c & \mbox{limit cycles} \\ \rho_c < \rho_0 & \mbox{two stable fixed points} \end{array}$



$$A[\rho] = \int_{0}^{1/2} \rho(x) \, dx - \int_{1/2}^{1} \rho(x) \, dx$$

Tobias Grafke Non-equ

Consider large **timescale separation**, $\alpha \ll 1$, i.e. fast propulsion, slow reproduction

 $\partial_t \rho = \nabla \cdot (D_e(\rho)\nabla\rho - \delta^2 \rho D(\rho)\nabla\Delta\rho) + \alpha \rho (1 - \rho/\rho_0)$

Asymptotic analysis:

- Propulsion is **conservative**, $\bar{\rho}$ is invariant under fast dynamics
- Emergence of slow manifold M,

 $0 = \nabla \cdot (D_e(\rho)\nabla\rho - \delta^2 \rho D(\rho)\nabla\Delta\rho)$

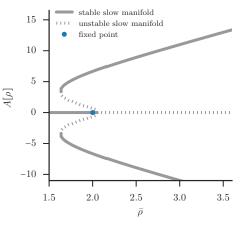
foliated by $\bar{\rho}$.

Obtain reduced dynamics

 $\dot{\bar{\rho}} = \alpha(\bar{\rho} - \overline{\rho^2}/\rho_0), \quad \rho = \rho_{\mathcal{M}}(x, \bar{\rho}(t))$

3 regimes

 $\begin{array}{ll} \rho_0 < \rho_S & \mbox{homogeneous solution} \\ \rho_S < \rho_0 < \rho_c & \mbox{limit cycles} \\ \rho_c < \rho_0 & \mbox{two stable fixed points} \end{array}$



$$A[\rho] = \int_{0}^{1/2} \rho(x) \, dx - \int_{1/2}^{1} \rho(x) \, dx$$

Consider large **timescale separation**, $\alpha \ll 1$, i.e. fast propulsion, slow reproduction

 $\partial_t \rho = \nabla \cdot \left(D_e(\rho) \nabla \rho - \delta^2 \rho D(\rho) \nabla \Delta \rho \right) + \alpha \rho (1 - \rho/\rho_0)$

Asymptotic analysis:

- Propulsion is **conservative**, $\bar{\rho}$ is invariant under fast dynamics
- Emergence of slow manifold M,

 $0 = \nabla \cdot (D_e(\rho)\nabla\rho - \delta^2 \rho D(\rho)\nabla\Delta\rho)$

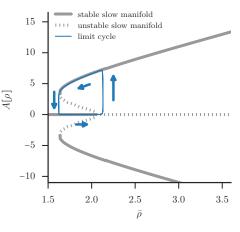
foliated by $\bar{\rho}$.

Obtain reduced dynamics

 $\dot{\bar{\rho}} = \alpha(\bar{\rho} - \overline{\rho^2}/\rho_0), \quad \rho = \rho_{\mathcal{M}}(x, \bar{\rho}(t))$

3 regimes

 $\begin{array}{ll} \rho_0 < \rho_S & \mbox{homogeneous solution} \\ \rho_S < \rho_0 < \rho_c & \mbox{limit cycles} \\ \rho_c < \rho_0 & \mbox{two stable fixed points} \end{array}$



$$A[\rho] = \int_{0}^{1/2} \rho(x) \, dx - \int_{1/2}^{1} \rho(x) \, dx$$

Consider large **timescale separation**, $\alpha \ll 1$, i.e. fast propulsion, slow reproduction

 $\partial_t \rho = \nabla \cdot (D_e(\rho)\nabla\rho - \delta^2 \rho D(\rho)\nabla\Delta\rho) + \alpha \rho (1 - \rho/\rho_0)$

Asymptotic analysis:

- Propulsion is **conservative**, $\bar{\rho}$ is invariant under fast dynamics
- Emergence of slow manifold M,

 $0 = \nabla \cdot (D_e(\rho)\nabla\rho - \delta^2 \rho D(\rho)\nabla\Delta\rho)$

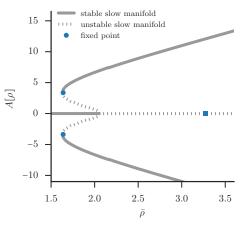
foliated by $\bar{\rho}$.

