# Shape design combining with a mixing device in an algal raceway pond

Olivier Bernard, Liu-Di LU, Jacques Sainte-Marie, Julien Salomon

Friday May 28, 2021

#### Introduction

- Motivation: High potential on commercial applications, e.g., cosmetics, pharmaceuticals, food complements, wastewater treatment, green energy, etc.
- Raceway ponds



Figure: A typical raceway for cultivating microalgae. Notice the paddle-wheel which mixes the culture suspension. Picture from INRA (ANR Symbiose project) [1].

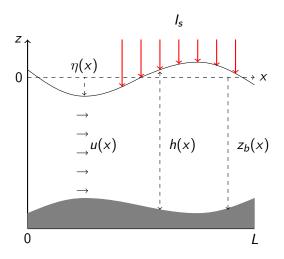


Figure: Representation of 1D raceway.

## Saint-Venant Equations

1D steady state Saint-Venant equations

$$\partial_{x}(hu)=0, \tag{1}$$

$$\partial_{x}(hu^{2}+g\frac{h^{2}}{2})=-gh\partial_{x}z_{b}.$$
 (2)

## Saint-Venant Equations

•  $u, z_h$  as a function of h

$$u = \frac{Q_0}{h},\tag{1}$$

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$$z_b = \frac{M_0}{g} - \frac{Q_0^2}{2gh^2} - h,$$
(1)

 $Q_0, M_0 \in \mathbb{R}^+$  are two constants.

• Froude number:

$$Fr := \frac{u}{\sqrt{gh}}$$

Fr < 1: subcritical case (i.e. the flow regime is fluvial)

Fr > 1: supercritical case (i.e. the flow regime is torrential)

• Given a smooth topography  $z_b$ , there exists a unique positive smooth solution of h which satisfies the subcritical flow condition [5, Lemma 1].

## Lagrangian Trajectories

• Incompressibility of the flow:  $\nabla \cdot \underline{\mathbf{u}} = 0$  with  $\underline{\mathbf{u}} = (u(x), w(x, z))$ 

$$\partial_{\mathsf{x}} u + \partial_{\mathsf{z}} w = 0. \tag{3}$$

• Integrating (3) from  $z_b$  to z and using the kinematic condition at bottom  $(w(x, z_b) = u(x)\partial_x z_b)$  gives:

$$w(x,z) = (\frac{M_0}{g} - \frac{3u^2(x)}{2g} - z)u'(x).$$

The Lagrangian trajectory is characterized by the system

$$\begin{pmatrix} \dot{x}(t) \\ \dot{z}(t) \end{pmatrix} = \begin{pmatrix} u(x(t)) \\ w(x(t), z(t)) \end{pmatrix}.$$

Liu-Di LU Ecole EGRIN Friday May 28, 2021 5/20

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A time free formulation of the Lagrangian trajectory:

$$z(x) = \frac{\eta(x)}{h(0)} + \frac{h(x)}{h(0)} (z(0) - \eta(0)). \tag{4}$$

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A: open and ready to harvest a photon,
 B: closed while processing the absorbed photon energy,
 C: inhibited if several photons have been absorbed simultaneously.

$$\begin{cases}
\dot{A} = -\sigma IA + \frac{B}{\tau}, \\
\dot{B} = \sigma IA - \frac{B}{\tau} + k_r C - k_d \sigma IB, \\
\dot{C} = -k_r C + k_d \sigma IB.
\end{cases} (5)$$

• A, B, C are the relative frequencies of the three possible states with A + B + C = 1.

Liu-Di LU Ecole EGRIN Friday May 28, 2021 6/20

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- A, B, C are the relative frequencies of the three possible states with A + B + C = 1.
- Using their sum equals to one to eliminate B

$$\begin{cases} \dot{A} = -(\sigma I + \frac{1}{\tau})A + \frac{1-C}{\tau}, \\ \dot{C} = -(k_r + k_d \sigma I)C + k_d \sigma I(1-A), \end{cases}$$

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- A, B, C are the relative frequencies of the three possible states with A + B + C = 1.
- Using fast-slow approximation, (5) can be reduced to:

$$\dot{C} = -(k_d \tau \frac{(\sigma I)^2}{\tau \sigma I + 1} + k_r)C + k_d \tau \frac{(\sigma I)^2}{\tau \sigma I + 1}.$$

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• The net growth rate:

$$\mu(C,I) := k\sigma IA - R = k\sigma I \frac{(1-C)}{\tau\sigma I + 1} - R,$$

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## Light intensity

The Beer-Lambert law describes how light is attenuated with depth

$$I(x,z) = I_s \exp\left(-\varepsilon(\eta(x) - z)\right),\tag{6}$$

where  $\varepsilon$  is the light extinction defined by:

$$\varepsilon = \frac{1}{h} \ln(\frac{I_s}{I_{Z_b}}).$$

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Liu-Di LU Ecole EGRIN Friday May 28, 2021 8 / 20

