

Determinantal formulas for the resultant of some mixed multilinear systems

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Inria



Solving mixed multilinear systems

Objective

Solve (symbolically) square some **mixed sparse** multilinear systems

- Take into the account the sparseness
- Polynomial time wrt the number of solutions

Results

- Sylvester- and Koszul-type determinantal formula for the resultant
- Extension of the Eigenvalue criteria
- Extension of the Eigenvector criteria
- Applications to the Multiparameter Eigenvalue Problem (MEP)

The resultant

Projective resultant

Necessary and sufficient condition for a homogeneous system in $(f_0, \dots, f_n) \in \mathbb{K}[x_0, \dots, x_n]^{n+1}$ to have solutions in \mathbb{P}^n .

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Example : Resultant of linear forms = Determinant

The system $\begin{cases} \mathbf{a}_1 x + \mathbf{a}_2 y + \mathbf{a}_3 z = 0 \\ \mathbf{b}_1 x + \mathbf{b}_2 y + \mathbf{b}_3 z = 0 \\ \mathbf{c}_1 x + \mathbf{c}_2 y + \mathbf{c}_3 z = 0 \end{cases}$ has a solution over \mathbb{P}^2



$$\det \begin{pmatrix} \mathbf{a}_1 & \mathbf{a}_2 & \mathbf{a}_3 \\ \mathbf{b}_1 & \mathbf{b}_2 & \mathbf{b}_3 \\ \mathbf{c}_1 & \mathbf{c}_2 & \mathbf{c}_3 \end{pmatrix} = 0.$$

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Example : Resultant of linear forms = Determinant

Example : Resultant of binary forms = Det of Sylvester matrix

$$\begin{cases} a_1 x^2 + a_2 x y + a_3 y^2 = 0 \\ b_1 x^3 + b_2 x^2 y + b_3 x y^2 + b_4 y^3 = 0 \end{cases} \text{ has a solution over } \mathbb{P}^1$$

$$\begin{array}{c} \Downarrow \\ \det \begin{pmatrix} a_1 & a_2 & a_3 & 0 & 0 \\ 0 & a_1 & a_2 & a_3 & 0 \\ 0 & 0 & a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 & b_4 & 0 \\ 0 & b_1 & b_2 & b_3 & b_4 \end{pmatrix} = 0. \end{array}$$

Sylvester-type formulas

Classical way of computing resultant \rightarrow Sylvester-type formula

$$(g_0, \dots, g_n) \mapsto \sum_{i=0}^n g_i f_i$$

Macaulay resultant matrix

[Macaulay, 1916]

		x^2	xy	xz	y^2	yz	z^2
$f_1 := a_1 x^2 + a_2 xy + a_3 xz +$ $a_4 y^2 + a_5 yz + a_6 z^2$	f_1	a_1	a_2	a_3	a_4	a_5	a_6
	$x f_2$	b_1	b_2	b_3			
$f_2 := b_1 x + b_2 y + b_3 z$	$y f_2$		b_1		b_2	b_3	
	$z f_2$			b_1		b_2	b_2
$f_3 := c_1 x + c_2 y + c_3 z$	$y f_3$		c_1		c_2	c_3	
	$z f_3$			c_1		c_2	c_3

Determinant = Resultant \cdot ExtraFactor .
 Minor of the matrix

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	$z f_3$			c_1		c_2	c_3

Determinant = Resultant \cdot ExtraFactor .
 Minor of the matrix

Determinantal formula \rightarrow ExtraFactor is a constant.

- We want to compute the two solutions $\alpha_1, \alpha_2 \in \mathbb{P}^2$ of

$$\begin{cases} f_1 := 1x^2 + -1xy + 4xz + -2y^2 + -5yz + 3z^2 \\ f_2 := 1x + -1y + -1z \end{cases} .$$

Solving

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- Introduce $f_0 := -1x + 2y + 1z$ and consider a Sylvester-type formula.

$$\left(\begin{array}{c|c} M_{1,1} & M_{1,2} \\ \hline M_{2,1} & M_{2,2} \end{array} \right) = \begin{array}{c|cccc|cc} & x^2 & xy & xz & y^2 & yz & z^2 \\ \hline f_1 & 1 & -1 & 4 & -2 & -5 & 3 \\ x f_2 & 1 & -1 & -1 & & & \\ y f_2 & & 1 & & -1 & -1 & \\ z f_2 & & & 1 & & -1 & -1 \\ \hline y f_0 & & -1 & & 2 & 1 & \\ z f_0 & & & -1 & & 2 & 1 \end{array}$$

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- Schur complement of $M_{2,2} \leftrightarrow$ Multiplication map

$$\tilde{M}_{2,2} = M_{2,2} - M_{2,1} M_{1,1}^{-1} M_{1,2} = \begin{pmatrix} 0 & 4 \\ 1 & 0 \end{pmatrix}$$

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- Eigenvalues of $\tilde{M}_{2,2} \leftrightarrow f_0(\alpha_i)$

[Lazard, 1981]

$$f_0(\alpha_1) = 2 \quad \text{and} \quad f_0(\alpha_2) = -2.$$

Solving

- We want to compute the two solutions $\alpha_1, \alpha_2 \in \mathbb{P}^2$ of

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- Eigenvectors of $\tilde{M}_{2,2} \leftrightarrow \begin{pmatrix} yz \\ z^2 \end{pmatrix}(\alpha_i)$ [Auzinger & Stetter, 1988]

$$\begin{pmatrix} yz \\ z^2 \end{pmatrix}(\alpha_1) = \begin{pmatrix} 2 \\ 1 \end{pmatrix} \quad \text{and} \quad \begin{pmatrix} yz \\ z^2 \end{pmatrix}(\alpha_2) = \begin{pmatrix} -2 \\ 1 \end{pmatrix}$$

Problems

We want to compute the two solutions a similar system

$$\begin{cases} f_1 := 1x^2 + -1xy + 4xz + -2y^2 + -5yz + 3z^2 \\ f_2 := \boxed{0}x + -1y + -1z \end{cases}$$

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The submatrix $M_{1,1}$ not invertible \implies we cannot compute Schur complement.

