

Objectives

We show that the Lagrange-projection scheme applied to the isentropic Euler equations is

- ▶ positivity-preserving
- ▶ L_∞ -stable
- ▶ locally entropy dissipative
- ▶ asymptotic preserving (AP) w.r.t. the Mach number under some Mach-uniform restrictions, and with well-prepared initial data.

Introduction: AP scheme

Isentropic Euler equations on domain $\Omega_T := \mathbb{T}(\Omega) \times \mathbb{R}_+$:

$$\partial_t \rho + \partial_x(\rho u) = 0, \quad (1)$$

$$\partial_t(\rho u) + \partial_x(\rho u^2 + \frac{p}{\epsilon^2}) = 0, \quad (2)$$

accompanied with energy inequality

$$\partial_t(\rho E) + \partial_x((\rho E + \frac{p}{\epsilon^2})u) \leq 0 \quad \text{in } \mathcal{D}'(\Omega_T). \quad (3)$$

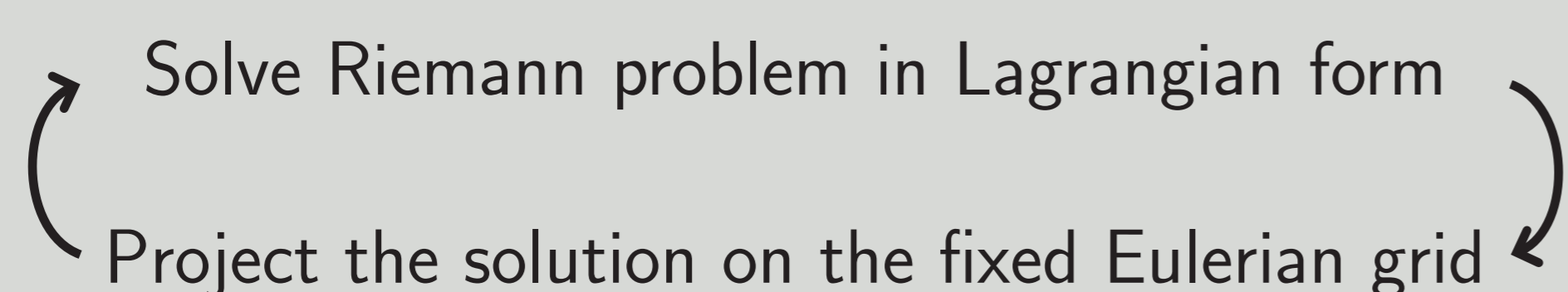
ϵ	Mach number
$p(\rho) := \kappa \rho^\gamma$	Pressure function
$E(\rho) := \frac{\kappa/\epsilon^2}{\gamma-1} \rho^{\gamma-1} + \frac{u^2}{2}$	Total energy density

Asymptotic Preserving (AP) Scheme [Jin, 1995]:

- ▶ Consistency of the scheme with the underlying PDE as $\epsilon \rightarrow 0$
- ▶ Stability of the scheme uniformly in ϵ

$$\begin{array}{ccc} \mathcal{M}_\Delta^\epsilon & \xrightarrow{\epsilon \rightarrow 0} & \mathcal{M}_\Delta^0 \\ \Delta \rightarrow 0 \downarrow & & \downarrow \Delta \rightarrow 0 \\ \mathcal{M}^\epsilon & \xrightarrow{\epsilon \rightarrow 0} & \mathcal{M}^0 \end{array}$$

Lagrange-projection approach



Equivalent to solve successively [Chalons et al., 2014]:

▶ Acoustic system

$$\tau_t - u_z = 0, \quad (4)$$

$$u_t + \frac{p_z}{\epsilon^2} = 0, \quad (5)$$

with $\tau := 1/\rho$ and $z := \rho dx$.

▶ Transport system for $\mathbb{U} := (\rho, \rho u)^T$ with velocity u :

$$\partial_t \mathbb{U} + u \partial_x \mathbb{U} = 0. \quad (6)$$

Relaxation scheme for Lagrange step: Suliciu relaxation

Add an auxiliary equation to make the system linearly-degenerate [Chalons et al., 2014]:

$$\tau_t - u_z = 0,$$

$$u_t + \Pi_z = 0,$$

$$\Pi_t + \alpha^2 u_z = \Lambda(p - \pi),$$

where $\Pi := \frac{\pi}{\epsilon^2}$, $\alpha := \frac{a}{\epsilon}$, $\Lambda := \frac{\lambda}{\epsilon^2}$.

