

# Uniqueness and stability in bottom detection through surface measurements of water waves

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The logo for ULCO, featuring the letters 'ulco' in a blue, lowercase, sans-serif font with a white wave-like line passing through the 'o'. Below it, the text 'Université Littoral Côte d'Opale' is written in a smaller, blue, sans-serif font.

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1 Introduction

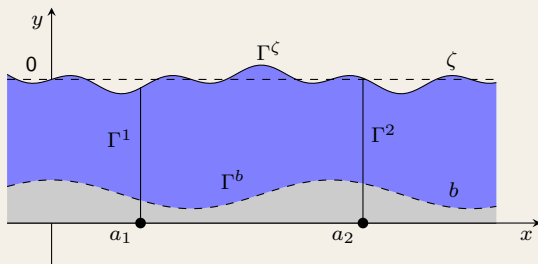
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# introduction

## Problem setting (2d)

Consider the motion of an ideal, inviscid, incompressible, and irrotational fluid, bounded below by a solid bottom  $b$  and above by a free surface  $\zeta$ :



**Figure:** Scheme for the inverse problem

We aim to establish the uniqueness and stability of detecting any fixed portion  $(a_1, a_2)$  of the bottom  $b$  from measurements taken on the surface  $\zeta$ :

► Uniqueness and upper-bound stability without imposing conditions on  $\zeta$  and  $b$ .

Furthermore, we avoid assumptions about the velocity of the fluid.

∋ **Joint work with Prof. Lionel Rosier.**

We define the spatial region confined between the bottom and the free surface as

$$\Omega_t = \{(X, y) \in \mathbb{R}^d \times \mathbb{R}, b(X) < y < \zeta(t, X)\}, \quad d = 1, 2.$$

Then, the motion of the fluid can be modeled as follows:

$$\left\{ \begin{array}{l} \partial_t \zeta - G(\zeta, b)\psi = 0, \\ \partial_t \psi + g\zeta + \frac{1}{2} |\nabla_X \psi|^2 + \frac{(G(\zeta, b)\psi + \nabla_X \zeta \cdot \nabla_X \psi)^2}{2(1 + |\nabla_X \zeta|^2)} = 0, \\ \zeta(0, X) = \zeta_0(X), \quad \psi(0, X) = \psi_0(X), \end{array} \right. \quad (1)$$

where  $\psi(t, X) = \phi(t, X, \zeta(t, X))$  is the trace of the velocity potential at the free surface, and  $G$  is the Dirichlet-Neumann operator defined by

$$\psi \longrightarrow G(\zeta, b)\psi = \sqrt{1 + |\nabla_X \zeta|^2} \partial_n \phi|_{y=\zeta},$$

such that,  $\phi$  is the solution to the elliptic problem

$$\left\{ \begin{array}{l} \Delta_{X,y} \phi = 0, \quad \Omega_t, \\ \phi|_{y=\zeta} = \psi, \quad \partial_n \phi|_{y=b} = 0. \end{array} \right. \quad (2)$$

1 Introduction

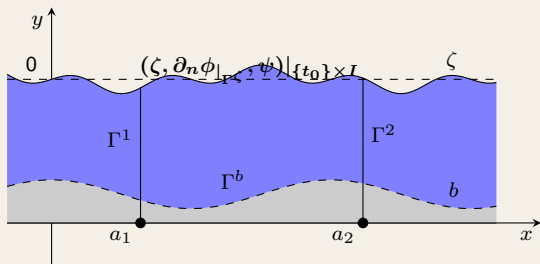
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# Uniqueness and Stability

## Surface measurements

Let  $I = (a_1, a_2)$ , based on the water wave equations (1)-(2), we assume access to the surface measurements  $(\zeta, \partial_n \phi|_{\Gamma^\zeta}, \psi)|_{\{t_0\} \times I}$  along  $\Gamma^\zeta$  at time  $t_0$ . Additionally, if the walls  $\Gamma^1$  and  $\Gamma^2$  are virtual walls, meaning the domain is not physically limited at  $\Gamma^1$  and  $\Gamma^2$  we also assume we have the values of the bottom at  $a_1$  and  $a_2$ , namely  $(b(a_1), b(a_2))$ .



**Figure:** Surface measurements

- based on the first equation in (1), one can replace the measurements  $(\zeta, \partial_n \phi|_{\Gamma^\zeta}, \psi)|_{\{t_0\} \times I}$  by  $(\zeta|_{[0, t^*] \times I}, \psi|_{\{t_0\} \times I})$ , where  $t_0 \in [0, t^*]$ .