Why? Because the ExtraFactor vanishes.

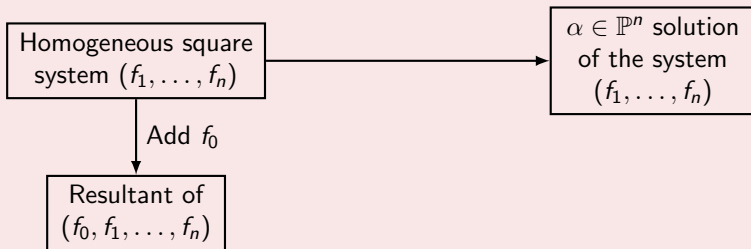
Solving polynomial systems using the resultant

Homogeneous square
system (f_1, \dots, f_n)

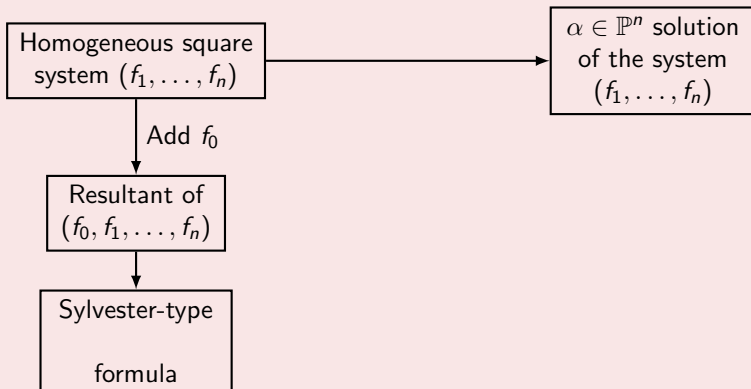
$\alpha \in \mathbb{P}^n$ solution
of the system
 (f_1, \dots, f_n)



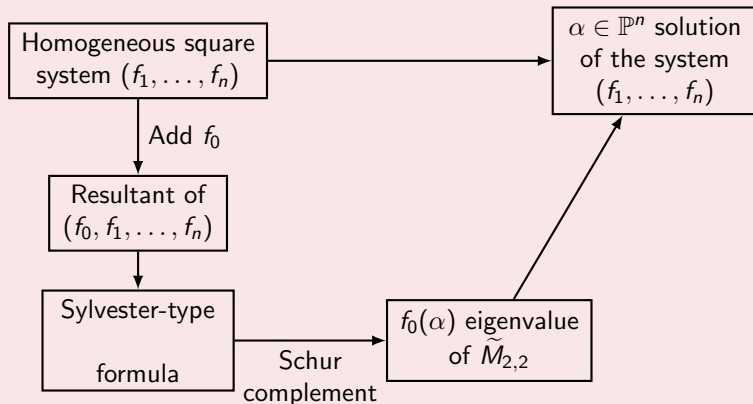
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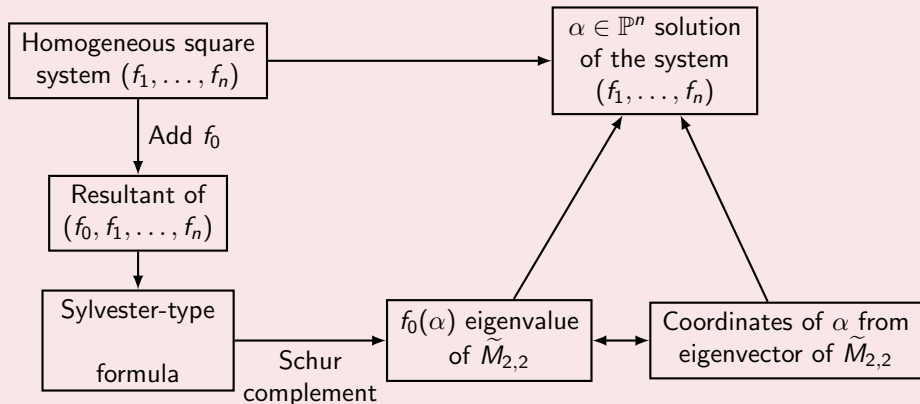


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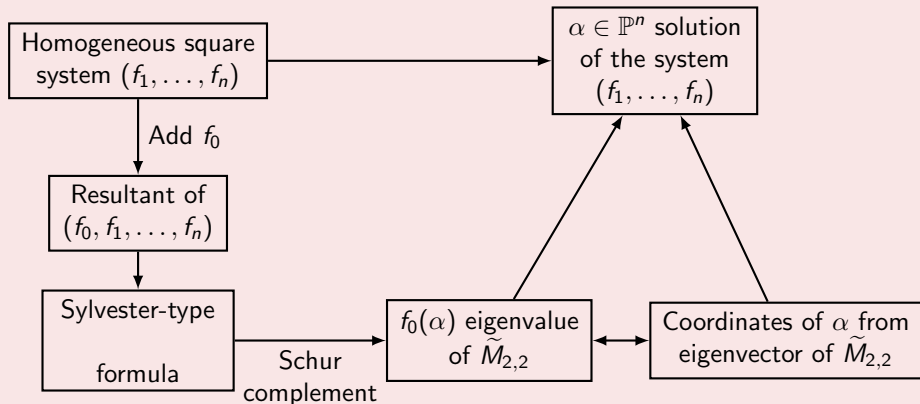
$$\begin{bmatrix} M_{1,1} & M_{1,2} \\ M_{2,1} & M_{2,2} \end{bmatrix} \rightarrow \begin{bmatrix} M_{1,1} & M_{1,2} \\ 0 & \tilde{M}_{2,2} \end{bmatrix}$$

