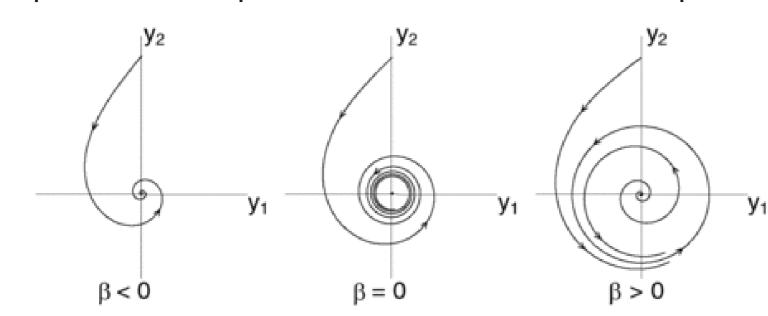
## Introduction to Stochastic Hopf Bifurcation

We study the two-dimensional normal form of a Hopf bifurcation with additive white noise and phase-amplitude coupling:

$$dy_1 = (\beta y_1 - \omega y_2 - (ay_1 + by_2)(y_1^2 + y_2^2))dt + \sigma dW_1(t),$$
  

$$dy_2 = (\beta y_2 + \omega y_1 - (ay_1 - by_2)(y_1^2 + y_2^2))dt + \sigma dW_2(t),$$
(1)

where  $W_1$ ,  $W_2$  are independent Brownian motions and  $\omega$ , a,  $\sigma$ , b > 0. If  $\sigma = 0$ , such a system exhibits a supercritical Hopf bifurcation for bifurcation parameter  $\beta \in \mathbb{R}$ :



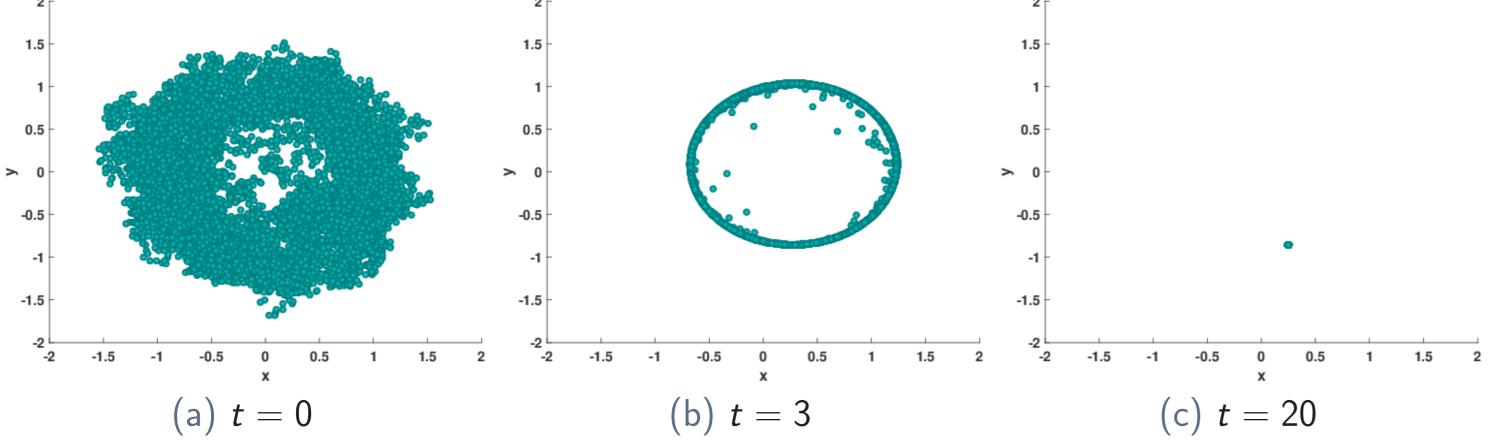
We investigate the system for  $\sigma>0$  and study the impact of the parameter b which represents shear via phase-amplitude coupling. This can be seen in polar coordinates

$$dr = \left(\beta r - ar^3 + \frac{\sigma^2}{2r}\right) dt + \sigma dW_r(t),$$
 $d\phi = \left[\omega + br^2\right] dt + \frac{\sigma}{r} dW_\phi(t).$ 

