ALGEBRAIC GEOMETRY, THEORY OF SINGULARITIES, AND CONVEX GEOMETRY

Conference "Singular Landscapes"
Aussois, France

Askold Khovanskii

Department of Mathematics, University of Toronto

June 22, 2015



I will talk about some interactions between these areas of mathematics.

I will talk about some interactions between these areas of mathematics.

Newton polyhedra connect algebraic geometry and the theory of singularities to the geometry of convex polyhedra with integral vertices in the framework of toric geometry.

I will talk about some interactions between these areas of mathematics.

Newton polyhedra connect algebraic geometry and the theory of singularities to the geometry of convex polyhedra with integral vertices in the framework of toric geometry.

The **theory of Newton-Okounkov bodies** relates algebra, singularities and geometry of convex bodies outside of that framework.

I will talk about some interactions between these areas of mathematics.

Newton polyhedra connect algebraic geometry and the theory of singularities to the geometry of convex polyhedra with integral vertices in the framework of toric geometry.

The **theory of Newton-Okounkov bodies** relates algebra, singularities and geometry of convex bodies outside of that framework.

There is also an intermediate version of these theories. It provides such a relation in the framework of **spherical varieties**.



Newton polyhedra

A **Laurent polynomial** P is a linear combination of monomials. The **support** s(P) is the set of the powers of the monomials in P. The **Newton polyhedron** $\Delta(P)$ is the convex hull of s(P).

Newton polyhedra

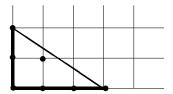
A **Laurent polynomial** P is a linear combination of monomials. The **support** s(P) is the set of the powers of the monomials in P. The **Newton polyhedron** $\Delta(P)$ is the convex hull of s(P). **Example**. Let P be $y^2 + a_0 + a_1x + a_2x^2 + a_3x^3$, where $a_0 \neq 0$, $a_1 \neq 0$, $a_2 \neq 0$, $a_3 \neq 0$. Then $\Delta(P)$ is



and
$$s(P) = \{(0,0), (0,1), (0,2), (0,3), (2,0)\}.$$

Newton polyhedra

A **Laurent polynomial** P is a linear combination of monomials. The **support** s(P) is the set of the powers of the monomials in P. The **Newton polyhedron** $\Delta(P)$ is the convex hull of s(P). **Example**. Let P be $y^2 + a_0 + a_1x + a_2x^2 + a_3x^3$, where $a_0 \neq 0$, $a_1 \neq 0$, $a_2 \neq 0$, $a_3 \neq 0$. Then $\Delta(P)$ is



and
$$s(P) = \{(0,0), (0,1), (0,2), (0,3), (2,0)\}.$$

Discrete invariants of $X \subset (\mathbb{C}^*)^n$ defined by a generic system of equations $P_1(x) = \cdots = P_k = 0$ with fixed support $s(P_i)$ depend only on Newton polyhedra $\Delta(P_1), \ldots, \Delta(P_k)$ of P_1, \ldots, P_k .

Example 1 (Kh). The **genus** g(X) is equal to the number $B(\Delta)$ of integral points in the interior of $\Delta = \Delta(P)$.

Example 1 (Kh). The **genus** g(X) is equal to the number $B(\Delta)$ of integral points in the interior of $\Delta = \Delta(P)$.

Example 2 (Kh). Let $\bar{X} = X \bigcup A(X)$ be a **smooth compact model of** X**. Then** #A(X) equals to the number of integral points in the boundary of Δ .

Example 1 (Kh). The **genus** g(X) is equal to the number $B(\Delta)$ of integral points in the interior of $\Delta = \Delta(P)$.

Example 2 (Kh). Let $\bar{X} = X \bigcup A(X)$ be a **smooth compact model of** X**. Then** #A(X) equals to the number of integral points in the boundary of Δ .

Example 3 (D.Berstein, Kh). The **Euler characteristic** $\chi(X)$ of X is equal to the volume $V(\Delta)$ of Δ multiplied by -2!

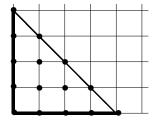
Example 1 (Kh). The **genus** g(X) is equal to the number $B(\Delta)$ of integral points in the interior of $\Delta = \Delta(P)$.

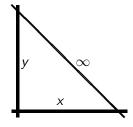
Example 2 (Kh). Let $\bar{X} = X \bigcup A(X)$ be a **smooth compact model of** X**. Then** #A(X) equals to the number of integral points in the boundary of Δ .

Example 3 (D.Berstein, Kh). The **Euler characteristic** $\chi(X)$ of X is equal to the volume $V(\Delta)$ of Δ multiplied by -2!

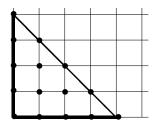
Toy geometric application. The invariants 1)-3) are related: $\chi(\bar{X}) = \chi(X) + \#A(X) = 2 - 2g(X)$. It implies the **Pick formula** for an integral polygon Δ : $V(\Delta) = \#((\Delta \setminus \partial \Delta) \cap \mathbb{Z}^2) + 1/2 \# \partial (\Delta \cap \mathbb{Z}^2) - 1$.

