

Palatini Gauss-Bonnet Theory

Marc Henneaux
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Pure Chern-Simons theory in 3 spacetime dimensions has been a constant source of inspiration since its inception in the 1970-1980's.

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Pure Chern-Simons theory in 3 spacetime dimensions has been a constant source of inspiration since its inception in the 1970-1980's.

Chern-Simons theories exist also in higher dimensions, but only in the odd-dimensional case.

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Palatini Gauss-Bonnet theories, which exist only in even spacetime dimensions $2n$, are theories that share many of the features of the Chern-Simons models in dimensions $2n + 1$.

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Palatini Gauss-Bonnet theories, which exist only in even spacetime dimensions $2n$, are theories that share many of the features of the Chern-Simons models in dimensions $2n + 1$.

These theories are topological in the sense that they do not involve a spacetime metric.

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These theories are topological in the sense that they do not involve a spacetime metric.

The coupling constant is dimensionless.

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These theories are topological in the sense that they do not involve a spacetime metric.

The coupling constant is dimensionless.

In 2 spacetime dimensions, the Lagrangian is non-trivial (not equal to a total divergence) but there is no local degree of freedom due to the big number of gauge symmetries.

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These theories are topological in the sense that they do not involve a spacetime metric.

The coupling constant is dimensionless.

In 2 spacetime dimensions, the Lagrangian is non-trivial (not equal to a total divergence) but there is no local degree of freedom due to the big number of gauge symmetries.

The theory does possess local degrees of freedom when $n > 1$, but identifying them turns out to be an intricate question, as for pure Chern-Simons theory in $2n + 1$ dimensions with $n \geq 2$.

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The purpose of this talk is to describe the general features of the Palatini Gauss-Bonnet theory (action, gauge symmetries)

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The 4-dimensional case illustrates the intricacies occurring in higher dimensions.

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The 4-dimensional case illustrates the intricacies occurring in higher dimensions.

The 2-dimensional case has no local degrees of freedom but an interesting and rich boundary dynamics.

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Based on M. Bañados and M.H, arXiv :2511.20903 [hep-th] (to appear in JHEP) and in preparation

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The action reads

$$I[g, \Gamma] = k \int \sqrt{|g|} e^{\alpha_1 \alpha_2 \dots \alpha_n} \beta_1 \beta_2 \dots \beta_n R_{\alpha_1}^{\beta_1} \wedge R_{\alpha_2}^{\beta_2} \wedge \dots \wedge R_{\alpha_n}^{\beta_n}$$

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where k is a dimensionless coupling constant, $R_{\alpha_1}^{\beta_1} = R_{\alpha_1}^{\beta_1}(\Gamma)$ the curvature 2-form and g is the determinant of the metric.

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$$I[g, \Gamma] = k \int \sqrt{|g|} \epsilon^{\alpha_1 \alpha_2 \dots \alpha_n}{}_{\beta_1 \beta_2 \dots \beta_n} R_{\alpha_1}^{\beta_1} \wedge R_{\alpha_2}^{\beta_2} \wedge \dots \wedge R_{\alpha_n}^{\beta_n}$$

where k is a dimensionless coupling constant, $R_{\alpha_1}^{\beta_1} = R_{\alpha_1}^{\beta_1}(\Gamma)$ the curvature 2-form and g is the determinant of the metric.

Here, $\epsilon^{\alpha_1 \alpha_2 \dots \alpha_n}{}_{\beta_1 \beta_2 \dots \beta_n} \equiv g^{\alpha_1 \gamma_1} g^{\alpha_2 \gamma_2} \dots g^{\alpha_n \gamma_n} \epsilon_{\gamma_1 \gamma_2 \dots \gamma_n \beta_1 \beta_2 \dots \beta_n}$,

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where $\epsilon_{\gamma_1 \gamma_2 \dots \gamma_n \beta_1 \beta_2 \dots \beta_n}$ is the $GL(2n)$ numerically invariant tensor density of weight minus one. The combination

$\sqrt{|g|} \epsilon^{\alpha_1 \alpha_2 \dots \alpha_n}{}_{\beta_1 \beta_2 \dots \beta_n}$, which is the only place where the metric enters, is a $GL(2n)$ tensor acting as a multilinear form.

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If the metric was fixed to be the Minkowski metric, restricting the group to the homogeneous Lorentz group, the action would be the Gauss-Bonnet topological invariant. However, because the metric is varied in the action principle, the dynamics is non-trivial.

