

Highly accurate methods for conservative two-phase flow models

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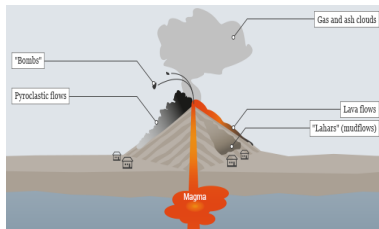
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- ▶ The main purpose is to study non-equilibrium two-phase flow models that represent gas and magma mixtures arising within volcanic eruptions phenomena.



- ▶ Mixture mass, momentum, and energy conservation equations:

$$\frac{\partial}{\partial t}(\rho) + \frac{\partial}{\partial x}(\rho u) = 0,$$

$$\frac{\partial}{\partial t}(\rho u) + \frac{\partial}{\partial x}(\rho u^2 + P + \rho c(1-c)u_r^2) = 0,$$

$$\frac{\partial}{\partial t}(\rho E) + \frac{\partial}{\partial x} \left(\rho u E + P u + \rho c(1-c)u_r \left(uu_r + (1-2c)\frac{u_r^2}{2} + \frac{\partial e}{\partial c} \right) \right) = 0.$$

- ▶ Volume and mass fractions for the gas phase and relative velocity:

$$\frac{\partial}{\partial t}(\rho \alpha) + \frac{\partial}{\partial x}(\rho u \alpha) = 0,$$

$$\frac{\partial}{\partial t}(\rho c) + \frac{\partial}{\partial x}(\rho u c + \rho c(1-c)u_r) = 0,$$

$$\frac{\partial}{\partial t}(u_r) + \frac{\partial}{\partial x} \left(uu_r + (1-2c)\frac{u_r^2}{2} + \frac{\partial e}{\partial c} \right) = \pi.$$

- ▶ Mixture velocity, density, momentum and pressure:

$$u = c_g u_g + c_m u_m, \quad \rho = \alpha \rho_g + (1 - \alpha) \rho_m \quad \text{and} \quad \rho u = \alpha \rho_g u_g + (1 - \alpha) \rho_m u_m.$$

- ▶ Mixture total energy and entropy:

$$E = e + c(1 - c) \frac{u_r u_r}{2} \quad \text{and} \quad P = \alpha p_g + (1 - \alpha) p_m.$$

$$e = c e_g(\rho_g, s) + (1 - c) e_m(\rho_m, s) \quad \text{and} \quad s = c s_g + (1 - c) s_m.$$

$$\alpha = \alpha_g = 1 - \alpha_m \quad \text{and} \quad c = c_g = \alpha_g \rho_g \rho^{-1}.$$

- ▶ Equations of state for perfect gas for gas and stiffened for magma:

$$e_g(\rho_g, s) = \frac{A_g}{\gamma_g - 1} \left(\frac{\rho_g}{\rho_g^0} \right)^{\gamma_g - 1} \exp \left(\frac{s}{c_V^g} \right),$$

$$e_m(\rho_m, s) = \frac{A_m}{\gamma_m - 1} \left(\frac{\rho_m}{\rho_m^0} \right)^{\gamma_m - 1} \exp \left(\frac{s}{c_V^m} \right) + A_0 \frac{\rho_m^0}{\rho_m}.$$

- ▶ Relative velocity between the two phases:

$$u_r = u_g - u_m.$$

- ▶ Mass densities and pressures of each of the phases:

$$\rho_g = \frac{c\rho}{\alpha}, \quad \rho_m = \frac{(1-c)\rho}{1-\alpha}, \quad p_g = \rho_g^2 \frac{\partial e_g}{\partial \rho_g} \quad \text{and} \quad p_m = \rho_m^2 \frac{\partial e_m}{\partial \rho_m}.$$

- ▶ Source term that represents the interfacial friction between phases:

$$\pi = \kappa(u_2 - u_1) = \kappa u_r.$$

- Conservative form of the governing equations: $\frac{\partial \mathbf{U}}{\partial t} + \frac{\partial \mathbf{F}(\mathbf{U})}{\partial x} = \mathbf{S}(\mathbf{U})$.

$$\mathbf{U} = \begin{pmatrix} \rho \\ \rho\alpha \\ \rho u \\ \rho c \\ u_r \\ \rho E \end{pmatrix}, \quad \mathbf{F}(\mathbf{U}) = \begin{pmatrix} \rho u \\ \rho u\alpha \\ \rho u^2 + P + \rho c(1-c)u_r^2 \\ \rho uc + \rho c(1-c)u_r \\ uu_r + (1-2c)\frac{u_r^2}{2} + \frac{\partial e}{\partial c} \\ \rho uE + Pu + \rho c(1-c)u_r \left(uu_r + (1-2c)\frac{u_r^2}{2} + \frac{\partial e}{\partial c} \right) \end{pmatrix},$$

$$\mathbf{S}(\mathbf{U}) = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \\ \pi \\ 0 \end{pmatrix}.$$