# Uniqueness and Stability

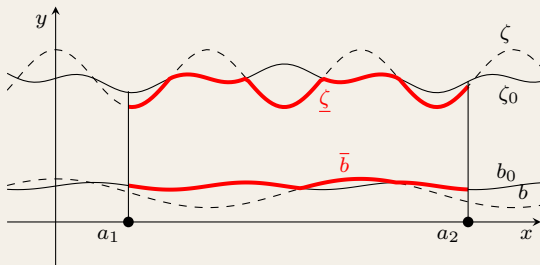
## Perturbations

We fix an instant of measurement  $t_0$  and we consider  $\zeta$  and  $\psi$  represent the perturbations resulting from measuring the physical correct values  $\zeta_0$  and  $\psi_0$ , and let  $b$  be the resulting bottom that replaces the exact bottom  $b_0$ , such that  $b$ ,  $b_0$ ,  $\zeta$  and  $\zeta_0$  be  $H^2(\mathbb{R})$ , and  $\psi$ ,  $\psi_0$  in  $\dot{H}^{3/2}(\mathbb{R})$ , where

$$\dot{H}^{3/2}(\mathbb{R}) = \left\{ \psi \in L^2_{loc}(\mathbb{R}), \quad \partial_x \psi \in H^{1/2}(\mathbb{R}) \right\}.$$

Moreover, we assume that there exist two positive constants  $h_0 > 0$  and  $h > 0$ , such that

$$\zeta_0(x) - b_0(x) \geq h_0 \quad \text{and} \quad \zeta(x) - b(x) \geq h, \quad \forall x \in \mathbb{R}. \quad (3)$$



**Figure:** Scheme for the domains

# Uniqueness and Stability

## Perturbations

The following two systems are well-posed, and each admits a unique solution with  $H^2$  regularity.

$$\begin{cases} \Delta\phi = 0, & \text{on } \Omega_b^\zeta, \\ \phi = \psi, & \text{in } \Gamma^\zeta, \\ \partial_n\phi = 0, & \text{in } \Gamma^b, \end{cases} \quad (4)$$

$$\begin{cases} \Delta\phi_0 = 0, & \text{on } \Omega_{b_0}^{\zeta_0}, \\ \phi_0 = \psi_0, & \text{in } \Gamma^{\zeta_0}, \\ \partial_n\phi_0 = 0, & \text{in } \Gamma^{b_0}, \end{cases} \quad (5)$$

To handle both domains, we introduce the following notations:

$$S_1 = (\zeta - \zeta_0)^{-1}(\mathbb{R}_*^+), \quad S_2 = (\zeta - \zeta_0)^{-1}(\mathbb{R}^-), \quad (6)$$

and we define the following Lipschitz continuous functions:

$$\underline{\zeta}(x) = \min(\zeta(x), \zeta_0(x)), \quad \bar{b}(x) = \max(b(x), b_0(x)), \quad \forall x \in I. \quad (7)$$

# Uniqueness and Stability

## Preliminaries

Consider the following Neumann Laplace problem

$$\begin{cases} \Delta u = 0, & \text{on } \Omega, \\ \partial_n u = v, & \text{in } \partial\Omega. \end{cases} \quad (8)$$

### Theorem - Lipschitz propagation of smallness

Let  $\Omega$  be a bounded Lipschitz domain in  $\mathbb{R}^2$  with constants  $r_0$  and  $M_0$ , and let  $u \in H^1(\Omega)$  be a solution of (8), such that  $v \in L^2(\partial\Omega)$ . Then, for every  $\rho > 0$  and for every  $(x, y) \in \Omega_{4\rho}$ , where

$$\Omega_{4\rho} = \{(x, y) \in \Omega : d((x, y), \partial\Omega) > 4\rho\},$$

we have

$$\int_{B_\rho((x,y))} |\nabla u|^2 \geq C_\rho \int_{\Omega} |\nabla u|^2. \quad (9)$$

Here,  $C_\rho$  only depends on  $\mu_2(\Omega)$ ,  $r_0$ ,  $M_0$ ,  $\rho$  and  $\frac{\|v\|_{L^2(\partial\Omega)}}{\|v\|_{H^{-1/2}(\partial\Omega)}}$ .