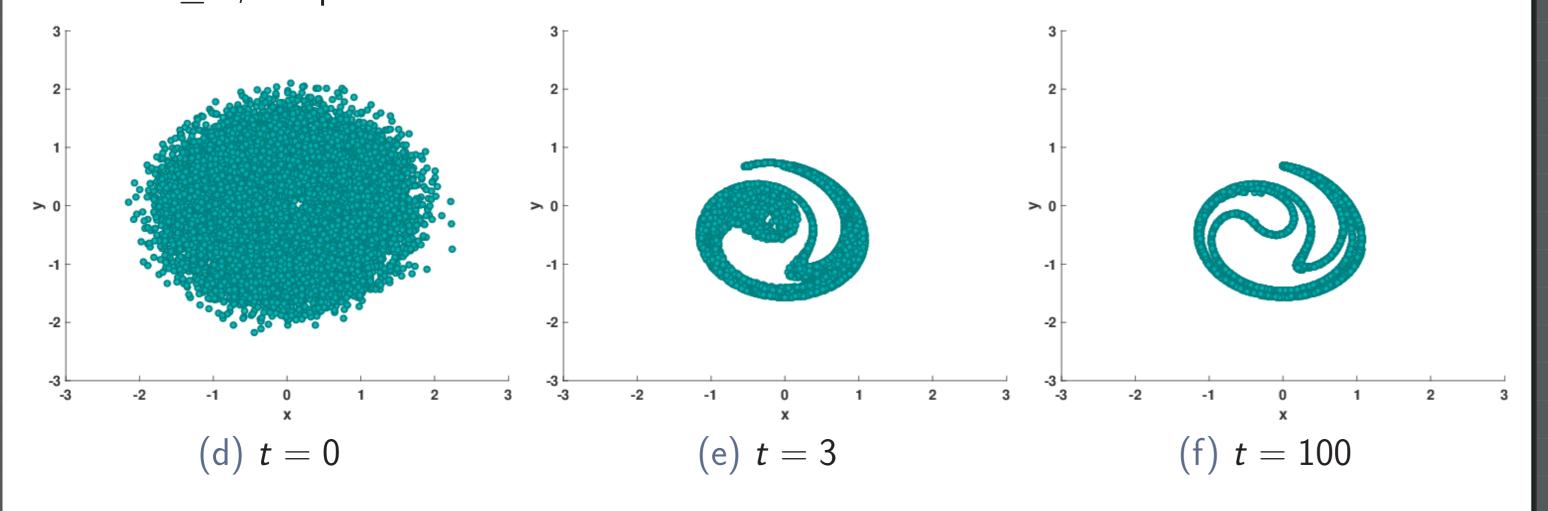
**Applications**: In the Zebiak-Cane model, which describes the tropical Pacific annual mean climate state, a Hopf bifurcation occurs at a critical value of the ocean-atmosphere coupling strength  $\beta$ . Dijkstra et al. (2008) study the impact of noise on the Hopf bifurcation but don't provide a dynamical analysis and don't consider phase-amplitude coupling. We show transitions between ordered and chaotic behaviour depending on continuous time noise and shear, partially solving a long-standing theoretical problem posed by Lai-Sang Young and co-workers and also investigated by Wieczorek (2009) with respect to Laser models.

#### Numerical observations

We start simulations at times t < 0 and run the system until time 0. This allows to study fixed attracting objects. We make the following observations for  $\beta > 0$ , i.e. after the bifurcation. First we observe that, for small  $b \ge 0$ , trajectories with different initial conditions but exposed to the same noise realisations synchronise:



For  $b \ge 8$ , the pullback attractor seems to show chaotic behaviour:



# Random Dynamical Systems induced by an SDE and invariant measures

We consider the problem of stochastic bifurcations within the framework of random dynamical systems: A **random dynamical system** (RDS) on the measurable space  $(X, \mathcal{B})$  over a *metric dynamical system*  $(\Omega, \mathcal{F}, \mathbb{P}, (\theta_t)_{t \in \mathbb{R}})$  with time  $\mathbb{T}$  is a  $\mathcal{B}(\mathbb{T}) \bigotimes \mathcal{F} \bigotimes \mathcal{B}$ -meas. map

$$\varphi: \mathbb{T} \times \Omega \times X \to \mathbb{R}^d, \quad (t, \omega, x) \mapsto \varphi(t, \omega)x,$$

which satisfies for all  $\omega \in \Omega$  and  $t,s \in \mathbb{T}$  the *cocycle* property

$$\varphi(0,\omega)=\operatorname{id},\quad \varphi(t+s,\omega)=\varphi(t,\theta_s\omega)\circ\varphi(s,\omega).$$

#### A stochastic differential equation(SDE) of the form

$$dX_t = f(X_t)dt + \sigma(X_t)dW_t \quad X_0 = x, \quad \text{on } \mathbb{R}^d,$$
 (2)

induces a continuous RDS  $(\theta, \varphi)$  for time  $\mathbb{T} = \mathbb{R}_+$  under typical Lipschitz and growth conditions. In this case  $(\Omega, \mathbb{P})$  is the Wiener space and  $\theta_t$  the ergodic shift map.