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The action possesses the following gauge symmetries :

- Internal $GL(2n)$ symmetry : $\delta\Gamma_{\beta}^{\alpha} = \nabla\Lambda_{\beta}^{\alpha}$, $\delta g_{\alpha\beta} = \Lambda_{\alpha\beta} + \Lambda_{\beta\alpha}$

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The action possesses the following gauge symmetries :

- **Internal GL(2n) symmetry** : $\delta\Gamma_{\beta}^{\alpha} = \nabla\Lambda_{\beta}^{\alpha}$, $\delta g_{\alpha\beta} = \Lambda_{\alpha\beta} + \Lambda_{\beta\alpha}$
- **(Improved) diff invariance** : $\delta\Gamma_{\beta\mu}^{\alpha} = R^{\alpha}_{\beta\mu\nu}\xi^{\nu}$, $\delta g_{\alpha\beta} = \xi^{\mu}\nabla_{\mu}g_{\alpha\beta}$

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- **Weyl symmetry** : $\delta\Gamma_{\beta}^{\alpha} = 0$, $\delta g_{\alpha\beta} = 2\sigma g_{\alpha\beta}$

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- Weyl symmetry : $\delta\Gamma_{\beta}^{\alpha} = 0$, $\delta g_{\alpha\beta} = 2\sigma g_{\alpha\beta}$
- Projective symmetry : $\delta\Gamma_{\beta}^{\alpha} = w\delta_{\beta}^{\alpha}$, $\delta g_{\alpha\beta} = 0$.

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where Λ_{β}^{α} , ξ^{μ} , σ and w (a 1-form) are arbitrary spacetime functions.

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The above gauge symmetries are neither independent, nor complete.

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The above gauge symmetries are neither independent, nor complete.

Exhibiting the missing gauge symmetries is a hard task in spacetime dimensions ≥ 4 .

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In two dimensions, the theory can be reformulated as a
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In two dimensions, the theory can be reformulated as a constrained B - F system

This is because the action reduces to :

$$I[g, \Gamma] = k \int \sqrt{|g|} \epsilon^\alpha_\beta R^\beta_\alpha(\Gamma)$$

with $\epsilon^\alpha_\beta = g^{\alpha\gamma} \epsilon_{\gamma\beta}$.

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Defining $B^\alpha_\beta = k\sqrt{|g|} \epsilon^\alpha_\beta = k\sqrt{|g|} g^{\alpha\gamma} \epsilon_{\gamma\beta}$,

one finds then that the action takes indeed the form of the action of a $GL(2)$ - BF system,

$$\int B^\alpha_\beta R^\beta_\alpha(\Gamma)$$

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with a B field constrained by the two conditions

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one finds then that the action takes indeed the form of the action of a $GL(2)$ - BF system,

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with a B field constrained by the two conditions

$$\psi \equiv B^\alpha_\alpha = 0, \quad \omega \equiv B^\alpha_\beta B^\beta_\alpha - 2k^2 \eta = 0 \quad (\eta = \frac{g}{|g|}).$$

B - F formulation – Hamiltonian formulation

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The action of two-dimensional Palatini-Gauss-Bonnet theory is thus equivalent to

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The action of two-dimensional Palatini-Gauss-Bonnet theory is thus equivalent to

$$I[B, \Gamma; \lambda_1, \lambda_2] = \int d^2x \left(B^\alpha_\beta R^\beta_\alpha(\Gamma) - (\lambda_1 \psi + \lambda_2 \omega) \right)$$

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with

$$\mathcal{G}^\alpha_\beta = -\nabla_1 B^\alpha_\beta.$$

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$$\{\Gamma_{\beta 1}^{\alpha}, B_{\kappa}^{\gamma}\} = \delta_{\kappa}^{\alpha} \delta_{\beta}^{\gamma},$$

as can be seen from the “ $p\dot{q}$ ” kinetic term.

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The variables $\Gamma_{\beta 0}^\alpha$, λ_1 and λ_2 are Lagrange multipliers enforcing respectively the constraints $\mathcal{G}_{\beta}^{\alpha} = 0$, $\psi = 0$, $\omega = 0$.

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The $\mathcal{G}_{\beta}^{\alpha}$'s generate $GL(2)$ gauge transformations.

