

Modeling and simulating spatio-temporal multivariate and non-stationary Gaussian Processes: a Gaussian mixtures perspective

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Outline

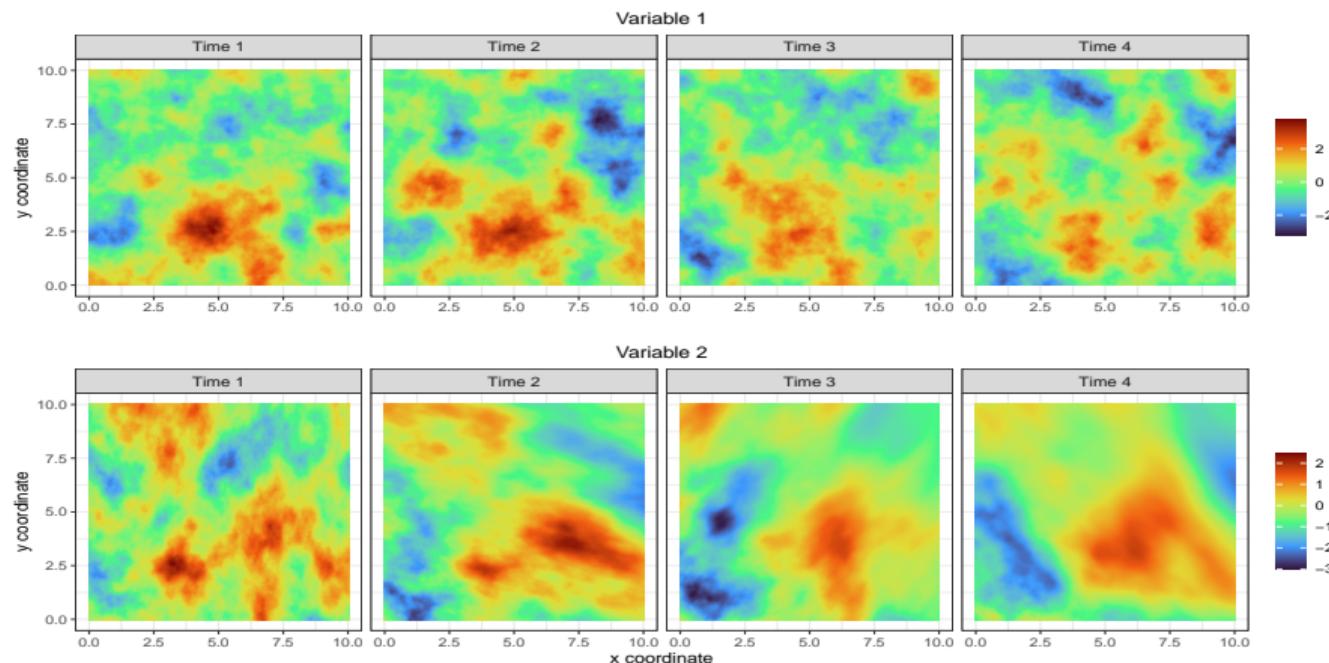
Introduction

Building bricks

Non-stationarity

Full combo

Motivation



Realization of a bivariate, spatio-temporal, non-stationary GP

Motivation

- ▶ **Building covariance functions** in complex settings: spatio-temporal, multivariate, nonstationary; **sometimes all at once**
- ▶ **Generating GPs on \mathbb{R}^p** characterized on by those
- ▶ Simulation algorithms are constructive arguments for defining **new classes of covariance functions** in these settings
- ▶ Particular focus on Gaussian mixtures
- ▶ <https://hal.inrae.fr/hal-05034982>

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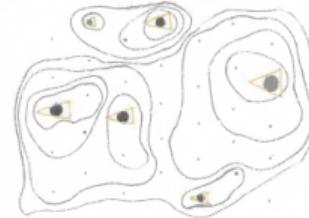
Outline

1. **Introduction:** reminders on the spectral method
2. **Building bricks:** Gaussian mixtures, geometric anisotropy, popular covariance functions; recent extensions
3. **Nonstationarity:** a general result relating to the Paciorek-Shervish construction
4. **The full combo:** new nonstationary, multivariate, spatio-temporal class

Artistic point of view

Waves into Patterns

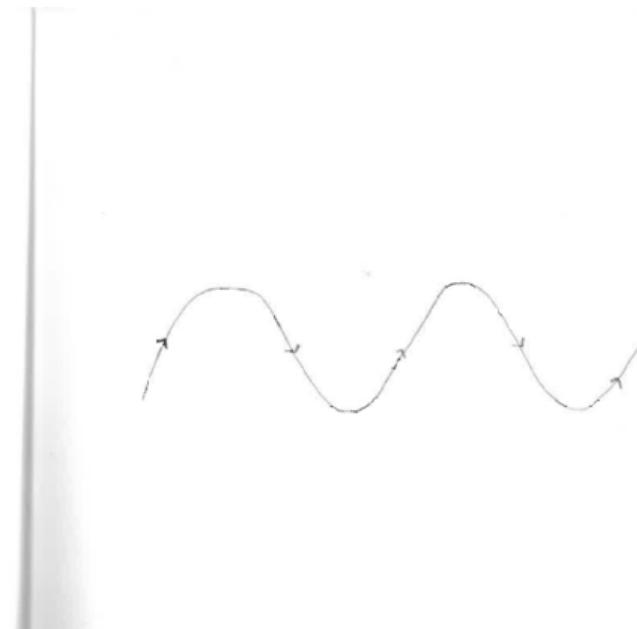
A book on changing scale, multiple perspectives, diversity, and ecological variability.



Dmitry Paranyushkin

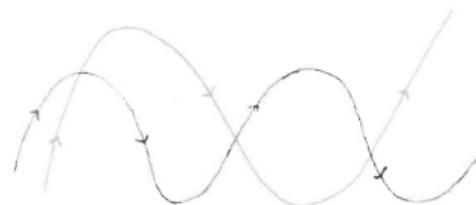
Artistic point of view

At the beginning, there was a wave.



