## The stability of elliptic solutions of the focusing NLS equation

Bernard Deconinck deconinc@uw.edu

University of Washington, Seattle, WA

Classical and Quantum Integrability Institutes de Mathématiques de Bourgogne September 2-6, 2019 Dijon, France

### Acknowledgments

- Joint work with Nate Bottman (IAS), Benjamin Segal (AA) and Jeremy Upsal (UW)
- Supported by the National Science Foundation (NSF-DMS-1008001, NSF-DMS-1522677, BD), a Boeing Fellowship and ARCS Award (BS)

### Introduction

 Analytically construct the linear stability spectrum for traveling wave solutions of focusing NLS

### Introduction

- Analytically construct the linear stability spectrum for traveling wave solutions of focusing NLS
- Extend previous work on problems with self-adjoint Lax pair to prove stability of periodic traveling wave solutions
  - Korteweg-de Vries (KdV) equation (Bottman, Deconinck, Kapitula, Nivala, 2009, 2010)
  - Defocusing nonlinear Schrödinger (NLS) equation (Bottman, Deconinck, & Nivala, 2011)
  - Defocusing modified KdV equation (Deconinck & Nivala, 2010)

### Introduction

- Analytically construct the linear stability spectrum for traveling wave solutions of focusing NLS
- Extend previous work on problems with self-adjoint Lax pair to prove stability of periodic traveling wave solutions
  - Korteweg-de Vries (KdV) equation (Bottman, Deconinck, Kapitula, Nivala, 2009, 2010)
  - Defocusing nonlinear Schrödinger (NLS) equation (Bottman, Deconinck, & Nivala, 2011)
  - Defocusing modified KdV equation (Deconinck & Nivala, 2010)
- Analytical description of some spectra of non-self-adjoint problems

$$i\psi_t + \frac{1}{2}\psi_{xx} + |\psi|^2\psi = 0$$

$$i\psi_t + \frac{1}{2}\psi_{xx} + |\psi|^2\psi = 0$$

Construct the "stationary" "periodic" solutions

$$i\psi_t + \frac{1}{2}\psi_{xx} + |\psi|^2\psi = 0$$

- Construct the "stationary" "periodic" solutions
- Linearize around stationary solutions to get a spectral problem
- Spectral elements in the right half plane correspond to instability

$$i\psi_t + \frac{1}{2}\psi_{xx} + |\psi|^2\psi = 0$$

- Construct the "stationary" "periodic" solutions
- Linearize around stationary solutions to get a spectral problem
- Spectral elements in the right half plane correspond to instability
- ► All stationary solutions (except soliton) are unstable
  - (Kartashov *et al.*, 2003), (Gallay and Haragus, 2007 (2×)), (Ivey & Lafortune, 2008), (Gustafson, Le Coz, and Tsai, 2016)

$$i\psi_t + \frac{1}{2}\psi_{xx} + |\psi|^2\psi = 0$$

- Construct the "stationary" "periodic" solutions
- Linearize around stationary solutions to get a spectral problem
- Spectral elements in the right half plane correspond to instability
- ► All stationary solutions (except soliton) are unstable
  - (Kartashov et al., 2003), (Gallay and Haragus, 2007 (2×)), (Ivey & Lafortune, 2008), (Gustafson, Le Coz, and Tsai, 2016)
- For all solutions, we obtain a fully analytical description of the stability spectrum

$$i\psi_t + \frac{1}{2}\psi_{xx} + |\psi|^2\psi = 0$$

- Construct the "stationary" "periodic" solutions
- Linearize around stationary solutions to get a spectral problem
- Spectral elements in the right half plane correspond to instability
- All stationary solutions (except soliton) are unstable
  - (Kartashov et al., 2003), (Gallay and Haragus, 2007 (2×)), (Ivey & Lafortune, 2008), (Gustafson, Le Coz, and Tsai, 2016)
- For all solutions, we obtain a fully analytical description of the stability spectrum
- ► For almost all spectrally stable solutions, we establish their orbital stability