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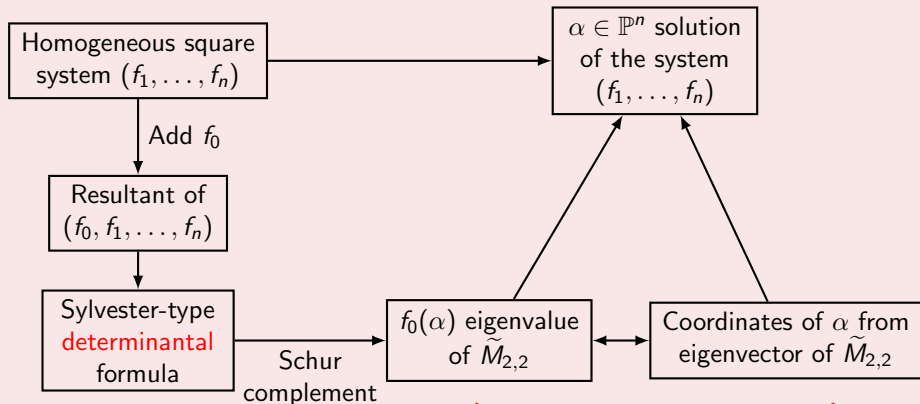


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- $M_{1,1}$ not invertible
- $M_{1,1}$ too big

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~~Problems~~

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- ~~• $M_{1,1}$ too big~~

Multihomogeneous systems

Multiprojective space $\mathbb{P}^{n_1} \times \cdots \times \mathbb{P}^{n_r} \leftrightarrow$ Multihomogeneous polynomials.

Multiprojective resultant

Necessary and sufficient condition for a multihomogeneous system in $(f_0, \dots, f_{n_1+\dots+n_r}) \in (\mathbb{K}[x_{1,0}, \dots, x_{1,n_1}] \otimes \cdots \otimes \mathbb{K}[x_{r,0}, \dots, x_{r,n_r}])^{n_1+\dots+n_r+1}$ to have solutions in $\mathbb{P}^{n_1} \times \cdots \times \mathbb{P}^{n_r}$.

Sylvester-type determinantal formulas

- Unmixed case (same support)
[Sturmfels, Zelevinsky, 1994], [Weyman, Zelevinsky, 1994],
[Dickenstein, Emiris, 2003], [Emiris, Mantzaflaris, 2012]
- Mixed case (different support)
- ...

We study **determinantal formulas** for some **mixed multilinear systems**.

The resultant as the determinant of a complex

Cayley method

- Compute the resultant as determinant of complex K_\bullet .

$$K_\bullet : 0 \rightarrow K_{n+1} \xrightarrow{\delta_{n+1}} \cdots \rightarrow K_1 \xrightarrow{\delta_1} K_0 \xrightarrow{\delta_0} \cdots \rightarrow K_{-n} \rightarrow 0.$$

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$$K_\bullet : 0 \rightarrow \cdots \rightarrow 0 \rightarrow K_1 \xrightarrow{\delta_1} K_0 \rightarrow 0 \rightarrow \cdots \rightarrow 0$$

Then, **determinantal formula** \rightarrow Determinant of $K_\bullet = \text{Det. of } \delta_1$.

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- These determinantal formula are not necessarily Sylvester-type.

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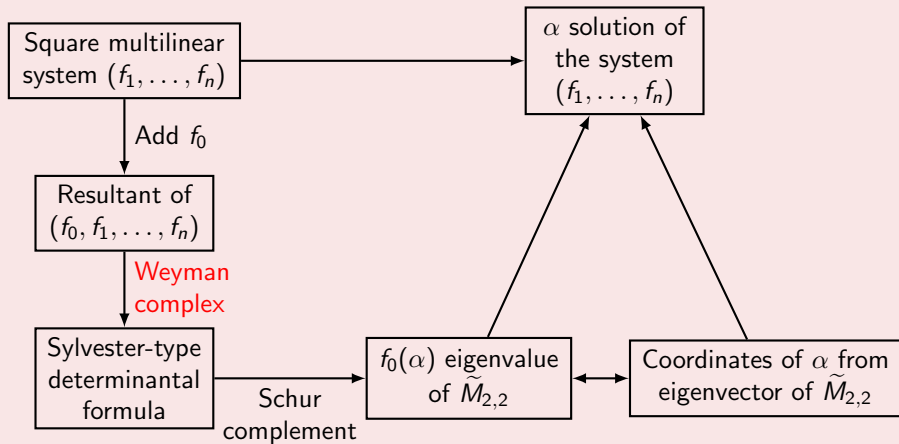
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Weyman complex

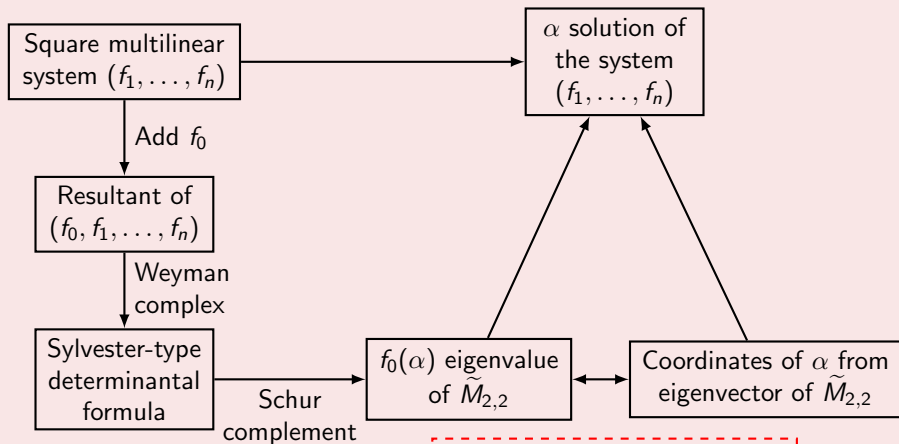
- Complex parameterized by vector \mathbf{m} . Its determinant is the resultant.
- Strategy \rightarrow Look for vectors \mathbf{m} such that the Weyman complex gives a determinantal formula.