Artistic point of view

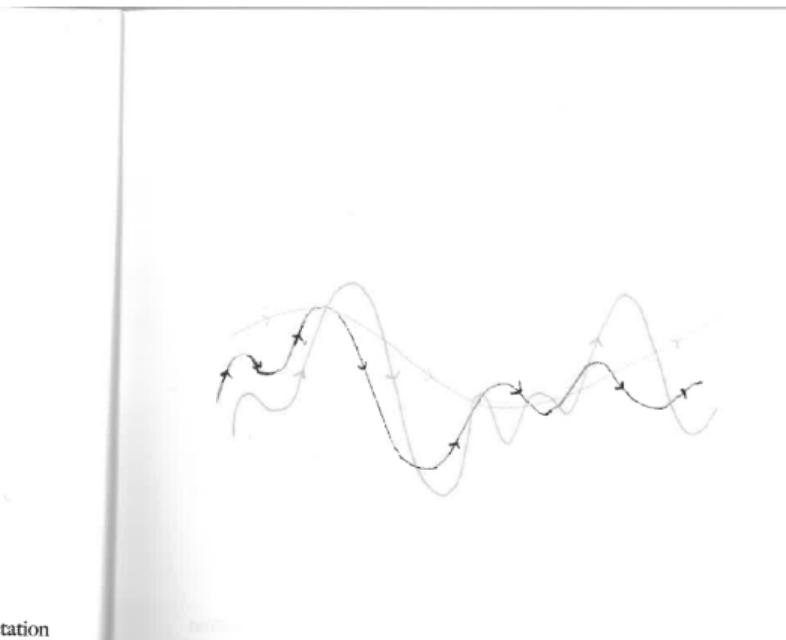
Then, there was another wave.



* perception

Artistic point of view

The waves made patterns.



* interpretation

The classic "classic spectral method"

Shinozuka (1971), Matheron (1973)

Use Bochner Theorem,

$$C(\mathbf{h}) = \int_{\mathbb{R}^d} \exp(i\mathbf{h}^t \boldsymbol{\omega}) d\mu(\boldsymbol{\omega}), \quad \forall \mathbf{h} \in \mathbb{R}^d.$$

Then,

$$\tilde{Z}_L(\mathbf{s}) = \sqrt{\frac{2}{L}} \sum_{l=1}^L \cos \left(\boldsymbol{\Omega}_l^t \mathbf{s} + \Phi_l \right), \quad \boldsymbol{\Omega}_l \sim \mu, \quad \Phi_l \sim \mathcal{U}(0, 2\pi), \quad \text{all i.i.d}$$

is approximately a GP with expectation 0 and covariance function C

The classic "classic spectral method"

Proof

- ▶ $E [\cos (\Omega_i^t \mathbf{s} + \Phi_i)] = 0$
- ▶

$$\begin{aligned} E \left[2 \cos (\Omega_i^t \mathbf{s} + \Phi_i) \cos (\Omega_i^t (\mathbf{s} + \mathbf{h}) + \Phi_i) \right] &= E \left[\cos (\Omega_i^t (2\mathbf{s} + \mathbf{h}) + 2\Phi_i) \right] + E \left[\cos (\Omega_i^t \mathbf{h}) \right] \\ &= 0 + \int_{\mathbb{R}^d} \cos(\omega^t \mathbf{h}) d\mu(\omega) \end{aligned}$$

- ▶ Then use CLT
- ▶ Similar to the "Random Fourier Features" (Rahimi and Recht, 2007), based on $(\cos(\Omega_i^t \mathbf{s}), \sin(\Omega_i^t \mathbf{s}))$

Extensions of the spectral method

- ▶ Multivariate (MV) (Emery et al., 2016) and non-stationary (NS) (Emery and Arroyo, 2018). Includes also NS – MV
- ▶ Saptio-temporal (ST) Allard et al. (2020)
- ▶ Spatio-temporal multivariate (ST – MV), Allard et al. (2022)

→ Propose an algorithm and models for "the full combo" NS – ST – MV

Extensions of the spectral method

S only –
Shinozuka,
Matheron (1973)

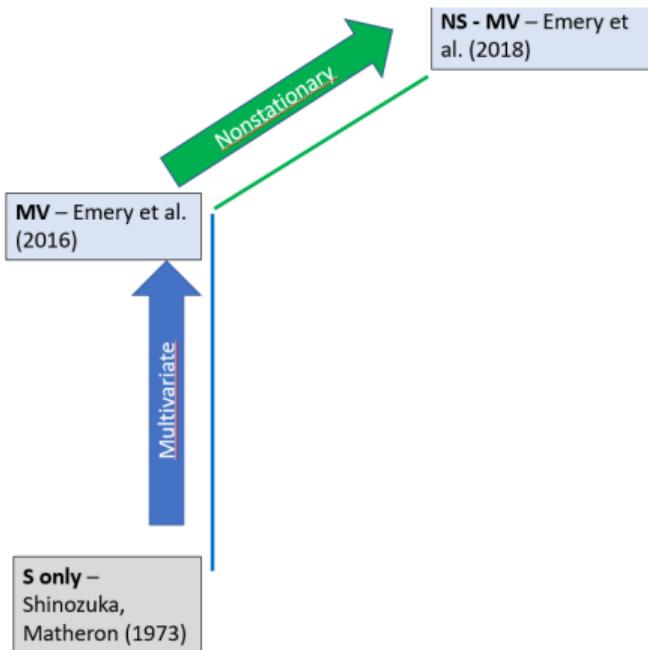
Extensions of the spectral method

MV – Emery et al.
(2016)

