Controllability properties of coupled PDEs



Emmanuel Trélat



(ongoing) works with Hugo Lhachemi and Christophe Prieur

Toulouse, Conference TRECOS ANR project

Coupled systems

Some (nonexhaustive!) bibliography on control and stabilization

of coupled (parabolic / hyperbolic) systems:

Lebeau Zuazua 1998 Zuazua 2001

Zhang Zuazua 2003-2004

Fernandez-Cara de Teresa 2004

Ammar Khodja Benabdallah Dupaix Gonzalez-Burgos de Teresa 2009-2016

Beauchard Zuazua 2011

Badra Takahashi 2014

Wang Krstic 2015 Wang Su Li 2015

Ammar Khodja Chouly Duprez 2016

Kang Guo 2016

Alabau Coron Olive 2017 Chen Vazquez Krstic 2017

Ghousein Witrant 2020

Katz Fridman 2020

Beauchard Koenig Le Balc'h 2020 Benabdallah Boyer Morancey 2020

Xu Liu Krstic Feng 2023

Auriol 2020-2024 Hu Olive 2020-2025 Boyer Olive 2024

Bhandari Boyer 2021

Bhandari Chowdhury Dutta Majumdar Kumbhakar 2023-2024

Tang Wang Kang 2024-2025

Ammar Khodja Benabdallah Gonzalez-Burgos Morancey de Teresa 2026?

Boyer book 2026?

 $c \in \mathbb{R}$, $\beta \in L^{\infty}(0,1)$ coupling function

(1D) Wave-heat cascade

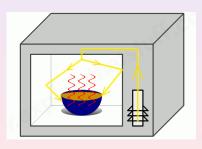
$$\partial_t y = \partial_{xx} y + c y + \beta z,$$

$$\partial_{tt}z = \partial_{xx}z,$$
 $z(t,0) =$

$$z(t,0) = 0$$
, $\partial_x z(t,1) = u(t)$

y(t,0) = y(t,1) = 0

Simplified model for control of microwave heating



Objectives: controllability properties; output feedback stabilization

Seminal paper on controllability of 1D hyperbolic-parabolic coupled systems:



X. Zhang, E. Zuazua, CRAS 2003 and JDE 2004.

$$\partial_t y = \partial_{xx} y$$

$$\partial_{tt} z = \partial_{xx} z$$

$$\partial_x y(t, 0) = \partial_x z(t, 0)$$

$$y(t, 1) = z(t, 1) = 0$$

What they did:

- Riesz spectral analysis.
- Establish and use an Ingham-Müntz inequality.
- \Rightarrow Controllability in a Hilbert space with exponential weights + polynomial decay.

Ingham-Müntz inequality

(parabolic part: Müntz-Sász)
$$\lambda_{1,n} \in \mathbb{C} \ (n \in \mathbb{N}^*) \ \text{satisfying:}$$

$$\exists \alpha > 1 \quad | \quad (\lambda_{1,n}/n^{\alpha})_{n \in \mathbb{N}^*} \ \text{ is bounded}$$

$$\exists n_0 \in \mathbb{N}^* \quad C_1, C_2 > 0 \quad | \quad -\operatorname{Re}(\lambda_{1,n}) \geqslant C_1 \operatorname{Im}(\lambda_{1,n}) \qquad \forall n \geqslant n_0$$

$$|\lambda_{1,n} - \lambda_{1,n'}| \geqslant C_2 |n^{\alpha} - n'^{\alpha}| \qquad \forall n, n' \geqslant n_0$$

(hyperbolic part: Ingham)
$$\lambda_{2,m} \in \mathbb{C}$$
 $(m \in \mathbb{Z})$ distinct, satisfying:

$$\exists m_0 \in \mathbb{N} \quad \gamma > 0 \quad z_0 \in \mathbb{C} \quad (\mu_m)_{m \in \mathbb{Z}} \in \ell^2(\mathbb{Z}) \quad | \quad \lambda_{2,m} = \gamma \, i \, m + z_0 + \mu_m \quad \forall |m| \geqslant m_0$$