Solving polynomial systems using the resultant



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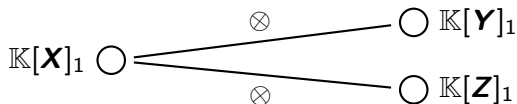
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Great, but...

Sylvester-type det. formulas does not exist in general,
Can we generalize the scheme ?

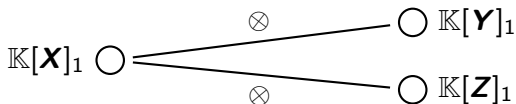
Example : Solving bilinear system with two supports

- Over $\mathbb{P}^{n_x} \times \mathbb{P}^{n_y} \times \mathbb{P}^{n_z}$, we want to solve (f_1, \dots, f_n) such that:
 - $f_1, \dots, f_r \in \mathbb{K}[\mathbf{X}]_1 \otimes \mathbb{K}[\mathbf{Y}]_1$, bilinear in the blocks \mathbf{X} and \mathbf{Y} , and
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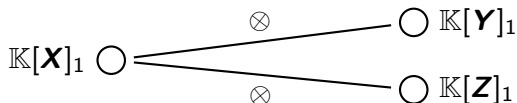
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- We introduce a trilinear polynomial $f_0 \in \mathbb{K}[\mathbf{X}]_1 \otimes \mathbb{K}[\mathbf{Y}]_1 \otimes \mathbb{K}[\mathbf{Z}]_1$.

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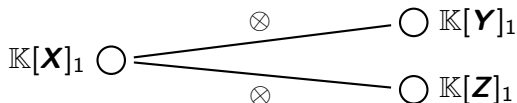
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- Weyman complex \rightarrow **Koszul-type formula** for the resultant.
 - Generalization of Sylvester-type formula (ie, $(g_0, \dots, g_n) \mapsto \sum_i g_i f_i$)
 - The elements in the matrix are \pm the coefficients of the polynomials.

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Number of solutions

of (f_1, \dots, f_n)

$$\binom{r}{n_y} \binom{n-r}{n_z}$$

Size of the Koszul-type matrix

$$(n_x + 1) \binom{r}{n_y} \binom{n-r}{n_z} \frac{r \cdot (n-r) - n_y \cdot n_z + n + 1}{(r - n_y + 1)(n - r - n_z + 1)}$$

Example : Koszul-type formula

$$\left\{ \begin{array}{l} f_1 := 7x_0y_0 + -8x_0y_1 + -1x_1y_0 + 2x_1y_1 \\ f_2 := -5x_0y_0 + 7x_0y_1 + -1x_1y_0 + -1x_1y_1 \\ f_3 := -6x_0z_0 + 9x_0z_1 + -1x_1z_0 + -2x_1z_1 \end{array} \right\} \begin{array}{l} \in \mathbb{K}[\mathbf{X}, \mathbf{Y}] \\ \in \mathbb{K}[\mathbf{X}, \mathbf{Z}] \end{array}$$

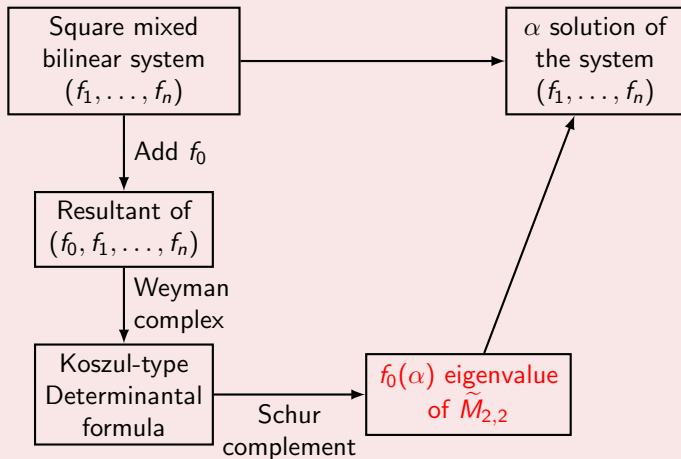
Example : Koszul-type formula

$$\left\{ \begin{array}{l} f_0 := 3x_0y_0z_0 + -1x_0y_0z_1 + -4x_0y_1z_0 + 2x_0y_1z_1 \\ \quad + 1x_1y_0z_0 + 2x_1y_0z_1 + 2x_1y_1z_0 + -2x_1y_1z_1 \\ f_1 := 7x_0y_0 + -8x_0y_1 + -1x_1y_0 + 2x_1y_1 \\ f_2 := -5x_0y_0 + 7x_0y_1 + -1x_1y_0 + -1x_1y_1 \\ f_3 := -6x_0z_0 + 9x_0z_1 + -1x_1z_0 + -2x_1z_1 \end{array} \right\} \begin{array}{l} \in \mathbb{K}[\mathbf{X}, \mathbf{Y}, \mathbf{Z}] \\ \in \mathbb{K}[\mathbf{X}, \mathbf{Y}] \\ \in \mathbb{K}[\mathbf{X}, \mathbf{Z}] \end{array}$$