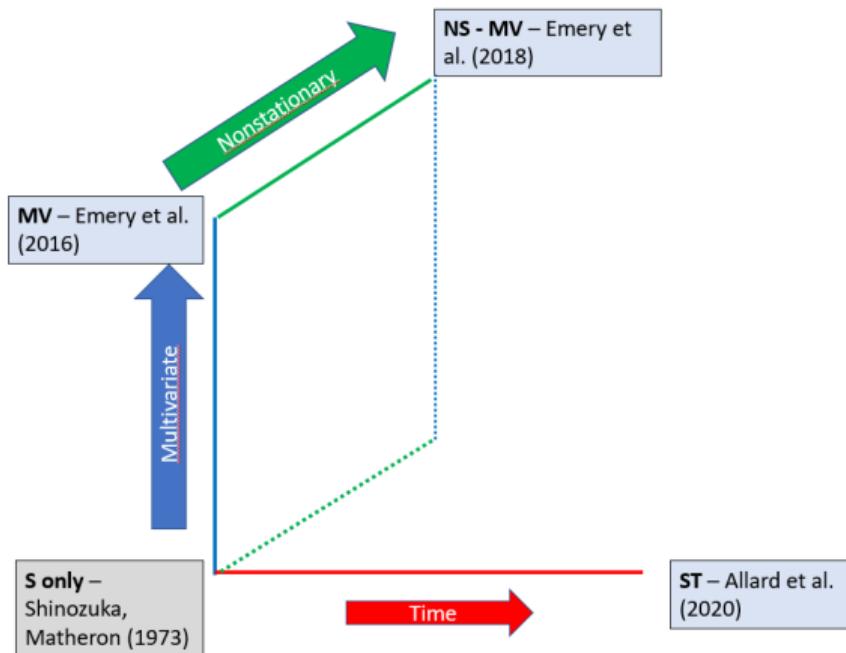


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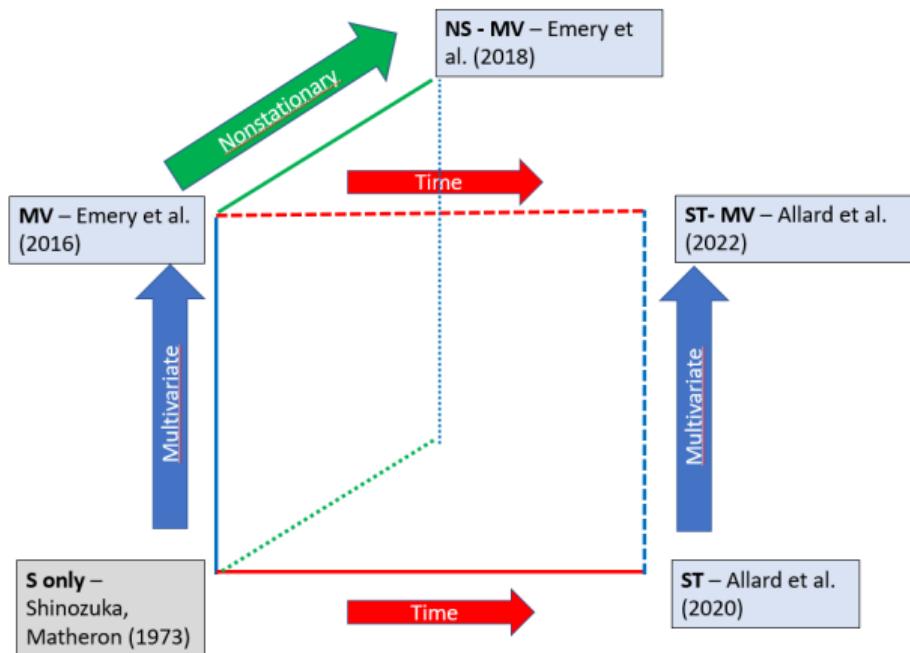
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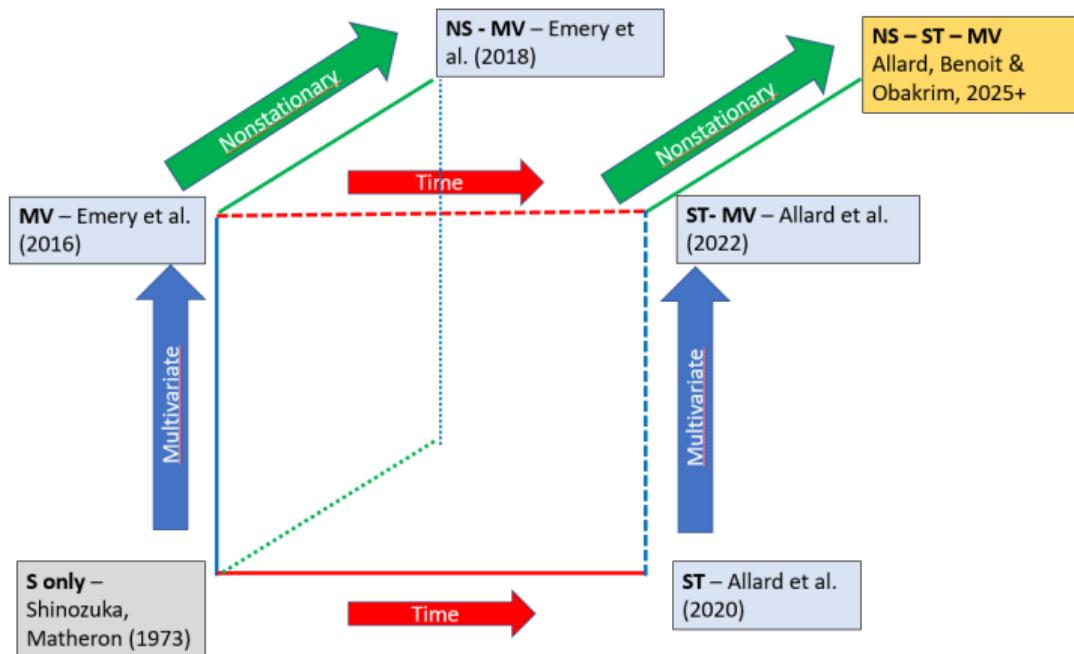
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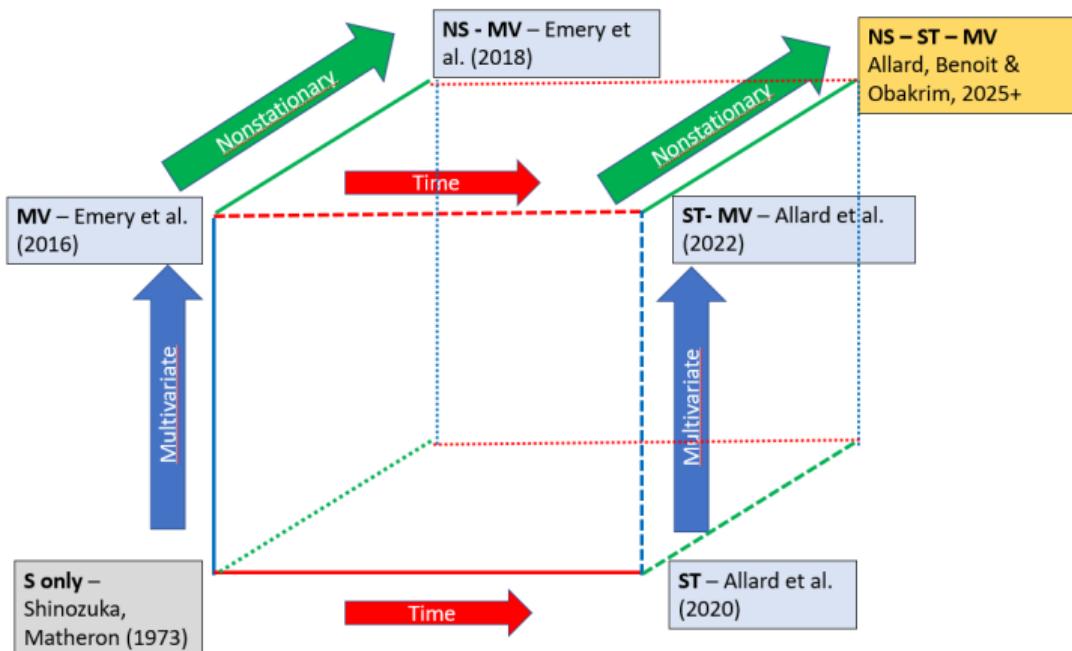
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Extensions of the spectral method