# Uniqueness and Stability

## Preliminaries

### Theorem : log-log stability

Let  $\Omega$  be a bounded Lipschitz domain in  $\mathbb{R}^2$  with constants  $r_0$  and  $M_0$ . Consider  $\Gamma^0$  a nonempty open subset of  $\partial\Omega$  and  $s \in (0, \frac{1}{2})$ . Then there exists two constants  $c > \exp(1)$  and  $C > 0$ , depends only on  $\Gamma^0, \Omega$  and  $s$ , such that for any  $u \in H^2(\Omega)$ ,  $u \neq 0$  with  $\Delta u = 0$  and

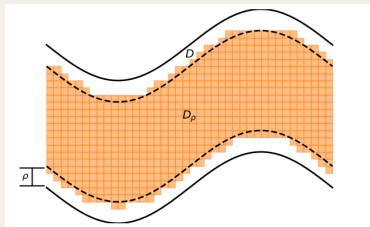
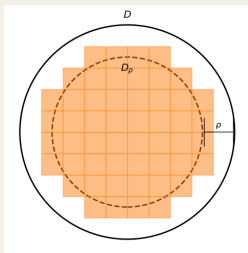
$$\|u\|_{H^2(\Omega)} \leq M \quad \text{and} \quad \|u\|_{L^2(\Gamma^0)} + \|\nabla u\|_{L^2(\Gamma^0)} \leq \frac{M}{2c},$$

where  $M$  is a positive constant, we have

$$\|u\|_{H^1(\Omega)} \leq CM \left[ \log \log \left( \frac{M}{\|u\|_{L^2(\Gamma^0)} + \|\nabla u\|_{L^2(\Gamma^0)}} \right) \right]^{-s/2}.$$

# Uniqueness and Stability

## Preliminaries: Size Estimation Method



**Figure:** A cover of  $D_\rho$  using internally nonoverlapping closed squares  $(q_n)_n$  of size less than  $\rho/2$ .

$$\int_D |\nabla u|^2 \geq \sum_{q_n} \int_{q_n} |\nabla u|^2 \geq \frac{\int_{q_{n,0}} |\nabla u|^2}{\mu_2(q_{n,0})} \sum_{q_n} \mu_2(q_n) \geq \frac{\int_{q_{n,0}} |\nabla u|^2}{\mu_2(q_{n,0})} \mu_2(D_\rho),$$

where  $q_{n,0}$ , is such that

$$\min_{q_n \subset Q_n} \int_{q_n} |\nabla u|^2 = \int_{q_{n,0}} |\nabla u|^2 \geq C_\rho \int_\Omega |\nabla u|^2.$$

# Uniqueness and Stability

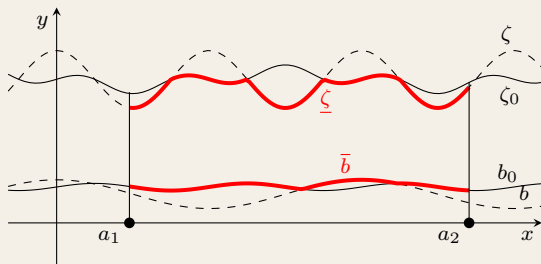
## Conditions

We assume that there exist two positive constants  $h_0 > 0$  and  $h > 0$ , such that

$$\zeta_0(x) - b_0(x) \geq h_0 \quad \text{and} \quad \zeta(x) - b(x) \geq h, \quad \forall x \in I. \quad (10)$$

Moreover, we assume

$$|\zeta(x) - \zeta_0(x)| \leq \min\left(\frac{h}{2}, \frac{h_0}{2}\right), \quad \forall x \in I. \quad (11)$$



**Figure:** Scheme for the domains

# Uniqueness and Stability

## Uniqueness result

### Theorem :Uniqueness

Let  $b$ ,  $b_0$ ,  $\zeta$  and  $\zeta_0$  to be  $H^2(\bar{I})$ , such that (10) and (11) holds, and consider  $\phi \in H^2(\Omega_b^\zeta)$ ,  $\phi_0 \in H^2(\Omega_{b_0}^{\zeta_0})$  solutions of the systems (4) and (5), respectively. Then, if,

$$\zeta(x) = \zeta_0(x) \neq 0, \quad \psi(x) = \psi_0(x) \neq 0, \quad \partial_n \phi|_{\Gamma^\zeta}(x) = \partial_n \phi_0|_{\Gamma^{\zeta_0}}(x), \quad \forall x \in I, \quad (12)$$

and

$$b(a_1) = b_0(a_1), \quad b(a_2) = b_0(a_2), \quad (13)$$

we have,

$$b(x) = b_0(x), \quad \forall x \in I.$$

# Uniqueness and Stability

## Stability upper bound result

### Theorem :Stability

Let fix  $s$  in the interval  $]0, 1/2[$ . Let  $b, b_0, \zeta$  and  $\zeta_0$  to be  $H^2(\bar{I})$ , such that (10) and (11) holds, and consider  $\phi \in H^2(\Omega_b^\zeta)$ ,  $\phi_0 \in H^2(\Omega_{b_0}^{\zeta_0})$  solutions of the systems (4) and (5), respectively. Then, there exists two constant  $c > \exp(1)$  and  $C > 0$ , such that, if,