Obtain reduced dynamics

 $\dot{\bar{\rho}} = \alpha(\bar{\rho} - \overline{\rho^2}/\rho_0), \quad \rho = \rho_{\mathcal{M}}(x, \bar{\rho}(t))$

3 regimes

 $\begin{array}{ll} \rho_0 < \rho_S & \mbox{homogeneous solution} \\ \rho_S < \rho_0 < \rho_c & \mbox{limit cycles} \\ \rho_c < \rho_0 & \mbox{two stable fixed points} \end{array}$



$$A[\rho] = \int_{0}^{1/2} \rho(x) \, dx - \int_{1/2}^{1} \rho(x) \, dx$$

Consider large **timescale separation**, $\alpha \ll 1$, i.e. fast propulsion, slow reproduction

 $\partial_t \rho = \nabla \cdot (D_e(\rho)\nabla\rho - \delta^2 \rho D(\rho)\nabla\Delta\rho) + \alpha \rho (1 - \rho/\rho_0)$

Asymptotic analysis:

- Propulsion is **conservative**, $\bar{\rho}$ is invariant under fast dynamics
- Emergence of slow manifold M,

 $0 = \nabla \cdot (D_e(\rho)\nabla\rho - \delta^2 \rho D(\rho)\nabla\Delta\rho)$

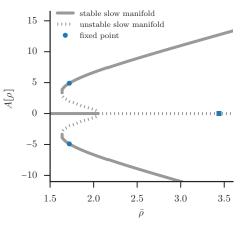
foliated by $\bar{\rho}$.

Obtain reduced dynamics

 $\dot{\bar{\rho}} = \alpha(\bar{\rho} - \overline{\rho^2}/\rho_0), \quad \rho = \rho_{\mathcal{M}}(x, \bar{\rho}(t))$

3 regimes

 $\begin{array}{ll} \rho_0 < \rho_S & \mbox{homogeneous solution} \\ \rho_S < \rho_0 < \rho_c & \mbox{limit cycles} \\ \rho_c < \rho_0 & \mbox{two stable fixed points} \end{array}$



$$A[\rho] = \int_{0}^{1/2} \rho(x) \, dx - \int_{1/2}^{1} \rho(x) \, dx$$

Consider large **timescale separation**, $\alpha \ll 1$, i.e. fast propulsion, slow reproduction

 $\partial_t \rho = \nabla \cdot (D_e(\rho)\nabla\rho - \delta^2 \rho D(\rho)\nabla\Delta\rho) + \alpha \rho (1 - \rho/\rho_0)$

Asymptotic analysis:

- Propulsion is **conservative**, $\bar{\rho}$ is invariant under fast dynamics
- Emergence of slow manifold M,

 $0 = \nabla \cdot (D_e(\rho)\nabla\rho - \delta^2 \rho D(\rho)\nabla\Delta\rho)$

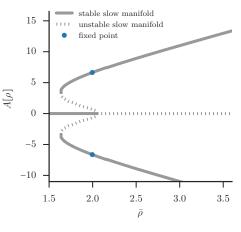
foliated by $\bar{\rho}$.

Obtain reduced dynamics

 $\dot{\bar{\rho}} = \alpha(\bar{\rho} - \overline{\rho^2}/\rho_0), \quad \rho = \rho_{\mathcal{M}}(x, \bar{\rho}(t))$

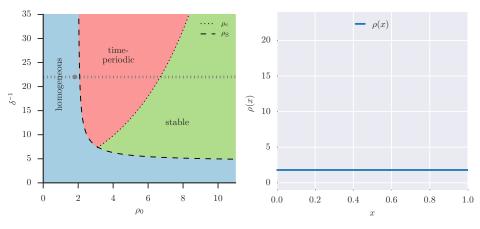
3 regimes

 $\begin{array}{ll} \rho_0 < \rho_S & \mbox{homogeneous solution} \\ \rho_S < \rho_0 < \rho_c & \mbox{limit cycles} \\ \rho_c < \rho_0 & \mbox{two stable fixed points} \end{array}$



$$A[\rho] = \int_{0}^{1/2} \rho(x) \, dx - \int_{1/2}^{1} \rho(x) \, dx$$

Tobias Grafke Non-eq

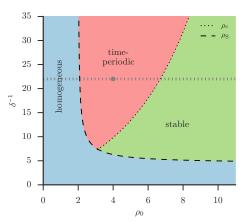


Homogeneous regime:

 $\rho_0 < \rho_c$

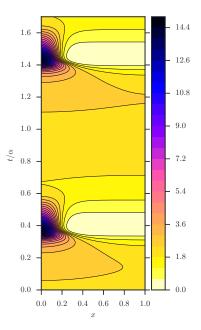
 $\label{eq:Omega} \Omega = [0,1]$ Neumann boundary conditions,

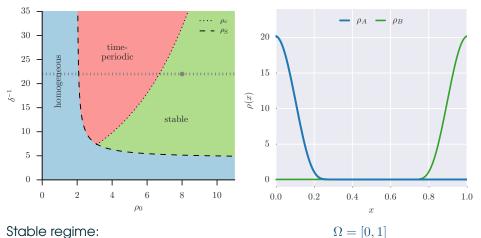
 $\partial_x \rho(0) = \partial_x \rho(1) = 0$



Time periodic regime:

$$\rho_c < \rho_0 < \rho_S$$





Stable regime:

 $\rho_c < \rho_0$

Neumann boundary conditions,

 $\partial_x \rho(0) = \partial_x \rho(1) = 0$

The effect of fluctuations

 $\partial_t \rho = \nabla \cdot (D_e(\rho) \nabla \rho - \delta^2 \rho D(\rho) \nabla \Delta \rho) + \alpha \rho (1 - \rho/\rho_0)$

- Is a **law of large numbers** (LLN) for $N \rightarrow \infty$ (where N typical number of particles)
- Gaussian fluctuations around these dynamics captured by central limit theorem (CLT)
- We are interested in long time behavior: Large deviation theory (LDT)
- Both propulsion and reproduction are subject to fluctuations for finite N.

Key object: Rate function

$$S_T(\phi) = \frac{1}{2} \int_0^T \left| \sigma(\phi)^{-1} \left(\dot{\phi} - b(\phi) \right) \right|^2 dt = \frac{1}{2} \int_0^T \mathcal{L}(\phi, \dot{\phi}) dt$$

associated with the S(P)DE

 $dX^{\epsilon}(t) = b(X^{\epsilon}(t)) dt + \sqrt{\epsilon}\sigma(X^{\epsilon}(t)) dW(t)$

Then, the probability that $\{X^{\epsilon}(t)\}_{t\in[0,T]}$ is close to a path $\{\phi(t)\}_{t\in[0,T]}$ is

$$\mathcal{P}\left\{\sup_{0\leq t\leq T} |X^{\epsilon}(t) - \phi(t)| < \delta\right\} \asymp \exp\left(-\epsilon^{-1}S_T(\phi)\right)$$

for $\epsilon \rightarrow 0$. The problem is reduced to a **minimization** problem

$$\mathcal{P}\left\{X^{\epsilon}(T) \in A | X^{\epsilon}(0) = x\right\} \asymp \exp\left(-\epsilon^{-1} \inf_{\phi:\phi(0) = x, \phi(T) \in A} S_{T}(\phi)\right)$$

Propulsion

Gradient system

$$\partial_t \rho = -M\delta E/\delta \rho + \sqrt{\frac{2}{N}}M^{1/2}\eta(x,t)$$

for

$$E(\rho) = \int_{\Omega} (\rho \log \rho - \rho + f(\rho) + \frac{1}{2} \delta^2 |\nabla \rho|^2) dx$$
$$M(\rho)\xi = \nabla \cdot (\rho D(\rho) \nabla \xi)$$

Propulsion

Gradient system

$$\partial_t \rho = -M\delta E/\delta \rho + \sqrt{\frac{2}{N}}M^{1/2}\eta(x,t)$$

for

$$E(\rho) = \int_{\Omega} (\rho \log \rho - \rho + f(\rho) + \frac{1}{2} \delta^2 |\nabla \rho|^2) dx$$
$$M(\rho)\xi = \nabla \cdot (\rho D(\rho) \nabla \xi)$$