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Introduction

Building bricks

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Gaussian mixtures

Schoenberg (1938)

Define \mathcal{C}_∞ the class of continuous isotropic covariance functions valid on \mathbb{R}^d , $\forall d \geq 1$. Then, $\phi \in \mathcal{C}_\infty$ if and only if

$$\phi(\mathbf{h}) = \int_{\mathbb{R}^+} \exp(-\|\mathbf{h}\|^2 \xi) f(\xi) d\xi$$

$f(\xi)$ is the **Gaussian scale mixture**

Proposition

$$\mu(\omega) = (2\sqrt{\pi})^{-d} \int_0^{+\infty} \exp(-\|\omega\|^2/4\xi) \xi^{-d/2} f(\xi) d\xi$$

In **purple**, spectral density of a Gaussian covariance with scale parameter $\xi^{-1/2}$.

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Geometric anisotropy

Geometric anisotropy in \mathbb{R}^2 (Chilès and Delfiner, 2012)

$$\boldsymbol{\Sigma}^{-1/2} = \begin{pmatrix} r_1 & 0 \\ 0 & r_2 \end{pmatrix} \begin{pmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{pmatrix}, \quad (1)$$

For the Gaussian covariance, one gets:

$$C_G(\mathbf{h}) = \exp\left(-\mathbf{h}^t \boldsymbol{\Sigma}^{-1} \mathbf{h}\right); \quad \mu_G(\boldsymbol{\omega}) = (2\sqrt{\pi})^{-d} |\boldsymbol{\Sigma}|^{1/2} \exp\left(-\boldsymbol{\omega}^t \boldsymbol{\Sigma} \boldsymbol{\omega} / 4\right)$$

Simulation algorithms for stationary univariate spatial GPs

Spectral simulation

Require: $C \in \mathcal{C}_\infty$ and μ

Require: A set of points, $\mathcal{S} \in \mathbb{R}^d$

Require: A large number L

1: **for** $l = 1$ to L **do**

2: **Simulate** $\Omega_l \sim \mu$

3: Simulate $\Phi_l \sim \mathcal{U}(0, 2\pi)$

4: **end for**

5: For each $\mathbf{s} \in \mathcal{S}$ return

$$\tilde{Z}(\mathbf{s}) = \sqrt{\frac{2}{L}} \sum_{l=1}^L \cos(\Sigma^{-1/2} \Omega_l^t \mathbf{s} + \Phi_l)$$

Gaussian mixture simulation

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2: **Simulate** $\xi_l \sim f$

3: **Simulate** $\Omega_l \sim \sqrt{2\xi_l} \mathcal{N}_d(\mathbf{0}, \mathbf{I}_d)$

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Some covariance functions

Matérn covariance

$$C_M(\mathbf{h}) = \frac{\sigma^2}{2^{\nu-1}\Gamma(\nu)}(\kappa||\mathbf{h}||)^\nu K_\nu(\kappa||\mathbf{h}||)$$

$$\mu_M(\omega) \propto \frac{1}{(1 + ||\omega||^2/\kappa^2)^{\nu+d/2}}$$

$$f_M(\xi) = \left(\frac{\kappa^2}{4}\right)^\nu \frac{\xi^{-1-\nu}}{\Gamma(\nu)} e^{-\kappa^2/4\xi}.$$

Hence

2 : Simulate $\xi_I \sim IG(\nu, \kappa^2/4)$

Cauchy covariance

$$C_C(\mathbf{h}) = (1 + a||\mathbf{h}||^2)^{-\nu}$$

μ_C = Unknown

$$f_C(\xi) = a^{-\nu} \Gamma(\nu)^{-1} \xi^{\nu-1} e^{-\xi/a}$$

Hence

2 : Simulate $\xi_I \sim G(\nu, a)$.