## Stationary travelling wave solutions

$$i\psi_t + \frac{1}{2}\psi_{xx} + |\psi|^2\psi = 0$$



$$\psi = e^{-i\omega t}\phi(x) = e^{-i\omega t}R(x)e^{i\theta(x)}$$

### Stationary travelling wave solutions

$$i\psi_t + \frac{1}{2}\psi_{xx} + |\psi|^2\psi = 0$$



$$\psi = e^{-i\omega t}\phi(x) = e^{-i\omega t}R(x)e^{i\theta(x)}$$

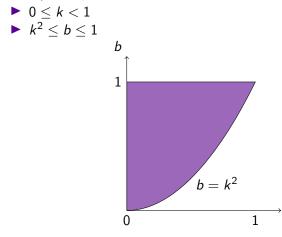


$$R^{2}(x) = b - k^{2} \operatorname{sn}^{2}(x, k)$$
$$\omega = \frac{1}{2}(1 + k^{2}) - \frac{3}{2}b$$
$$\theta(x) = \int_{0}^{x} \frac{c}{R^{2}(y)} dy$$
$$c^{2} = b(1 - b)(b - k^{2})$$

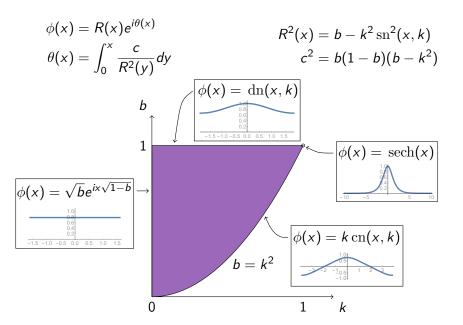
#### Parameter space

$$R^{2}(x) = b - k^{2} \operatorname{sn}^{2}(x, k)$$
$$c^{2} = b(1 - b)(b - k^{2})$$

We require  $R, c \in \mathbb{R}$  so



#### Parameter space



Stability of stationary solutions: Orbital, Spectral

Introducing

$$\psi(x,t)=e^{-i\omega t}\Psi(x,t),$$

we have that stationary solutions  $\Psi(x,t)=\phi(x)$  are fixed points of

$$i\Psi_t + \omega\Psi + \frac{1}{2}\Psi_{xx} + |\Psi|^2\Psi = 0. \tag{(*)}$$

Stability of stationary solutions: Orbital, Spectral

Introducing

$$\psi(x,t)=e^{-i\omega t}\Psi(x,t),$$

we have that stationary solutions  $\Psi(x,t)=\phi(x)$  are fixed points of

$$i\Psi_t + \omega\Psi + \frac{1}{2}\Psi_{xx} + |\Psi|^2\Psi = 0. \tag{(*)}$$

A fixed-point solution  $\Psi(x,t) = \phi(x)$  of (\*) is orbitally stable if

$$orall \epsilon > 0, \exists \delta > 0: ext{if } ||\Psi(x,0) - \phi(x)|| < \delta$$
  
 $\Rightarrow \inf_{\gamma, x_0} ||\Psi(x,t) - e^{i\gamma}\phi(x+x_0)|| < \epsilon.$ 

To start, we consider infinitesimal perturbations: let

$$\Psi(x,t) = e^{i\theta(x)} \left( R(x) + \varepsilon(u(x,t) + iv(x,t)) + \mathcal{O}(\varepsilon^2) \right).$$

To start, we consider infinitesimal perturbations: let

$$\Psi(x,t) = e^{i\theta(x)} \left( R(x) + \varepsilon(u(x,t) + iv(x,t)) + \mathcal{O}(\varepsilon^2) \right).$$

To first order in  $\varepsilon$ , u(x, t) and v(x, t) satisfy

$$\frac{\partial}{\partial t} \left(\begin{array}{c} u \\ v \end{array}\right) = J\mathcal{L} \left(\begin{array}{c} u \\ v \end{array}\right) = \left(\begin{array}{c} 0 & 1 \\ -1 & 0 \end{array}\right) \left(\begin{array}{c} L_{+} & S \\ -S & L_{-} \end{array}\right) \left(\begin{array}{c} u \\ v \end{array}\right),$$

with

$$\begin{split} L_{-} &= -\frac{1}{2}\partial_{x}^{2} - R^{2}(x) - \omega + \frac{c^{2}}{2R^{4}(x)}, \\ L_{+} &= -\frac{1}{2}\partial_{x}^{2} - 3R^{2}(x) - \omega + \frac{c^{2}}{2R^{4}(x)}, \\ S &= \frac{c}{R^{2}(x)}\partial_{x} - \frac{cR'(x)}{R^{3}(x)}. \end{split}$$

Since  $L_+$ ,  $L_-$  and S do not depend on t, let

$$u(x,t) = e^{\lambda t} U(x;\lambda), \quad v(x,t) = e^{\lambda t} V(x;\lambda).$$