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ω generates

$$\{\Gamma_{\beta 1}^{\alpha}, \int dy \zeta \omega\} = 2\zeta B_{\beta}^{\alpha}, \quad \{B_{\beta}^{\alpha}, \int dy \zeta \omega\} = 0,$$

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$$\{\Gamma_{\beta 1}^{\alpha}, \int dy \zeta \omega\} = 2\zeta B_{\beta}^{\alpha}, \quad \{B_{\beta}^{\alpha}, \int dy \zeta \omega\} = 0,$$

which is a **new** (= unlisted before) gauge symmetry.

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The number of first class constraints is $4 + 1 + 1$ but they cannot be independent because the number of independent conjugate pairs is 4.

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This reflect the redundancy of the gauge transformations.

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The number of first class constraints is $4 + 1 + 1$ but they cannot be independent because the number of independent conjugate pairs is 4.

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In fact there are exactly 4 independent first class constraints (and not less)

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(Note in particular that the diffeomorphisms are not independent symmetries.)

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The theory has therefore zero local degree of freedom.

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In fact there are exactly 4 independent first class constraints (and not less)

(Note in particular that the diffeomorphisms are not independent symmetries.)

The theory has therefore zero local degree of freedom.

However, in the presence of boundaries, there are non trivial boundary degrees of freedom, as explained later in the talk.

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The situation is much more intricate in higher dimensions (4 and higher).

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The situation is much more intricate in higher dimensions (4 and higher).

This will be illustrated for 4 dimensions, where the action is

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The situation is much more intricate in higher dimensions (4 and higher).

This will be illustrated for 4 dimensions, where the action is

$$I[g, \Gamma] = \int \sqrt{g} \epsilon^{\alpha\gamma}{}_{\beta\delta} R^\beta{}_\alpha(\Gamma) \wedge R^\delta{}_\gamma(\Gamma)$$

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$$I[g, \Gamma] = \int \sqrt{g} \epsilon^{\alpha\gamma}{}_{\beta\delta} R^\beta{}_\alpha(\Gamma) \wedge R^\delta{}_\gamma(\Gamma)$$

To understand the dynamical structure, the safest way to proceed is to go to the Hamiltonian formulation.

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By following the standard (Dirac) procedure, one can rewrite the action in Hamiltonian form,

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$$\begin{aligned} I[\Gamma_{\alpha i}^{\beta}, p_{\beta}^{i\alpha}, g_{\alpha\beta}, \pi^{\alpha\beta}; \Gamma_{\alpha 0}^{\beta}, X_{\beta i}^{\alpha}, Y_{\alpha\beta}] \\ = \int p_{\beta}^{i\alpha} \dot{\Gamma}_{\alpha i}^{\beta} + \pi^{\alpha\beta} \dot{g}_{\alpha\beta} - (\Gamma_{\alpha 0}^{\beta} \mathcal{G}_{\beta}^{\alpha} + X_{\beta i}^{\alpha} \phi_{\alpha}^{i\beta} + Y_{\alpha\beta} \pi^{\alpha\beta}) \end{aligned}$$

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with

$$\mathcal{G}_{\beta}^{\alpha} = -\nabla_i p_{\beta}^{i\alpha} + 2\pi^{\alpha\gamma} g_{\gamma\beta}, \quad \phi_{\mu}^{i\nu} = \phi_{\alpha}^{i\beta} = p_{\alpha}^{i\beta} - \sqrt{g} \epsilon^{\beta\gamma}{}_{\alpha\delta} R^{\delta}{}_{\gamma jk} \epsilon^{ijk}.$$

Hamiltonian formulation

By following the standard (Dirac) procedure, one can rewrite the action in Hamiltonian form,

$$I[\Gamma_{\alpha i}^{\beta}, p_{\beta}^{i\alpha}, g_{\alpha\beta}, \pi^{\alpha\beta}; \Gamma_{\alpha 0}^{\beta}, X_{\beta i}^{\alpha}, Y_{\alpha\beta}] \\ = \int p_{\beta}^{i\alpha} \dot{\Gamma}_{\alpha i}^{\beta} + \pi^{\alpha\beta} \dot{g}_{\alpha\beta} - (\Gamma_{\alpha 0}^{\beta} \mathcal{G}_{\beta}^{\alpha} + X_{\beta i}^{\alpha} \phi_{\alpha}^{i\beta} + Y_{\alpha\beta} \pi^{\alpha\beta})$$

with

$$\mathcal{G}_{\beta}^{\alpha} = -\nabla_i p_{\beta}^{i\alpha} + 2\pi^{\alpha\gamma} g_{\gamma\beta}, \quad \phi_{\mu}^{i\nu} = \phi_{\alpha}^{i\beta} = p_{\alpha}^{i\beta} - \sqrt{g} \epsilon^{\beta\gamma}{}_{\alpha\delta} R^{\delta}{}_{\gamma jk} \epsilon^{ijk}.$$

