

Modelling liquid foams with an elastoviscoplastic fluid

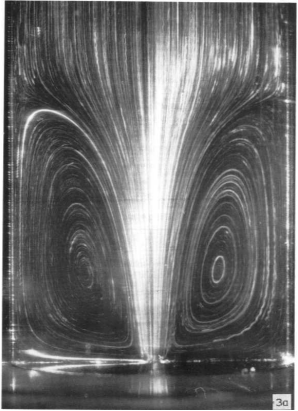
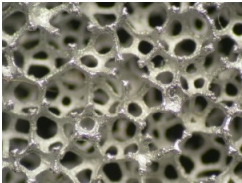
Prediction of shearband and smooth or abrupt localization

Pierre Saramito¹

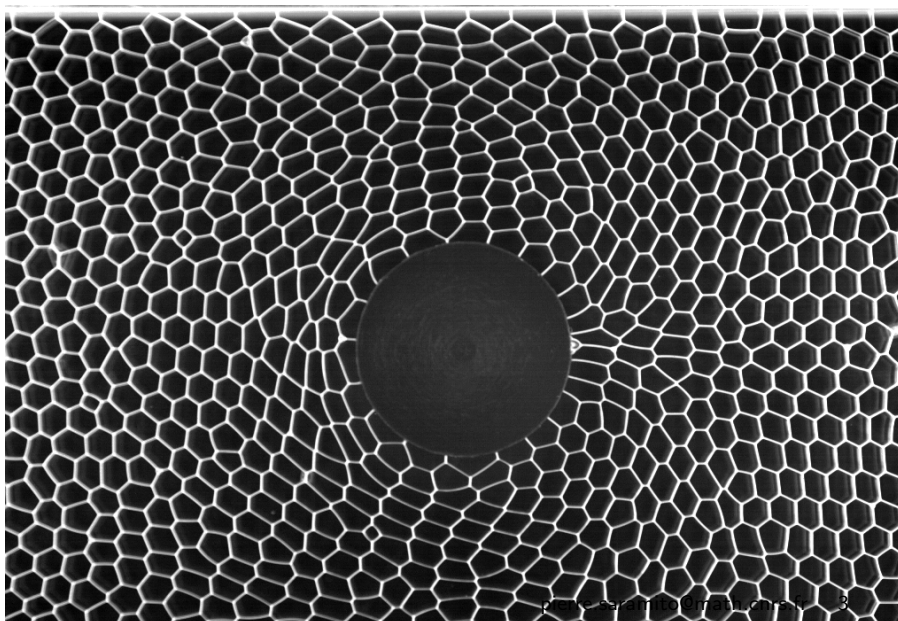
Ibrahim Cheddadi² and François Graner³

- 1: LJK, CNRS and univ. Grenoble, France
- 2: TIMC, univ. Grenoble, France
- 3: MSC, CNRS and univ. Paris Diderot, France

Motivations



Liquid foam: a model material



Outline

1. Mathematical model
2. Test: Couette flow
3. Test: flow around a cylinder

Viscoplastic fluid: Herschel & Bulkley (1926)

$$\begin{cases} \tau = K|\dot{\epsilon}|^{n-1}\dot{\epsilon} + \tau_Y \frac{\dot{\epsilon}}{|\dot{\epsilon}|} & \text{when } \dot{\epsilon} \neq 0 \\ |\tau| \leq \tau_Y & \text{when } \dot{\epsilon} = 0 \end{cases}$$

\Leftrightarrow

$$\max\left(0, \frac{|\tau| - \tau_Y}{K|\tau|^n}\right)^{\frac{1}{n}} \tau = \dot{\epsilon}$$

and

$$\sigma = -pl + \tau = \text{Cauchy stress}$$

Notes

- material = rigid solid, then Newtonian fluid
- $|\tau| \leq \tau_Y \Rightarrow \tau$ undetermined
- $n \in \mathbb{R}^+$: power law index
- $n = 1$: Bingham (1920)

Viscoelastic fluid: Oldroyd (1950)

$$\frac{1}{G} \overset{\nabla}{\tau} + \frac{1}{\eta_m} \tau = \dot{\epsilon}$$

and

$$\sigma = -pl + 2\eta_s D(\mathbf{v}) + \tau = \text{Cauchy stress}$$

Notes

- *objective* tensor derivative

$$\overset{\nabla}{\tau} = \frac{\partial \tau}{\partial t} + \mathbf{v} \cdot \nabla \tau - \tau \cdot \nabla \mathbf{v}^T - \nabla \mathbf{v} \cdot \tau.$$