Example : Koszul-type formula

$$\left. \begin{aligned}
 f_0 &:= 3x_0y_0z_0 + -1x_0y_0z_1 + -4x_0y_1z_0 + 2x_0y_1z_1 \\
 &\quad + 1x_1y_0z_0 + 2x_1y_0z_1 + 2x_1y_1z_0 + -2x_1y_1z_1 \\
 f_1 &:= 7x_0y_0 + -8x_0y_1 + -1x_1y_0 + 2x_1y_1 \\
 f_2 &:= -5x_0y_0 + 7x_0y_1 + -1x_1y_0 + -1x_1y_1 \\
 f_3 &:= -6x_0z_0 + 9x_0z_1 + -1x_1z_0 + -2x_1z_1
 \end{aligned} \right\} \begin{array}{l} \in \mathbb{K}[\mathbf{X}, \mathbf{Y}, \mathbf{Z}] \\ \\ \in \mathbb{K}[\mathbf{X}, \mathbf{Y}] \\ \\ \in \mathbb{K}[\mathbf{X}, \mathbf{Z}] \end{array}$$

$$M = \begin{bmatrix}
 & & & 5 & -7 & 1 & 1 & & & \\
 & & & 7 & -8 & -1 & 2 & & & \\
 & -1 & & & & & & -1 & -5 & 7 \\
 7 & & -1 & & & & & -1 & & -5 \\
 & 1 & & & & & & -2 & -7 & 8 \\
 8 & & -2 & & & & & 1 & & -7 \\
 & 2 & & 9 & & -2 & & -2 & -1 & 2 \\
 2 & & -2 & & 9 & & -2 & 2 & & -1 \\
 & 1 & & -6 & & -1 & & 2 & 3 & -4 \\
 -4 & & 2 & & -6 & & -1 & 1 & & 3
 \end{bmatrix}$$



$$\begin{bmatrix} M_{1,1} & M_{1,2} \\ M_{2,1} & M_{2,2} \end{bmatrix} \rightarrow \begin{bmatrix} M_{1,1} & M_{1,2} \\ 0 & \tilde{M}_{2,2} \end{bmatrix}$$

Example : Generalized Eigenvalue Criterion

$$\left\{ \begin{array}{l} f_0 := \boxed{3} x_0 y_0 z_0 + -1 x_0 y_0 z_1 + -4 x_0 y_1 z_0 + 2 x_0 y_1 z_1 \\ \quad + 1 x_1 y_0 z_0 + 2 x_1 y_0 z_1 + 2 x_1 y_1 z_0 + -2 x_1 y_1 z_1 \\ f_1 := 7 x_0 y_0 + -8 x_0 y_1 + -1 x_1 y_0 + 2 x_1 y_1 \\ f_2 := -5 x_0 y_0 + 7 x_0 y_1 + -1 x_1 y_0 + -1 x_1 y_1 \\ f_3 := -6 x_0 z_0 + 9 x_0 z_1 + -1 x_1 z_0 + -2 x_1 z_1 \end{array} \right.$$

$$\left[\begin{array}{c|c} M_{1,1} & M_{1,2} \\ \hline M_{2,1} & M_{2,2} \end{array} \right] = \left[\begin{array}{cccccccc|cc} 0 & 0 & 0 & 5 & -7 & 1 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 7 & -8 & -1 & 2 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 & 0 & 0 & 0 & -1 & -5 & 7 \\ 7 & 0 & -1 & 0 & 0 & 0 & 0 & -1 & 0 & -5 \\ 0 & 1 & 0 & 0 & 0 & 0 & 0 & -2 & -7 & 8 \\ 8 & 0 & -2 & 0 & 0 & 0 & 0 & 1 & 0 & -7 \\ 0 & 2 & 0 & 9 & 0 & -2 & 0 & -2 & -1 & 2 \\ 2 & 0 & -2 & 0 & 9 & 0 & -2 & 2 & 0 & -1 \\ \hline 0 & 1 & 0 & -6 & 0 & -1 & 0 & 2 & \boxed{3} & -4 \\ -4 & 0 & 2 & 0 & -6 & 0 & -1 & 1 & 0 & \boxed{3} \end{array} \right]$$

Example : Generalized Eigenvalue Criterion

$$\begin{cases} f_0 := 3x_0y_0z_0 + (-1)x_0y_0z_1 + (-4)x_0y_1z_0 + 2x_0y_1z_1 \\ \quad + 1x_1y_0z_0 + 2x_1y_0z_1 + 2x_1y_1z_0 + (-2)x_1y_1z_1 \\ f_1 := 7x_0y_0 + (-8)x_0y_1 + (-1)x_1y_0 + 2x_1y_1 \\ f_2 := (-5)x_0y_0 + 7x_0y_1 + (-1)x_1y_0 + (-1)x_1y_1 \\ f_3 := (-6)x_0z_0 + 9x_0z_1 + (-1)x_1z_0 + (-2)x_1z_1 \end{cases}$$

$$\left[\begin{array}{c|c} M_{1,1} & M_{1,2} \\ \hline M_{2,1} & M_{2,2} \end{array} \right] = \left[\begin{array}{cccccccc|cc} 0 & 0 & 0 & 5 & -7 & 1 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 7 & -8 & -1 & 2 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 & 0 & 0 & 0 & -1 & -5 & 7 \\ 7 & 0 & -1 & 0 & 0 & 0 & 0 & -1 & 0 & -5 \\ 0 & 1 & 0 & 0 & 0 & 0 & 0 & -2 & -7 & 8 \\ 8 & 0 & -2 & 0 & 0 & 0 & 0 & 1 & 0 & -7 \\ 0 & 2 & 0 & 9 & 0 & -2 & 0 & -2 & -1 & 2 \\ 2 & 0 & -2 & 0 & 9 & 0 & -2 & 2 & 0 & -1 \\ \hline 0 & 1 & 0 & -6 & 0 & -1 & 0 & 2 & 3 & -4 \\ -4 & 0 & 2 & 0 & -6 & 0 & -1 & 1 & 0 & 3 \end{array} \right]$$

$$\tilde{M}_{2,2} := \left(M_{2,2} - M_{2,1} \cdot M_{1,1}^{-1} \cdot M_{1,2} \right) = \begin{bmatrix} 5 & -2 \\ 4 & -1 \end{bmatrix}$$