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Main take aways

Use Gaussian mixtures

- ▶ Almost identical simulation algorithm
- ▶ Restricted to kernels in \mathcal{C}_∞
- ▶ Paves the way to many extensions

ST extension

Allard et al. (2020)

Gneiting covariance

$$C(\mathbf{h}, u) = \frac{1}{(\gamma(u) + 1)^{\delta + bd/2}} \phi \left(\frac{||\mathbf{h}||}{(\gamma(u) + 1)^{b/2}} \right)$$

with $b \in [0, 1]$ and $\delta > 0$ is a **S-T separability parameter**.

- ▶ Define $W(t) \sim \text{GP}(0, \gamma)$ with $W(0) = 0$
- ▶ Define $Z_T(t) \sim \text{GP}(0, C_T)$ with

$$C_T(u) = \frac{1}{(\gamma(u) + 1)^\delta}$$

Simulation for univariate stationary Gneiting ST GRFs

Require: $C \in \mathcal{C}_\infty$ and associated f ; spatial anisotropy $\Sigma^{-1/2}$

Require: Variogram γ

Require: Parameters $b \in [0, 1]$ and $\delta > 0$

Require: A set of points, $\mathcal{S} \in \mathbb{R}^d \times \mathbb{R}$; a large number L

- 1: **for** $l = 1$ to L **do**
- 2: Simulate a RF $Z_{T,l}$ with covariance function $C_T(u) = (1 + \gamma(u))^{-\delta}$
- 3: Simulate a RF W_l with Gaussian increments and variogram $\gamma_b = (1 + \gamma)^b - 1$
- 4: Simulate $\xi_l \sim f$
- 5: Simulate $\mathbf{V}_l \sim \mathcal{N}_d(0, \mathbf{I}_d)$
- 6: set $\Omega_l = \sqrt{2\xi_l} \Sigma^{-1/2} \mathbf{V}_l$
- 7: Simulate $\Phi_l \sim \mathcal{U}(0, 2\pi)$
- 8: **end for**
- 9: For each $(\mathbf{s}, t) \in \mathcal{S}$ return

$$\tilde{Z}_L(\mathbf{s}, t) = \sqrt{\frac{2}{L}} \sum_{l=1}^L Z_{T,l}(t) \cos \left(\Omega_l^t \mathbf{s} + \frac{\|\mathbf{V}_l\|}{\sqrt{2}} W_l(t) + \Phi_l \right)$$

ST – MV extension

Allard et al. (2022)

Multivariate Gneiting

$$C_{ij}(\mathbf{h}, u) = \frac{\sigma_{ij}}{(\gamma_{ij}(u) + 1)^{\delta+bd/2}} \phi_{ij} \left(\frac{\Sigma^{-1/2} \mathbf{h}}{(\gamma_{ij}(u) + 1)^{b/2}} \right)$$

with $\phi_{ij}(\mathbf{h}) = \int_0^\infty e^{-\xi \|\mathbf{h}\|^2} (f_{ij}(\xi) d\xi)$ and $f_{ij} = \sqrt{f_{ii} f_{jj}}$

For example, for a Matérn covariance: $2\nu_{ij} = \nu_{ii} + \nu_{jj}$ and $2\kappa_{ij}^2 = \kappa_{ii}^2 + \kappa_{jj}^2$

- ▶ γ is a **pseudo-variogram** with $\gamma_{ij}(u) = 0.5 \text{Var} [\mathbf{W}_i(t) - \mathbf{W}_j(t + u)]$
- ▶ Define $(\mathbf{W}_1, \dots, \mathbf{W}_p)$ a p -variate 1d-GP $(0, \gamma)$ with $\mathbf{W}_i(0) = 0$
- ▶ Define $(\mathbf{Z}_{T,1}, \dots, \mathbf{Z}_{T,p})$ a p -variate 1d-GP $(0, [C_{T,ij}]_{ij=1,p})$ with

$$C_{T,ij}(u) = \sigma_{ij} (\gamma_{ij}(u) + 1)^{-\delta}$$

Simulation for p -variate stationary Gneiting ST GRFs

Require: C Matérn or Cauchy and associated f_{ii} ; spatial anisotropy $\Sigma^{-1/2}$

Require: Pseudo variogram γ ; parameters $b \in [0, 1]$ and $\delta > 0$

Require: A covariance matrix $\sigma = LL^t$

Require: A pdf f , with support equal to $(0, \infty)$

Require: A set of points, $\mathcal{S} \in \mathbb{R}^d \times \mathbb{R}$; a large number L

- 1: **for** $l = 1$ to L **do**
- 2: Simulate a p -variate GRF $\mathbf{Z}_{T,l}$ with matrix-valued covariance function $\mathbf{C}_T(u) = (1 + \gamma(u))^{-\delta}$
- 3: Simulate a p -variate RF $\mathbf{W}_l = [\mathbf{W}_{l,i}]_{i=1}^p$ with Gaussian direct and cross-increments, with 0 mean and pseudo-variogram $\gamma_b = (1 + \gamma)^b - 1$
- 4: Simulate $\xi_l \sim f$
- 5: Simulate $\mathbf{V}_l \sim \mathcal{N}_d(0, \mathbf{I}_d)$; set $\Omega_l = \sqrt{2\xi_l} \Sigma^{-1/2} \mathbf{V}_l$; simulate $\Phi_l \sim \mathcal{U}(0, 2\pi)$
- 6: Simulate $\mathbf{A}_l \sim \mathcal{N}_p(0, \sigma)$
- 7: **end for**
- 8: For each $(\mathbf{s}, t) \in \mathcal{S}$ return

$$\tilde{Z}_{L,i}(\mathbf{s}, t) = \sqrt{\frac{2}{L}} \sum_{l=1}^L \mathbf{Z}_{T,l,i}(t) \sqrt{\frac{f_{ii}(\xi_l)}{f(\xi_l)}} \mathbf{A}_{l,i} \cos \left(\Omega_l^t \mathbf{s} + \frac{\|\mathbf{V}_l\|}{\sqrt{2}} \mathbf{W}_{l,i}(t) + \Phi_l \right), \quad i = 1, \dots, p$$