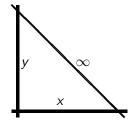
Toric varieties and the combinatorics of polyhedra





Toric varieties and the combinatorics of polyhedra





Toric variety is a normal connected n-dimensional algebraic variety M on which an $(\mathbb{C}^*)^n$ acts algebraically and has one orbit isomorphic to $(\mathbb{C}^*)^n$. Under the action of $(\mathbb{C}^*)^n$, M is broken up into a finite number of orbits isomorphic to tori of different dimensions. To every Newton polyhedron Δ we can associate a compact projective toric variety M_Δ in such a way that every k-dimensional face $\Gamma \subset \Delta$ corresponds to a complex k-dimensional orbit $O_\Gamma \subset M_\Delta$. If $\Gamma_1 \subset \Gamma_2$ then $O_{\Gamma_1} \subset \bar{O}_{\Gamma_2}$.

Simple polyhedra and quasismooth toric varieties

A polyhedron is **simple** if it is an intersection of half-spaces in general position. An n-dimensional simple polyhedron about each vertex has the same structure as the positive orthant in \mathbb{R}^n near the origin. In particular, each vertex of a simple n-dimensional polyhedron is incident with n edges, and any k of these edges belong to one k-dimensional face containing the vertex.

Simple polyhedra and quasismooth toric varieties

A polyhedron is **simple** if it is an intersection of half-spaces in general position. An n-dimensional simple polyhedron about each vertex has the same structure as the positive orthant in \mathbb{R}^n near the origin. In particular, each vertex of a simple n-dimensional polyhedron is incident with n edges, and any k of these edges belong to one k-dimensional face containing the vertex.

The F-vector of a simple n-dimensional polyhedron is the vector (F_0, \ldots, F_n) where F_k is the number of k-dimensional faces of the polyhedron. The necessary and sufficient conditions for a vector to be F-vector of a simple n-dimensional polyhedron were conjectured by McMullen.

Simple polyhedra and quasismooth toric varieties

A polyhedron is **simple** if it is an intersection of half-spaces in general position. An n-dimensional simple polyhedron about each vertex has the same structure as the positive orthant in \mathbb{R}^n near the origin. In particular, each vertex of a simple n-dimensional polyhedron is incident with n edges, and any k of these edges belong to one k-dimensional face containing the vertex.

The F-vector of a simple n-dimensional polyhedron is the vector (F_0, \ldots, F_n) where F_k is the number of k-dimensional faces of the polyhedron. The necessary and sufficient conditions for a vector to be F-vector of a simple n-dimensional polyhedron were conjectured by McMullen.

Simple polyhedra correspond to **guasismooth toric varieties**. Using topology and algebraic geometry of such varieties *Stanley*, *Billera* and *Lee* proved McMullen's conjecture.

Theorem (Nikulin). The average number of I-dimensional faces of a k-dimensional face of a simple n-dimensional polyhedron for $0 \le l < k \le (n+1)/2$ is $\le f(l,k,n)$ where f is an explicit function. If $n \to \infty$, f tends to the number of I-dimensional faces of a k-dimensional cube.

Theorem (Nikulin). The average number of I-dimensional faces of a k-dimensional face of a simple n-dimensional polyhedron for $0 \le l < k \le (n+1)/2$ is $\le f(l,k,n)$ where f is an explicit function. If $n \to \infty$, f tends to the number of I-dimensional faces of a k-dimensional cube.

Theorem (Vinberg). In a Lobachevsky space of dimension > 32 there are no discrete groups generated by reflections with a compact fundamental polyhedron.

Theorem (Nikulin). The average number of I-dimensional faces of a k-dimensional face of a simple n-dimensional polyhedron for $0 \le l < k \le (n+1)/2$ is $\le f(l,k,n)$ where f is an explicit function. If $n \to \infty$, f tends to the number of I-dimensional faces of a k-dimensional cube.

Theorem (Vinberg). In a Lobachevsky space of dimension > 32 there are no discrete groups generated by reflections with a compact fundamental polyhedron.

Theorem (Kh). The bound in Nikulin's Theorem is valid not only for simple polyhedra, but also for edge simple polyhedra.

Theorem (*Nikulin*). The average number of *I*-dimensional faces of a *k*-dimensional face of a simple n-dimensional polyhedron for $0 \le l < k \le (n+1)/2$ is $\le f(l,k,n)$ where f is an explicit function. If $n \to \infty$, f tends to the number of l-dimensional faces of a k-dimensional cube.

Theorem (*Vinberg*). In a Lobachevsky space of dimension > 32 there are no discrete groups generated by reflections with a compact fundamental polyhedron.