Then:
$$\forall T > \frac{2\pi}{\gamma} \quad \exists C_T > 0 \text{ s.t.}$$

$$\int_0^T \Big| \sum_{n \in \mathbf{N}^*} a_n e^{\lambda_{1,n}t} + \sum_{m \in \mathbb{Z}} b_m e^{\lambda_{2,m}t} \Big|^2 dt \geqslant C_T \bigg(\sum_{n \in \mathbf{N}^*} |a_n|^2 e^{2\operatorname{Re}(\lambda_{1,n})T} + \sum_{m \in \mathbb{Z}} |b_m|^2 \bigg) \\ \forall (a_n)_{n \in \mathbf{N}^*}, (b_m)_{m \in \mathbb{Z}} \in \ell^2(\mathbb{Z})$$

$$\partial_t y = \partial_{xx} y + c y + \beta z,$$
 $y(t,0) = y(t,1) = 0$
 $\partial_t z = \partial_{xx} z,$ $z(t,0) = 0,$ $\partial_x z(t,1) = u(t)$

of the form

$$\dot{\mathcal{X}}(t) = \mathcal{A}_0 \mathcal{X}(t) + \mathcal{B}_0 u(t)$$
 with $\mathcal{X} = \begin{pmatrix} y \\ z \\ \partial_t z \end{pmatrix}$

Well-posed system (i.e., \mathcal{B}_0 admissible) with:

$$\mathcal{A}_{0}: D(A_{0}) \to \mathcal{H}^{0}$$

$$\mathcal{H}^{0} = L^{2}(0,1) \times H^{1}_{(0)}(0,1) \times L^{2}(0,1), \qquad H^{1}_{(0)}(0,1) = \{g \in H^{1}(0,1) \mid g(0) = 0\}$$

$$\mathcal{A}_{0} = \begin{pmatrix} \partial_{xx} + c \operatorname{id} & \beta \operatorname{id} & 0 \\ 0 & 0 & \operatorname{id} \\ 0 & \partial_{xx} & 0 \end{pmatrix}$$

$$D(A_{0}) = \{(f,g,h) \in H^{2}(0,1) \times H^{2}(0,1) \times H^{1}(0,1) \mid f(0) = f(1) = g(0) = g'(1) = h(0) = 0\}$$

$$\bullet \ \mathcal{B}_0 \in \mathit{L}(\mathbb{R}, \mathit{D}(\mathcal{A}_0^*)') \ \text{given by} \ \mathcal{B}_0^* \phi = \phi_3(1) \quad \forall \phi = (\phi_1, \phi_2, \phi_3)^\top \in \mathit{D}(\mathcal{A}_0^*)$$

Spectral properties of A_0 :

• Parabolic part $(n \in \mathbb{N}^*)$:

$$\lambda_{1,n} = c - n^2 \pi^2, \qquad \phi_{1,n} = (\phi_{1,n}^1, \phi_{1,n}^2, \phi_{1,n}^3)^{\top}$$

$$\phi_{1,n}^1(x) = \sqrt{2}\sin(n\pi x), \qquad \phi_{1,n}^2(x) = \phi_{1,n}^3(x) = 0$$

• Hyperbolic part $(m \in \mathbb{Z})$:

$$\lambda_{2,m} = (m+1/2)i\pi, \qquad \phi_{2,m} = (\phi_{2,m}^1, \phi_{2,m}^2, \phi_{2,m}^3)^{\top}$$

$$\begin{split} \phi_{2,m}^1(x) &= \frac{1}{A_m r_m} \int_x^1 \beta(s) \sinh(\lambda_{2,m} s) \sinh(r_m(x-s)) \, \mathrm{d}s + \frac{\sinh(r_m(1-x))}{A_m r_m \sinh(r_m)} \int_0^1 \beta(s) \sinh(\lambda_{2,m} s) \sinh(r_m s) \, \mathrm{d}s \\ \phi_{2,m}^2(x) &= \frac{1}{A_m} \sinh(\lambda_{2,m} x), \qquad \phi_{2,m}^3(x) &= \frac{\lambda_{2,m}}{A_m} \sinh(\lambda_{2,m} x) \end{split}$$

where r_m is a square root of $\lambda_{2,m}-c$ of nonnegative real part, and $A_m=|\lambda_{2,m}|=|m+1/2|\pi$.