($p_{\beta}^{i\alpha}$ are the conjugate momenta to the spatial components $\Gamma_{\alpha i}^{\beta}$;
 $\pi^{\alpha\beta}$ are the conjugate momenta to $g_{\alpha\beta}$; $\Gamma_{\alpha 0}^{\beta}$, $X_{\beta i}^{\alpha}$ and $Y_{\alpha\beta}$ are
Lagrange multipliers for the constraints $\mathcal{G}_{\beta}^{\alpha} \approx 0$, $\phi_{\alpha}^{i\beta} \approx 0$ and
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$(p_{\beta}^{i\alpha})$ are the conjugate momenta to the spatial components $\Gamma_{\alpha i}^{\beta}$;
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Lagrange multipliers for the constraints $\mathcal{G}_{\beta}^{\alpha} \approx 0$, $\phi_{\alpha}^{i\beta} \approx 0$ and
 $\pi^{\alpha\beta} \approx 0$)

The constraints are not independent because

$\nabla_i \phi_{\alpha}^{i\alpha} + \mathcal{G}_{\alpha}^{\alpha} - 2\pi^{\alpha}_{\alpha} = 0$. There are $16 + 3 \times 16 + 10 - 1 = 73$
independent constraints.

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The above constraints satisfy the Poisson bracket relations,

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The above constraints satisfy the Poisson bracket relations,

$$[\mathcal{G}_\beta^\alpha, \mathcal{G}_\delta^\gamma] = \delta_\beta^\gamma \mathcal{G}_\delta^\alpha - \delta_\delta^\alpha \mathcal{G}_\beta^\gamma$$

$$[\mathcal{G}_\beta^\alpha, \phi_\delta^{i\gamma}] = \delta_\beta^\gamma \phi_\delta^{i\alpha} - \delta_\delta^\alpha \phi_\beta^{i\gamma}$$

$$[\mathcal{G}_\beta^\alpha, \pi^{\gamma\delta}] = \pi^{\alpha\delta} \delta_\beta^\gamma + \pi^{\gamma\alpha} \delta_\beta^\delta$$

$$[\phi_\beta^{i\alpha}, \phi_\delta^{i\gamma}] = \Omega^{\kappa\lambda\alpha\gamma}{}_{\beta\delta} \epsilon^{ijk} \nabla_k g_{\kappa\lambda}$$

$$[\phi_\beta^{i\alpha}, \pi^{\kappa\lambda}] = \Omega^{\kappa\lambda\alpha\gamma}{}_{\beta\delta} \epsilon^{ijk} R_{\gamma jk}^\delta$$

$$[\pi^{\alpha\beta}, \pi^{\gamma\delta}] = 0$$

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$$[\phi_\beta^{i\alpha}, \phi_\delta^{i\gamma}] = \Omega^{\kappa\lambda\alpha\gamma} \epsilon_{\beta\delta}^{ijk} \nabla_k g_{\kappa\lambda}$$

$$[\phi_\beta^{i\alpha}, \pi^{\kappa\lambda}] = \Omega^{\kappa\lambda\alpha\gamma} \epsilon_{\beta\delta}^{ijk} R_{\gamma jk}^\delta$$

$$[\pi^{\alpha\beta}, \pi^{\gamma\delta}] = 0$$

$$\Omega^{\kappa\lambda\alpha\gamma}{}_{\beta\delta} = \frac{1}{2} \sqrt{g} \left(g^{\kappa\lambda} \epsilon_{\beta\delta}^{\alpha\gamma} - g^{\alpha\sigma} \epsilon^{\rho\gamma}{}_{\beta\delta} - g^{\alpha\rho} \epsilon^{\sigma\gamma}{}_{\beta\delta} - g^{\gamma\rho} \epsilon^{\alpha\sigma}{}_{\beta\delta} - g^{\gamma\sigma} \epsilon^{\alpha\rho}{}_{\beta\delta} \right).$$

