

Superpositions, transition probabilities and primitive observables in infinite quantum systems

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Motivation

Simple systems (“particles”) in quantum mechanics are

- described by *pure* states (maximal information)
- satisfy superposition principle (interference, entanglement)
- admit statistical interpretation (transition probabilities)

Meaningful for finite systems; but problems in QFT:

- localized (partial) states are *never* pure (Reeh-Schlieder)
- inevitable loss of information due to radiation (Huygens)
- appearance of horizons (Unruh . . .)

Simple systems are often to be described by non-pure states.

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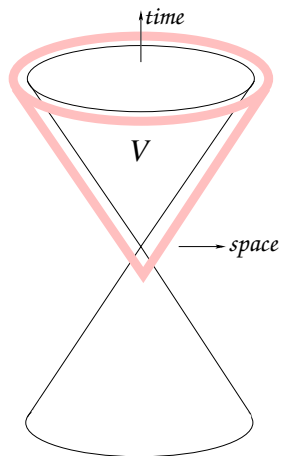


Fig. Restricted information in V due to outgoing radiation

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Basics: (finite quantum systems)

- observables: $\mathcal{N} \simeq \mathcal{B}(\mathcal{H})$ type I factors
- states: $\omega : \mathcal{N} \rightarrow \mathbb{C}$ positive, linear, normalized functionals
- pure states: $\omega \neq p_1 \omega_1 + p_2 \omega_2$ (not mixed)

Pure states admit:

- bijective lifts: $\omega \rightarrow \mathbb{T} \Omega \subset \mathcal{H}$ s.t. $\omega(A) = \langle \Omega, A \Omega \rangle$, $A \in \mathcal{N}$
- superpositions: $\omega_1, \omega_2 \rightarrow \mathbb{T} \Omega_1, \mathbb{T} \Omega_2 \rightarrow \mathbb{T}(c_1 \Omega_1 + c_2 \Omega_2) \rightarrow \omega_{12}$
resulting states are again pure (relative phases matter)
- transition probabilities: $\omega_1, \omega_2 \rightarrow \omega_1 \cdot \omega_2 \doteq |\langle \Omega_1, \Omega_2 \rangle|^2$
expectation values of observables $\omega_1 \cdot \omega_2 = \omega_1(P_2) = \omega_2(P_1)$

Fact: Algebras of observables \mathcal{M} are not always factors of type I

Task: Characterization of “simple systems” on non-type I factors \mathcal{M} and determination of their properties

Observation: Algebras \mathcal{M} of interest are hyperfinite factors

Ingredients for solution:

- funnels of type I algebras (replace $\mathcal{B}(\mathcal{H})$ for finite systems)
- generic states on funnels (replaces concept of pure states)
- primitive observables (replace minimal projections)

Message: Generic states on funnels describe “simple systems”

Funnels

Hyperfinite factors \mathcal{M} generated by

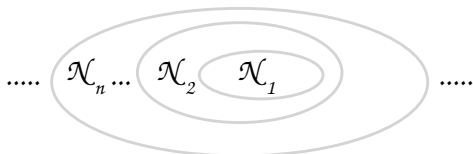
- $\mathcal{N}_1 \subset \mathcal{N}_2 \cdots \subset \mathcal{N}_n \cdots$ type I_∞ factors with common identity
- s.t. $\mathcal{N}'_n \cap \mathcal{N}_{n+1}$ infinite dimensional (hence type I_∞), $n \in \mathbb{N}$,
- $\mathcal{N} = \bigcup_n \mathcal{N}_n$ dense in \mathcal{M} in strong operator topology

Remarks:

- \mathcal{N} called proper sequential type I_∞ **funnel** [Takesaki]
- C^* -algebras generated by funnels \mathcal{N} are isomorphic
- different funnels generating \mathcal{M} are related elements of $\text{In } \mathcal{M}$

Present context:

\mathcal{N} **not** closed, allowing unified analysis of states of any infinite type

Physical interpretation:

Observables localized in increasing regions

- relativistic QFT's having split property (semilocal nets)
- non-relativistic QFT's
- infinite lattice systems . . .

Generic states

States $\omega : \mathcal{N} \rightarrow \mathbb{C}$, GNS–representation $(\pi, \mathcal{H}, \Omega)$

- locally normal, *i.e.* weakly continuous on unit balls of \mathcal{N}_n , $n \in \mathbb{N}$,
- faithful, *i.e.* $\omega(A^*A) = 0$ implies $A = 0$
- **generic**, *viz.* representing vector Ω cyclic for $\mathcal{N}'_n \cap \mathcal{N}_{n+1}$, $n \in \mathbb{N}$

Remark: Generic vector states form dense G_δ set [Dixmier, Marechal]

Definition

Let ω be generic. Its **orbit** under non–mixing operations is given by

$$\omega_{\mathcal{N}} \doteq \{\omega_A = \omega \circ \text{Ad } A : A \in \mathcal{N}, \omega_A(1) = 1\},$$

where $\text{Ad } A(B) \doteq A^*BA$, $B \in \mathcal{N}$.