Theorem (Kh). The bound in Nikulin's Theorem is valid not only for simple polyhedra, but also for edge simple polyhedra.

Theorem (*Prokhorov*, *Kh*). In a Lobachevsky space of dimension > 995 there are no discrete groups generated by reflections with a fundamental polyhedron of finite volume.

Denote by L_{A_i} be the space generated x^m , where $m \in A_i$. Denote by Δ_i the convex hull of A_i . **How many solutions in** $(\mathbb{C}^*)^n$ has a system of equations $P_1 = \cdots = P_n = 0$ where $P_1 \in L_{A_1}, \ldots, P_n \in L_{A_n}$ is a generic n-tuple of functions?

Denote by L_{A_i} be the space generated x^m , where $m \in A_i$. Denote by Δ_i the convex hull of A_i .

How many solutions in $(\mathbb{C}^*)^n$ has a system of equations $P_1 = \cdots = P_n = 0$ where $P_1 \in L_{A_1}, \ldots, P_n \in L_{A_n}$ is a generic n-tuple of functions?

Theorem (Kouchnirenko). If $A_1 = \cdots = A_n = A$ then the number of solutions of the system is equal to the volume $V(\Delta)$ of $\Delta = \Delta_1 = \cdots = \Delta_n$ multiplied by n!

Denote by L_{A_i} be the space generated x^m , where $m \in A_i$. Denote by Δ_i the convex hull of A_i .

How many solutions in $(\mathbb{C}^*)^n$ has a system of equations $P_1 = \cdots = P_n = 0$ where $P_1 \in L_{A_1}, \ldots, P_n \in L_{A_n}$ is a generic n-tuple of functions?

Theorem (Kouchnirenko). If $A_1 = \cdots = A_n = A$ then the number of solutions of the system is equal to the volume $V(\Delta)$ of $\Delta = \Delta_1 = \cdots = \Delta_n$ multiplied by n!

Theorem (Bernstein) (also known as BKK theorem). The number of solutions of the system is equal to the mixed volume $V(\Delta_1, \ldots, \Delta_n)$ of $\Delta_1, \ldots, \Delta_n$ multiplied ny n!



Mixed volume is a unique function $V(\Delta_1, ..., \Delta_n)$ on n-tuples of convex bodies in $\Delta_i \subset \mathbb{R}^n$, such that:

- $V(\Delta,...,\Delta)$ is the volume of Δ ;
- V is symmetric;
- lacksquare V is multi-linear; for example, $V(\Delta_1'+\Delta_1'',\Delta_2,\dots)=V(\Delta_1',\Delta_2,\dots)+V(\Delta_1'',\Delta_2,\dots);$

Mixed volume is a unique function $V(\Delta_1, ..., \Delta_n)$ on n-tuples of convex bodies in $\Delta_i \subset \mathbb{R}^n$, such that:

- $V(\Delta,...,\Delta)$ is the volume of Δ ;
- V is symmetric;
- $lackbox{ V is multi-linear; for example,} V(\Delta_1'+\Delta_1'',\Delta_2,\dots)=V(\Delta_1',\Delta_2,\dots)+V(\Delta_1'',\Delta_2,\dots);$

Mixed volume has the following properties:

Mixed volume is a unique function $V(\Delta_1, ..., \Delta_n)$ on n-tuples of convex bodies in $\Delta_i \subset \mathbb{R}^n$, such that:

- $V(\Delta,...,\Delta)$ is the volume of Δ ;
- V is symmetric;
- lacksquare V is multi-linear; for example, $V(\Delta_1' + \Delta_1'', \Delta_2, \dots) = V(\Delta_1', \Delta_2, \dots) + V(\Delta_1'', \Delta_2, \dots);$

Mixed volume has the following properties:

- **4** V is nonnegative, i.e. $0 \le V(\Delta_1, \ldots, \Delta_n)$;
- $\bullet \Delta_1' \subseteq \Delta_1, \ldots, \Delta_n' \subseteq \Delta_n \Rightarrow V(\Delta_1', \ldots, \Delta_n') \leq V(\Delta_1, \ldots, \Delta_n);$
- The following **Alexandrov–Fenchel inequality** holds: $V^2(\Delta_1, \Delta_2, \dots, \Delta_n) \ge V(\Delta_1, \Delta_1, \dots, \Delta_n)V(\Delta_2, \Delta_2, \dots, \Delta_n);$
- o in particular (for n=2, the unite ball Δ_1 and for $\Delta=\Delta_2$) the isoperimetric inequality $(\frac{1}{2}$ length of $\partial\Delta)^2 \geq \pi V(\Delta)$ holds.



Let K(X) be the **semigroup of spaces** L of rational functions on X such that: a) dim $L < \infty$, and b) $L \neq 0$. For $L_1, L_2 \in K(X)$, the **product** is the space $L_1L_2 \in K(X)$ generated by elements fg, where $f \in L_1$, $g \in L_2$.