Large deviation Hamiltonian

$$\begin{aligned} \mathcal{H}_p(\rho,\theta) &= \int\limits_{\Omega} \theta \nabla \cdot \left(\mathcal{D}_e \nabla \rho - \delta^2 \rho D \nabla \nabla^2 \rho \right) \\ &+ \frac{1}{2} \rho D |\nabla \theta|^2 \, dx \end{aligned}$$

Propulsion

 $E(\rho) =$

 $M(\rho)\xi =$

Reproduction

Gradient system

$$\partial_t \rho = -M\delta E/\delta \rho + \sqrt{\frac{2}{N}}M^{1/2}\eta(x,t)$$

Poisson processes at each location for the reactions

for

$$A \xrightarrow{\lambda_r} A + A, \quad \lambda_r = \alpha \qquad \text{(reproduction)}$$

$$A + A \xrightarrow{\lambda_c} A, \qquad \lambda_c = \alpha/\rho_0 \quad \text{(competition)}$$

$$\int_{\Omega} (\rho \log \rho - \rho + f(\rho) + \frac{1}{2}\delta^2 |\nabla \rho|^2) \, dx \text{ then LLN is}$$

$$\nabla \cdot (\rho D(\rho) \nabla \xi) \qquad \qquad \partial_t \rho = \alpha \rho (1 - \rho/\rho_0)$$

with Poisson noise.

Large deviation Hamiltonian

$$\begin{split} \mathcal{H}_p(\rho,\theta) = & \int_{\Omega} \theta \nabla \cdot \left(\mathcal{D}_e \nabla \rho - \delta^2 \rho D \nabla \nabla^2 \rho \right) \\ & + \frac{1}{2} \rho D |\nabla \theta|^2 \ dx \end{split}$$

Propulsion

Reproduction

Gradient system

$$\partial_t \rho = -M\delta E/\delta \rho + \sqrt{\frac{2}{N}}M^{1/2}\eta(x,t)$$

Poisson processes at each location for the reactions

 $A \xrightarrow{\lambda_r} A + A$, $\lambda_r = \alpha$ (reproduction)

for

for
$$A + A \xrightarrow{\lambda_c} A, \qquad \lambda_c = \alpha/\rho_0 \quad \text{(competition)}$$
$$E(\rho) = \int_{\Omega} (\rho \log \rho - \rho + f(\rho) + \frac{1}{2}\delta^2 |\nabla \rho|^2) \, dx \text{ then LLN is}$$
$$M(\rho)\xi = \nabla \cdot (\rho D(\rho) \nabla \xi) \qquad \qquad \partial_t \rho = \alpha \rho (1 - \rho/\rho_0)$$

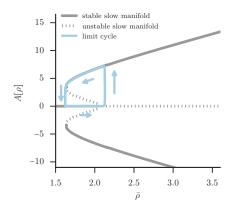
with Poisson noise.

Large deviation Hamiltonian

$$\begin{aligned} \mathcal{H}_{p}(\rho,\theta) &= \int_{\Omega} \theta \nabla \cdot \left(\mathcal{D}_{e} \nabla \rho - \delta^{2} \rho D \nabla \nabla^{2} \rho \right) \\ &+ \frac{1}{2} \rho D |\nabla \theta|^{2} dx \end{aligned} \qquad \qquad \mathcal{H}_{r}(\rho,\theta) &= \alpha \int_{\Omega} \left(\rho(e^{\theta} - 1) + \rho^{2} / \rho_{0}(e^{-\theta} - 1) \right) dx \end{aligned}$$

(corresponding SPDE is ill-posed)

Tobias Grafke Non-equilibrium self-organization of motile bacteria



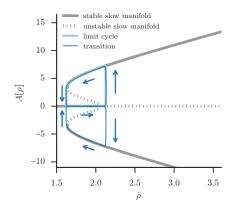
Consider $\rho_S < \rho_0 < \rho_c$

- Tiny fluctuations alter the structure of the limit cycle
- These are not rare events:

Zero action for transition when $\alpha \rightarrow 0$

T. Grafke, M. Cates, E. Vanden-Eijnden (2017) arXiv:1703.06923

Tobias Grafke Non-equilibrium self-organization of motile bacteria



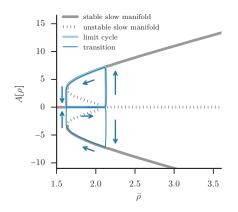
Consider $\rho_S < \rho_0 < \rho_c$

- Tiny fluctuations alter the structure of the limit cycle
- These are not rare events:

Zero action for transition when $\alpha \rightarrow 0$

T. Grafke, M. Cates, E. Vanden-Eijnden (2017) arXiv:1703.06923

Tobias Grafke Non-equilibrium self-organization of motile bacteria

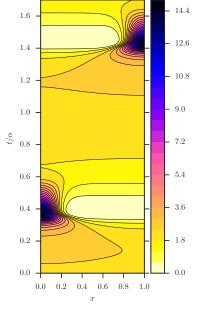


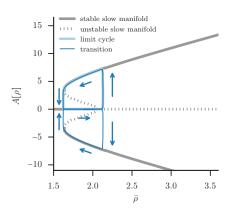
Consider $\rho_S < \rho_0 < \rho_c$

- Tiny fluctuations alter the structure of the limit cycle
- These are not rare events: Zero action for transition when $\alpha \rightarrow 0$

T. Grafke, M. Cates, E. Vanden-Eijnden (2017) arXiv:1703.06923

Tobias Grafke



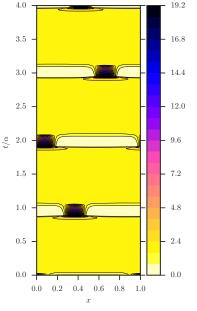


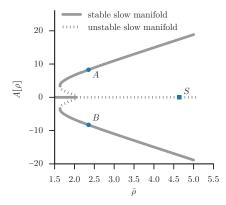
Consider $\rho_S < \rho_0 < \rho_c$

- Tiny fluctuations alter the structure of the limit cycle
- These are not rare events: Zero action for transition when $\alpha \rightarrow 0$

T. Grafke, M. Cates, E. Vanden-Eijnden (2017) arXiv:1703.06923

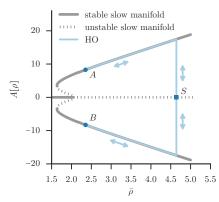
Tobias Grafke





Consider $\rho_c < \rho_0$

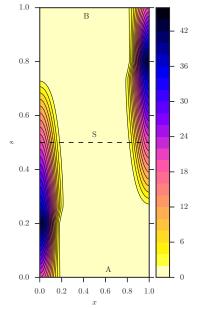
- Fixed points become metastable
- Transitions between them:
 Finite action, exponentially small probability, LDT regime

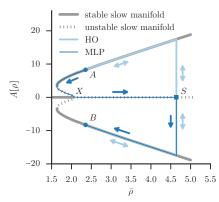


Consider $\rho_c < \rho_0$

- Fixed points become metastable
- Transitions between them:
 Finite action, exponentially small probability, LDT regime



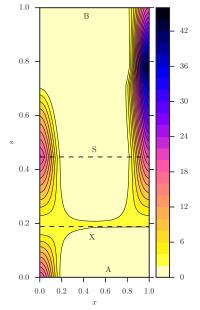


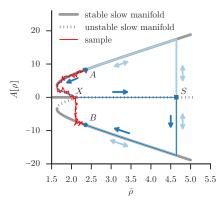


Consider $\rho_c < \rho_0$

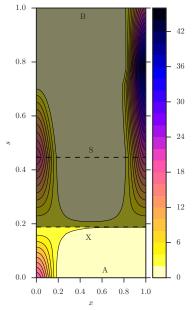
- Fixed points become metastable
- Transitions between them:
 Finite action, exponentially small probability, LDT regime







At finite N, accounting for entropy, only part of the transition with **non-zero action** is robust (and matters).