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Introduction

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State of the art

Non-stationary spatial models

Let $\phi \in \mathcal{C}_\infty$ and $\Sigma^{-1/2}(\mathbf{s})$ anisotropy matrices, $\mathbf{s} \in \mathbb{R}^d$. Then,

$$\phi_{NS}(\mathbf{s}, \mathbf{s}') = |\Sigma_{\mathbf{s}}|^{1/4} |\Sigma_{\mathbf{s}'}|^{1/4} |\Sigma_{\mathbf{s}, \mathbf{s}'}|^{-1/2} \phi\left(\sqrt{(\mathbf{s} - \mathbf{s}')^t \Sigma_{\mathbf{s}, \mathbf{s}'}^{-1} (\mathbf{s} - \mathbf{s}')}\right),$$

is a nonstationary covariance on \mathbb{R}^d , with $\Sigma_{\mathbf{s}, \mathbf{s}'} = (\Sigma_{\mathbf{s}} + \Sigma_{\mathbf{s}'})/2$, (Paciorek and Schervish, 2006).

- ▶ It is the covariance function of

$$Z(\mathbf{s}) = \sqrt{\frac{2\mu_{\mathbf{s}}(\Omega)}{\mu_0(\Omega)}} \cos(\Omega^t \mathbf{s} + \Phi), \quad \Omega \sim \mu_0$$

- ▶ Univariate and multivariate simulation algorithms in Emery and Arroyo (2018)

A more general result

- ▶ Consider f belongs to the exponential family

$$f(\xi; \theta) = h(\theta) \exp \left(-\ell(\theta)^t \mathbf{T}(\xi) \right)$$

- ▶ Includes Gamma (Cauchy cov.), Inverse Gamma (Matérn cov.), Beta, Gaussian, Inverse Gaussian, etc.

Theorem (Allard et al., 2025+)

Let $C(\cdot, \theta)$ be an isotropic stationary covariance function in \mathcal{C}_∞ characterized by $f(\cdot; \theta)$. Then,

$$C^*(\mathbf{s}, \mathbf{s}') = |\boldsymbol{\Sigma}_{\mathbf{s}}|^{1/4} |\boldsymbol{\Sigma}_{\mathbf{s}'}|^{1/4} |\boldsymbol{\Sigma}_{\mathbf{s}, \mathbf{s}'}|^{-1/2} C(\boldsymbol{\Sigma}_{\mathbf{s}, \mathbf{s}'}^{-1/2}(\mathbf{s} - \mathbf{s}'); \boldsymbol{\theta}_{\mathbf{s}, \mathbf{s}'}),$$

is a nonstationary covariance on \mathbb{R}^d , where $\boldsymbol{\theta}_{\mathbf{s}, \mathbf{s}'}$ is such that

$$\ell(\boldsymbol{\theta}_{\mathbf{s}, \mathbf{s}'}) = \frac{\ell(\boldsymbol{\theta}_{\mathbf{s}}) + \ell(\boldsymbol{\theta}_{\mathbf{s}'})}{2}.$$

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Construction and example

- ▶ It is the covariance function of

$$Z(\mathbf{s}) = \sqrt{2f(\xi; \theta_s)/f_1(\xi)} \sqrt{\mu_{\Sigma_s}^G(\Omega)/\mu_{I_d}^G(\Omega)} \cos(\Omega^t \mathbf{s} + \Phi),$$

- ▶ Matérn → the covariance in Emery and Arroyo (2018)
- ▶ Cauchy → since $f_c(\xi; (\nu, a)) = a^{-\nu} \Gamma(\nu)^{-1} \xi^{\nu-1} e^{-\xi/a}$, we get $\ell(\theta) = (1 - \nu, 1/a)^t$, $T(\xi) = (\ln \xi, \xi)^t$ and $h(\theta) = a^{-\nu} \Gamma(\nu)^{-1}$. Hence,

$$\ell(\theta_{s,s'}) = \left(1 - (\nu_s + \nu'_{s'})/2, (a_s^{-1} + a'_{s'}^{-1})/2\right)^t, \quad h(\theta_{s,s'}) = \frac{1}{\Gamma((\nu_s + \nu'_{s'})/2)} \left(\frac{2a_s a'_{s'}}{a_s + a'_{s'}}\right)^{-(\nu_s + \nu'_{s'})/2}$$

and

$$\nu_{s,s'} = (\nu_s + \nu'_{s'})/2, \quad a_{s,s'}^{-1} = (a_s^{-1} + a'_{s'}^{-1})/2$$

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$$\ell(\theta_{s,s'}) = \left(1 - (\nu_s + \nu'_s)/2, (\mathbf{a}_s^{-1} + \mathbf{a}'_s^{-1})/2\right)^t, \quad h(\theta_{s,s'}) = \frac{1}{\Gamma((\nu_s + \nu'_s)/2)} \left(\frac{2\mathbf{a}_s \mathbf{a}'_s}{\mathbf{a}_s + \mathbf{a}'_s}\right)^{-(\nu_s + \nu'_s)/2}$$

and

$$\nu_{s,s'} = (\nu_s + \nu_{s'})/2, \quad \mathbf{a}_{s,s'}^{-1} = (\mathbf{a}_s^{-1} + \mathbf{a}'_{s'})/2$$

Construction and example

- ▶ It is the covariance function of

$$Z(\mathbf{s}) = \sqrt{2f(\xi; \theta_s)/f_1(\xi)} \sqrt{\mu_{\Sigma_s}^G(\Omega)/\mu_{I_d}^G(\Omega)} \cos(\Omega^t \mathbf{s} + \Phi),$$

