

Fluctuations and Concentration in Two-layer Neural Networks

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Plan

1. Setting
2. Mean-field limit
3. Fluctuation process
4. Concentration bounds

Setting

Supervised learning for regression

Data points: $(x_k, y_k) \stackrel{i.i.d.}{\sim} \pi \quad x \in \mathbb{R}^d, y \in \mathbb{R}.$

Goal: Find \hat{y} s.t. $\hat{y}(x) \approx y$ for previously unseen x .

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Two-layer neural network:

$$\hat{y}_\theta(x) = \frac{1}{N} \sum_{i=1}^N \sigma_*(\theta^i, x),$$

where

- $N \geq 1$ is the number of *neurons*;
- $\theta = (\theta^i)_{i=1}^N \in (\mathbb{R}^D)^N$ are the *parameters*;
- $\sigma_* : \mathbb{R}^D \times \mathbb{R}^d \rightarrow \mathbb{R}$ is the *activation function*, e.g.,

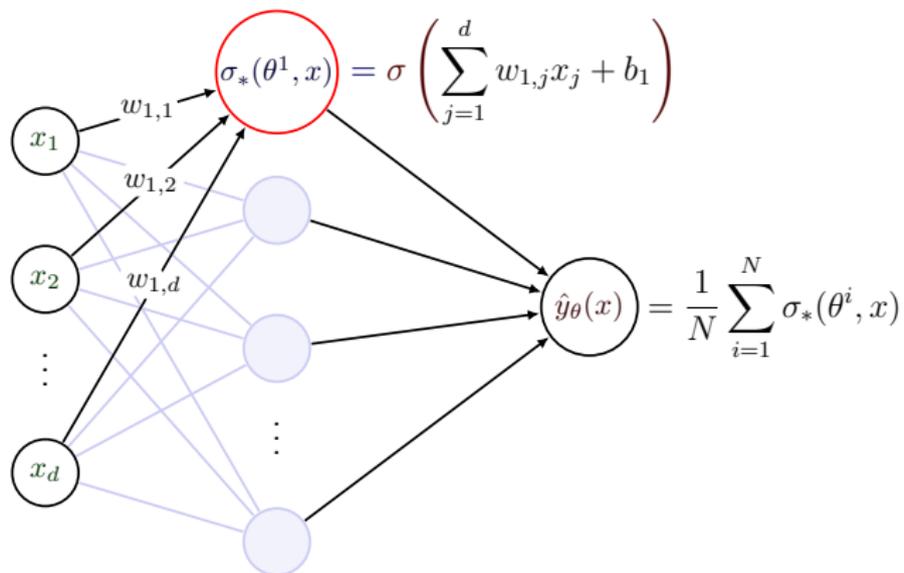
$$\theta^i = (w_i, b_i) \in \mathbb{R}^{d+1}, \quad \sigma_*(\theta^i, x) = \sigma(w_i \cdot x + b_i).$$

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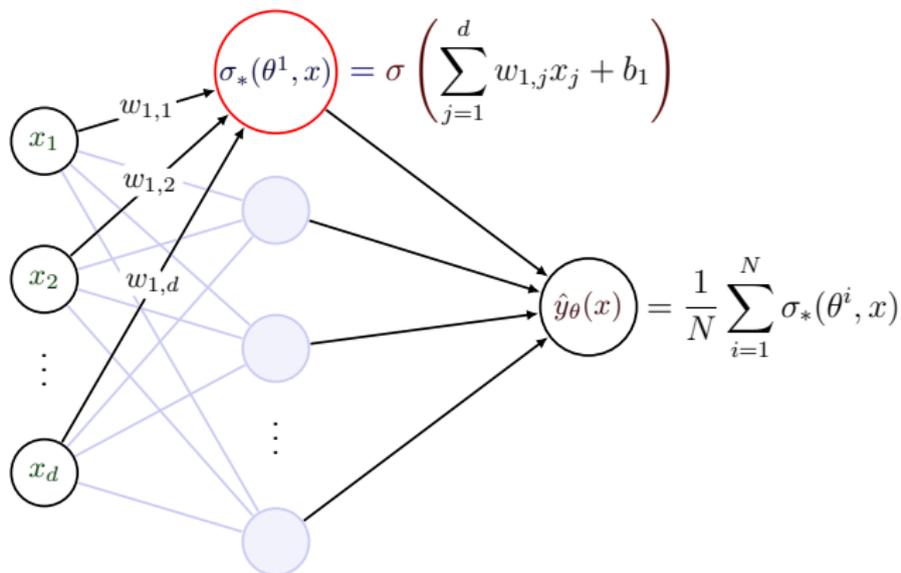