- Our goal: Topography  $z_b$ .
- Objective function: Average net growth rate

$$\begin{split} \bar{\mu}_{\infty} := & \frac{1}{V} \int_0^L \int_{z_b(x)}^{\eta(x)} \mu \big( C(x,z), I(x,z) \big) \mathrm{d}z \mathrm{d}x, \\ \bar{\mu}_{N_z} := & \frac{1}{VN_z} \sum_{i=1}^{N_z} \int_0^L \mu \big( C_i, I_i \big) h \mathrm{d}x. \end{split}$$

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Volume of the system

$$V = \int_0^L h(x) \mathrm{d}x. \tag{7}$$

• Parameterize h by a vector  $a := [a_1, \cdots, a_N] \in \mathbb{R}^N$ .

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- Parameterize h by a vector  $a := [a_1, \dots, a_N] \in \mathbb{R}^N$ .
- The computational chain:

$$a \rightarrow h \rightarrow z_i \rightarrow l_i \rightarrow C_i \rightarrow \bar{\mu}_{N_z}$$
.

• Optimization Problem:  $\bar{\mu}_{N_z}(a) = \frac{1}{VN_z} \sum_{i=1}^{N_z} \int_0^L \mu(C_i, I_i(a)) h(a) dx$ , where  $C_i$  satisfy

$$C'_i = (-\alpha(I_i(a)) C_i + \beta(I_i(a))) \frac{h(a)}{Q_0}.$$

Liu-Di LU Ecole EGRIN Friday May 28, 2021 9/20

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Lagrangian

$$\mathcal{L}(C_i, a, p_i) = \frac{1}{VN_z} \sum_{i=1}^{N_z} \int_0^L \left( -\gamma(I_i(a))C_i + \zeta(I_i(a)) \right) h(a) dx$$
$$- \sum_{i=1}^{N_z} \int_0^L p_i \left( C_i' + \frac{\alpha(I_i(a)) - \beta(I_i(a))}{Q_0} h(a) \right) dx.$$

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$$-\sum_{i=1}^{N_z} \int_0^L p_i \left( C_i' + \frac{\alpha(I_i(a)) - \beta(I_i(a))}{Q_0} h(a) \right) dx.$$

• The gradient  $\nabla \bar{\mu}_{N_z}(a) = \partial_a \mathcal{L}$  is given by

$$\partial_{a}\mathcal{L} = \sum_{i=1}^{N_{z}} \int_{0}^{L} \left( \frac{-\gamma'(I_{i}) C_{i} + \zeta'(I_{i})}{V N_{z}} + p_{i} \frac{-\alpha'(I_{i}) C_{i} + \beta'(I_{i})}{Q_{0}} \right) h \partial_{a}I_{i} dx$$

$$+ \sum_{i=1}^{N_{z}} \int_{0}^{L} \left( \frac{-\gamma(I_{i}) C_{i} + \zeta(I_{i})}{V N_{z}} + p_{i} \frac{-\alpha(I_{i}) C_{i} + \beta(I_{i})}{Q_{0}} \right) \partial_{a}h dx.$$

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## Numerical settings

Parameterization of h: Truncated Fourier

$$h(x) = a_0 + \sum_{n=1}^{N} a_n \sin(2n\pi \frac{x}{L}).$$
 (8)

10 / 20

Parameter to be optimized: Fourier coefficients  $a := [a_1, ..., a_N]$ . We use this parameterization based on the following reasons :

- We consider a hydrodynamic regime where the solutions of the shallow water equations are smooth and hence the water depth can be approximated by (8).
- One has naturally h(0) = h(L) under this parameterization, which means that we have accomplished one lap of the raceway pond.
- We assume a constant volume of the system V, which can be achieved by fixing  $a_0$ . Indeed, under this parameterization and using (7), one finds  $V = a_0 L$ .

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## Convergence

We fix N=5 and take 100 random initial guesses of a. For  $N_z$  varying from 1 to 80, we compute the average value of  $\bar{\mu}_{N_z}$  for each  $N_z$ .

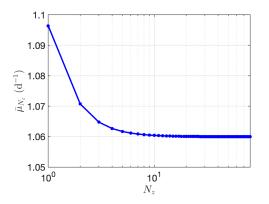


Figure: The value of  $\bar{\mu}_{N_z}$  for  $N_z = [1, 80]$ .

## Optimal Topography

We take  $N_z = 40$ . As an initial guess, we consider the flat topography, meaning that a is set to 0.

Liu-Di LU Ecole EGRIN Friday May 28, 2021 12 / 20

#### Periodic case

#### Assumption

Photoinhibition state C is periodic meaning that  $C_i(L) = C_i(0)$ 

#### Consequence

Differentiating  $\mathcal{L}$  with respect to  $C_i(L)$ , we have

$$\partial_{C_i(L)}\mathcal{L}=p_i(L)-p_i(0).$$

so that equating the above equation to zero gives the periodicity for  $p_i$ .