- ▶ Matérn → the covariance in Emery and Arroyo (2018)
- ▶ Cauchy → since $f_C(\xi; (\nu, a)) = a^{-\nu} \Gamma(\nu)^{-1} \xi^{\nu-1} e^{-\xi/a}$, we get $\ell(\theta) = (1 - \nu, 1/a)^t$, $\mathbf{T}(\xi) = (\ln \xi, \xi)^t$ and $h(\theta) = a^{-\nu} \Gamma(\nu)^{-1}$. Hence,

$$\ell(\theta_{s,s'}) = \left(1 - (\nu_s + \nu'_{s'})/2, (\mathbf{a}_s^{-1} + \mathbf{a}'_{s'}^{-1})/2\right)^t, \quad h(\theta_{s,s'}) = \frac{1}{\Gamma((\nu_s + \nu'_{s'})/2)} \left(\frac{2\mathbf{a}_s \mathbf{a}'_{s'}}{\mathbf{a}_s + \mathbf{a}'_{s'}}\right)^{-(\nu_s + \nu'_{s'})/2}$$

and

$$\nu_{s,s'} = (\nu_s + \nu'_{s'})/2, \quad \mathbf{a}_{s,s'}^{-1} = (\mathbf{a}_s^{-1} + \mathbf{a}'_{s'}^{-1})/2$$

Outline

Introduction

Building bricks

Non-stationarity

Full combo

A simulation algorithm for NS MV S-T GRFs

Require: A family of scale mixtures, $f(\cdot; \theta)$, belonging to the exponential family

Require: A set of points, $\mathbf{x} = (\mathbf{s}, t) \in \mathcal{S} \in \mathbb{R}^d \times \mathbb{R}$

Require: Parameters $\theta_{ii, \mathbf{x}}$ and anisotropy matrices $\Sigma_{ii, \mathbf{x}}^{-1/2}$; covariance matrices $\sigma_{\mathbf{x}} = \mathbf{L}_{\mathbf{x}} \mathbf{L}_{\mathbf{x}}^t$

Require: Pseudo variogram γ ; $\delta > 0$

- 1: Set $f_1 := f(\theta)$ for $\theta = 1$
- 2: **for** $l = 1$ to L **do**
- 3: Simulate a p -variate RF $\mathbf{Z}_{T,l}$ with matrix-valued covariance function $\mathbf{C}_T(t) = (1 + \gamma(t))^{-\delta}$
- 4: Simulate a p -variate RF $\mathbf{W}_l = [\mathbf{W}_{l,i}]_{i=1}^p$ with pseudo-variogram γ
- 5: Simulate $\xi_l \sim f_1$
- 6: Simulate $\mathbf{V}_l \sim \mathcal{N}_d(0, \mathbf{I}_d)$; set $\Omega_l = \sqrt{2\xi_l} \mathbf{V}_l$
- 7: Simulate $\Phi_l \sim \mathcal{U}(0, 2\pi)$; Simulate $\mathbf{A}_l \sim \mathcal{N}_p(0, \mathbf{I}_p)$
- 8: **end for**
- 9: For each $\mathbf{x} = (\mathbf{s}, t) \in \mathcal{S}$, and for $i = 1, \dots, p$ return

$$\tilde{Z}_{L,i}(\mathbf{s}, t) = \sqrt{\frac{2}{L}} \sum_{l=1}^L \mathbf{Z}_{T,l,i}(t) \sqrt{\frac{f_{ii, \mathbf{x}}(\xi_l)}{f_1(\xi_l)}} \sqrt{\frac{\mu_{\Sigma_{ii, \mathbf{x}}}^G(\sqrt{2}\mathbf{V}_l)}{\mu_{I_d}^G(\sqrt{2}\mathbf{V}_l)}} (\mathbf{L}_{\mathbf{x}} \mathbf{A}_l)_i \cos \left(\Omega_l^t \mathbf{s} + \frac{\|\mathbf{V}_l\|}{\sqrt{2}} \mathbf{W}_l(t) + \Phi_l \right)$$

Nonstationary multivariate space-time model

Theorem (Allard et al., 2025+)

Let us denote $\mathbf{x} = (\mathbf{s}, t)$. Then,

$$C_{ij}(\mathbf{s}_1, \mathbf{s}_2; t_1, t_2) = |\boldsymbol{\Sigma}_{ii, \mathbf{x}_1}|^{1/4} |\boldsymbol{\Sigma}_{jj, \mathbf{x}_2}|^{1/4} \frac{\sigma_{ij, \mathbf{x}_1 \mathbf{x}_2}}{|\boldsymbol{\Lambda}_{ij, \mathbf{x}_1, \mathbf{x}_2}|^{1/2}} \phi_{ij} \left(\boldsymbol{\Lambda}_{ij, \mathbf{x}_1, \mathbf{x}_2}^{-1/2} (\mathbf{s}_1 - \mathbf{s}_2); \boldsymbol{\theta}_{\mathbf{x}_1, \mathbf{x}_2} \right)$$

where $\boldsymbol{\Lambda}_{ij, \mathbf{x}_1, \mathbf{x}_2} = (\boldsymbol{\Sigma}_{ii, \mathbf{x}_1} + \boldsymbol{\Sigma}_{jj, \mathbf{x}_2})/2 + \boldsymbol{\gamma}_{ij}(t_1 - t_2) \mathbf{I}_d$.

- ▶ Proof: it is the covariance resulting from the Algorithm above

Temporal trace

Theorem (Allard et al., 2025+)

$$C_{Tij}(\mathbf{s}_1, \mathbf{s}_1; t_1, t_2) = |\boldsymbol{\Sigma}_{ii, \mathbf{x}_1}|^{1/4} |\boldsymbol{\Sigma}_{jj, \mathbf{x}_2}|^{1/4} \frac{\sigma_{ij, \mathbf{x}_1 \mathbf{x}_1}}{|\boldsymbol{\Sigma}_{ij, \mathbf{x}_1} + \gamma_{ij}(t_1 - t_2) \mathbf{I}_d|^{1/2}}$$

where $\boldsymbol{\Sigma}_{ij, \mathbf{x}_1} = (\boldsymbol{\Sigma}_{ii, \mathbf{x}_1} + \boldsymbol{\Sigma}_{jj, \mathbf{x}_1})/2$