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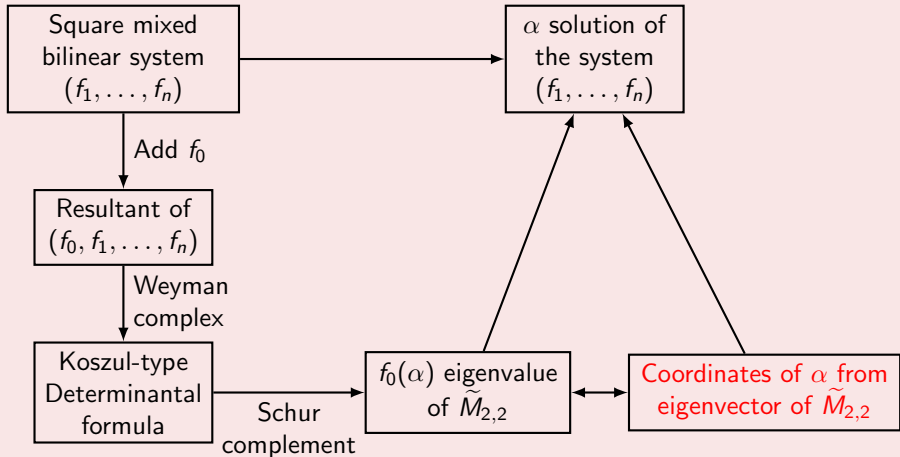
$$\tilde{M}_{2,2} := (M_{2,2} - M_{2,1} \cdot M_{1,1}^{-1} \cdot M_{1,2}) = \begin{bmatrix} 5 & -2 \\ 4 & -1 \end{bmatrix}$$

(f_1, f_2, f_3) has 2 solutions

$$\left. \begin{array}{l} (1:1; 1:1; 1:1) \\ (1:3; 1:2; 1:3) \end{array} \right\} \in \mathbb{P}^1 \times \mathbb{P}^1 \times \mathbb{P}^1$$

Eigenvalues of $\tilde{M}_{2,2}$

$$\begin{aligned} \frac{f_0}{x_0y_0z_0} ((1:1; 1:1; 1:1)) &= 3 \\ \frac{f_0}{x_0y_0z_0} ((1:3; 1:2; 1:3)) &= 1 \end{aligned}$$



$$\begin{bmatrix} M_{1,1} & M_{1,2} \\ M_{2,1} & M_{2,2} \end{bmatrix} \rightarrow \begin{bmatrix} M_{1,1} & M_{1,2} \\ 0 & \tilde{M}_{2,2} \end{bmatrix}$$

Example : Generalization of the eigenvector criterion

$$\frac{f_0}{x_0 y_0 z_0} ((\mathbf{1:3} ; \mathbf{1:2} ; 1:3)) = \mathbf{1} \quad \bar{\mathbf{v}} := \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

$$\begin{bmatrix} 5 & -2 \\ 4 & -1 \end{bmatrix} \cdot \bar{\mathbf{v}} = \mathbf{1} \cdot \bar{\mathbf{v}}$$

We can not recover $(\mathbf{1:3} ; \mathbf{1:2} ; 1:3)$ from $\begin{bmatrix} 1 \\ 2 \end{bmatrix}$.

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We can not recover $(\mathbf{1:3} ; \mathbf{1:2} ; 1:3)$ from $\begin{bmatrix} 1 \\ 2 \end{bmatrix}$.

We extend $\bar{\mathbf{v}} \rightarrow \mathbf{v}$ s.t.

$$\left[\begin{array}{c|c} M_{1,1} & M_{1,2} \\ \hline M_{2,1} & M_{2,2} \end{array} \right] \cdot \mathbf{v} = \frac{f_0}{\mathbf{m}}(\alpha) \cdot \left[\begin{array}{c} 0 \\ \bar{\mathbf{v}} \end{array} \right] \quad \begin{bmatrix} 1 \\ 2 \end{bmatrix} \rightarrow \begin{bmatrix} 4 = \mathbf{1 \cdot 2 \cdot 2} \\ 3 = \mathbf{3 \cdot 1 \cdot 1} \\ 12 = \mathbf{3 \cdot 2 \cdot 2} \\ 1 = \mathbf{1 \cdot 1 \cdot 1} \\ 2 = \mathbf{1 \cdot 1 \cdot 2} \\ 3 = \mathbf{3 \cdot 1} \\ 6 = \mathbf{3 \cdot 1 \cdot 2} \\ 6 = \mathbf{3 \cdot 2} \\ 1 = \mathbf{1 \cdot 1} \\ 2 = \mathbf{1 \cdot 2} \end{bmatrix}$$

$$\begin{cases} (\mathbf{1} \cdot \partial_{x_0} + \mathbf{3} \cdot \partial_{x_1}) \otimes (\mathbf{1} \cdot \mathbf{1} \cdot \partial_{y_0}^2 + \mathbf{1} \cdot \mathbf{2} \cdot \partial_{y_0} \partial_{y_1} + \mathbf{2} \cdot \mathbf{2} \cdot \partial_{y_1}^2) \otimes 1 \\ (\mathbf{1} \cdot \partial_{x_0} + \mathbf{3} \cdot \partial_{x_1}) \otimes (\mathbf{1} \cdot \partial_{y_0} + \mathbf{2} \cdot \partial_{y_1}) \otimes 1 \end{cases}$$

Solving Mixed Square Multilinear Systems

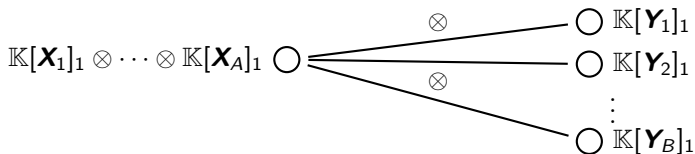
Let $(f_1, \dots, f_n) \in (\mathbb{K}[\mathbf{X}_1] \otimes \cdots \otimes \mathbb{K}[\mathbf{X}_A] \otimes \mathbb{K}[\mathbf{Y}_1] \otimes \cdots \otimes \mathbb{K}[\mathbf{Y}_B])^n$.