Physical interpretation:

Generic state ω describes “global background” in which physical operations are performed (“state of the world”). These operations produce the corresponding orbit $\omega_{\mathcal{N}}$.

Examples:

- vacuum state in QFT
- thermal equilibrium states in QFT
- Hadamard states in QFT on curved spacetime

Superpositions

Fix generic state ω (any type), orbit $\omega_{\mathcal{N}}$. Norm distance

$$\|\omega_A - \omega_B\| \doteq \sup_{C \in \mathcal{N}_1} |\omega_A(C) - \omega_B(C)|, \quad \omega_A, \omega_B \in \omega_{\mathcal{N}}.$$

Proposition

There exists a lift from $\omega_{\mathcal{N}}$ to rays in \mathcal{N} which is

- 1 *bijjective: $\omega_A = \omega_B$ iff $B = tA$ for $t \in \mathbb{T}$*
- 2 *locally continuous: if $\|\omega_{A_m} - \omega_A\| \rightarrow 0$ for (bounded) $A_m, A \in \mathcal{N}_n$, n fixed, then $t_m A_m \rightarrow A$ in the strong operator topology*
- 3 *locally complete: if $\|\omega_{A_l} - \omega_{A_m}\| \rightarrow 0$ for (bounded) $A_l, A_m \in \mathcal{N}_n$, there is $A \in \mathcal{N}_n$ such that $t_m A_m \rightarrow A$ and $\|\omega_{A_m} - \omega_A\| \rightarrow 0$.*

Note that \mathcal{N} is a pre-Hilbert space, i.e. result analogous to lifting pure states to rays in Hilbert space

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Physical interpretation:

- ③ $\omega_{\mathcal{N}}$ maximal set of states arising from local non-mixing operations
- ① superpositions of states in $\omega_{\mathcal{N}}$ are meaningful,

$$\omega_A, \omega_B \rightarrow \mathbb{T} A, \mathbb{T} B \rightarrow \mathbb{T} (c_A A + c_B B) \rightarrow \omega_{(c_A A + c_B B)},$$

and relative phase between $c_A, c_B \in \mathbb{C}$ matters

Mixtures:

$$\text{Conv } \omega_{\mathcal{N}} \doteq \left\{ \sum_m p_m \omega_{A_m} : \omega_{A_m} \in \omega_{\mathcal{N}}, p_m > 0, \sum_m p_m = 1 \right\}$$

Proposition

Let $\omega_A = \sum_{m=1}^M p_m \omega_{A_m} \in \omega_{\mathcal{N}}$; then $\omega_{A_1} = \dots = \omega_{A_M} = \omega_A$.

$\omega_{\mathcal{N}}$ are the extreme points of $\text{Conv } \omega_{\mathcal{N}}$ in complete analogy to case of pure states

Transition probabilities

Definition

Transition probability for $\omega_A, \omega_B \in \omega_{\mathcal{N}}$: $\omega_A \cdot \omega_B \doteq |\omega(A^*B)|^2$

Remark: comparison with Uhlmann transition probability

$$\omega_A \cdot \omega_B \leq \omega_A \overset{U}{\cdot} \omega_B = \sup_{\Omega_A, \Omega_B} |\langle \Omega_A, \Omega_B \rangle|^2.$$

Proposition

Let $\omega_A, \omega_B \in \omega_{\mathcal{N}}$.

- 1 $0 \leq \omega_A \cdot \omega_B \leq 1$ (notion of **orthogonality**), $\omega_A \cdot \omega_B = \omega_B \cdot \omega_A$
- 2 $\omega_A \cdot \omega_B \leq 1 - \frac{1}{4} \|\omega_A - \omega_B\|^2$ where equality holds iff ω is pure
- 3 $\omega_A, \omega_B \mapsto \omega_A \cdot \omega_B$ **locally continuous**
- 4 there exist **complete families** of orthogonal states $\omega_{A_m} \in \omega_{\mathcal{N}}$, $m \in \mathbb{N}$, i.e. $\sum_m \omega_B \cdot \omega_{A_m} = 1$ for any $\omega_B \in \omega_{\mathcal{N}}$.

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Algebra of states

Input: $\text{Span } \omega_{\mathcal{N}}$. By polarization formula

$$\omega(B^* \cdot A) = \frac{1}{4} \sum_{k=0}^3 i^k \omega((B + i^k A)^* \cdot (B + i^k A)) \in \text{Span } \omega_{\mathcal{N}}.$$

Note: Expression not invariant under substitutions $A \mapsto t_A A$, $B \mapsto t_B B$.

Definition

Let $\omega_A, \omega_B \in \omega_{\mathcal{N}}$. Corresponding product $\omega_A \times \omega_B \in \text{Span } \omega_{\mathcal{N}}$ given by

$$\omega_A \times \omega_B(C) \doteq \omega(A^* B) \omega(B^* C A), \quad C \in \mathcal{N},$$

is well defined (phases t_A, t_B cancel).