## Theorem (Flat topography [2])

Assume the volume of the system V is constant. Then  $\nabla \bar{\mu}_{N_r}(0) = 0$ .

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13 / 20

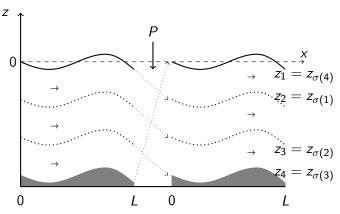
# Optimal topography (C periodic)

We keep  $N_z = 40$ . As an initial guess, we consider a random topography.

Liu-Di LU Ecole EGRIN Friday May 28, 2021 14/20

## Mixing devices

- An ideal rearrangement of trajectories: at each new lap, the algae at depth  $z_i(0)$  are entirely transferred into the position  $z_j(0)$  when passing through the mixing device.
- We denote by  $\mathcal P$  the set of permutation matrices of size  $N \times N$  and by  $\mathfrak S_N$  the associated set of permutations of N elements.



Liu-Di LU Ecole EGRIN Friday May 28, 2021

15/20

## Test with a permutation

We keep  $N_z=40$  and choose  $\sigma=(1\ N_z)(2\ N_z-1)\dots$ 

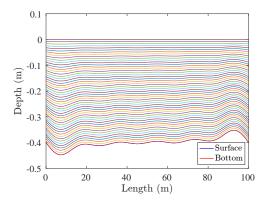


Figure: The optimal topography for two laps.

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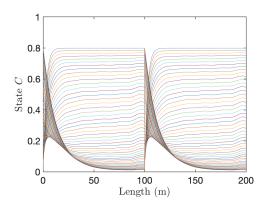


Figure: The evolution of the photo-inhibition state *C* for two laps.

It has been shown in [3] that if the system is periodic, then the period equals to one.

16/20

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- Optimization Problem:

$$\max_{P \in \mathcal{P}} \max_{a \in \mathbb{R}^N} \bar{\mu}_{N_z}^P(a) = \max_{P \in \mathcal{P}} \max_{a \in \mathbb{R}^N} \frac{1}{V N_z} \sum_{i=1}^{N_z} \int_0^L \mu(C_i^P, I_i(a)) h(a) dx,$$

where  $C_i^P$  satisfy

$$C_i^{P'} = \left(-\alpha \left(I_i(a)\right) C_i^P + \beta \left(I_i(a)\right)\right) \frac{h(a)}{Q_0},$$
  
$$PC^P(L) = C^P(0).$$

Lagrangian multiplier

$$p_i^{P'} = p_i^P \alpha(I_i(a)) \frac{h(a)}{Q_0} - \frac{h(a)}{VN_z} \gamma(I_i(a)),$$
  
$$p^P(L) = p^P(0)P.$$

Liu-Di LU Ecole EGRIN Friday May 28, 2021 17 / 20

# Optimal Topography (Constant volume)

We take  $N_z = 7$ . As an initial guess, we consider the flat topography, meaning that a is set to 0.

$$P_{\text{max}}^{100} = \begin{pmatrix} 0 & 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 & 0 & 0 \end{pmatrix}$$

Liu-Di LU Ecole EGRIN Friday May 28, 2021

18 / 20

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Liu-Di LU Ecole EGRIN Friday May 28, 2021

18 / 20

#### Variable volume

• Volume related parameter  $a_0$  as the average depth of the raceway system:

$$a_0 := \bar{h} = \frac{1}{L} \int_0^L h(x) dx = \frac{V}{L}.$$
 (9)

19 / 20

New parameter  $\tilde{a} = [a_0, a_1, \dots, a_N]$ .

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19 / 20

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Optimization Problem:

$$\Pi_{N_z}(\tilde{\mathbf{a}}) := \bar{\mu}_{N_z}(\tilde{\mathbf{a}}) X h(\tilde{\mathbf{a}}) = \frac{Y_{\mathsf{opt}} - \alpha_1 a_0}{V N_z \alpha_0} \sum_{i=1}^{N_z} \int_0^L \mu(C_i^P, I_i(\tilde{\mathbf{a}})) h(\tilde{\mathbf{a}}) dx$$

where  $C_i^P$  satisfy

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• Extra element in gradient:  $\nabla \Pi_{N_z}(\tilde{\mathbf{a}}) = [\partial_{\mathbf{a}_0} \mathcal{L}, \partial_{\mathbf{a}} \mathcal{L}].$ 

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## Optimal Topography (Variable volume)

We keep  $N_z = 7$ . As an initial guess, we consider the flat topography with  $a_0 = 0.4$ .

$$P_{\mathsf{max}}^{\mathsf{100}} = \begin{pmatrix} 0 & 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \end{pmatrix}$$

Liu-Di LU Ecole EGRIN Friday May 28, 2021

20 / 20

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20 / 20



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Liu-Di LU Ecole EGRIN Friday May 28, 2021 20 / 20