Let K(X) be the **semigroup of spaces** L of rational functions on X such that: a) dim $L < \infty$, and b) $L \neq 0$. For $L_1, L_2 \in K(X)$, the **product** is the space $L_1L_2 \in K(X)$ generated by elements $f_{\mathcal{B}}$, where $f \in L_1$, $g \in L_2$.

If dim X=n then for $L_1,\ldots,L_n\in K(X)$ the **intersection index** $[L_1,\ldots,L_n]$ is defined as $\#X|x\in X\Leftrightarrow (f_1(x)=\cdots=f_n(x)=0)$, where $f_1\in L_1,\ldots,f_n\in L_n$ is a generic n-tuple of functions. We neglect roots $x\in X$ such that $\exists i:(f\in L_i\Rightarrow f(x)=0)$, and such that $\exists f\in L_j$ for $1\leq j\leq n$ having a pole at x.

Let K(X) be the **semigroup of spaces** L of rational functions on X such that: a) dim $L < \infty$, and b) $L \neq 0$. For $L_1, L_2 \in K(X)$, the **product** is the space $L_1L_2 \in K(X)$ generated by elements fg, where $f \in L_1$, $g \in L_2$.

If dim X=n then for $L_1,\ldots,L_n\in K(X)$ the **intersection index** $[L_1,\ldots,L_n]$ is defined as $\#X|x\in X\Leftrightarrow (f_1(x)=\cdots=f_n(x)=0),$ where $f_1\in L_1,\ldots,f_n\in L_n$ is a generic n-tuple of functions. We neglect roots $x\in X$ such that $\exists i:(f\in L_i\Rightarrow f(x)=0),$ and such that $\exists f\in L_j$ for $1\leq j\leq n$ having a pole at x.

The intersection index is well-defined. It is multi-linear with respect to the product in K(X).

Let K(X) be the **semigroup of spaces** L of rational functions on X such that: a) dim $L < \infty$, and b) $L \neq 0$.

For $L_1, L_2 \in K(X)$, the **product** is the space $L_1L_2 \in K(X)$ generated by elements fg, where $f \in L_1$, $g \in L_2$.

If dim X=n then for $L_1,\ldots,L_n\in K(X)$ the **intersection index** $[L_1,\ldots,L_n]$ is defined as $\#X|x\in X\Leftrightarrow (f_1(x)=\cdots=f_n(x)=0),$ where $f_1\in L_1,\ldots,f_n\in L_n$ is a generic n-tuple of functions. We neglect roots $x\in X$ such that $\exists i:(f\in L_i\Rightarrow f(x)=0),$ and such that $\exists f\in L_i$ for $1\leq j\leq n$ having a pole at x.

The intersection index is well-defined.

It is **multi-linear** with respect to the product in K(X).

BKK theorem computes the intersection index for $X = (\mathbb{C}^*)^n$ and for an *n*-tuple of spaces generated by monomials.

Grothendieck semigroup and group

For a commutative semigroup S consider the following equivalence relation:

$$a \sim b \Leftrightarrow (\exists c \in S) | (a + c = b + c).$$

The **Grothendieck semigroup** $Gr_s(S)$ of S is S modulo the equivalents relation \sim .

Grothendieck semigroup and group

For a commutative semigroup S consider the following equivalence relation:

$$a \sim b \Leftrightarrow (\exists c \in S) | (a + c = b + c).$$

The **Grothendieck semigroup** $Gr_s(S)$ of S is S modulo the equivalents relation \sim .

The **Grothendieck group** Gr(S) of S is the group of formal differences of $Gr_s(S)$. Let $\rho: S \to Gr_s(S)$ be the natural map.

Grothendieck semigroup and group

For a commutative semigroup *S* consider the following equivalence relation:

$$a \sim b \Leftrightarrow (\exists c \in S) | (a + c = b + c).$$

The **Grothendieck semigroup** $Gr_s(S)$ of S is S modulo the equivalents relation \sim .

The **Grothendieck group** Gr(S) of S is the group of formal differences of $Gr_s(S)$. Let $\rho: S \to Gr_s(S)$ be the natural map.

Theorem (Kh). Let K be the semigroup of finite subsets $\mathbb{Z}^n \subset \mathbb{R}^n$ with respect to addition. Then $Gr_s(K)$ is the semigroup of convex integral polyhedra in \mathbb{R}^n and $\rho(A)$ is the convex hull $\Delta(A)$ of A.

We need the following algebraic analog of this theorem.



The Grothendieck semigroup $Gr_s(K(X))$ of K(X)

A function $f \in \mathbb{C}(X)$ is **integral over** $L \in K(X)$ if it satisfies an equation $f^m + a_1 f^{m-1} + \cdots + a_m = 0$ with m > 0 and $a_i \in L^i$.

The **completion** \overline{L} **of** $L \in K(X)$ is the set of all functions integral over L. The **set** \overline{L} **is a finite-dimensional space**, so $\overline{L} \in K(X)$.

