

# On the stability of IMEX schemes for singular hyperbolic PDE's

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joint with

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## Key example

Isentropic gas dynamics

$$\begin{aligned}\partial_t \rho + \operatorname{div}(\rho \mathbf{u}) &= 0, \\ \partial_t(\rho \mathbf{u}) + \operatorname{div}(\rho \mathbf{u} \otimes \mathbf{u}) + \frac{1}{\varepsilon^2} \nabla p(\rho) &= 0.\end{aligned}$$

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Mach number:

$$\varepsilon = \frac{U_{\text{ref}}}{c_{\text{ref}}}$$

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$$\mathbf{u} \cdot \mathbf{n}, \quad \mathbf{u} \cdot \mathbf{n} \pm \frac{c}{\varepsilon}$$

$\varepsilon \rightarrow 0$ : change of type

compressible to incompressible flow  
Klainerman-Majda

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## Preserve the Asymptotics

Asymptotic Consistency

Asymptotic Stability

⇒ AP property (Shi Jin)



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## Preserve the Asymptotics

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⇒ AP property (Shi Jin)

## Efficiency:

implicit for stiff part

explicit for non-stiff part

⇒ IMEX

# Today's Talk

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- a key stability structure
- a new class of IMEX schemes
- examples, applications, stability

# Prototype linear system

$$U_t + AU_x = 0.$$

with stiff eigenvalues

$$\lambda_{max} := \max |\lambda| = O\left(\frac{1}{\varepsilon}\right)$$

$$\lambda_{min} := \min |\lambda| = O(1)$$

# Admissible Splittings

## Definition

A splitting

$$A = \tilde{A} + \hat{A}.$$

is **admissible**, if

(i) both  $\tilde{A}$  and  $\hat{A}$  induce a hyperbolic system

(ii)

$$\tilde{\lambda} := \rho(\tilde{A}) = O\left(\frac{1}{\varepsilon}\right)$$

$$\hat{\lambda} := \rho(\hat{A}) = O(1)$$

## CFL Conditions

$$\nu := \lambda_{max} \frac{\Delta t}{\Delta x} \quad \text{full CFL number}$$

$$\widehat{\nu} := \widehat{\lambda} \frac{\Delta t}{\Delta x} \quad \text{nonstiff CFL number}$$

$$\nu = O(1) \quad \Rightarrow \quad \widehat{\nu} = O(\varepsilon) \quad \text{stable} \quad \text{inefficient}$$

$$\nu = O\left(\frac{1}{\varepsilon}\right) \quad \Leftarrow \quad \widehat{\nu} = O(1) \quad \text{unstable} \quad \text{efficient}$$



# Flux-Splitting & IMEX Time-Discretization

Implicit-explicit discretization

Klein 1996

Degond, Tang 2011

Haack, Jin, Liu 2011

$$U^{n+1} = U^n + \tilde{A}U_x^{n+1} + \hat{A}U_x^n$$

# Examples of stability/instability

## Numerical experiments:

IMEX schemes which are

- based on admissible splittings
- asymptotic consistent

can be stable and unstable

Noelle, Bispen, Arun, Lukacova, Munz  
Euler, Low Mach, IMEX, weakly AP

SISC 2014

Bispen, Arun, Lukacova, Noelle  
Shallow water, Low Froude, IMEX, AP

CiCP 2014

## Modified equation, cf. Warming/Hyett 1974

Theorem (Schütz, Noelle JSC 2014)

The modified equation of the IMEX scheme is

$$w_t + Aw_x = \frac{\Delta t}{2} C w_{xx}$$

with diffusion matrix

$$C := (\widehat{\alpha} + \widetilde{\alpha}) \frac{\Delta x}{\Delta t} \mathbf{I} - (\widehat{A} - \widetilde{A})(\widehat{A} + \widetilde{A})$$

and numerical upwind viscosities  $\widehat{\alpha}$ ,  $\widetilde{\alpha}$ .

