

Backstepping methods

Sunday, December 17, 2017 2:00 PM (30 minutes)

The use of linear Volterra operators in constructing backstepping transformations and feedback laws for stabilization of PDE systems by boundary control will be reviewed. Basic PDEs of both parabolic and hyperbolic types will be covered. With time permitting, an example of backstepping in observer design with boundary sensing will be covered.

Primary author: Mr KRSTIC, Miroslav (Department of Mechanical & Aero. Eng. University of California)

Presenter: Mr KRSTIC, Miroslav (Department of Mechanical & Aero. Eng. University of California)