The Grothendieck semigroup $Gr_s(K(X))$ of K(X)

A function $f \in \mathbb{C}(X)$ is **integral over** $L \in K(X)$ if it satisfies an equation $f^m + a_1 f^{m-1} + \cdots + a_m = 0$ with m > 0 and $a_i \in L^i$.

The **completion** \overline{L} **of** $L \in K(X)$ is the set of all functions integral over L. The **set** \overline{L} **is a finite-dimensional space**, so $\overline{L} \in K(X)$.

The completion and the equivalence \sim in K(X) are related:

The Grothendieck semigroup $Gr_s(K(X))$ of K(X)

A function $f \in \mathbb{C}(X)$ is **integral over** $L \in K(X)$ if it satisfies an equation $f^m + a_1 f^{m-1} + \cdots + a_m = 0$ with m > 0 and $a_i \in L^i$.

The **completion** \overline{L} **of** $L \in K(X)$ is the set of all functions integral over L. The **set** \overline{L} **is a finite-dimensional space**, so $\overline{L} \in K(X)$.

The completion and the equivalence \sim in K(X) are related:

- $2 L \sim \overline{L}.$

The index $[L_1, \ldots, L_n]$ can be extended to the Grothendieck group Gr(K(X)) of K(X) and can be considered as

a birationally invariant version of the intersection index of divisors, which is applicable to non-complete varieties.



Regularization of a semigroup of integral points

For a **semigroup** $S \subset \mathbb{Z}^n$ **of integral points** let:

- 1) $G(S) \subset \mathbb{Z}^n$ be the group generated by S;
- 2) $L(S) \subset \mathbb{R}^n$ be the subspace spanned by S;
- 3) C(S) be the closure of the convex spanned by S.

Regularization of a semigroup of integral points

For a **semigroup** $S \subset \mathbb{Z}^n$ **of integral points** let:

- 1) $G(S) \subset \mathbb{Z}^n$ be the group generated by S;
- 2) $L(S) \subset \mathbb{R}^n$ be the subspace spanned by S;
- 3) C(S) be the closure of the convex spanned by S.

The **regularization** \tilde{S} of S is the semigroup $C(S) \cap G(S)$.

Regularization of a semigroup of integral points

For a **semigroup** $S \subset \mathbb{Z}^n$ **of integral points** let:

- 1) $G(S) \subset \mathbb{Z}^n$ be the group generated by S;
- 2) $L(S) \subset \mathbb{R}^n$ be the subspace spanned by S;
- 3) C(S) be the closure of the convex spanned by S.

The **regularization** \tilde{S} of S is the semigroup $C(S) \cap G(S)$.

Theorem (Kaveh, Kh) Let $C' \subset C(S)$ be a strongly convex cone which intersects the boundary (in the topology of the linear space L(S)) of the cone C(S) only at the origin. Then there exists a constant N > 0 (depending on C') such that any point in the group G(S) which lies in C' and whose distance from the origin is bigger than N belongs to S.

Semigroup of integral points and its NO body

Let M by a hyperplane in L(S). Let M_k be the affine space parallel to M and intersecting G(S) and C(S) which has distance k from the origin (the distance is normalized in such a way that as values it takes all the non-negative integers k).

The Hilbert function H_S of the semigroup S in the codirection M is defined by $H_S(k) = \# M_k \cap S$.

The Newton–Okounkov body (NO body) of the semigroup S in the codirection M is defined by $\Delta(S, M) = C(S) \cap M_1$.

Semigroup of integral points and its NO body

Let M by a hyperplane in L(S). Let M_k be the affine space parallel to M and intersecting G(S) and C(S) which has distance k from the origin (the distance is normalized in such a way that as values it takes all the non-negative integers k).

The Hilbert function H_S of the semigroup S in the codirection M is defined by $H_S(k) = \# M_k \cap S$.

The Newton–Okounkov body (NO body) of the semigroup S in the codirection M is defined by $\Delta(S, M) = C(S) \cap M_1$.

Theorem (Kaveh, Kh) The function $H_S(k)$ grows like $a_q k^q$ where q is the dimension of the convex body $\Delta(S)$, and the q-th growth coefficient a_q is equal to the (normalized in the appropriate way) q-dimensional volume of $\Delta(S)$.

Algebra of almost finite type, its NO body (begging)

Let F be a field of transcendence degree n over \mathbf{k} . We deal with the following kinds of graded subalgebras in the algebra F[t]:

- ① With any subspace $L \subset F$ over \mathbf{k} of finite dimension one associates the **algebra** $A_L = \bigoplus_{k \geq 0} L^k t^k$, where $L^0 = \mathbf{k}$ and L^k is the span of all the products $f_1 \cdots f_k$ with $f_1, \ldots, f_k \in L$.
- ② An algebra of almost finite type is a graded subalgebra in some algebra A_I .