- ▶ Relaxation system for the conservative form of the governing equations:

$$\frac{\partial \mathbf{U}}{\partial t} + \frac{\partial \mathbf{V}}{\partial x} = \mathbf{S}(\mathbf{U}),$$

$$\frac{\partial \mathbf{V}}{\partial t} + \mathbf{B}^2 \frac{\partial \mathbf{U}}{\partial x} = -\frac{1}{\tau} (\mathbf{V} - \mathbf{F}(\mathbf{U})).$$

$\mathbf{V} \in \mathbb{R}^6$ is the relaxation variable and $\mathbf{B}^2 = \text{diag}\{B_1^2, \dots, B_6^2\}$ is a diagonal matrix with positive diagonal elements B_k^2 , $k = 1, \dots, 6$.

$\tau \in [0, 1)$ is the relaxation rate.

- ▶ Semi-discrete relaxation scheme:

$$\frac{d\mathbf{U}_i}{dt} + \frac{\mathbf{V}_{i+1/2} - \mathbf{V}_{i-1/2}}{\Delta x} = \mathbf{S}(\mathbf{U})_i,$$

$$\frac{d\mathbf{V}_i}{dt} + \mathbf{B}_i^2 \frac{\mathbf{U}_{i+1/2} - \mathbf{U}_{i-1/2}}{\Delta x} = -\frac{1}{\tau} (\mathbf{V}_i - \mathbf{F}(\mathbf{U})_i).$$

\mathbf{W}_i ($\mathbf{W} = \mathbf{U}$ or $\mathbf{W} = \mathbf{V}$) is the space average of a generic solution \mathbf{W} in the cell $[x_{i-1/2}, x_{i+1/2}]$ at time t and $\mathbf{W}_{i+1/2}$ is the numerical flux at $x = x_{i+1/2}$ and time t .

$$\mathbf{W}_i(t) = \frac{1}{\Delta x} \int_{x_{i-1/2}}^{x_{i+1/2}} \mathbf{W}(x, t) dx, \quad \mathbf{W}_{i+1/2} = \mathbf{W}(x_{i+1/2}, t).$$

► Implementation of an s -stage IMEX scheme: **Step 1**

For $l = 1, \dots, s$:

(1) Evaluate $(\hat{u}_i^{(l)}, \hat{v}_i^{(l)})$ as:

$$\hat{u}_i^{(l)} = \mathbf{U}_i^n - \Delta t \sum_{m=1}^{l-1} \tilde{a}_{lm} \frac{\hat{v}_{i+1/2}^{(m)} - \hat{v}_{i-1/2}^{(m)}}{\Delta x},$$

$$\hat{v}_i^{(l)} = \mathbf{V}_i^n - \Delta t \mathbf{B}_i^2 \sum_{m=1}^{l-1} \tilde{a}_{lm} \frac{\hat{u}_{i+1/2}^{(m)} - \hat{u}_{i-1/2}^{(m)}}{\Delta x}.$$

(2) Then solve for $(u_i^{(l)}, v_i^{(l)})$:

$$u_i^{(l)} = \hat{u}_i^{(l)} + \Delta t \sum_{m=1}^l a_{lm} \mathbf{S}(u^{(l)})_i,$$

$$v_i^{(l)} = \hat{v}_i^{(l)} - \frac{\Delta t}{\tau} \sum_{m=1}^l a_{lm} (v_i^{(l)} - \mathbf{F}(u^{(l)})_i).$$



- Implementation of an s -stage IMEX scheme: [Step 2](#)

For $l = 1, \dots, s$, update $(\mathbf{U}_i^{n+1}, \mathbf{V}_i^{n+1})$ as:

$$\mathbf{U}_i^{n+1} = \mathbf{U}_i^n - \Delta t \sum_{l=1}^s \tilde{b}_l \frac{\mathcal{V}_{i+1/2}^{(l)} - \mathcal{V}_{i-1/2}^{(l)}}{\Delta x} + \Delta t \sum_{l=1}^s b_l \mathbf{S}(\mathcal{U}^{(l)})_i,$$

$$\mathbf{V}_i^{n+1} = \mathbf{V}_i^n - \Delta t \mathbf{B}_i^2 \sum_{l=1}^s \tilde{b}_l \frac{\mathcal{U}_{i+1/2}^{(l)} - \mathcal{U}_{i-1/2}^{(l)}}{\Delta x} - \frac{\Delta t}{\tau} \sum_{l=1}^s b_l (\mathcal{V}_i^{(l)} - \mathbf{F}(\mathcal{U}^{(l)})_i).$$