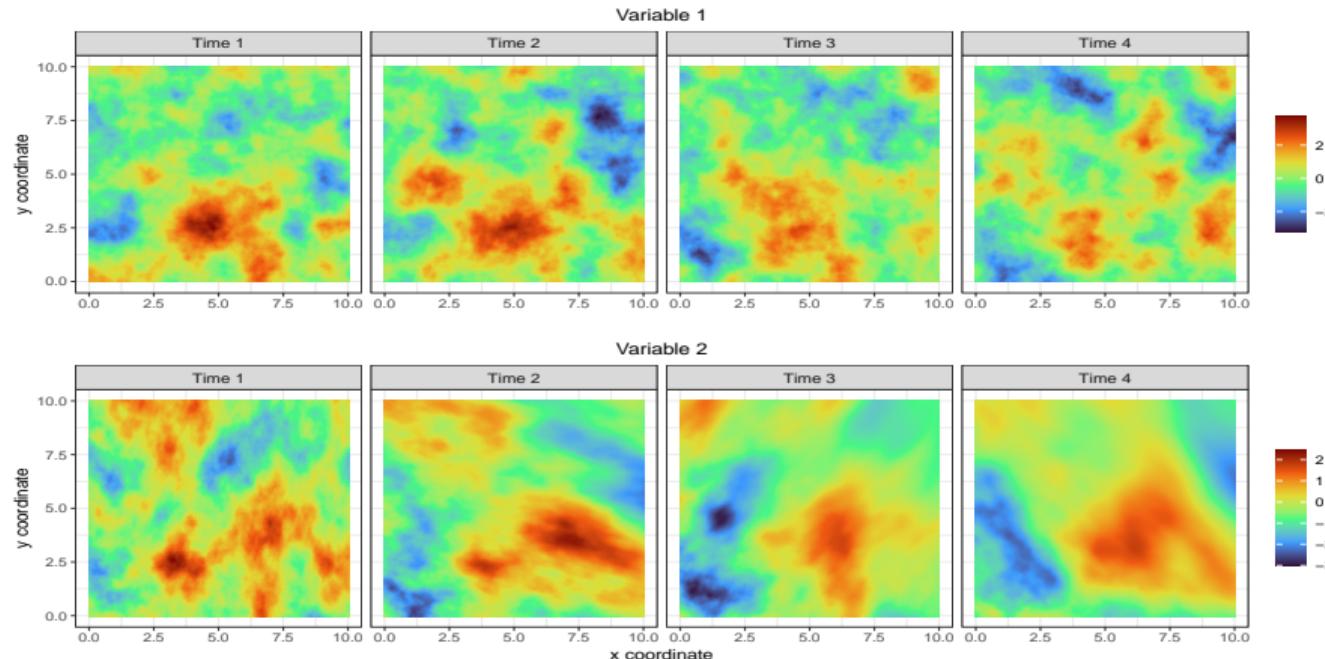
- ▶ The temporal correlation trace is thus

$$|\boldsymbol{\Sigma}_{ij, \mathbf{x}_1} + \gamma_{ij}(u) \mathbf{I}_d|^{-1/2}$$

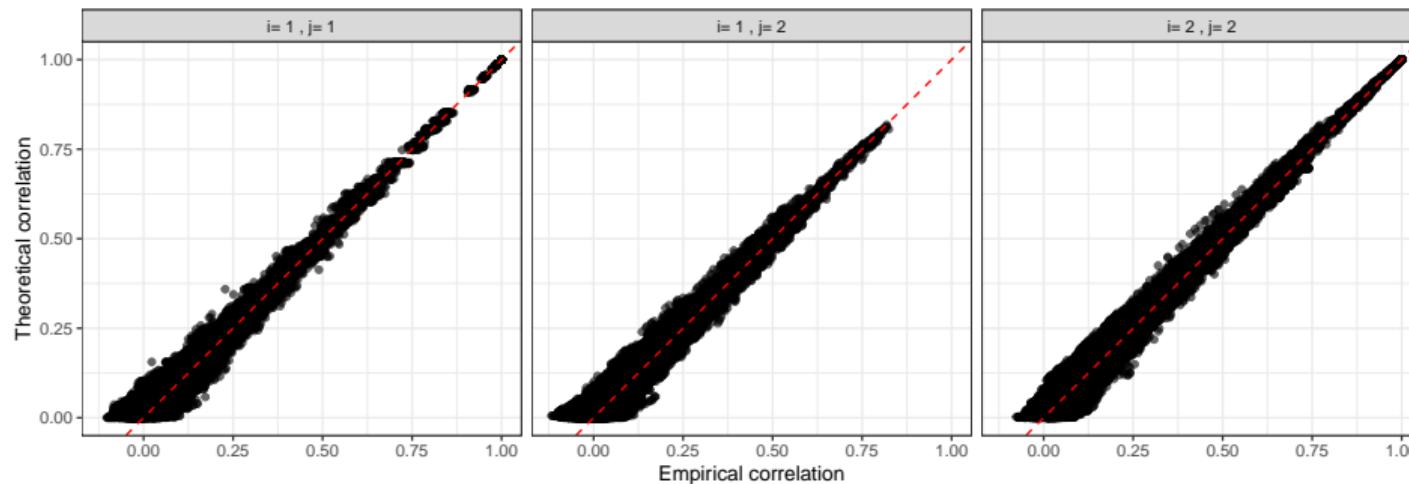
- ▶ It is non stationary in space !

The **spatial trace** is identical to the construction in Paciorek and Schervish (2006).

Illustration



Illustration



Final words

- ▶ We propose a change of perspective: from spectral representation to Gaussian mixture representation
- ▶ It paves the way to general theorem allowing for the construction of a new and wide class of nonstationary covariance functions
- ▶ Two well separated steps: i) stochastic generation; ii) projection onto \mathcal{S}
- ▶ The second step is massively parallelizable
- ▶ Possible extensions to non Euclidean spaces

<https://hal.inrae.fr/hal-05034982>

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