- requires an initial condition:

$$\tau(t=0) = \tau_0$$

- $\eta_s = 0$: Maxwell (1967)

Elastoviscoplastic fluid

$$\frac{1}{G} \nabla \cdot \tau + \max \left(0, \frac{|\tau| - \tau_Y}{K|\tau|^n} \right)^{\frac{1}{n}} \tau = \dot{\varepsilon}$$

and

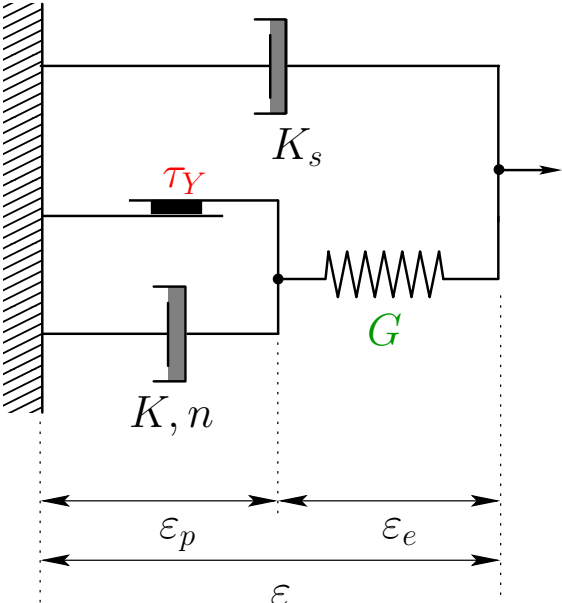
$$\sigma = -pl + 2K_s D(\mathbf{v}) + \tau = \text{Cauchy stress}$$

Notes

- $1/G = 0$: Herschel-Bulkley
- $\tau_Y = 0$ and $n = 1$: Oldroyd
- $1/G = \tau_Y = 0$ and $n = 1$: Navier-Stokes

[Saramito, JNNFM, 2007 & 2009]

Elastoviscoplastic fluid



Thermodynamics

$$\varepsilon = \varepsilon_e + \varepsilon_p$$

Free energy and dissipation potential:

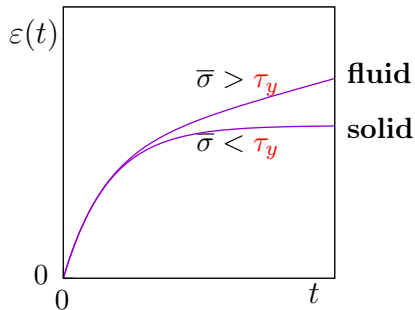
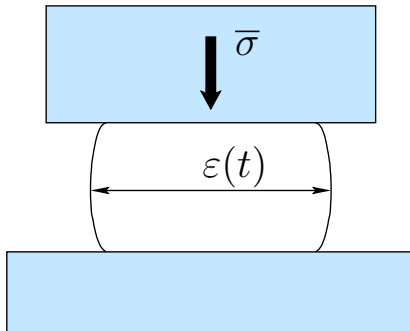
$$\begin{aligned}\mathcal{E}(\varepsilon, \varepsilon_e) &= G |\varepsilon_e|^2 \\ \mathcal{D}(\dot{\varepsilon}, \dot{\varepsilon}_e) &= K_s |\dot{\varepsilon}|^2 + K |\dot{\varepsilon} - \dot{\varepsilon}_e|^n + \tau_Y |\dot{\varepsilon} - \dot{\varepsilon}_e|\end{aligned}$$

Properties

- Onsager symmetry principle satisfied
- \mathcal{D} convex \implies the second law is satisfied

[Halphen & NGuyen, 1975]

Creeping test



material = viscoelastic **solid**, then viscoelastic **fluid**

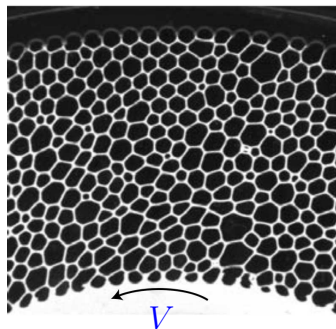
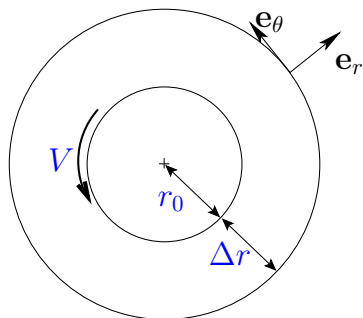
Problem statement