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The above constraints satisfy the Poisson bracket relations,

$$[\mathcal{G}_\beta^\alpha, \mathcal{G}_\delta^\gamma] = \delta_\beta^\gamma \mathcal{G}_\delta^\alpha - \delta_\delta^\alpha \mathcal{G}_\beta^\gamma$$

$$[\mathcal{G}_\beta^\alpha, \phi_\delta^{i\gamma}] = \delta_\beta^\gamma \phi_\delta^{i\alpha} - \delta_\delta^\alpha \phi_\beta^{i\gamma}$$

$$[\mathcal{G}_\beta^\alpha, \pi^{\gamma\delta}] = \pi^{\alpha\delta} \delta_\beta^\gamma + \pi^{\gamma\alpha} \delta_\beta^\delta$$

$$[\phi_\beta^{i\alpha}, \phi_\delta^{i\gamma}] = \Omega^{\kappa\lambda\alpha\gamma} \epsilon^{ijk} \nabla_k g_{\kappa\lambda}$$

$$[\phi_\beta^{i\alpha}, \pi^{\kappa\lambda}] = \Omega^{\kappa\lambda\alpha\gamma} \epsilon^{ijk} R_{\gamma jk}^\delta$$

$$[\pi^{\alpha\beta}, \pi^{\gamma\delta}] = 0$$

$$\Omega^{\kappa\lambda\alpha\gamma} = \frac{1}{2} \sqrt{g} \left(g^{\kappa\lambda} \epsilon^{\alpha\gamma}_{\beta\delta} - g^{\alpha\sigma} \epsilon^{\rho\gamma}_{\beta\delta} - g^{\alpha\rho} \epsilon^{\sigma\gamma}_{\beta\delta} - g^{\gamma\rho} \epsilon^{\alpha\sigma}_{\beta\delta} - g^{\gamma\sigma} \epsilon^{\alpha\rho}_{\beta\delta} \right).$$

Among these $16 + 3 \times 16 + 10 - 1 = 73$ constraints, some are first class and generate the gauge symmetries while some are second class.

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A difficulty is that the rank of the matrix of the Poisson brackets depends on the location on the constraint surface.

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A difficulty is that the rank of the matrix of the Poisson brackets depends on the location on the constraint surface.

For instance, if the connection vanishes and the metric is constant (which is a solution of the equations of motion), the brackets of the constraints all weakly vanish.

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A difficulty is that the rank of the matrix of the Poisson brackets depends on the location on the constraint surface.

For instance, if the connection vanishes and the metric is constant (which is a solution of the equations of motion), the brackets of the constraints all weakly vanish.

On the other hand for less trivial solutions, some of the brackets do not vanish, even weakly, implying the presence of second class constraints.

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The situation is similar to that encountered for higher-dimensional pure Chern-Simons theories (M. Banados, L. J. Garay and M. H, Phys. Rev. D **53** (1996), 593-596 [arXiv :hep-th/9506187 [hep-th]] ; Nucl. Phys. B **476** (1996), 611-635 [arXiv :hep-th/9605159 [hep-th]])

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Just as in those references, we focus our attention on the generic situation where the rank of the matrix of the Poisson brackets takes the maximum possible value compatible with the constraints,

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Just as in those references, we focus our attention on the generic situation where the rank of the matrix of the Poisson brackets takes the maximum possible value compatible with the constraints,

which is the generic case.

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Of course, there are always the first class constraints associated with the gauge symmetries identified above (no matter what the rank is).

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Of course, there are always the first class constraints associated with the gauge symmetries identified above (no matter what the rank is).

The \mathcal{G}_β^α are first class because they generate the internal $GL(4)$ transformations.

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The \mathcal{G}_β^α are first class because they generate the internal $GL(4)$ transformations.

$g_{\alpha\beta}\pi^{\alpha\beta}$ is first class because it generates the Weyl symmetry.

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The trace $P^i := \phi^{i\alpha}_\alpha$ generates (the spatial part of) the projective symmetry.

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As we mentioned, the constraints are not independent; there is one reducibility identity and there is no more reducibility (generically).

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As we mentioned, the constraints are not independent; there is one reducibility identity and there is no more reducibility (generically).

We have thus identified $16 + 1 + 3 + 3 - 1 = 22$ independent first class constraints, which account for all gauge symmetries listed above.

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There are $73 - 22 = 51$ remaining constraints, which cannot all be second class (odd number).

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There are $73 - 22 = 51$ remaining constraints, which cannot all be second class (odd number).

There are necessarily additional gauge symmetries!

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There are $73 - 22 = 51$ remaining constraints, which cannot all be second class (odd number).

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These are not in the list given above.

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There are $73 - 22 = 51$ remaining constraints, which cannot all be second class (odd number).

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These are not in the list given above.