Algebra of almost finite type, its NO body (begging)

Let F be a field of transcendence degree n over \mathbf{k} . We deal with the following kinds of graded subalgebras in the algebra F[t]:

- ① With any subspace $L \subset F$ over \mathbf{k} of finite dimension one associates the **algebra** $A_L = \bigoplus_{k \geq 0} L^k t^k$, where $L^0 = \mathbf{k}$ and L^k is the span of all the products $f_1 \cdots f_k$ with $f_1, \ldots, f_k \in L$.
- ② An algebra of almost finite type is a graded subalgebra in some algebra A_I .

One can construct a \mathbb{Z}^{n+1} -valued valuation v_t on F[t] by extending a \mathbb{Z}^n -valuation v on F which takes all the values in \mathbb{Z}^n .

The **NO** body of algebra A of almost finite type is the NO body of the semigroup $S(A) = v_t(A \setminus \{0\})$ projected to the first factor $\mathbb{R}^n \times \mathbb{R} \to \mathbb{R}^n$.



Algebra and its NO body (continuation)

Theorem (Kaveh, Kh). The Hilbert function $H_A(k)$ of an algebra A of almost finite type grows like $a_q k^q$, where $q = \dim_{\mathbb{R}} \Delta(A)$ and a_q is the (normalized) q-dimensional volume of $\Delta(A)$.

Algebra and its NO body (continuation)

Theorem (Kaveh, Kh). The Hilbert function $H_A(k)$ of an algebra A of almost finite type grows like $a_q k^q$, where $q = \dim_{\mathbb{R}} \Delta(A)$ and a_q is the (normalized) q-dimensional volume of $\Delta(A)$.

One defines a componentwise product of graded subalgebras. Consider the class of graded algebras of almost finite type such that, for $k\gg 0$, all their k-th homogeneous components are non-zero. Let A_1 , A_2 be algebras of such kind and put $A_3=A_1A_2$. It is easy to verify the inclusion $\Delta(A_1)+\Delta(A_2)\subset\Delta(A_3)$.

Algebra and its NO body (continuation)

Theorem (Kaveh, Kh). The Hilbert function $H_A(k)$ of an algebra A of almost finite type grows like $a_q k^q$, where $q = \dim_{\mathbb{R}} \Delta(A)$ and a_q is the (normalized) q-dimensional volume of $\Delta(A)$.

One defines a componentwise product of graded subalgebras. Consider the class of graded algebras of almost finite type such that, for $k\gg 0$, all their k-th homogeneous components are non-zero. Let A_1 , A_2 be algebras of such kind and put $A_3=A_1A_2$. It is easy to verify the inclusion $\Delta(A_1)+\Delta(A_2)\subset\Delta(A_3)$.

Brunn–Minkowsky inequality in convex geometry $V^{1/n}(\Delta_1) + V^{1/n}(\Delta_2) \leq V^{1/n}(\Delta_1 + \Delta_2)$.

Theorem (*Kaveh*, *Kh*).
$$a_n^{1/n}(A_1) + a_n^{1/n}(A_2) \le a_n^{1/n}(A_3)$$
.



With a space $L \in K(X)$ we associate the NO body $\Delta(\overline{A_L})$ of the integral closure $\overline{A_L}$ of the algebra A_L .

With a space $L \in K(X)$ we associate the NO body $\Delta(\overline{A_L})$ of the integral closure $\overline{A_L}$ of the algebra A_L .

Theorem (*Kaveh*, *Kh*). For $L \in K(X)$ we have:

- 1. $[L, \ldots, L] = n! \operatorname{Vol}(\Delta(\overline{A_L}));$
- 2. $\Delta(\overline{A_{L_1L_2}}) \supseteq \Delta(\overline{A_{L_1}}) + \Delta(\overline{A_{L_2}}).$

With a space $L \in K(X)$ we associate the NO body $\Delta(\overline{A_L})$ of the integral closure $\overline{A_L}$ of the algebra A_L .

Theorem (Kaveh, Kh). For $L \in K(X)$ we have:

- 1. $[L, \underline{\ldots}, L] = n! \text{Vol}(\Delta(\overline{A_L}));$
- 2. $\Delta(\overline{A_{L_1L_2}}) \supseteq \Delta(\overline{A_{L_1}}) + \Delta(\overline{A_{L_2}}).$

The Kušnirenko theorem is a special case of this theorem.

The BBK theorem also follows for it because

for any couple of Laurent polynomials P_1, P_2 the relation $\Delta(P_1P_2) = \Delta(P_1) + \Delta(P_2)$ holds.

With a space $L \in K(X)$ we associate the NO body $\Delta(A_L)$ of the integral closure $\overline{A_L}$ of the algebra A_L .

Theorem (Kaveh, Kh). For $L \in K(X)$ we have:

- 1. $[L, \ldots, L] = n! \operatorname{Vol}(\Delta(\overline{A_L}));$
- 2. $\Delta(\overline{A_{L_1L_2}}) \supseteq \Delta(\overline{A_{L_1}}) + \Delta(\overline{A_{L_2}})$.