(P): find τ , \mathbf{v} and p such that

$$\begin{aligned} \frac{1}{G} \nabla \tau + \max \left(0, \frac{|\tau| - \tau_Y}{K|\tau|^n} \right)^{\frac{1}{n}} \tau - 2D(\mathbf{v}) &= 0 \\ \rho \left(\frac{\partial \mathbf{v}}{\partial t} + \mathbf{v} \cdot \nabla \mathbf{v} \right) - \mathbf{div} \{ -p \mathbf{I} + 2K_s D(\mathbf{v}) + \tau \} &= \mathbf{f} \\ -\mathbf{div} \mathbf{v} &= 0 \\ &+ B.C. + I.C. \end{aligned}$$

Implementation: Rheolef FEM C++ library (free software)

Couette Geometry



$$\mathbf{v} = \begin{pmatrix} 0 \\ v_\theta(r) \end{pmatrix}$$

$$\boldsymbol{\tau} = \begin{pmatrix} \tau_{rr}(r) & \tau_{r\theta}(r) \\ \tau_{\theta r}(r) & \tau_{\theta\theta}(r) \end{pmatrix}$$

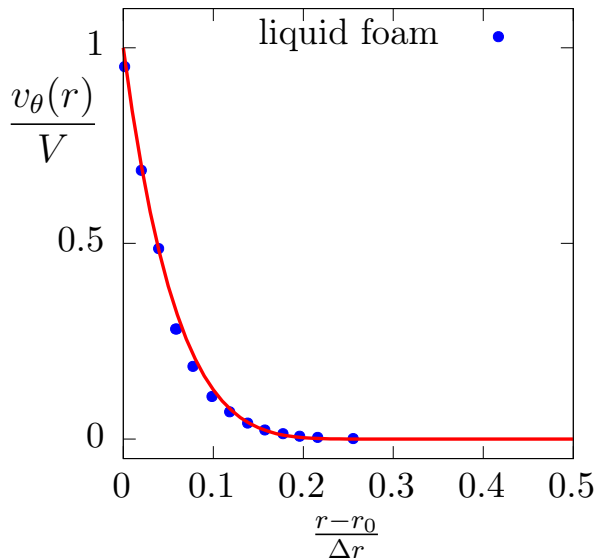
Two dimensionless numbers

$$We = \frac{\eta \dot{\gamma}}{G} \quad \text{viscoelasticity}$$

$$Bi = \frac{\tau_Y}{\eta \dot{\gamma}} \quad \text{viscoplasticity}$$

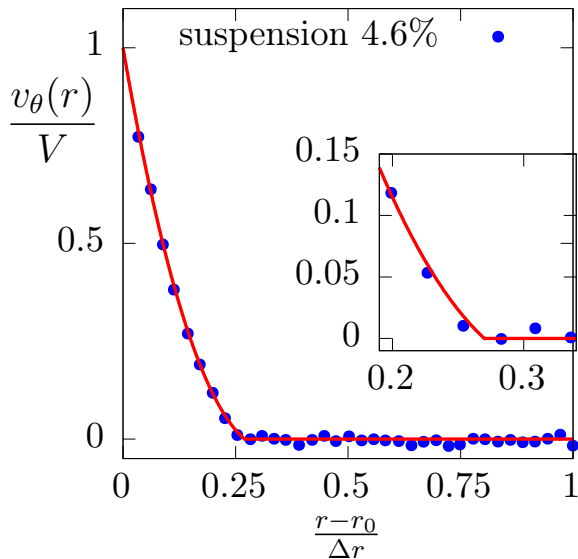
with $\eta = K \dot{\gamma}^{n-1}$: dimension of a viscosity
 $\dot{\gamma} = V/\Delta r$: representative shear rate

Observation: (1) smooth profile



experiment: *Debrégeas et al., PRL, 2001*

Observation: (2) abrupt profile



experiment: *Coussot et al., PRL, 2002*

10 years of questioning

year	profil	authors	material
2001	smooth	<i>Debrégeas et al.</i>	liquid foam
2002	abrupt	<i>Coussot et al.</i>	suspensions, emulsions
2003	abrupt	<i>Salmon et al.</i>	wormlike micelles
2004	abrupt	<i>Lauridsen et al.</i>	liquid foam
2006	abrupt	<i>Gilbreth et al.</i>	liquid foam
2008	abrupt	<i>Dennin et al.</i>	liquid foam

⇒ are profils abrupts ?