A **probability measure**  $\mu$  on  $\Omega \times \mathbb{R}^d$  is **invariant** for the RDS if for  $\Theta_t : \Omega \times X \to \Omega \times X$  denoting the skew-product flow, i.e.  $\Theta_t(\omega, x) = (\theta_t \omega, \varphi(t, \omega)x)$ ,

- $1. \Theta_t \mu = \mu$  for all  $t \in \mathbb{T}$ ,
- 2. the marginal of  $\mu$  on  $\Omega$  is  $\mathbb{P}$ , i.e.  $\mu(d\omega, dx) = \mu_{\omega}(dx)\mathbb{P}(d\omega)$ .

### Random attractors and Lyapunov exponents

Let the state space X be a Polish space (e.g.  $\mathbb{R}^d$  as in our case): A **random attractor**  $A: \Omega \to \mathcal{P}(X)$  of the RDS  $(\theta, \varphi)$  is a  $\mathbb{P}$ -a.s. compact set valued mapping with

- 1.  $\varphi(t,\omega)A(\omega)=A(\theta_t\omega)$  for all t>0 and a.a.  $\omega\in\Omega$ ,
- 2.  $\lim_{t\to\infty} d(\varphi(t,\theta_{-t}\omega)B,A(\omega))=0$   $\mathbb{P}$ -a.s. for every compact  $B\subset X$ .

If attraction in the limit just holds for all points  $x \in X$ , we call it a **random point attractor** which is the support for the disintegrations  $\mu_{\omega}$  of an invariant measure  $\mu$ .

Consider the SDE (2): If  $f \in C^{1,\delta}$  and  $\sigma \in C^{2,\delta}$  for some  $\delta > 0$ , the induced RDS  $(\theta, \varphi)$  is  $C^1$ . If it has an ergodic inv. measure  $\mu$  and satisfies an integrability condition, there are real numbers  $\lambda_1 > \cdots > \lambda_p$ , the **Lyapunov exponents** of  $\varphi$  w.r.t.  $\mu$ , s.t. for  $\mu$ -a.e.  $(\omega, x)$  and for all  $0 \neq v \in \mathbb{R}^d$ 

$$\lim_{t\to\infty}\frac{1}{t}\log\|D\varphi(t,\omega,x)v\|\in\{\lambda_i\}_{i=1}^p.$$

#### Theorem (Synchronisation)

The random dynamcial system induced by the stochastic differential equation (1) possesses a random attractor  $A(\omega)$  and exhibits synchronisation, i.e.  $A(\omega)$  is a singleton, for any  $\beta \in \mathbb{R}$  if  $\lambda_1 < 0$ . We know that  $\lambda_1 < 0$  if

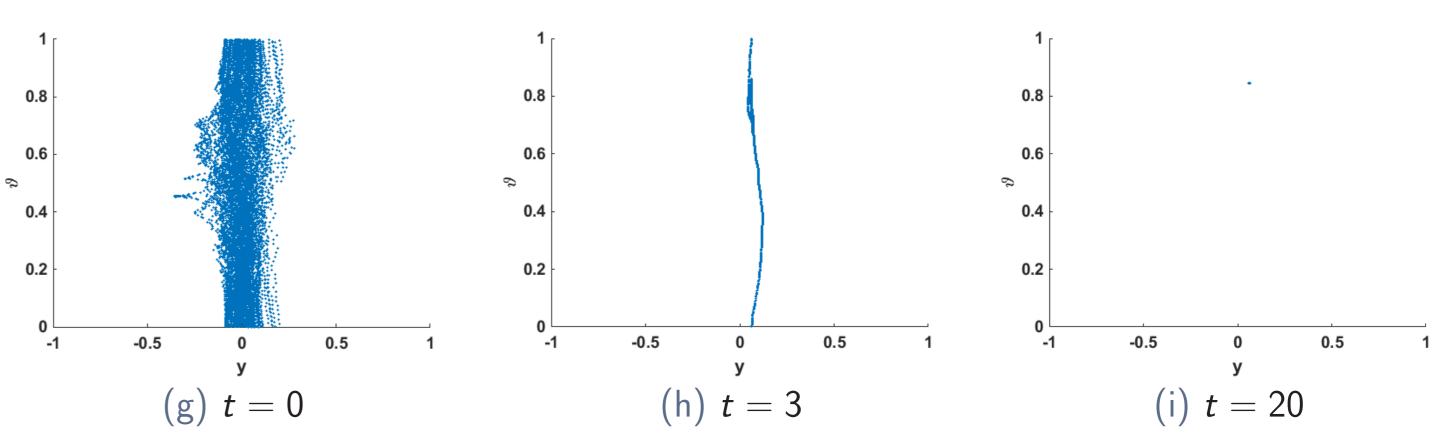
- a)  $\beta \leq 0$  and b < a (and/or  $\sigma$  small),
- b)  $\beta > 0$  and  $0 \le b \le \frac{ac}{2(\alpha+c)} \le \frac{1}{2}a$ , where  $c = \mathcal{O}(\sigma)$ .
- c) we fix  $b \ge 0$ , define  $\varepsilon = \sigma^2 a^2/\beta^2$  and let  $\varepsilon \to 0$  ( $\lambda_1 = C\varepsilon + \mathcal{O}(\varepsilon^2)$  with C < 0).