This gives the spectral problem

$$\left(\begin{array}{cc} -S & L_{-} \\ -L_{+} & -S \end{array}\right) \left(\begin{array}{c} U \\ V \end{array}\right) = \lambda \left(\begin{array}{c} U \\ V \end{array}\right).$$

Since  $L_+$ ,  $L_-$  and S do not depend on t, let

$$u(x,t) = e^{\lambda t} U(x;\lambda), \quad v(x,t) = e^{\lambda t} V(x;\lambda).$$

This gives the spectral problem

$$\begin{pmatrix} -S & L_{-} \\ -L_{+} & -S \end{pmatrix} \begin{pmatrix} U \\ V \end{pmatrix} = \lambda \begin{pmatrix} U \\ V \end{pmatrix}$$

٠

The stability spectrum  $\sigma(J\mathcal{L})$  of  $J\mathcal{L}$  is defined as

$$\sigma(J\mathcal{L}) = \{\lambda \in \mathbb{C} : \exists ||U + iV|| < \infty\}.$$

Since  $L_+$ ,  $L_-$  and S do not depend on t, let

$$u(x,t) = e^{\lambda t} U(x;\lambda), \quad v(x,t) = e^{\lambda t} V(x;\lambda).$$

This gives the spectral problem

$$\begin{pmatrix} -S & L_{-} \\ -L_{+} & -S \end{pmatrix} \begin{pmatrix} U \\ V \end{pmatrix} = \lambda \begin{pmatrix} U \\ V \end{pmatrix}$$

٠

The stability spectrum  $\sigma(J\mathcal{L})$  of  $J\mathcal{L}$  is defined as

$$\sigma(J\mathcal{L}) = \{\lambda \in \mathbb{C} : \exists ||U + iV|| < \infty\}$$

A fixed-point solution  $\Psi(x, t) = \phi(x)$  of (\*) is spectrally stable if

$$\sigma(J\mathcal{L}) \cap \mathsf{RHP} = \emptyset.$$

Following earlier work (Bottman, Deconinck, Nivala 2009, 2011):

- Examine spectrum for Lax pair associated with NLS
- Use squared-eigenfunction connection to associate spectrum of Lax pair with spectrum of the linear operator for NLS

The Lax pair

$$\chi_{x} = \begin{pmatrix} -i\xi & \phi \\ -\phi^{*} & i\xi \end{pmatrix} \chi,$$
$$\chi_{t} = \begin{pmatrix} -i\xi^{2} + \frac{i}{2}|\phi|^{2} + \frac{i}{2}\omega & \xi\phi + \frac{i}{2}\phi_{x} \\ -\xi\phi^{*} + \frac{i}{2}\phi_{x}^{*} & i\xi^{2} - \frac{i}{2}|\phi|^{2} - \frac{i}{2}\omega \end{pmatrix} \chi = \begin{pmatrix} A & B \\ C & -A \end{pmatrix} \chi,$$

with the compatibility condition  $\chi_{xt} = \chi_{tx}$  gives that  $\Psi = e^{-i\omega t}\phi(x)$  satisfies

$$i\Psi_t + \omega\Psi + \frac{1}{2}\Psi_{xx} + |\Psi|^2\Psi = 0.$$

Since A and B are independent of t, we let

$$\chi(x,t)=e^{\Omega t}\varphi(x),$$

leading to

$$\Omega^2 = A^2 + BC = -\xi^4 + \omega\xi^2 + c\xi + \frac{1}{16} \left( -4\omega b - 3b^2 - (1-k^2)^2 \right),$$

and

$$\varphi(x) = \gamma(x) \left( egin{array}{c} -B(x) \ A(x) - \Omega \end{array} 
ight).$$

The scalar function  $\gamma(x)$  is determined from

$$\chi_{\mathbf{x}} = \begin{pmatrix} -i\xi & \phi \\ -\phi^* & i\xi \end{pmatrix} \chi,$$

resulting in a linear, first-order, homogeneous ODE for  $\gamma(x)$ , so that

$$\gamma(x) = \gamma_0 e^{-\int \frac{(A-\Omega)\phi + B_x + i\xi B}{B} dx}$$

.