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2006	abrupt	<i>Gilbreth et al.</i>	liquid foam
2008	abrupt	<i>Dennin et al.</i>	liquid foam
2008	smooth	<i>Kätgert et al.</i>	liquid foam
2010	smooth	<i>Coussot et al.</i>	suspensions, emulsions
2010	smooth	<i>Ovarlez et al.</i>	liquid foam
2010	smooth	<i>Kätgert et al.</i>	liquid foam

⇒ are profiles **smooth** ?

⇒ computations + theoretical interpretation

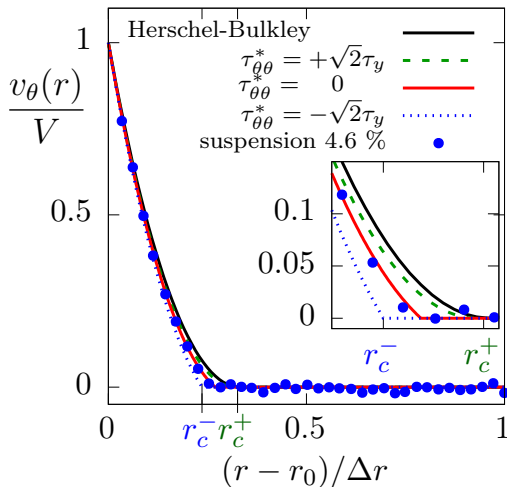
Initial stress influence ?

$$\tau(t=0) = \begin{pmatrix} \tau_{rr} & \tau_{r\theta} \\ \tau_{\theta r} & \tau_{\theta\theta} \end{pmatrix} \Leftarrow \begin{pmatrix} 0 & 0 \\ 0 & \tau_{\theta\theta}^* \end{pmatrix}$$

Three extremal cases:

$\tau_{\theta\theta}^*$	
0	no pre-stress
$+\sqrt{2}\tau_Y$	pre-stress
$-\sqrt{2}\tau_Y$	pre-stress