Adjoint operator $\mathcal{A}_0^*: \textit{D}(\mathcal{A}_0^*) \to \mathcal{H}^0$

$$\mathcal{A}_0^* = \begin{pmatrix} \partial_{xx} + c \operatorname{id} & 0 & 0 \\ P_{\beta} & 0 & -\operatorname{id} \\ 0 & -\partial_{xx} & 0 \end{pmatrix}$$

where $P_{\beta}f=\int_{0}^{(\cdot)}\int_{ au}^{1}eta(s)f(s)\,\mathrm{d}s\,\mathrm{d} au$ and

$$D(\mathcal{A}_0^*) = \left\{ (f, g, h) \in H^2(0, 1) \times H^2(0, 1) \times H^1(0, 1) \mid f(0) = f(1) = g(0) = g'(1) = h(0) = 0 \right\}$$

Spectral properties of \mathcal{A}_0^* :

• Parabolic part $(n \in \mathbf{N}^*)$: $\lambda_{1,n} = c - n^2 \pi^2$, $\psi_{1,n} = (\psi_{1,n}^1, \psi_{1,n}^2, \psi_{1,n}^3)^\top$

$$\begin{split} & \psi_{1,n}^{1}(x) = \sqrt{2}\sin{(n\pi x)} \\ & \psi_{1,n}^{2}(x) = -\frac{\gamma_{n}}{\lambda_{1,n}^{2}\cosh(\lambda_{1,n})} \sqrt{2}\cosh(\lambda_{1,n}(x-1)) \\ & -\frac{1}{\lambda_{1,n}^{2}} \sqrt{2} \int_{x}^{1} \beta(s)\sin{(n\pi s)}\sinh(\lambda_{1,n}(x-s)) \, \mathrm{d}s - \frac{1}{\lambda_{1,n}} \sqrt{2} \int_{0}^{x} \int_{1}^{\tau} \beta(s)\sin{(n\pi s)} \, \mathrm{d}s \, \mathrm{d}\tau \\ & \psi_{1,n}^{3}(x) = \frac{\gamma_{n}}{\lambda_{1,n}\cosh(\lambda_{1,n})} \sqrt{2}\cosh(\lambda_{1,n}(x-1)) + \frac{1}{\lambda_{1,n}} \sqrt{2} \int_{x}^{1} \beta(s)\sin{(n\pi s)}\sinh(\lambda_{1,n}(x-s)) \, \mathrm{d}s \end{split}$$

with $\gamma_n = \int_0^1 \beta(s) \sin(n\pi s) \sinh(\lambda_{1,n} s) ds$ (important role in what follows)

• Hyperbolic part $(m \in \mathbb{Z})$: $\lambda_{2,m} = (m+1/2)i\pi, \quad \psi_{2,m} = (\psi_{2,m}^1, \psi_{2,m}^2, \psi_{2,m}^3)^\top$

$$\psi_{2,m}^1(x) = 0, \quad \psi_{2,m}^2(x) = \frac{A_m}{|\lambda_{2,m}|^2} \sinh(\lambda_{2,m}x), \quad \psi_{2,m}^3(x) = \frac{A_m\lambda_{2,m}}{|\lambda_{2,m}|^2} \sinh(\lambda_{2,m}x).$$

$$\begin{split} \Phi &= \{\phi_{1,n} \mid n \in \mathbb{N}^*\} \cup \{\phi_{2,m} \mid m \in \mathbb{Z}\} \text{ is a Riesz basis of } \mathcal{H}^0 = \mathit{L}^2 \times \mathit{H}^1_{(0)} \times \mathit{L}^2, \\ \text{of dual Riesz basis } \Psi &= \{\psi_{1,n} \mid n \in \mathbb{N}^*\} \cup \{\psi_{2,m} \mid m \in \mathbb{Z}\}. \end{split}$$

Hence, \mathcal{A}_0 is a Riesz spectral operator and

$$e^{t\mathcal{A}_0}\mathcal{X} = \sum_{\textbf{n} \in \mathbf{N}^*} e^{\lambda_{1,\textbf{n}}t} \left\langle \mathcal{X}, \psi_{1,\textbf{n}} \right\rangle \phi_{1,\textbf{n}} + \sum_{\textbf{m} \in \mathbb{Z}} e^{\lambda_{2,\textbf{m}}t} \left\langle \mathcal{X}, \psi_{2,\textbf{m}} \right\rangle \phi_{2,\textbf{m}} \qquad \forall \mathcal{X} \in \mathcal{H}^0.$$

Similarly for \mathcal{A}_0^* .