T. Grafke, E. Vanden-Eijnden (2017) arXiv:1704.06723

Tobias Grafke

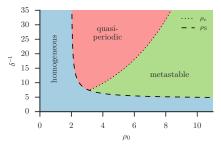
Non-equilibrium self-organization

Complex collective behavior for simple active agents:

Propulsion and Reproduction

- When $\rho_0 < \rho_S$, **planktonic** phase is robust.
- When ρ_S < ρ₀ < ρ_c, particles oscillate between biofilm and planktonic phase
- When ρ₀ < ρ_c, biofilms are metastable. They rarely disperse and reform by dieing out
- Full **phase diagram** depends on carrying capacity ρ_0 and **domain size** δ^{-1} .





T. Grafke, M. Cates, E. Vanden-Eijnden (2017) arXiv:1703.06923

Tobias Grafke Non-equilibrium self-organization of motile bacteria

Numerical Computation of Large Deviation Minimizers

Main problem

For our system and observable, find the **minimizer** ϕ^\star such that

 $S_T(\phi^\star) = \inf_{\phi} S_T(\phi) \,,$

where the minimization is over all trajectories fulfilling the boundary conditions.

The knowledge of this minimizer (MLP) yields

- Most probable evolution in time from initial state into this final configuration
- Corresponding **optimal force**, computable from auxiliary field θ
- Tail scaling behavior of the **PDF** of our observable, roughly through $\mathcal{P}\{x^{\epsilon}(T)\} \sim \exp(-\frac{1}{\epsilon} \inf_{\phi} S_T(\phi))$

Numerical Computation of Large Deviation Minimizers

Main problem

For our system and observable, find the **minimizer** ϕ^\star such that

 $S_T(\phi^\star) = \inf_{\phi} S_T(\phi) \,,$

where the minimization is over all trajectories fulfilling the boundary conditions.

Its computation is challenging:

- This is an infinite-dimensional PDE constraint optimization. The search space is large (space-time).
 Each iteration we have to solve a system of coupled PDEs.
- If we are computing transition probabilities, we are interested in the Quasipotential,

$$V(x_1, x_2) = \inf_{T>0} \inf_{\phi} S_T(\phi)$$

This infimum is not attained in general, $T \rightarrow \infty$.

Challenges: Infinite transition time and geometric rate function

Quasipotential

$$V(x_1, x_2) = \inf_{T>0} \inf_{\phi} S_T(\phi)$$

This infimum is not attained in general, $T \rightarrow \infty$.

In the case $T \to \infty$, realize, that $\mathcal{H}(x, \theta) = 0$, so that

$$\int \mathcal{L}(x,\dot{x}) dt = \int \sup_{\theta} \left(\langle \dot{x}, \theta \rangle - \mathcal{H}(x,\theta) \right) dt = \sup_{\theta: \mathcal{H}(x,\theta)=0} \int \langle \dot{x}, \theta \rangle dt$$

Effectively:

Reduce minimization over all paths to finding **geodesic** of the associated (Finsler) **metric**.

Challenges: Infinite transition time and geometric rate function

Quasipotential

$$V(x_1, x_2) = \inf_{T>0} \inf_{\phi} S_T(\phi)$$

This infimum is not attained in general, $T \rightarrow \infty$.

In the case $T \to \infty$, realize, that $\mathcal{H}(x, \theta) = 0$, so that

$$\int \mathcal{L}(x,\dot{x}) dt = \int \sup_{\theta} \left(\langle \dot{x}, \theta \rangle - \mathcal{H}(x,\theta) \right) dt = \sup_{\theta: \mathcal{H}(x,\theta)=0} \int \langle \dot{x}, \theta \rangle dt$$

Effectively:

Reduce minimization over all paths to finding **geodesic** of the associated (Finsler) **metric**.

Heymann, Vanden-Eijnden (2008), Grafke, Schäfer, Vanden-Eijnden (2017)

Summary

- Non-equilibrium statistical mechanics theory of active matter is still in its infancy
- One example is Motility induced phase separation direct consequence of motile agents with density dependent drift velocity
- Adding population dynamics is enough to yield complex emergent behavior reminiscent of biofilm-planktonic lifecycle
- Fluctuations in MIPS + Reproduction can be analyzed by LDT
- Noise-driven spatio-temporal self-organization
 - Limit cycles are temporally but not spatially robust against fluctuations
 - Transitions between metastable colonies are out-of-equilibrium and occurs different to detailed-balance intuition
- Computation via **geometric minimization** of LDT rate function