Computation: (1) abrupt profile

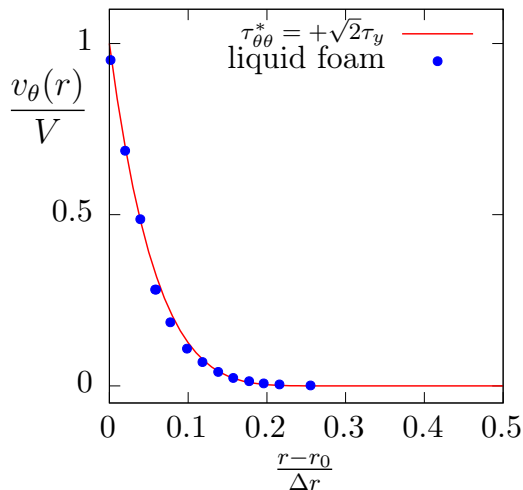


computation: $We = 0.026$, $Bi = 27$, $n = 1$

Cheddadi, Saramito, Graner, JoR, 2012

experiment: *Coussot et al., PRL, 2002*

Computation: (2) smooth profile



computation: $We = 0.035$, $Bi = 10$, $n = 1/3$

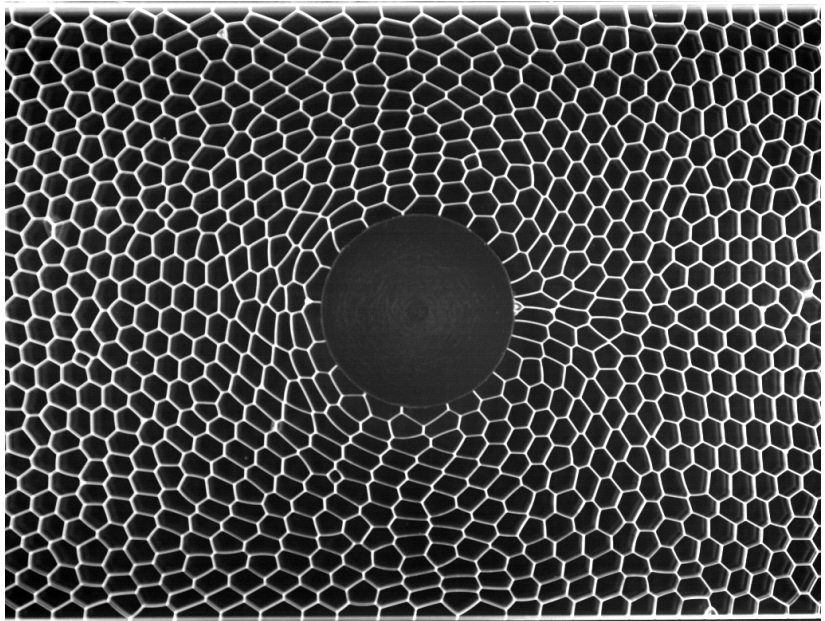
Cheddadi, Saramito, Graner, JoR, 2012

experiment: *Debrégeas et al., PRL, 2001*

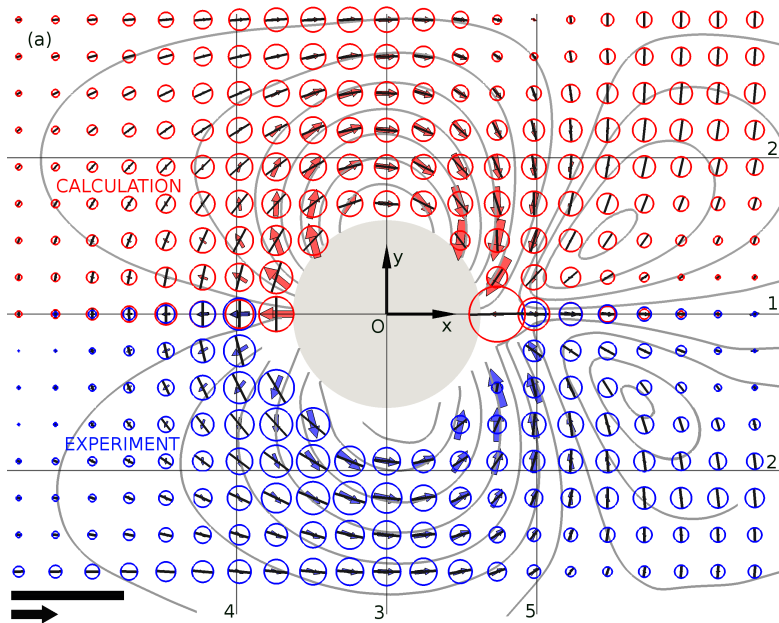
Discussion

- ▶ *" To eliminate transient effects, we ran the experiment a full round before taking data."*
[Debrégeas, Tabuteau & di Meglio, 2001]
- ▶ [Cousot et al., 2002]: not presheared
- ▶ *" Before any measurement, the Laponite sample is presheared for 1 min at $+1500 \text{ s}^{-1}$ and for 1 min at -1500 s^{-1} to erase most of the sample history. We checked that this procedure leads to reproducible results over a few hours."*
[Gibaud, Barentin & Manneville, 2008]
- ▶ *" The preshear protocol prior to the experiment may strongly influence the results."*
[Divoux, Fardin, Manneville & Lerouge, 2016]