Exact (null) controllability for $\dot{\mathcal{X}}(t)=\mathcal{A}_0\mathcal{X}(t)+\mathcal{B}_0u(t)$ in some Hilbert space V (V_0) is equivalent, by duality, to the observability inequality

$$\begin{split} \int_0^T |\mathcal{X}^3(t,1)|^2 \, \mathrm{d}t &\geqslant C_T \|\mathcal{X}(0,\cdot)\|_{V'}^2 \qquad \left(\|\mathcal{X}(T,\cdot)\|_{V_0'}^2\right) \\ \text{for any solution } \mathcal{X} &= \begin{pmatrix} \mathcal{X}^1 \\ \mathcal{X}^2 \\ \mathcal{X}^3 \end{pmatrix} \text{ of the dual system } \dot{\mathcal{X}}(t) = \mathcal{A}_0^* \mathcal{X}(t). \end{split} \tag{pivot space \mathcal{H}^0}$$

Exact (null) controllability for $\dot{\mathcal{X}}(t) = \mathcal{A}_0 \mathcal{X}(t) + \mathcal{B}_0 u(t)$ in some Hilbert space $V(V_0)$ is equivalent, by duality, to the observability inequality

$$\int_0^T |\mathcal{X}^3(t,1)|^2 \,\mathrm{d}t \geqslant C_T \|\mathcal{X}(0,\cdot)\|_{V'}^2 \qquad \left(\|\mathcal{X}(T,\cdot)\|_{V_0'}^2\right)$$
 for any solution $\mathcal{X} = \begin{pmatrix} \mathcal{X}^1 \\ \mathcal{X}^2 \\ \mathcal{X}^3 \end{pmatrix}$ of the dual system $\dot{\mathcal{X}}(t) = \mathcal{A}_0^* \mathcal{X}(t)$. (pivot space \mathcal{H}^0)

$$\text{Since } \mathcal{X}^3(t,1) = \sum_{n \in \mathbf{N}^*} e^{\lambda_{1,n}t} \left\langle \mathcal{X}(\mathbf{0}), \phi_{1,n} \right\rangle \psi_{1,n}^3(\mathbf{1}) + \sum_{m \in \mathbb{Z}} e^{\bar{\lambda}_{2,m}t} \left\langle \mathcal{X}(\mathbf{0}), \phi_{2,m} \right\rangle \psi_{2,m}^3(\mathbf{1}),$$

it follows from the Ingham-Müntz inequality that $\forall T > 2 \quad \exists \operatorname{Cst} > 0 \quad \text{s.t.}$

$$\int_{0}^{T} |\mathcal{X}^{3}(t,1)|^{2} dt \geqslant \operatorname{Cst} \sum_{n \in \mathbb{N}^{*}} |\langle \mathcal{X}(0), \phi_{1,n} \rangle|^{2} |\psi_{1,n}^{3}(1)|^{2} \underbrace{e^{2\lambda_{1,n}T}}_{\sim \operatorname{Cst} e^{-2n^{2}\pi^{2}T}} + \operatorname{Cst} \sum_{m \in \mathbb{Z}} |\langle \mathcal{X}(0), \phi_{2,m} \rangle|^{2} |\psi_{2,m}^{3}(1)|^{2} \underbrace{\psi_{2,m}^{3}(1)|^{2}}_{\operatorname{as} |m| \gg 1}$$

$$\geqslant \operatorname{Cst} \left(\sum_{n \in \mathbb{N}^{*}} |\langle \mathcal{X}(0), \phi_{1,n} \rangle|^{2} \frac{\gamma_{n}^{2}}{n^{4}} e^{-\nu n^{2}} + \sum_{m \in \mathbb{Z}} |\langle \mathcal{X}(0), \phi_{2,m} \rangle|^{2} \right) \quad \text{with} \quad \nu = 2\pi^{2}(1+T)$$

$$\text{this defines } \|\mathcal{X}(0,\cdot)\|_{\mathcal{U}}^{2}$$

Exact (null) controllability for $\dot{\mathcal{X}}(t)=\mathcal{A}_0\mathcal{X}(t)+\mathcal{B}_0u(t)$ in some Hilbert space V (V_0) is equivalent, by duality, to the observability inequality

$$\int_{0}^{T} |\mathcal{X}^{3}(t,1)|^{2} dt \geqslant C_{T} \|\mathcal{X}(0,\cdot)\|_{V'}^{2} \qquad \left(\|\mathcal{X}(T,\cdot)\|_{V'_{0}}^{2}\right)$$

for any solution
$$\mathcal{X} = \begin{pmatrix} \mathcal{X}^1 \\ \mathcal{X}^2 \\ \mathcal{X}^3 \end{pmatrix}$$
 of the dual system $\dot{\mathcal{X}}(t) = \mathcal{A}_0^* \mathcal{X}(t)$. (pivot space \mathcal{H}^0)