Liu's sub-characteristic condition

$$a^2 > \max(-p_\tau) \quad (7)$$

Using Riemann invariants [Coquel et al., 2010]:

$$\begin{aligned} \tau_t - u_z &= 0, \\ \vec{w}_t + \alpha \vec{w}_z &= 0, & \vec{w} &:= \Pi + \alpha u, \\ \vec{w}_t - \alpha \vec{w}_z &= 0, & \vec{w} &:= \Pi - \alpha u. \end{aligned}$$

Numerical scheme

▶ Lagrange step ($n \rightarrow n^\dagger$):

$$\tau_j^{n^\dagger} = \tau_j^n + \frac{\Delta t}{\Delta z_j} (\tilde{u}_{j+1/2}^{n^\dagger} - \tilde{u}_{j-1/2}^{n^\dagger}), \quad (8)$$

$$\vec{w}_j^{n^\dagger} = \vec{w}_j^n - \frac{a \Delta t}{\epsilon \Delta z_j} (\vec{w}_j^{n^\dagger} - \vec{w}_{j-1}^{n^\dagger}), \quad (9)$$

$$\hat{w}_j^{n^\dagger} = \hat{w}_j^n + \frac{a \Delta t}{\epsilon \Delta z_j} (\hat{w}_{j+1}^{n^\dagger} - \hat{w}_j^{n^\dagger}), \quad (10)$$

where

$$\tilde{u}_{j+1/2}^{n^\dagger} = \frac{u_j^{n^\dagger} + u_{j+1}^{n^\dagger}}{2} - \frac{1}{2a\epsilon} (\pi_{j+1}^{n^\dagger} - \pi_j^{n^\dagger}).$$

▶ Projection step ($n^\dagger \rightarrow n+1$):

$$\begin{aligned} \mathbb{U}_j^{n+1} = \mathbb{U}_j^{n^\dagger} + \frac{\Delta t}{\Delta x} & \left[(\tilde{u}_{j-1/2}^{n^\dagger})^+ \mathbb{U}_{j-1}^{n^\dagger} - (\tilde{u}_{j+1/2}^{n^\dagger})^- \mathbb{U}_{j+1}^{n^\dagger} \right. \\ & \left. + \left((\tilde{u}_{j+1/2}^{n^\dagger})^- - (\tilde{u}_{j-1/2}^{n^\dagger})^+ \right) \mathbb{U}_j^{n^\dagger} \right]. \end{aligned} \quad (11)$$

Main theorem: Uniform stability

Definition (Well-prepared initial data)

For isentropic Euler equation, with constant p_0 and u_0 :

$$p_{WP}^0(x) := p_0 + \mathcal{O}(\epsilon^2) p_2(x),$$

$$u_{WP}^0(x) := u_0 + \mathcal{O}(\epsilon) u_1(x).$$

Lemma (cf. [Coquel et al., 2010])

The time step restriction

$$\frac{\Delta t}{\Delta x} \leq \frac{2a/\epsilon}{(\bar{M}^n - \bar{m}^n)^+ - (\bar{m}^n - \bar{M}^n)^-}, \quad (12)$$

is uniform in ϵ , where \bar{M}^n and \bar{m}^n denote the maximum and minimum of \vec{w}^n , similarly for \hat{w} .

Theorem [Zakerzadeh, 2015] (cf. [Coquel et al., 2010])

The Lagrange-projection scheme for well-prepared initial data and under the ϵ -uniform CFL constraint (12)

- is in the locally conservative form
- is AP consistent, i.e.

$$\text{div} u_{(0)}^n = 0, \quad \rho_{(0)j}^n, \rho_{(1)j}^n = \text{const.}$$

- is positivity-preserving
- is stable in L_∞ -norm, uniformly in ϵ
- satisfies cell entropy inequality (consistent with (3)), under (7), i.e.

$$\frac{(\rho E)_j^{n+1} - (\rho E)_j^n}{\Delta t} + \frac{(\rho E \tilde{u} + \frac{\tilde{\pi} \tilde{u}}{\epsilon^2})_{j+1/2}^{n^\dagger} - (\rho E \tilde{u} + \frac{\tilde{\pi} \tilde{u}}{\epsilon^2})_{j-1/2}^{n^\dagger}}{\Delta x} \leq 0.$$

- ▶ Proof is similar to Coquel et al. [2010] with additional parameter ϵ
- ▶ Direct L_∞ estimate is a new result compared to [Coquel et al., 2010]

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