The scalar function  $\gamma(x)$  is determined from

$$\chi_{\mathsf{x}} = \left(\begin{array}{cc} -i\xi & \phi \\ -\phi^* & i\xi \end{array}\right) \chi,$$

resulting in a linear, first-order, homogeneous ODE for  $\gamma(x)$ , so that

$$\gamma(x) = \gamma_0 e^{-\int \frac{(A-\Omega)\phi + B_x + i\xi B}{B}} dx.$$

Since  $\varphi$  and thus  $\gamma$  should be bounded, we need

$$\operatorname{Re}\left\langle\!\frac{(A(x,\xi) - \Omega(\xi))\phi(x) + B_x(x,\xi) + i\xi B(x,\xi)}{B(\xi,x)}\right\rangle = 0,$$

where  $\langle \cdot \rangle$  denotes a spatial average.

#### The Lax spectrum

The Lax Spectrum  $\sigma_L$  consists of all  $\xi \in \mathbb{C}$  for which

$$\operatorname{Re}\left(-2i\xi K(k)\pm 2\left(\zeta(\alpha)K(k)-\zeta(K(k))\alpha\right)\right)=0,$$

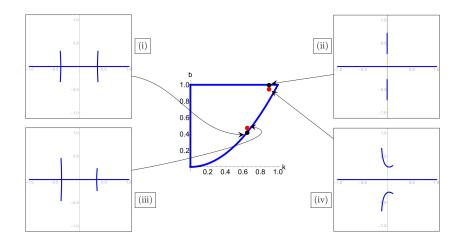
where  $\zeta$  is the Weierstrass  $\zeta$  function with lattice invariants

$$g_2 = \frac{4}{3} \left( 1 - k^2 + k^4 \right), \ g_3 = \frac{4}{27} \left( 2 - 3k^2 - 3k^4 + 2k^6 \right),$$

and

$$\alpha = \alpha(\xi) = \wp^{-1}\left(2\Omega(\xi) + 2i\xi^2 + \frac{\omega}{3}, g_2, g_3\right)$$

#### The Lax spectrum



#### The stability spectrum

The stability spectrum  $\sigma(J\mathcal{L})$  is given by all  $\lambda \in \mathbb{C}$  for which

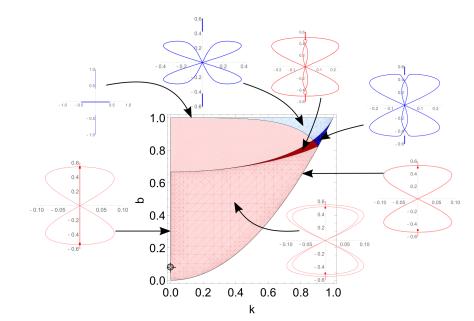
$$\lambda = 2\Omega(\xi),$$

where  $\xi \in \sigma_L$ , and

$$\begin{split} \Omega^2 &= -\xi^4 + \omega\xi^2 + c\xi + \frac{1}{16} \left( -4\omega b - 3b^2 - (1-k^2)^2 \right). \\ \text{Also,} \\ \left( \begin{array}{c} U \\ V \end{array} \right) &= \left( \begin{array}{c} e^{-i\theta(x)}\varphi_1^2 - e^{i\theta(x)}\varphi_2^2 \\ -ie^{-i\theta(x)}\varphi_1^2 - ie^{i\theta(x)}\varphi_2^2 \end{array} \right), \end{split}$$

where  $\varphi_1$  and  $\varphi_2$  are known explicitly.

#### Parameter space: topology of spectra



#### Stability with respect to subharmonic perturbations

Consider the class of subharmonic perturbations: g(x) is subharmonic with respect to f(x) = f(x + T), if

$$\exists N \in \mathbb{N}_0 : g(x + NT) = g(x).$$

#### Stability with respect to subharmonic perturbations

Consider the class of subharmonic perturbations: g(x) is subharmonic with respect to f(x) = f(x + T), if

$$\exists N \in \mathbb{N}_0 : g(x + NT) = g(x).$$

Since the spectral problem has periodic coefficients, we know from Floquet's Theorem that all eigenfunctions are of the form

$$\left( egin{array}{c} U(x) \ V(x) \end{array} 
ight) = e^{i\mu x} \left( egin{array}{c} \hat{U}(x) \ \hat{V}(x) \end{array} 
ight),$$

where  $\hat{U}(x)$  and  $\hat{V}(x)$  are periodic with period T(k). Thus,

$$\mu = rac{\pi}{PT(k)} \mod rac{2\pi}{T(k)} \in (-\pi/T(K), \pi/T(K)]$$

corresponds to perturbations of period PT(k).