## the crucial commutator

Is  $C$  positive definite?

$$\begin{aligned} C &= ((\widehat{\alpha} + \widetilde{\alpha}) \frac{\Delta x}{\Delta t} \mathbf{I} - \widehat{A}^2) + (\widetilde{A}\widehat{A} - \widehat{A}\widetilde{A}) + \widetilde{A}^2 \\ &= O(1) + O\left(\frac{1}{\varepsilon}\right) + O\left(\frac{1}{\varepsilon^2}\right) \end{aligned}$$

Certainly yes, if commutator  $[\widetilde{A}, \widehat{A}] = 0$

## Example (Schütz, Noelle 2014)

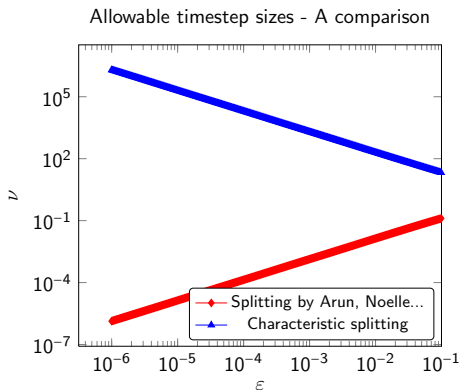
Fourier stability analysis for prototype system

$$A = \begin{pmatrix} a & 1 & 0 \\ \frac{1}{\varepsilon^2} & a & \frac{1}{\varepsilon^2} \\ 0 & 1 & a \end{pmatrix}$$

$a > 0$ , eigenvalues

$$\lambda = a, a \pm \frac{\sqrt{2}}{\varepsilon}$$

## Euler: classical versus characteristic splitting



Comparison of **classical** versus **characteristic** splitting

# How to recover stability

Need e.g.

$\widehat{A}$  and  $\widetilde{A}$  symmetric

or

$$\widetilde{A}\widehat{A} - \widehat{A}\widetilde{A} = O(1)$$

or

$$\widehat{A} = O(\varepsilon)$$

### Theorem (Stability for Haack-Jin-Liu (Zakerzadeh 2015))

*For the isentropic Euler equations, the Haack-Jin-Liu scheme with Mach-uniform CFL condition, has (strictly) stable modified equation in the sense of Majda-Pego, i.e. it is **AP stable**.*



# Reference-Solution IMEX

Nonlinear hyperbolic system of balance laws

$$\partial_t U(x, t; \varepsilon) + \nabla \cdot F(U, x, t; \varepsilon) = S(U, x, t; \varepsilon)$$

with

$$U : \mathbb{R}^d \times \mathbb{R}_+ \times (0, 1] \rightarrow \mathbb{R}^m, \quad (x, t; \varepsilon) \mapsto U(x, t; \varepsilon)$$

- Challenge: **Stiffness** as  $\varepsilon \rightarrow 0$
- Goal: **Asymptotic stability**

Reference solution and scaled perturbation:  $U = \bar{U} + DV$

$$\begin{aligned} \bar{U}: \quad \mathbb{R}^d \times \mathbb{R}_+ &\rightarrow \mathbb{R}^m, & (x, t) &\mapsto \bar{U}(x, t) \\ V: \quad \mathbb{R}^d \times \mathbb{R}_+ \times (0, 1] &\rightarrow \mathbb{R}^m, & (x, t; \varepsilon) &\mapsto U(x, t; \varepsilon) \end{aligned}$$

and

$$D = \text{diag}(\varepsilon^{k_1}, \dots, \varepsilon^{k_m})$$

Taylor expansion with remainder of  $F$  and  $S$  around  $\bar{U}$ :

$$F = F(\bar{U}) + A(\bar{U}) DV + \hat{F}(\bar{U}, V) = D(\bar{G} + \tilde{G} + \hat{G})$$

$$S = S(\bar{U}) + \bar{S}' V DV + \hat{S}(\bar{U}, V) = D(\underbrace{\bar{Z} + \tilde{Z} + \hat{Z}}_{RS+IM+EX})$$

Theorem (Modified equation for RS-IMEX (Noelle 2014))

$$B_0 W_t = -\nabla \cdot B_1 + B_2 + \nabla \cdot (B_3 \cdot \nabla W)$$

with

$$B_0 := I - \frac{\Delta t}{2}(\tilde{Z}' - \widehat{Z}'),$$

$$B_1 := \tilde{G} + \widehat{G} + \frac{\Delta t}{2}((\tilde{G}' - \widehat{G}')(\tilde{Z}' + \widehat{Z}' - \tilde{G}_x - \widehat{G}_x)),$$

$$B_2 := \tilde{Z} + \widehat{Z} + \frac{\Delta t}{2}(\tilde{Z}_t - \widehat{Z}_t),$$

$$B_3 := \frac{(\widehat{\alpha} + \bar{\alpha})\Delta x}{2}I + \frac{\Delta t}{2}(\tilde{G}' - \widehat{G}')(\tilde{G}' + \widehat{G}').$$