► Fully-discrete relaxation scheme

$$\frac{\partial \mathcal{F}^+}{\partial t} + \mathbf{B} \frac{\partial \mathcal{F}^+}{\partial x} = -\frac{1}{\tau} (\mathcal{F}^+ - \mathcal{M}^+),$$

$$\frac{\partial \mathcal{F}^-}{\partial t} - \mathbf{B} \frac{\partial \mathcal{F}^-}{\partial x} = -\frac{1}{\tau} (\mathcal{F}^- - \mathcal{M}^-).$$

\mathcal{F}^+ and \mathcal{F}^- are kinetic variables (Riemann invariants) the components of which are

$$\mathcal{F}_k^+ = \frac{1}{2} \left(U_k + \frac{V_k}{B_k} \right), \quad \mathcal{F}_k^- = \frac{1}{2} \left(U_k - \frac{V_k}{B_k} \right), \quad k = 1, \dots, 6,$$

whereas the local equilibrium functions (or Maxwellians) \mathcal{M}^+ and \mathcal{M}^- are

$$\mathcal{M}_k^+ = \frac{1}{2} \left(U_k + \frac{F_k(U)}{B_k} \right), \quad \mathcal{M}_k^- = \frac{1}{2} \left(U_k - \frac{F_k(U)}{B_k} \right), \quad k = 1, \dots, 6.$$



- Fully-discrete relaxation scheme: **First-order reconstruction**

$$\mathcal{F}_{i+1/2}^+ = \mathcal{F}_i^+, \quad \mathcal{F}_{i+1/2}^- = \mathcal{F}_{i+1}^-.$$

The intermediate solutions are

$$U_{i+1/2} = \frac{U_i + U_{i+1}}{2} - \frac{V_{i+1} - V_i}{2B_k}$$

$$V_{i+1/2} = \frac{V_i + V_{i+1}}{2} - B_k \frac{U_{i+1} - U_i}{2}$$

For time integration, the first-order IMEX scheme defined by the double Butcher's *tableau* is considered.

$$\begin{array}{c|c} 0 & 0 \\ \hline & 1 \end{array} \quad \begin{array}{c|c} 1 & 1 \\ \hline & 1 \end{array}$$

- Fully-discrete relaxation scheme: **Second-order reconstruction**

$$\mathcal{F}_{i+1/2}^+ = \mathcal{F}_i^+ + \frac{1}{2}\Delta x \sigma_i^+, \quad \mathcal{F}_{i+1/2}^- = \mathcal{F}_{i+1}^- + \frac{1}{2}\Delta x \sigma_{i+1}^-.$$

σ_i^+ and σ_i^- are the slope of \mathcal{F}^+ and \mathcal{F}^- on the cell $[x_{i-1/2}, x_{i+1/2}]$.

$$\sigma_i^\pm = \frac{1}{\Delta x} \left(\mathcal{F}_{i+1}^\pm - \mathcal{F}_i^\pm \right) \Phi(\theta_i^\pm), \quad \theta_i^\pm = \frac{\mathcal{F}_i^\pm - \mathcal{F}_{i-1}^\pm}{\mathcal{F}_{i+1}^\pm - \mathcal{F}_i^\pm}, \quad \Phi(\theta) = \frac{|\theta| + \theta}{1 + |\theta|}.$$

The intermediate solutions are

$$U_{i+1/2} = \frac{U_i + U_{i+1}}{2} - \frac{V_i - V_{i+1}}{2B_k} + \frac{\sigma_i^+ + \sigma_{i+1}^-}{4B_k},$$

$$V_{i+1/2} = \frac{V_i + V_{i+1}}{2} - B_k \frac{U_{i+1} - U_i}{2} + \frac{\sigma_i^+ - \sigma_{i+1}^-}{4}.$$

For time integration, the second-order IMEX scheme defined by the double Butcher's *tableau* is considered.

$$\begin{array}{c|cc} 0 & 0 & 0 \\ 0 & 1 & 0 \\ \hline & \frac{1}{2} & \frac{1}{2} \end{array} \quad \begin{array}{c|cc} -1 & -1 & 0 \\ 2 & 1 & 1 \\ \hline & \frac{1}{2} & \frac{1}{2} \end{array}$$

- Expansion tube problem for a mixture of gas and magma:

Magma

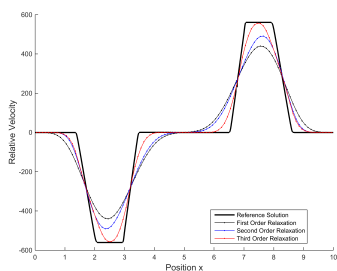
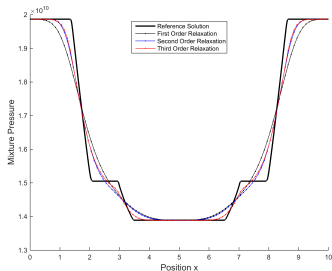
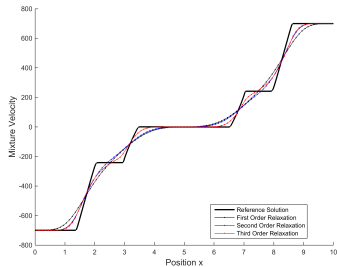
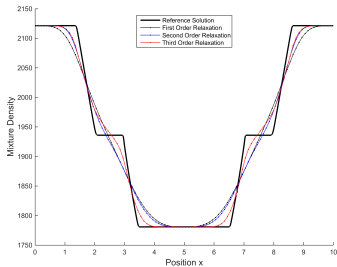
$$(\rho_m, u_m, s_m)_L = (3800 \text{ kg/m}^3, -700 \text{ m/s}, 7556.5895 \text{ J/K.kg})$$

$$(\rho_m, u_m, s_m)_R = (3800 \text{ kg/m}^3, 700 \text{ m/s}, 7556.5895 \text{ J/K.kg})$$

Gas

$$(\alpha, \rho_g, u_g, s_g)_L = (0.75, 1562 \text{ kg/m}^3, -700 \text{ m/s}, 12658.879 \text{ J/K.kg})$$

$$(\alpha, \rho_g, u_g, s_g)_R = (0.75, 1562 \text{ kg/m}^3, 700 \text{ m/s}, 12658.879 \text{ J/K.kg})$$



- ▶ Shock tube problem for a mixture of gas and magma:

Magma

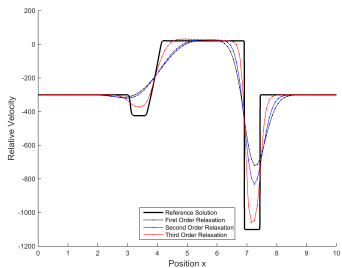
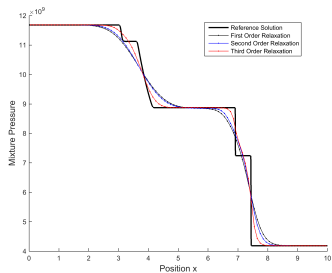
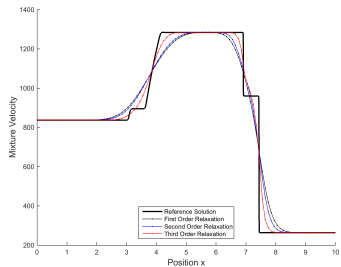
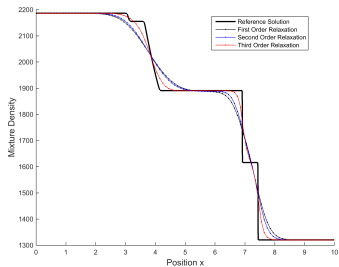
$$(\rho_m, u_m, s_m)_L = (2500 \text{ kg/m}^3, 1000 \text{ m/s}, 7556.5895 \text{ J/K.kg})$$

$$(\rho_m, u_m, s_m)_R = (1800 \text{ kg/m}^3, 400 \text{ m/s}, 7556.5895 \text{ J/K.kg})$$

Gas

$$(\alpha, \rho_g, u_g, s_g)_L = (0.6, 1977 \text{ kg/m}^3, 700 \text{ m/s}, 12658.879 \text{ J/K.kg})$$

$$(\alpha, \rho_g, u_g, s_g)_R = (0.6, 1000 \text{ kg/m}^3, 100 \text{ m/s}, 12658.879 \text{ J/K.kg})$$



Conclusions and Perspectives

- ▶ The relaxation method transforms the nonlinear hyperbolic system to a semi-linear model which can be solved numerically without using either Riemann solvers or linear iterations.
- ▶ The scheme can be applied to other systems of non-equilibrium two-phase flow problems such as slurry pipeline flows.





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M.K. Banda and M. Seaid, *Higher-order relaxation schemes for hyperbolic systems of conservation laws*, J. Numer. Math., 2005.



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THANK YOU !