To identify them, one needs to compute the zero eigenvectors of the matrix of the Poisson bracket of the constraints.

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Quite intricate!

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"Drawing at random procedure" to be in generic case.

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Rank of remaining matrix is 48 (generically).

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Quite intricate!

“Drawing at random procedure” to be in generic case.

Rank of remaining matrix is 48 (generically).

Hence there are 3 additional first class constraints, i.e., 3 additional gauge symmetries (generically)!

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Quite intricate!

"Drawing at random procedure" to be in generic case.

Rank of remaining matrix is 48 (generically).

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These symmetries are hard to write analytically, in covariant form... completely unexpected!

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Denoting by X the **three** new gauge symmetries, we have the following table :

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Denoting by X the **three** new gauge symmetries, we have the following table :

Fields	$\{p_{\beta}^{i\alpha}, A_{\delta j}^{\gamma}\}, \{g_{\alpha\beta}, \pi^{\gamma\delta}\}$	$2 \times 3 \times 16 + 2 \times 10 = 116$
Constraints	$\mathcal{G}_{\beta}^{\alpha}, \phi_{\delta}^{i\gamma}, \pi^{\kappa\lambda}$	$15 + 3 \times 16 + 10 = 73$
Symmetries	$gl(4)$, diff, projective, Weyl, X	$16 + 3 + 3 + 1 - 1 + 3 = 25$
Second class		$73 - 25 = 48$
Physical dof	fields - $2 \times$ (first) - (second)	$116 - 2 \times 25 - 48 = 18$

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Second class		$73 - 25 = 48$
Physical dof	fields - $2 \times$ (first) - (second)	$116 - 2 \times 25 - 48 = 18$

This theory has therefore $\frac{116 - 2 \times 25 - 48}{2} = 9$ physical (local) degrees of freedom.

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As we have seen, the $d = 2$ Palatini Einstein-Hilbert theory can be reformulated as a constrained B - F theory, with action

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As we have seen, the $d = 2$ Palatini Einstein-Hilbert theory can be reformulated as a constrained B - F theory, with action

$$I[B, \lambda_1, \lambda_2] = \int dt \int dr \text{Tr} \left(B \dot{\Gamma} + \Gamma_0 \nabla B - \lambda_1 B - \lambda_2 (B^2 - \eta k^2 I_{2 \times 2}) \right)$$

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It has no local degrees of freedom. On $\mathbb{R} \times S_1$, the theory has no global degree of freedom either, because all the invariants are fixed by the constraints.

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This is not true on $\mathbb{R} \times [r_1, r_2]$, where the theory has boundary degrees of freedom.

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We thus consider the theory on the interval,

$$I[B, \lambda_1, \lambda_2] = \int dt \int_{r_1}^{r_2} dr \text{Tr} \left(B \dot{\Gamma} + \Gamma_0 \nabla B - \lambda_1 B - \lambda_2 (B^2 - \eta k^2 I_{2 \times 2}) \right)$$

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The expression

$$G[\epsilon] = - \int dr \text{Tr} (\epsilon \nabla B)$$

where $\epsilon \in gl(2)$,

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The expression

$$G[\epsilon] = - \int dr \text{Tr} (\epsilon \nabla B)$$

where $\epsilon \in gl(2)$,

is a well defined generator when ϵ vanishes at the boundaries.

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$$\delta \Gamma^\alpha{}_{\beta 1} = \nabla_1 \epsilon^\alpha{}_\beta, \quad \delta B^\alpha{}_\beta = [B, \epsilon]^\alpha{}_\beta$$

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It generates then “proper gauge transformations”,

$$\delta \Gamma^\alpha_{\beta 1} = \nabla_1 \epsilon^\alpha_{\beta}, \quad \delta B^\alpha_{\beta} = [B, \epsilon]^\alpha_{\beta}$$

When ϵ does not vanish at the boundaries, one must supplement $G[\epsilon]$ by a boundary term,

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When ϵ does not vanish at the boundaries, one must supplement $G[\epsilon]$ by a boundary term,

$$G[\epsilon] = - \int dr \text{Tr} (\epsilon \nabla B) + \left[\text{Tr} (\epsilon B) \right]_{r_1}^{r_2}$$

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where $\epsilon \in \mathfrak{gl}(2)$,

is a well defined generator when ϵ vanishes at the boundaries.