**Study this for each application!**

# RS-IMEX is AP for isentropic Euler

## Theorem (Consistency for RS-IMEX (Zakerzadeh 2015))

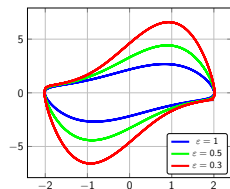
*For isentropic Euler equations, the RS-IMEX scheme is consistent with the asymptotic limit in the fully-discrete settings, i.e. it is **AP consistent**.*

- (Schöbel 2015) AP consistency for semi-discrete scheme

## Theorem (Stability for RS-IMEX (Zakerzadeh 2015))

*For isentropic Euler equations, the RS-IMEX scheme with Mach-uniform CFL condition, has (strictly) stable modified equation in the sense of Majda-Pego, i.e. it is **AP stable**.*

## van der Pol and IMEX (Schütz, Kaiser 2015)



- Prototype example

$$\begin{pmatrix} y' \\ z' \end{pmatrix} = \begin{pmatrix} z \\ \frac{g(y,z)}{\varepsilon} \end{pmatrix}.$$

- 'Traditional' splitting:  $\begin{pmatrix} 0 \\ \frac{g(y,z)}{\varepsilon} \end{pmatrix} + \begin{pmatrix} z \\ 0 \end{pmatrix}$

## van der Pol and IMEX

- 'Reference solution' (RS)  $\varepsilon \rightarrow 0$ :

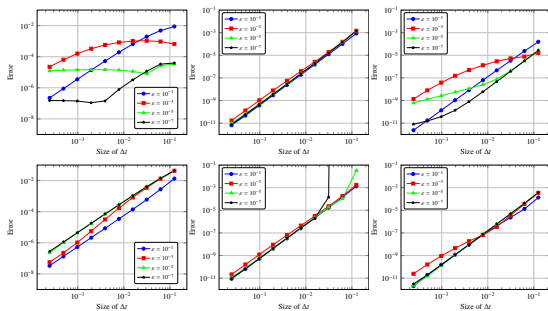
$$\begin{pmatrix} y'_{(0)} \\ 0 \end{pmatrix} = \begin{pmatrix} z_{(0)} \\ g(y_{(0)}, z_{(0)}) \end{pmatrix}.$$

- RS-IMEX splitting based on  $w_{(0)}$ :

$$f(w) = f(w_{(0)}) + f'(w_{(0)})(w - w_{(0)}) + \text{Rest}$$

- Motivation:  $w - w_{(0)} = O(\varepsilon)$ .

## RS-IMEX + Runge-Kutta



(Left to right) DPA-242, BHR-553, BPR-353. (Top to bottom) Standard / RS-IMEX

- IMEX Runge-Kutta (Pareschi, Russo, Boscarino ...)
- standard splitting loses convergence order
- RS-IMEX gives full order of accuracy

# Numerical Comparison for Isentropic Euler Equations

Haack-Jin-Liu scheme

RS-IMEX scheme

initial data from Degond-Tang (CiCP 2011) / Haack-Jin-Liu (JSC 2012)

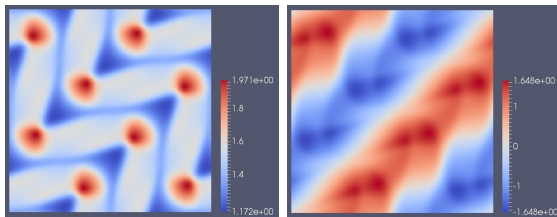
$$\rho(x, y, 0) = 1 + \varepsilon^2 \sin^2(2\pi(x + y))$$

$$\rho u(x, y, 0) = \sin(2\pi(x - y)) + \varepsilon^2 \sin(2\pi(x + y))$$

$$\rho v(x, y, 0) = \sin(2\pi(x - y)) + \varepsilon^2 \cos(2\pi(x + y))$$



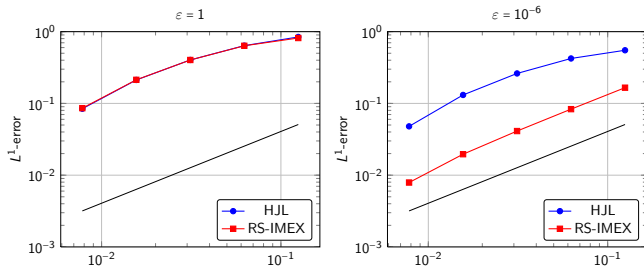
# Results



(a) Density

(b) Momentum

## Results



Numerical comparison of HJL vs. RS-IMEX