$$\|\phi\|_{H^2(\Omega_b^\zeta)} \leq \frac{M}{2}, \quad \|\phi_0\|_{H^2(\Omega_{b_0}^{\zeta_0})} \leq \frac{M}{2} \quad \text{and} \quad \sqrt{G_4} + \sqrt{G_5} \leq \frac{M}{2c},$$

where  $M$  is a positive constant, we have

$$\|b - b_0\|_{L^1(I)} \leq \frac{1}{\min \left\{ \int_{\Omega_b^\zeta} |\nabla \phi|^2, \int_{\Omega_{b_0}^{\zeta_0}} |\nabla \phi_0|^2 \right\}} (G_2 + G_3 + T \log_1 + T_{bot}), \quad (14)$$

# Stability estimate

Measurements taken over  $\Gamma^\zeta$  and  $\Gamma^{\zeta_0}$

where  $G_1, G_2, G_3, G_4$  and  $G_5$  are given by:

$$\begin{aligned} G_1(\zeta - \zeta_0, \psi - \psi_0, \partial_n \phi|_{\Gamma^\zeta} - \partial_n \phi_0|_{\Gamma^{\zeta_0}}) &= \|\partial_x \psi - \partial_x \psi_0\|_{L^2(I)}^2 + C_{1,1} \left\| \partial_n \phi|_{\Gamma^\zeta} - \partial_n \phi_0|_{\Gamma^{\zeta_0}} \right\|_{L^2(I)}^2 \\ &\quad + C_{1,1} \|\partial_x \zeta - \partial_x \zeta_0\|_{L^\infty(I)}^2 \\ &\quad + C_{1,2} \|\partial_x \psi - \partial_x \psi_0\|_{L^2(I)} \left\| \partial_n \phi|_{\Gamma^\zeta} - \partial_n \phi_0|_{\Gamma^{\zeta_0}} \right\|_{L^2(I)} \\ &\quad + C_{1,2} \|\partial_x \zeta - \partial_x \zeta_0\|_{L^\infty(I)} \|\partial_x \psi - \partial_x \psi_0\|_{L^2(I)} \\ &\quad + 2C_{1,1} \|\partial_x \zeta - \partial_x \zeta_0\|_{L^\infty(I)} \left\| \partial_n \phi|_{\Gamma^\zeta} - \partial_n \phi_0|_{\Gamma^{\zeta_0}} \right\|_{L^2(I)} \\ G_2(\zeta - \zeta_0, \psi - \psi_0) &= C_{2,1} \|\zeta - \zeta_0\|_{L^\infty(I)}^{\frac{1}{2}} + C_{2,2} \|\psi - \psi_0\|_{L^2(I)}, \\ G_3 \left( \zeta - \zeta_0, \partial_n \phi|_{\Gamma^\zeta} - \partial_n \phi_0|_{\Gamma^{\zeta_0}} \right) &= C_{3,1} \left\| \partial_n \phi|_{\Gamma^\zeta} - \partial_n \phi_0|_{\Gamma^{\zeta_0}} \right\|_{L^2(I)} + C_{3,2} \|\zeta - \zeta_0\|_{L^\infty(I)}^{\frac{1}{2}} \\ &\quad + C_{3,3} \|\partial_x \zeta - \partial_x \zeta_0\|_{L^\infty(I)}, \\ G_4(\zeta - \zeta_0, \psi - \psi_0) &= C_{4,1} \|\psi - \psi_0\|_{L^2(I)}^2 + C_{4,2} \|\zeta - \zeta_0\|_{L^\infty(I)} \\ &\quad + C_{4,3} \|\zeta - \zeta_0\|_{L^\infty(I)}^{\frac{1}{2}} \|\psi - \psi_0\|_{L^2(I)}, \\ G_5 \left( \zeta - \zeta_0, \psi - \psi_0, \partial_n \phi|_{\Gamma^\zeta} - \partial_n \phi_0|_{\Gamma^{\zeta_0}} \right) &= C_{5,1} \|\zeta - \zeta_0\|_{L^\infty(I)} \\ &\quad + C_{5,2} \|\zeta - \zeta_0\|_{L^\infty(I)}^{\frac{1}{2}} G_1^{\frac{1}{2}} \\ &\quad + C_{5,3} G_1. \end{aligned}$$

(15)



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Thank you for your attention!  
Any questions?