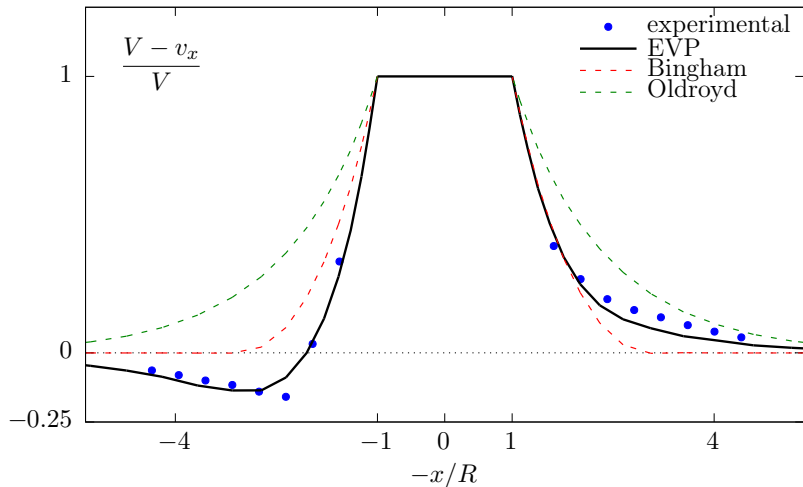
Flow around an obstacle



Computation / experiment



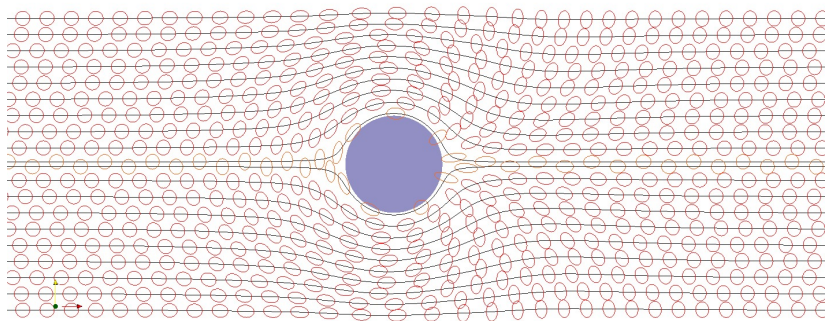
Velocity along the axis: negative wake



Cheddadi, Saramito, *JNNFM*, 2013

Cheddadi, Saramito, Dollet, Raufaste, Graner, *EPJE*, 2011

Flow around an obstacle



Conclusion

- ▶ modeling: 3D, objective derivative
few parameters, all measurable:

$$G, \tau\gamma, K, n.$$

- ▶ Couette: predict both smooth or abrupt profiles
⇒ pre-stress dependence
quantitative predictions
- ▶ obstacle: quantitative predictions on complex geometry
⇒ negative wake
prediction - measure $\leq 5\%$

success story: Carbopol around an obstacle

[Fraggedakis, Dimakopoulos, Tsamopoulos, Soft Mat. 2016]

Perspectives

- **lab**: others complex geometries (contractions, etc)
- **geophysics**: sea ice cover (add plasticity), earthquake, crustal large deformations, meteorite impact ...
- **biology**: tissues and embryogenesis, blood flow...

More reading

paper: Cheddadi, Saramito, JNNFM, 2013

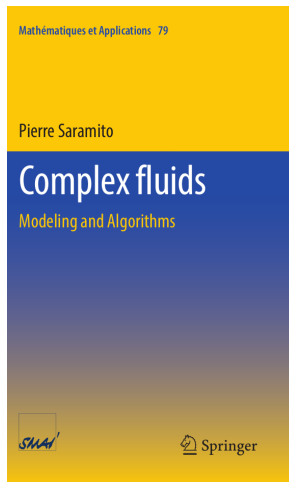
Cheddadi, Saramito, Graner, JoR, 2012

Saramito, JNNFM, 2009, 2007

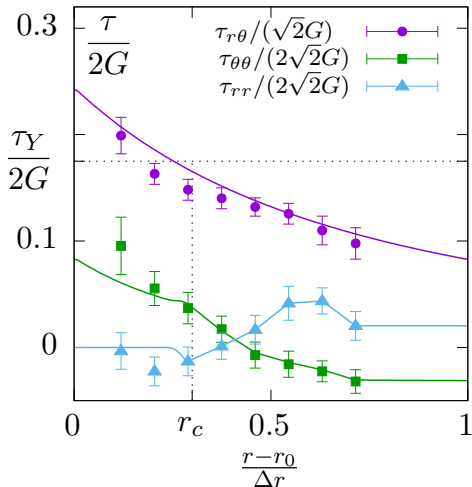
book: Saramito, *Complex fluids*
Springer, 2016

code: Saramito, 2018
Rheolef FEM C++ library
Free software: GPL licence

<http://www-ljk.imag.fr/membres/Pierre.Saramito/rheolef>



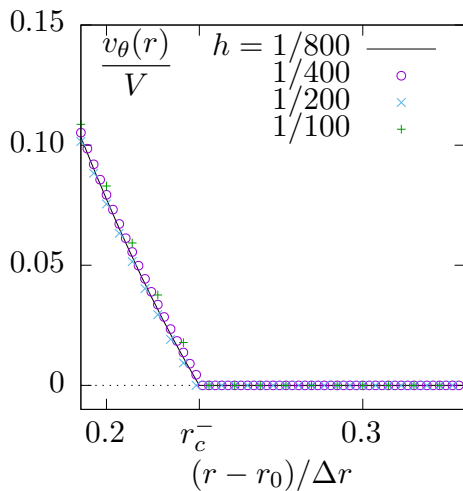
Full stress tensor comparisons



computation: $We = 0.035$, $Bi = 10$, $n = 1/3$

experiment: *Debréguas et al. (2001), PRL 87:178305.*

Convergence of abrupt solutions



Convergence of abrupt solutions