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Ideally, we choose θ so as to minimize the *population risk*

$$\mathcal{R}(\theta) = \mathbb{E}_\pi [\ell(y, \hat{y}_\theta(x))]$$

for some *loss function* $\ell : \mathbb{R} \times \mathbb{R} \rightarrow \mathbb{R}$, e.g., $\ell(y, y') = \frac{1}{2}(y - y')^2.$

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In practice, we choose θ so as to minimise the *empirical risk*

$$\hat{\mathcal{R}}(\theta, x_k, y_k) = \ell(y_k, \hat{y}_\theta(x_k)) + \Omega(\theta).$$

(Online) Stochastic Gradient Descent

Initialization: $\theta_0^j \stackrel{i.i.d.}{\sim} \mu_0 \in \mathcal{P}(\mathbb{R}^D)$.

Update: SGD with fixed *learning rate* $\alpha > 0$,

$$\theta_{k+1} = \theta_k - \alpha \nabla \widehat{\mathcal{R}}(\theta_k, x_k, y_k) \quad (\text{square loss})$$

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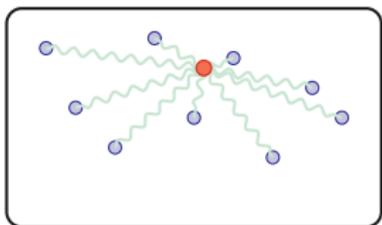
$$\mu_t^N = \frac{1}{N} \sum_{i=1}^N \delta_{\theta^i}_{[Nt]} \in \mathcal{P}(\mathbb{R}^D).$$

Mean-field limit

Mean-field approximation

Microscopic (finite width)

N neurons $\equiv N$ interacting particles

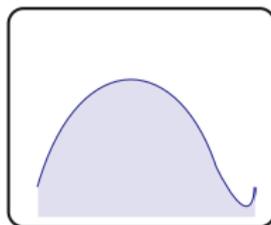


$N \rightarrow \infty$

→

Macroscopic (mean-field)

deterministic limit $\bar{\mu}_t$



SGD: $\theta_{k+1}^i =$

$$\theta_k^i - \frac{\alpha}{N} (y_k - \hat{y}_{\theta_k}(x_k)) \nabla_{\theta^i} \sigma_*(\theta_k^i, x_k)$$

Empirical measure: $\mu_t^N = \frac{1}{N} \sum_{i=1}^N \delta_{\theta_{[Nt]}^i}$

Mean-field predictor:

$$\bar{y}_t(x) = \langle \sigma_*(\cdot, x), \bar{\mu}_t \rangle$$

A law of large numbers

Theorem (Descours et al.'22)

Under standard regularity assumptions on σ_* , μ_0 and π ,

$$(\mu_t^N)_{t \geq 0} \xrightarrow[N \rightarrow \infty]{\mathbb{P}} (\bar{\mu}_t)_{t \geq 0} \in \mathcal{D}(\mathbb{R}_+, \mathcal{P}_\gamma(\mathbb{R}^D)) \quad (\gamma > \frac{D}{2})$$

where $\bar{\mu}$ is characterized as the unique (deterministic) solution in $\mathcal{C}(\mathbb{R}_+, \mathcal{P}_1(\mathbb{R}^D))$ to the evolution equation:

$$\partial_t \bar{\mu}_t + \alpha \nabla \cdot (G(\cdot, \bar{\mu}_t) \bar{\mu}_t) = 0, \quad \bar{\mu}_0 = \mu_0.$$

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Question

Can we quantify the deviations of μ_t^N from its mean-field limit $\bar{\mu}_t$?

Fluctuation process

A central limit theorem

Fluctuation process: $t \geq 0 \mapsto \eta_t^N = \sqrt{N}(\mu_t^N - \bar{\mu}_t)$
(signed measure) $\in \mathcal{D}(\mathbb{R}_+, H^{-J_0+1, j_0}(\mathbb{R}^D))$.