Proposition

- 1 The map $\omega_A, \omega_B \mapsto \omega_A \times \omega_B$ extends linearly in both entries to an associative product, i.e. $\text{Span } \omega_{\mathcal{N}}$ is an algebra.
- 2 The antilinear involution $\dagger : \text{Span } \omega_{\mathcal{N}} \rightarrow \text{Span } \omega_{\mathcal{N}}$ given by

$$\left(\sum_m c_m \omega_{A_m}\right)^\dagger \doteq \left(\sum_m \bar{c}_m \omega_{A_m}\right)$$
 is consistent with the product, i.e. $\mathcal{C} \doteq \text{Span } \omega_{\mathcal{N}}$ is a $*$ -algebra
- 3 \mathcal{C} is an \mathcal{N} -bimodule

Further structure:

- spectral theorem exists in \mathcal{C} (in particular: unique decomposition of elements of $\text{Conv } \omega_{\mathcal{N}}$ into orthogonal states)
- there exists spatial isomorphism $\mathcal{C} \leftrightarrow \mathcal{C}_{\mathcal{H}}$ where $\mathcal{C}_{\mathcal{H}} \subset \mathcal{B}(\mathcal{H})$ is \mathcal{N} -bimodule of finite rank operators.

Question: How is the type of ω , respectively of \mathcal{M} , encoded in the structure of the “skeleton” \mathcal{C} of $\mathcal{C}^{-\omega} = \mathcal{M}_*$?

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Primitive observables

Question: (When) are the transition probabilities observable?

Recall: Non-mixing operations, $V \in \mathcal{N}$,

$$\omega \mapsto (1/\omega(V^*V)) \omega \circ \text{Ad } V.$$

Restrict to unitaries $U^*U = 1 = UU^*$ (observable) inducing transitions

$$\omega_A \mapsto \omega_A \circ \text{Ad } U = \omega_{UA}, \quad \omega_A \in \omega_{\mathcal{N}}.$$

Standard examples: Effects of temporary perturbations of dynamics

Transition probability between initial and final states:

$$\omega_A \cdot (\omega_A \circ \text{Ad } U) = \omega_A \cdot \omega_{UA} = |\omega_A(U)|^2$$

Alternative interpretation: "Fidelity" of operation U in given state ω_A

$\omega_A \cdot \omega_{UA}$ can be determined by measurements of U in state ω_A .

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A primitive observable is fixed by a unitary $U \in \mathcal{N}$. For any $\omega_A \in \omega_{\mathcal{N}}$,

- $\omega_A \mapsto \omega_{UA}$ (result of operation)
- $\omega_A \cdot \omega_{UA} = |\omega_A(U)|^2$ (transition probability/fidelity of operation)

Primitive observables replace (generalize) minimal projections

Standard expectation values of observables can be recovered:

Proposition

Given projection $E \in \mathcal{N}$, (finite number of) states $\omega_A \in \omega_{\mathcal{N}}$, and $\varepsilon > 0$. There are unitaries $U \in \mathcal{N}$

- 1 $|\omega_A \cdot \omega_{UA} - \omega_A(E)^2| < \varepsilon$, i.e. “standard probabilities $\approx \sqrt{\text{fidelities}}$ ”
- 2 $\omega_{UA}(1 - E) < \varepsilon$ (compare von Neumann projection postulate)

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Question: Is $\omega_A \cdot \omega_B$ operationally defined for each pair $\omega_A, \omega_B \in \omega_{\mathcal{N}}$?
(This would require that there are unitaries $U \in \mathcal{N}$ such that $\|\omega_B - \omega_{UA}\| < \varepsilon$.)

Theorem (Connes, Haagerup, Størmer)

Let ω be of type III_λ and let

- 1 $0 \leq \lambda < 1$. There are $\omega_A, \omega_B \in \omega_{\mathcal{N}}$ s.t. $\inf_U \|\omega_B - \omega_{UA}\| > \varepsilon(\lambda)$.
- 2 $\lambda = 1$. Then $\inf_U \|\omega_B - \omega_{UA}\| = 0$ for any $\omega_A, \omega_B \in \omega_{\mathcal{N}}$.

Concept of transition probabilities (operationally) meaningful for

- pure states ω on \mathcal{N} [Kadison]
- generic states ω on \mathcal{N} of type III_1 [Connes, Størmer]

These are exactly the two cases of interest in infinite quantum systems.

Summary

Generic states ω on funnels: generalization of concept of pure states

- excitations – non-mixing operations $\omega \mapsto \omega_A$
- superpositions – bijective lifts $\omega_A \mapsto \mathbb{T} A$
- transition probabilities – product $\omega_A \cdot \omega_B = |\omega(A^* B)|^2$
- primitive observables – replace projections $\omega_A \cdot \omega_{UA} = |\omega_A(U)|^2$

Meaningful framework for simple (elementary) quantum systems