The Kušnirenko theorem is a special case of this theorem.

The BBK theorem also follows for it because

for any couple of Laurent polynomials P_1, P_2 the relation $\Delta(P_1P_2) = \Delta(P_1) + \Delta(P_2)$ holds.

Theorem (Kaveh, Kh). Let $L_1, L_2 \in K(X)$ and $L_3 = L_1L_2$.

- 1. $[L_1, \ldots, L_1]^{1/n} + [L_2, \ldots, L_2]^{1/n} \leq [L_3, \ldots, L_3]^{1/n}$.
- 2. Hodge type inequality. For n = 2 we have $[L_1, L_1][L_2, L_2] \le [L_1, L_2]^2$.

Alexandrov–Fenchel inequality in convex geometry claims that $V^2(\Delta_1, \Delta_2, \dots, \Delta_n) \geq V(\Delta_1, \Delta_1, \dots, \Delta_n) V(\Delta_2, \Delta_2, \dots, \Delta_n)$.

Alexandrov–Fenchel inequality in convex geometry claims that $V^2(\Delta_1, \Delta_2, \dots, \Delta_n) \geq V(\Delta_1, \Delta_1, \dots, \Delta_n) V(\Delta_2, \Delta_2, \dots, \Delta_n)$.

Let X, dim X = n, be an irreducible variety, let $L_1, \ldots, L_n \in K(X)$. **Theorem** (Kaveh, Kh). If L_3, \ldots, L_n are big subspaces then $[L_1, L_2, L_3, \ldots, L_n]^2 \geq [L_1, L_1, L_3, \ldots, L_n][L_2, L_2, L_3, \ldots, L_n]$.

Alexandrov–Fenchel inequality in convex geometry claims that $V^2(\Delta_1, \Delta_2, \dots, \Delta_n) \geq V(\Delta_1, \Delta_1, \dots, \Delta_n) V(\Delta_2, \Delta_2, \dots, \Delta_n)$.

Let X, dim X = n, be an irreducible variety, let $L_1, \ldots, L_n \in K(X)$. **Theorem** (Kaveh, Kh). If L_3, \ldots, L_n are big subspaces then $[L_1, L_2, L_3, \ldots, L_n]^2 \geq [L_1, L_1, L_3, \ldots, L_n][L_2, L_2, L_3, \ldots, L_n]$.

An older version of this theorem dealing with the intersection theory of divisors due to **Bernard Teissier** and me.

Alexandrov–Fenchel inequality in convex geometry claims that $V^2(\Delta_1, \Delta_2, \dots, \Delta_n) \geq V(\Delta_1, \Delta_1, \dots, \Delta_n) V(\Delta_2, \Delta_2, \dots, \Delta_n)$.

Let X, dim X = n, be an irreducible variety, let $L_1, \ldots, L_n \in K(X)$. **Theorem** (Kaveh, Kh). If L_3, \ldots, L_n are big subspaces then $[L_1, L_2, L_3, \ldots, L_n]^2 \ge [L_1, L_1, L_3, \ldots, L_n][L_2, L_2, L_3, \ldots, L_n]$.

An older version of this theorem dealing with the intersection theory of divisors due to **Bernard Teissier** and me.

The Alexandrov–Fenchel inequality in convex geometry follows easily from this theorem via the BKK theorem. This trick has been known. Our elementary proof of the key analogue of the Hodge index inequality which makes all the chain of arguments involved elementary and more natural.



Other results (begginng)

1. Let \mathbf{K}_a be the set of primary ideals of the ring of regular functions at $\mathbf{a} \in X$, $\dim X = n$. The local intersection index $[L_1, \ldots, L_n]_a$ for $L_i \in \mathbf{K}_a$ is equal to the multiplicity at \mathbf{a} of a system $f_1 = \cdots = f_n = 0$, where f_i is a generic function from L_i . A version of Teissier inequality for mixed multiplicities $[L_1, L_2, \ldots, L_n]_a^2 \leq [L_1, L_1, \ldots, L_n]_a[L_2, L_2, \ldots, L_n]_a$.

Other results (begginng)

- 1. Let \mathbf{K}_a be the set of primary ideals of the ring of regular functions at $\mathbf{a} \in X$, $\dim X = n$. The local intersection index $[L_1, \ldots, L_n]_a$ for $L_i \in \mathbf{K}_a$ is equal to the multiplicity at \mathbf{a} of a system $f_1 = \cdots = f_n = 0$, where f_i is a generic function from L_i . A version of Teissier inequality for mixed multiplicities $[L_1, L_2, \ldots, L_n]_a^2 \leq [L_1, L_1, \ldots, L_n]_a[L_2, L_2, \ldots, L_n]_a$.
- 2. Let $C \subset \mathbb{R}^n$ be a strongly convex cone. A compact set $A \subset C$ is called C-co-convex body if $C \setminus A$ is convex. One can construct a **theory of** C- co-convex bodies analogous to the theory of convex bodies and define the mixed volume $V_C(A_{i_1} \dots, A_{i_n})$ of an n-tuple of C-co-convex bodies $A_{i_1} \dots, A_{i_n}$).