It generates then “proper gauge transformations”,

$$\delta \Gamma^{\alpha}{}_{\beta 1} = \nabla_1 \epsilon^{\alpha}{}_{\beta}, \quad \delta B^{\alpha}{}_{\beta} = [B, \epsilon]^{\alpha}{}_{\beta}$$

When ϵ does not vanish at the boundaries, one must supplement $G[\epsilon]$ by a boundary term,

$$G[\epsilon] = - \int dr \text{Tr} (\epsilon \nabla B) + \left[\text{Tr} (\epsilon B) \right]_{r_1}^{r_2}$$

that makes it well-defined as a generator.

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$$G[\epsilon] = - \int dr \text{Tr} (\epsilon \nabla B) + \left[\text{Tr} (\epsilon B) \right]_{r_1}^{r_2}$$

that makes it well-defined as a generator.

It generates then the same gauge transformations but with ϵ now arbitrary

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The “surface” term does not vanish in general, even when the constraints hold – except for the trace.

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We get at each boundary a copy of

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The “surface” term does not vanish in general, even when the constraints hold – except for the trace.

We get at each boundary a copy of

$$sl(2) \simeq \frac{gl(2)}{\mathbb{R}I_{2 \times 2}}$$

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$$sl(2) \simeq \frac{gl(2)}{\mathbb{R}I_{2 \times 2}}$$

The three charges Q_i at r_2 and the three charges \bar{Q}_i at r_1

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The three charges Q_i at r_2 and the three charges \bar{Q}_i at r_1 are subject to the conditions

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The three charges Q_i at r_2 and the three charges \bar{Q}_i at r_1 are subject to the conditions

$$Q_1^2 + Q_2 Q_3 = 1, \quad \bar{Q}_1^2 + \bar{Q}_2 \bar{Q}_3 = 1$$

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The three charges Q_i at r_2 and the three charges \bar{Q}_i at r_1 are subject to the conditions

$$Q_1^2 + Q_2 Q_3 = 1, \quad \bar{Q}_1^2 + \bar{Q}_2 \bar{Q}_3 = 1$$

(Casimirs fixed)

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One can integrate the Gauss constraint by writing

$$\Gamma(r) = U(r)^{-1} U(r)'$$

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One can integrate the Gauss constraint by writing

$$\Gamma(r) = U(r)^{-1} U(r)'$$

for some $U \in sl(2)$.

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One can integrate the Gauss constraint by writing

$$\Gamma(r) = U(r)^{-1} U(r)'$$

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One gets explicitly

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One can integrate the Gauss constraint by writing

$$\Gamma(r) = U(r)^{-1} U(r)'$$

for some $U \in sl(2)$.

One gets explicitly

$$U(r) = \text{Pe}^{\int_{r_1}^r \Gamma(r) dr} U(r_1)$$

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for some $U \in sl(2)$.

One gets explicitly

$$U(r) = \text{Pe}^{\int_{r_1}^r \Gamma(r) dr} U(r_1)$$

One then finds that the Gauss constraint implies

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One gets explicitly

$$U(r) = \text{Pe}^{\int_{r_1}^r \Gamma(r) dr} U(r_1)$$

One then finds that the Gauss constraint implies

$$B(r) = U^{-1}(r) b U(r)$$

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$$\Gamma(r) = U(r)^{-1} U(r)'$$

for some $U \in sl(2)$.

One gets explicitly

$$U(r) = P e^{\int_{r_1}^r \Gamma(r) dr} U(r_1)$$

One then finds that the Gauss constraint implies

$$B(r) = U^{-1}(r) b U(r)$$

where b does not depend on r (but can of course depend on the unwritten time t).

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Plugging these expressions into the action, one gets the boundary action

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Plugging these expressions into the action, one gets the boundary action

$$I_I[V, b; \lambda] = \int dt \text{Tr} [b \dot{V} V^{-1} - \lambda (b^2 - k^2 \eta_{2 \times 2})],$$

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$$I_I[V, b; \lambda] = \int dt \text{Tr} [b \dot{V} V^{-1} - \lambda (b^2 - k^2 \eta I_{2 \times 2})],$$

with

$$V(t) \equiv U(t, r_2)$$

($b = b(t)$ by the constraint)

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with

$$V(t) \equiv U(t, r_2)$$

($b = b(t)$ by the constraint)

and

$$\lambda(t) := \int_{r_1}^{r_2} dr \lambda_2(r, t).$$

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$$\lambda(t) := \int_{r_1}^{r_2} dr \lambda_2(r, t).$$

Given that the theory has no local degree of freedom, it does not come as a surprise that it can be reformulated as a boundary theory in one dimension less.