Stability with respect to subharmonic perturbations

Using the explicit form of the eigenfunction in terms of  $\boldsymbol{\xi},$  and noticing that

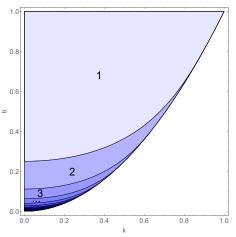
$$e^{i\mu T(k)} = \frac{U(x+T(k))}{U(x)},$$

we find a parametric form of the spectrum as a function of the Floquet parameter  $\mu:$ 

$$egin{array}{rcl} \mu &=& \mu(\xi), \ \lambda^2 &=& -4\xi^4 + 4\omega\xi^2 + 4c\xi + rac{1}{4}\left(-4\omega b - 3b^2 - (1-k^2)^2
ight). \end{array}$$

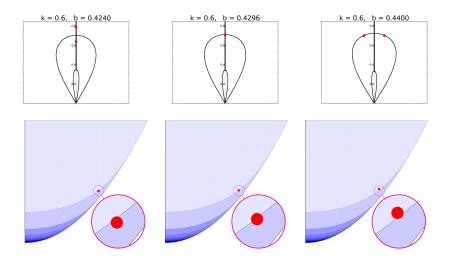
for all  $\xi$  in  $\sigma_L$ .

## Spectral stability with respect to subharmonic perturbations



Solutions (including those on the border, and all those below) are spectrally stable with respect to perturbations of period NT(k) = 2K(k)N.

# Spectral stability with respect to subharmonic perturbations



We wish to show that the solutions that are spectrally stable with respect to subharmonic perturbations of period NT(k) are orbitally stable with respect to these perturbations.

We wish to show that the solutions that are spectrally stable with respect to subharmonic perturbations of period NT(k) are orbitally stable with respect to these perturbations.

- First, establish formal stability: find a Lyapunov functional
- Second, use Grillakis, Shatah and Strauss (87, 90) & Maddocks and Sachs (1993) to establish formal stability

▶ For harmonic perturbations (N = 1), Gallay & Haragus showed that the Hamiltonian

$$H_{2,N} = \int_{-NT(k)/2}^{NT(k)/2} \left(\frac{1}{2} |\Psi_x|^2 - \frac{1}{2} |\Psi|^4 - \omega |\Psi|^2\right) dx$$

is a Lyapunov functional. In other words, the fixed point solutions minimize  $H_{2,1}$ .

▶ For harmonic perturbations (*N* = 1), Gallay & Haragus showed that the Hamiltonian

$$H_{2,N} = \int_{-NT(k)/2}^{NT(k)/2} \left(\frac{1}{2} |\Psi_x|^2 - \frac{1}{2} |\Psi|^4 - \omega |\Psi|^2\right) dx$$

is a Lyapunov functional. In other words, the fixed point solutions minimize  $H_{2,1}$ .

The quadratic part of the Hamiltonian is given by the Krein signature

$$K_{2,N} = \langle \Psi, \mathcal{L}\Psi \rangle_N,$$

where the inner product is taken over  $N \in \mathbb{N}$  periods.

▶ For harmonic perturbations (N = 1), Gallay & Haragus showed that the Hamiltonian

$$H_{2,N} = \int_{-NT(k)/2}^{NT(k)/2} \left(\frac{1}{2} |\Psi_x|^2 - \frac{1}{2} |\Psi|^4 - \omega |\Psi|^2\right) dx$$

is a Lyapunov functional. In other words, the fixed point solutions minimize  $H_{2,1}$ .

The quadratic part of the Hamiltonian is given by the Krein signature

$$K_{2,N} = \left\langle \Psi, \mathcal{L}\Psi \right\rangle_N,$$

where the inner product is taken over  $N \in \mathbb{N}$  periods.

 Using the eigenfunctions of the spectral stability problem, *K*<sub>2,N</sub>(ξ) is calculated explicitly, with different directions indexed by different ξ. For all *N*, the set of ξ is countable.

► For N = 1, no negative directions, and H<sub>2</sub> is a Lyapunov functional for harmonic perturbations, for all fixed point solutions.

- ► For N = 1, no negative directions, and H<sub>2</sub> is a Lyapunov functional for harmonic perturbations, for all fixed point solutions.
- ► For N > 1 this is no longer true: this is a larger function space, and negative directions appear.

We need a different Lyapunov functional...