Local geometric Alexandrov–Fenchel inequality

$$V_C(A_1, A_2, \ldots, A_n)^2 \leq V_C(A_1, A_1, \ldots, A_n) V_C(A_2, A_2, \ldots, A_n).$$



Other results (continuation)

3. **NO body and Fujita approximation theorem**. One can prove an analogues of Fujita approximation theorem for semigroups of integral points and for graded algebras of almost finite type. As a corollary one obtains a generalization of the classical Fujita theorem for arbitrary linear series.

Other results (continuation)

- 3. **NO body and Fujita approximation theorem**. One can prove an analogues of Fujita approximation theorem for semigroups of integral points and for graded algebras of almost finite type. As a corollary one obtains a generalization of the classical Fujita theorem for arbitrary linear series.
- 4. **NO** body and reductive group action. Assume that X is equipped with an action of a reductive group G and that one is interested only in G-invariant subspaces $L \in \mathcal{K}(X)$. Then it is possible by choosing an appropriate \mathbb{Z}^n -valued valuation v on $\mathbb{C}(X)$ to make all results more precise and explicit.

Other results (continuation)

- 3. **NO body and Fujita approximation theorem**. One can prove an analogues of Fujita approximation theorem for semigroups of integral points and for graded algebras of almost finite type. As a corollary one obtains a generalization of the classical Fujita theorem for arbitrary linear series.
- 4. **NO body and reductive group action**. Assume that X is equipped with an action of a reductive group G and that one is interested only in G-invariant subspaces $L \in \mathcal{K}(X)$. Then it is possible by choosing an appropriate \mathbb{Z}^n -valued valuation v on $\mathbb{C}(X)$ to make all results more precise and explicit.

If an action is **spherical** one can compute the **arithmetic genus** an some other invariants of a generic complete intersection of G-invariant linear systems.

References I

- Khovanskii A. Newton Polyhedra and the genus of complete intersections // Funct. Anal. Appl. 1978. V. 12, No 1, 38–46.
- Khovanskii A. Newton polyhedra, and toroidal varieties // Funct. Anal. Appl. 1977. V. 11, No 4, 289–296 (1978).
- Khovanskii A. Combinatorics of sections of polytopes and Coxeter groups in Lobachevsky spaces // Fields Inst. Communications, AMS, Providence, RI. 2006. V. 46, 129–157.
- Kušnirenko A. G. Polyedres de Newton et nombres de Milnor // Invent. Math. 1976. V. 32, No 1, 1–31.
- Bernstein D. N. The number of roots of a system of equations // Funcional. Anal. i Prilozhen. 1975. V. 9, No 3, 1–4.

References II

- Kaveh.; Khovanskii A. Mixed volume and an extension of intersection theory of divisors // MMJ. 2010. V. 10, No 2, 343–375.
- Kaveh K.; Khovanskii A. Newton–Okounkov convex bodies, semigroups of integral points, graded algebras and intersection theory // Annals of Math. 2012. V. 176, No 2, 925–978.
- Lazarsfeld R.; Mustata M. Convex bodies associated to linear series // Ann. de l'ENS. 2009. V. 42, No 5, 783–835.
- Khovanskii A. Algebra and mixed volumes // Appendix 3 in: Burago Yu. D.; Zalgaller V. A. Geometric inequalities. Springer Series in Soviet Math. 1988.

References III

- Teissier B. Du theoreme de l'index de Hodge aux inegalites isoperimetriques // C. R. Acad. Sci. Paris Ser. A-B. 1979. V. 288, No 4, A287–A289.
- Kaveh K; Khovanskii A. Convex Bodies and Multiplicities of Ideals // Proceedings of the Steklov Inst. of Math. 2014. V. 286, 268–284.
- Khovanskii A.; Timorin V. On the theory of coconvex bodies // Discrete & Computational Geometry. 2014. V. 52, No 3, 806–823.
- Kaveh K.; Khovanskii A. Convex bodies associated to actions of reductive groups // MMJ. 2012. V. 12, No 2, 369–396.

References IV

- Kaveh K.; Khovanskii A. Moment polytopes, semigroup of representations and Kazarnovskii's theorem // J. of Fixed Point Theory and Appl. 2010, V. 7, No 2, 401–417.
- Kaveh K.; Khovanskii A. Newton polytopes for horospherical spaces // MMJ. 2011. V. 11, No 2, 343–375.
- Kaveh K.; Khovanskii A. Complete intersections in spherical varieties. arXiv:1506.03155, 10 Jun 2015, 36 pages.

CONGRATULATIONS!

BEST WISHES TO BERNARD TEISSIER