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- **Star multilinear system:** For every f_k , there is j_k such that

$$f_k \in \mathbb{K}[\mathbf{X}_1]_1 \otimes \dots \otimes \mathbb{K}[\mathbf{X}_A]_1 \otimes \mathbb{K}[\mathbf{Y}_{j_k}]_1.$$

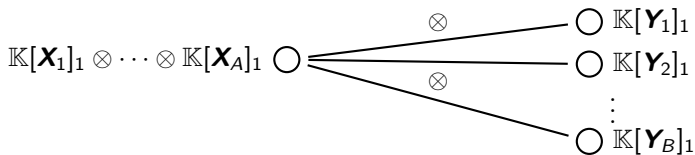


Solving Mixed Square Multilinear Systems

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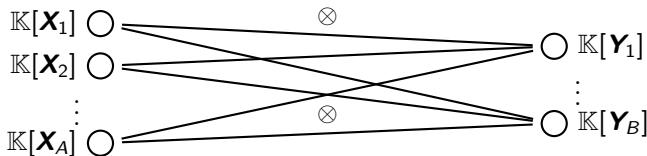
- **Star multilinear system:** For every f_k , there is j_k such that

$$f_k \in \mathbb{K}[\mathbf{X}_1]_1 \otimes \dots \otimes \mathbb{K}[\mathbf{X}_A]_1 \otimes \mathbb{K}[\mathbf{Y}_{j_k}]_1.$$



- **Bipartite bilinear system:** For every f_k , there are i_k and j_k such that

$$f_k \in \mathbb{K}[\mathbf{X}_{i_k}]_1 \otimes \mathbb{K}[\mathbf{Y}_{j_k}]_1.$$



Generalized Eigenvalue Problem

$$\left(\begin{bmatrix} -7 & -3 \\ -8 & -2 \end{bmatrix} - \lambda \begin{bmatrix} 12 & 2 \\ 13 & 1 \end{bmatrix} \right) \begin{bmatrix} v_0 \\ v_1 \end{bmatrix} = 0$$

Applications : Multiparameter Eigenvalue Problem

- Generalization of the Generalized Eigenvalue Problem

$$\left(\lambda_0 \begin{bmatrix} -7 & -3 \\ -8 & -2 \end{bmatrix} + \lambda_1 \begin{bmatrix} 12 & 2 \\ 13 & 1 \end{bmatrix} + \lambda_2 \begin{bmatrix} -7 & -1 \\ -7 & -1 \end{bmatrix} \right) \begin{bmatrix} v_0 \\ v_1 \end{bmatrix} = 0$$

$$\left(\lambda_0 \begin{bmatrix} -11 & -3 \\ 4 & 1 \end{bmatrix} + \lambda_1 \begin{bmatrix} 7 & -1 \\ 1 & 2 \end{bmatrix} + \lambda_2 \begin{bmatrix} -4 & 0 \\ -1 & -1 \end{bmatrix} \right) \begin{bmatrix} w_0 \\ w_1 \end{bmatrix} = 0$$

Applications : Multiparameter Eigenvalue Problem

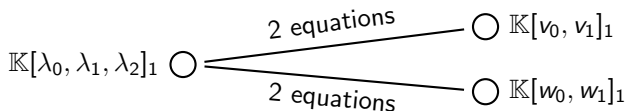
- Generalization of the Generalized Eigenvalue Problem
- Applications in physics (Sturm-Liouville theory)

$$\left(\lambda_0 \begin{bmatrix} -7 & -3 \\ -8 & -2 \end{bmatrix} + \lambda_1 \begin{bmatrix} 12 & 2 \\ 13 & 1 \end{bmatrix} + \lambda_2 \begin{bmatrix} -7 & -1 \\ -7 & -1 \end{bmatrix} \right) \begin{bmatrix} v_0 \\ v_1 \end{bmatrix} = 0$$

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Applications : Multiparameter Eigenvalue Problem

- Generalization of the Generalized Eigenvalue Problem
- Applications in physics (Sturm-Liouville theory)
- It is a square star multilinear system

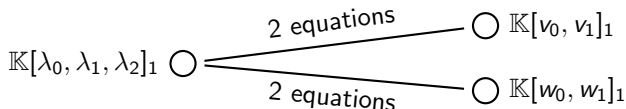


$$\left(\lambda_0 \begin{bmatrix} -7 & -3 \\ -8 & -2 \end{bmatrix} + \lambda_1 \begin{bmatrix} 12 & 2 \\ 13 & 1 \end{bmatrix} + \lambda_2 \begin{bmatrix} -7 & -1 \\ -7 & -1 \end{bmatrix} \right) \begin{bmatrix} v_0 \\ v_1 \end{bmatrix} = 0$$

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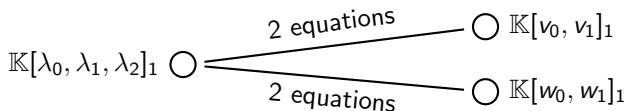


$$\begin{bmatrix} (-7\lambda_0 + 12\lambda_1 - 7\lambda_2) & (-3\lambda_0 + 2\lambda_1 - \lambda_2) \\ (-8\lambda_0 + 13\lambda_1 - 7\lambda_2) & (-2\lambda_0 + \lambda_1 - \lambda_2) \end{bmatrix} \cdot \begin{bmatrix} v_0 \\ v_1 \end{bmatrix} = 0$$

$$\begin{bmatrix} (-11\lambda_0 + 7\lambda_1 - 4\lambda_2) & (-3\lambda_0 - \lambda_1) \\ (4\lambda_0 + \lambda_1 - \lambda_2) & (\lambda_0 + 2\lambda_1 - \lambda_2) \end{bmatrix} \cdot \begin{bmatrix} w_0 \\ w_1 \end{bmatrix} = 0$$