NLS is a member of an infinite hierarchy of integrable equations whose dynamics commute:

$$\Psi_{t_n}=i\frac{\delta H_{n,N}}{\delta\Psi^*}.$$

▶ Thus  $\hat{H}_{n,N} := H_{n,N} + \sum_{j=0}^{n-1} c_{n,j} H_{j,N}$  are conserved quantities, for arbitrary  $j \in \mathbb{N}$ .

NLS is a member of an infinite hierarchy of integrable equations whose dynamics commute:

$$\Psi_{t_n}=i\frac{\delta H_{n,N}}{\delta\Psi^*}.$$

- ▶ Thus  $\hat{H}_{n,N} := H_{n,N} + \sum_{j=0}^{n-1} c_{n,j} H_{j,N}$  are conserved quantities, for arbitrary  $j \in \mathbb{N}$ .
- Can we find  $c_{n,j}$  so that  $\hat{H}_{n,N}$  is a Lyapunov functional for the  $t = t_2$  dynamics near  $\Psi = \phi$ ?

▶ Impose constraints on *c*<sub>*n,j*</sub> such that

$$\frac{\delta \hat{H}_{n,N}}{\delta \Psi^*}\bigg|_{\Psi=\phi}=0,$$

*i.e.*,  $\phi$  is stationary with respect to  $t_n$ .

▶ Impose constraints on *c*<sub>n,j</sub> such that

$$\frac{\delta \hat{H}_{n,N}}{\delta \Psi^*}\bigg|_{\Psi=\phi}=0,$$

*i.e.*,  $\phi$  is stationary with respect to  $t_n$ .

• Crucial observation: for  $n \ge 2$ ,

$$\mathcal{K}_{n,N}(\xi) := \left\langle \Psi, \hat{\mathcal{L}}_n \Psi \right\rangle = p_n(\xi) \mathcal{K}_{2,N}(\xi),$$

where  $p_n(\xi)$  is polynomial in  $\xi$  with coefficients determined by  $c_{n,j}$ , using the same  $\Psi$  as before since the different NLS flows commute.

▶ Impose constraints on *c*<sub>n,j</sub> such that

$$\frac{\delta \hat{H}_{n,N}}{\delta \Psi^*}\bigg|_{\Psi=\phi}=0,$$

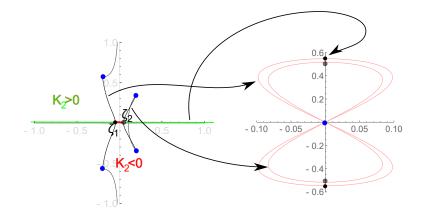
*i.e.*,  $\phi$  is stationary with respect to  $t_n$ .

• Crucial observation: for  $n \ge 2$ ,

$$\mathcal{K}_{n,N}(\xi) := \left\langle \Psi, \hat{\mathcal{L}}_n \Psi \right\rangle = p_n(\xi) \mathcal{K}_{2,N}(\xi),$$

where  $p_n(\xi)$  is polynomial in  $\xi$  with coefficients determined by  $c_{n,j}$ , using the same  $\Psi$  as before since the different NLS flows commute.

► Impose more constraints on  $c_{j,N}$  such that  $K_{n,N} \ge 0$ , with equality only for  $\Psi \in \ker \hat{\mathcal{L}}_n = \ker \mathcal{L}$ .



For all N, it suffices to let n = 4, thus  $p_2(\zeta) = (\zeta - \zeta_1)(\zeta - \zeta_2)$ .

- ► The above construction establishes formal stability.
- The conditions of Grillakis, Shatah and Strauss (87, 90) need to be verified. Mainly, we have to check that kerL<sub>4</sub> is spanned by the generators of the Lie point symmetry group (Maddocks and Sachs, 93).
- ► For all N, kerL<sub>4</sub> is identical to kerL = kerL<sub>2</sub>, for which the condition is easily verified.

- ► The above construction establishes formal stability.
- The conditions of Grillakis, Shatah and Strauss (87, 90) need to be verified. Mainly, we have to check that kerL<sub>4</sub> is spanned by the generators of the Lie point symmetry group (Maddocks and Sachs, 93).
- ► For all N, kerL<sub>4</sub> is identical to kerL = kerL<sub>2</sub>, for which the condition is easily verified.
- This establishes orbital stability for all solutions that are spectrally stable, except for the solutions on the boundary curves.

## Summary

- Complete understanding of the stability spectra of elliptic solutions of focusing NLS
- Explicit description of the spectra of some non-self-adjoint problems
- Orbital stability with respect to subharmonic perturbations