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$$(\eta_t^N)_{t \geq 0} \xrightarrow[N \rightarrow \infty]{d} (\eta_t^*)_{t \geq 0} \in \mathcal{C}(\mathbb{R}_+, H^{-J_0+1, j_0}(\mathbb{R}^D)).$$

The law of η^* is characterized as the unique (weak) solution to

$$\begin{aligned} \text{a.s., } \forall \varphi \in H^{J_0, j_0}(\mathbb{R}^D), \forall t \geq 0, \quad & \langle \varphi, \eta_t^* \rangle = \langle \varphi, \eta_0^* \rangle + \langle \varphi, \mathcal{G}_t \rangle \\ & + \int_0^t \int_{\mathcal{X} \times \mathcal{Y}} \alpha(y - \langle \sigma_*(\cdot, x), \bar{\mu}_s \rangle) \langle \nabla \varphi \cdot \nabla \sigma_*(\cdot, x), \eta_s^* \rangle \pi(dx, dy) ds \\ & - \int_0^t \int_{\mathcal{X} \times \mathcal{Y}} \alpha \langle \sigma_*(\cdot, x), \eta_s^* \rangle \langle \nabla \varphi \cdot \nabla \sigma_*(\cdot, x), \bar{\mu}_s \rangle \pi(dx, dy) ds, \end{aligned}$$

with initial condition $\nu_0 \in H^{-J_0+1, j_0}(\mathbb{R}^D)$ s.t. for any $\varphi_1, \dots, \varphi_k \in H^{J_0-1, j_0}(\mathbb{R}^D)$,
 $(\langle \varphi_1, \nu_0 \rangle, \dots, \langle \varphi_k, \nu_0 \rangle)^\top \sim \mathcal{N}(0, \Gamma(\varphi_1, \dots, \varphi_k))$, where $\Gamma(\varphi_1, \dots, \varphi_k)$ is the covariance matrix of
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Law of the asymptotic fluctuation process

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Theorem (DGLMNS'26⁺)

For any test function $\varphi \in \mathcal{C}_b^\infty(\mathbb{R}^D)$, $(\langle \varphi, \eta_t^* \rangle)_{t \geq 0}$ is a centered Gaussian process, with variance

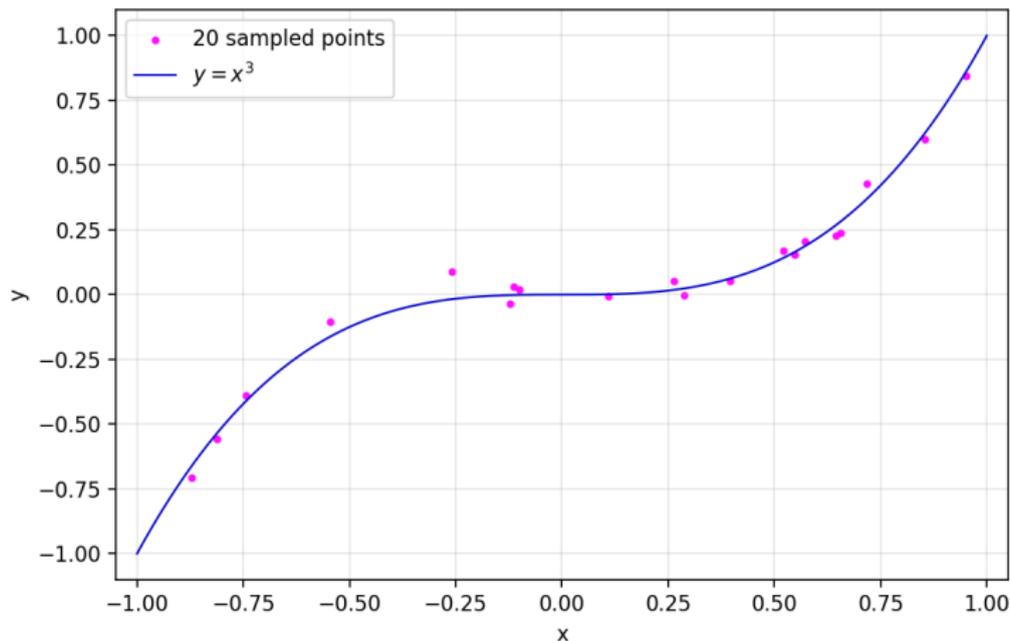
$$V_t = V_0 + \alpha^2 \int_0^t \text{Var}_\pi(Q_s[f(s, \cdot)]) ds.$$

where $f \in \mathcal{C}^1([0, t] \times \mathbb{R}^2)$ is the solution of the following backward PDE, with final datum $f(t, \cdot) = \varphi$:

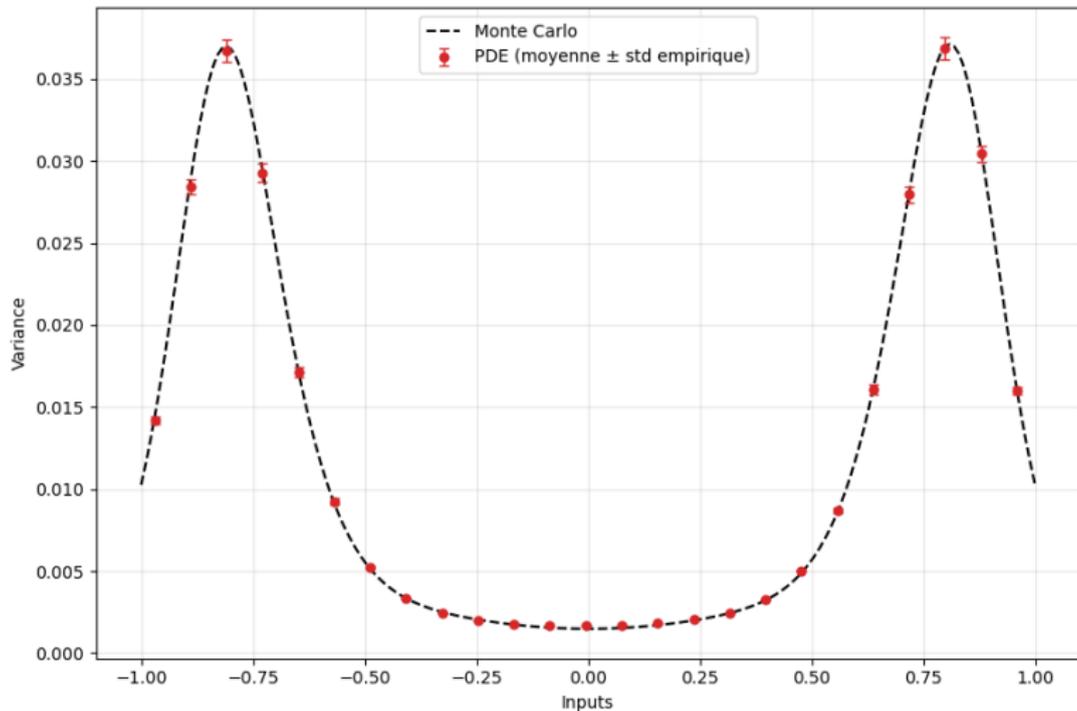
$$\partial_s f + F \cdot \nabla_\theta f + Af = 0.$$

Numerical simulations on a toy dataset

Toy Dataset: $y = x^3 + \varepsilon$, $x \sim \mathcal{U}([-1, 1]) \perp\!\!\!\perp \varepsilon \sim \mathcal{N}(0, 0.05^2)$.



Numerical simulations on toy dataset



Concentration bounds

Finite-width approximation bounds

Theorem (MMN'18)

For any bounded-Lipschitz $f : \mathbb{R}^D \rightarrow \mathbb{R}$, for all $T > 0$ and $z > 0$, with probability $1 - e^{-z^2}$,

$$\sup_{t \in [0, T]} |\langle f, \mu_t^N \rangle - \langle f, \bar{\mu}_t \rangle| \leq C e^{CT} \delta_{N,d}(z)$$

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Theorem (Guillin, Nectoux, S.'26)

For any $t \geq 0$ and $\delta \in (0, 1)$, with probability $1 - \delta$,

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with $\kappa_N \rightarrow 0$ as $N \rightarrow \infty$ and C independent of N and t .

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Thank you for your attention!