Applications : Multiparameter Eigenvalue Problem

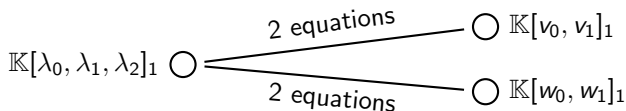
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$$\left\{ \begin{array}{l} (-7\lambda_0 + 12\lambda_1 - 7\lambda_2)v_0 + (-3\lambda_0 + 2\lambda_1 - \lambda_2)v_1 = 0 \\ (-8\lambda_0 + 13\lambda_1 - 7\lambda_2)v_0 + (-2\lambda_0 + \lambda_1 - \lambda_2)v_1 = 0 \\ (-11\lambda_0 + 7\lambda_1 - 4\lambda_2)w_0 + (-3\lambda_0 - \lambda_1)w_1 = 0 \\ (4\lambda_0 + \lambda_1 - \lambda_2)w_0 + (\lambda_0 + 2\lambda_1 - \lambda_2)w_1 = 0 \end{array} \right. .$$

Applications : Multiparameter Eigenvalue Problem

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$$\left\{ \begin{array}{l} f_1 := (-7\lambda_0 + 12\lambda_1 - 7\lambda_2)v_0 + (-3\lambda_0 + 2\lambda_1 - \lambda_2)v_1 \\ f_2 := (-8\lambda_0 + 13\lambda_1 - 7\lambda_2)v_0 + (-2\lambda_0 + \lambda_1 - \lambda_2)v_1 \\ f_3 := (-11\lambda_0 + 7\lambda_1 - 4\lambda_2)w_0 + (-3\lambda_0 - \lambda_1)w_1 \\ f_4 := (4\lambda_0 + \lambda_1 - \lambda_2)w_0 + (\lambda_0 + 2\lambda_1 - \lambda_2)w_1 \end{array} \right. .$$

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To solve, we add linear $f_0 := -\lambda_0 + 5\lambda_1 - 3\lambda_2 \in \mathbb{K}[\boldsymbol{\lambda}]_1$.

Weyman complex \rightarrow Sylvester-type formula

$$\delta : (\mathbb{K}[\mathbf{v}]_1 \otimes \mathbb{K}[\mathbf{w}]_1) \times (\mathbb{K}[\mathbf{w}]_1)^2 \times (\mathbb{K}[\mathbf{v}]_1)^2 \rightarrow (\mathbb{K}[\boldsymbol{\lambda}]_1 \otimes \mathbb{K}[\mathbf{v}]_1 \otimes \mathbb{K}[\mathbf{w}]_1)$$

$$\left(\quad g_0, \quad g_1, g_2 \quad g_3, g_4 \quad \right) \mapsto \sum_{i=0}^4 g_i f_i$$

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Weyman complex \rightarrow Sylvester-type formula

$$\delta : (\mathbb{K}[\mathbf{v}]_1 \otimes \mathbb{K}[\mathbf{w}]_1) \times (\mathbb{K}[\mathbf{w}]_1)^2 \times (\mathbb{K}[\mathbf{v}]_1)^2 \rightarrow (\mathbb{K}[\boldsymbol{\lambda}]_1 \otimes \mathbb{K}[\mathbf{v}]_1 \otimes \mathbb{K}[\mathbf{w}]_1)$$

$$\left(g_0, \quad g_1, g_2 \quad g_3, g_4 \right) \mapsto \sum_{i=0}^4 g_i f_i$$

Applications : Multiparameter Eigenvalue Problem

$$\begin{cases} f_1 := (-7\lambda_0 + 12\lambda_1 - 7\lambda_2) v_0 + (-3\lambda_0 + 2\lambda_1 - \lambda_2) v_1 \\ f_2 := (-8\lambda_0 + 13\lambda_1 - 7\lambda_2) v_0 + (-2\lambda_0 + \lambda_1 - \lambda_2) v_1 \\ f_3 := (-11\lambda_0 + 7\lambda_1 - 4\lambda_2) w_0 + (-3\lambda_0 - \lambda_1) w_1 \\ f_4 := (4\lambda_0 + \lambda_1 - \lambda_2) w_0 + (\lambda_0 + 2\lambda_1 - \lambda_2) w_1 \end{cases}$$

To solve, we add linear $f_0 := -\lambda_0 + 5\lambda_1 - 3\lambda_2 \in \mathbb{K}[\boldsymbol{\lambda}]_1$.

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$w_0 f_1$	-7	-1	12	2	-7	-3	
$w_1 f_1$		-7	-1	12	2	-7	-3
$w_0 f_2$	-7	-1	13	1	-8	-2	
$w_1 f_2$		-7	-1	13	1	-8	-2
$v_0 f_3$	-4		7	-1	-11	-3	
$v_1 f_3$		-4		7	-1	-11	-3
$v_0 f_4$	-1	-1	1	2	4	1	
$v_1 f_4$		-1	-1	1	2	4	1
$v_0 w_0 f_0$	-3		5		-1		
$v_0 w_1 f_0$		-3		5	-1		
$v_1 w_0 f_0$			-3		5	-1	
$v_1 w_1 f_0$				-3		5	

Tools

- Weyman complex \rightarrow Determinantal formula
- Sylvester- and Koszul-type formulas
- Eigenvalues/Eigenvectors
(Evaluation of the solutions/coordinates of the solutions)

Results

- Sylvester- and Koszul-type determinantal formula for the resultant
- Extension of the Eigenvalue and Eigenvector criteria
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Questions

- Can we exploit structure of Koszul-type formulas?
- What can we say numerically?

Summing-up

Tools

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Thank you!