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($b = b(t)$ by the constraint)

and

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Given that the theory has no local degree of freedom, it does not come as a surprise that it can be reformulated as a boundary theory in one dimension less.

This is achieved here by solving the Gauss constraint inside the action and eliminating the corresponding Lagrange multiplier (“inverse Lagrange multiplier method”).

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The group manifold of $SL(2)$ can be identified with AdS_3 . The action is then the action for a free particle propagating (on geodesics) in AdS_3 .

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The group manifold of $SL(2)$ can be identified with AdS_3 . The action is then the action for a free particle propagating (on geodesics) in AdS_3 .

This can be made explicit by introducing the conjugate momenta $\pi = V^{-1}b$ and rewrite the action as

$$I[V, \pi; \lambda] = \int dt \text{Tr} [\pi \dot{V} - \lambda ((V\pi)^2 - k^2 \eta I_{2 \times 2})].$$

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$$I[V, \pi; \lambda] = \int dt \text{Tr} [\pi \dot{V} - \lambda ((V\pi)^2 - k^2 \eta I_{2 \times 2})].$$

By choosing appropriate coordinate q^α ($\alpha = 0, 1, 2$) on the group manifold and appropriate parametrization of π in terms of p^α , the action reads

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By choosing appropriate coordinate q^α ($\alpha = 0, 1, 2$) on the group manifold and appropriate parametrization of π in terms of p^α , the action reads

$$I[q^\alpha, p_\alpha; \lambda] = \int dt (p_\alpha \dot{q}^\alpha - \lambda (\gamma^{\alpha\beta} p_\alpha p_\beta - 2k^2 \eta)),$$

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By choosing appropriate coordinate q^α ($\alpha = 0, 1, 2$) on the group manifold and appropriate parametrization of π in terms of p^α , the action reads

$$I[q^\alpha, p_\alpha; \lambda] = \int dt \left(p_\alpha \dot{q}^\alpha - \lambda (\gamma^{\alpha\beta} p_\alpha p_\beta - 2k^2 \eta) \right),$$

where $\gamma^{\alpha\beta}$ is the inverse to the anti-de Sitter metric,

$$ds^2 = \gamma_{\alpha\beta} dq^\alpha dq^\beta = -(1+r^2)dt^2 + \frac{dr^2}{1+r^2} + r^2 d\varphi^2$$

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The quadratic constraint is the mass-shell condition

$$\gamma^{\alpha\beta} p_\alpha p_\beta + m^2 = 0$$

with mass squared $m^2 = -2k^2\eta$.

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The quadratic constraint is the mass-shell condition

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with mass squared $m^2 = -2k^2\eta$.

By eliminating the conjugate momenta, one gets the standard form of the action

$$I[q^\alpha] = -m \int ds$$

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with mass squared $m^2 = -2k^2\eta$.

By eliminating the conjugate momenta, one gets the standard form of the action

$$I[q^\alpha] = -m \int ds$$

for a free particle following geodesics in AdS_3 .

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Palatini Gauss-Bonnet Theory

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The boundary symmetries act as follows on the degrees of freedom of the $1 + 0$ theory :

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- Improper gauge transformation at r_1 ($S(r_1) = h \in SL(2)$,
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$$V \rightarrow h^{-1}V, \quad b \rightarrow h^{-1}bh$$

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Note that neither h nor g depends on time; these are global symmetries.

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The charges corresponding to these transformations read, with
 $h = I_{2 \times 2} + \zeta$, $g = I_{2 \times 2} + \epsilon$

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In our derivation, one copy comes from the left boundary, the
other comes from the right boundary.

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The quantum theory is derived by imposing the constraint on the physical states,

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The quantum theory is derived by imposing the constraint on the physical states,

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The mass squared is positive if $\eta = -1$ (Minkowskian signature of the spacetime metric).

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The mass squared is positive if $\eta = -1$ (Minkowskian signature of the spacetime metric).

It is negative but satisfies the Breitenlohner-Freedman bound with Euclidean signature, provided k is small enough.

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The Palatini Gauss-Bonnet theory is an interesting theory that parallels closely the properties of the Chern-Simons theory in one spacetime dimension higher.

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The Palatini Gauss-Bonnet theory is an interesting theory that parallels closely the properties of the Chern-Simons theory in one spacetime dimension higher.

Although (interestingly) intricate in dimensions ≥ 4 , it is very simple but non trivial in two spacetime dimensions, where it reduces to a constrained B - F theory.

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THANK YOU!