# Cylinder model

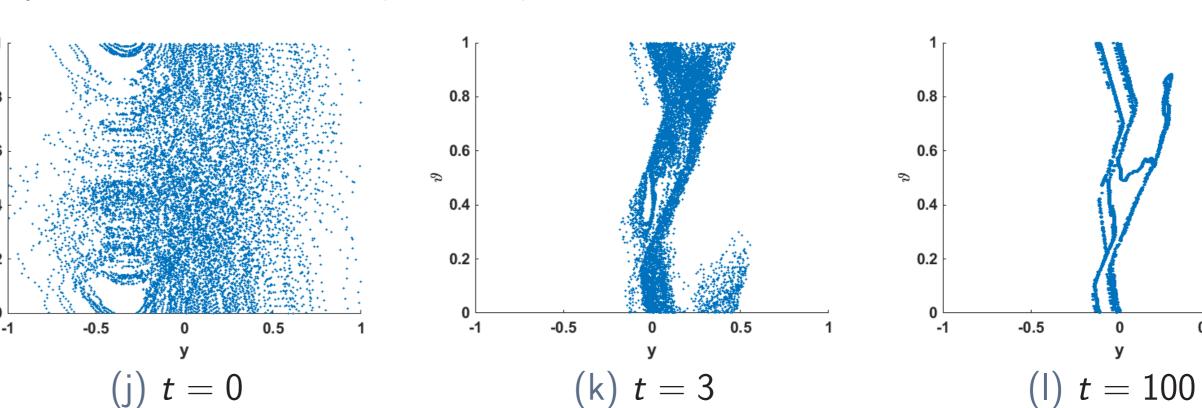
In the case of large shear we expect  $\lambda_1>0$  which indicates the existence of a chaotic attractor. As this is difficult to show for (1), we consider the following simlified model of a stochastically driven limit cycle

$$dy = -\alpha y dt + \sigma f(\vartheta) \circ dW_t^1, d\vartheta = (1 + by) dt,$$
(3)

where  $(y, \vartheta) \in \mathbb{R} \times \mathbb{S}^1$  are cylindrical amplitude-phase coordinates, and  $W^1_t$  denotes one-dimensional Brownian motion entering the equation as noise of Stratonovich type. For the parameter values  $\sigma = 0.5, \alpha = 1.5, b = 3$ , we observe synchronisation.



For parameter values  $\sigma=2, \alpha=1.5, b=3$ , we observe chaos:



#### Theorem (Transition to chaos)

Consider the stochastic differential equation (3) where  $f: \mathbb{S}^1 \simeq [0,1) \to \mathbb{R}$  is continuous and piecewise linear with constant absolute value of the derivative almost everywhere. Then for all  $\alpha > 0$  and  $b \neq 0$ , there exist  $\sigma_-(\alpha, b) \leq \sigma_0(\alpha, b) \leq \sigma_+(\alpha, b)$  such that the top Lyapunov exponent  $\lambda_1(\alpha, b, \sigma)$  of the random attractor of (3) satisfies

$$\lambda_1(\alpha, b, \sigma) \left\{ egin{array}{ll} < 0 & ext{if } 0 < \sigma < \sigma_-(lpha, b) \,, \ &= 0 & ext{if } \sigma = \sigma_0(lpha, b) \,, \ &> 0 & ext{if } \sigma > \sigma_+(lpha, b) \,. \end{array} 
ight.$$

This has the following implications: If  $0 < \sigma < \sigma_{-}(\alpha, b)$ , the random point attractor of (3) is an attracting random equilibrium. If  $\sigma > \sigma_{+}(\alpha, b)$  the random point attractor of system (3) is a random strange attractor (and not an attracting random equilibrium).

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