This leads to define

$$V' = \left\{ \sum_{n \in \mathbb{N}^*} a_n \psi_{1,n} + \sum_{m \in \mathbb{Z}} b_m \psi_{2,m} \quad | \quad \sum_{n \in \mathbb{N}^*} |a_n|^2 \frac{\gamma_n^2}{n^4} e^{-\nu n^2} + \sum_{m \in \mathbb{Z}} |b_m|^2 < +\infty \right\}$$

where $\nu = 2\pi^2(1+T)$. Endowed with the norm

$$\|\mathcal{X}\|_{V'}^2 = \sum_{n \in \mathbb{N}^*} |\langle \mathcal{X}, \phi_{1,n} \rangle|^2 \frac{\gamma_n^2}{n^4} e^{-\nu n^2} + \sum_{m \in \mathbb{Z}} |\langle \mathcal{X}, \phi_{2,m} \rangle|^2$$

V' is a Hilbert space under the assumption that $\gamma_n \neq 0$ for any $n \in \mathbb{N}^*$.

 \Rightarrow We have observability in this space V'.

Exact (null) controllability for $\dot{\mathcal{X}}(t)=\mathcal{A}_0\mathcal{X}(t)+\mathcal{B}_0u(t)$ in some Hilbert space V (V_0) is equivalent, by duality, to the observability inequality

$$\int_{0}^{T} |\mathcal{X}^{3}(t,1)|^{2} dt \ge C_{T} \|\mathcal{X}(0,\cdot)\|_{V'}^{2} \qquad \left(\|\mathcal{X}(T,\cdot)\|_{V'_{0}}^{2}\right)$$

 $\text{for any solution } \mathcal{X} = \begin{pmatrix} \mathcal{X}^1 \\ \mathcal{X}^2 \\ \mathcal{X}^3 \end{pmatrix} \text{ of the dual system } \dot{\mathcal{X}}(t) = \mathcal{A}_0^* \mathcal{X}(t). \tag{pivot space } \mathcal{H}^0)$

By duality, if $\gamma_n \neq 0$ for any $n \in \mathbb{N}^*$, we have exact controllability in

$$V = \left\{ \sum_{n \in \mathbb{N}^*} a_n \phi_{1,n} + \sum_{m \in \mathbb{Z}} b_m \phi_{2,m} \quad | \quad \sum_{n \in \mathbb{N}^*} |a_n|^2 \frac{n^4}{\gamma_n^2} e^{\nu n^2} + \sum_{m \in \mathbb{Z}} |b_m|^2 < +\infty \right\}$$

where $\nu = 2\pi^2(1+T)$, endowed with the norm

$$\|\mathcal{X}\|_{V}^{2} = \sum_{n \in \mathbb{N}^{*}} |\langle \mathcal{X}, \psi_{1,n} \rangle|^{2} \frac{n^{4}}{\gamma_{n}^{2}} e^{\nu n^{2}} + \sum_{m \in \mathbb{Z}} |\langle \mathcal{X}, \psi_{2,m} \rangle|^{2}$$

Recall that $\gamma_n = \int_0^1 \beta(s) \sin(n\pi s) \sinh(\lambda_{1,n} s) ds$ (different expression when $\lambda_{1,n} = 0$).

Similarly, we have exact null controllability in V_0 defined like V but with $\nu=2\pi^2$.

$$\partial_t y = \partial_{xx} y + c y + \beta z,$$
 $y(t,0) = y(t,1) = 0$
 $\partial_{tt} z = \partial_{xx} z,$ $z(t,0) = 0,$ $\partial_x z(t,1) = u(t)$

$$V \subset V_0 \subset \mathcal{H}^0 \subset V_0' \subset V'$$
 $\gamma_n = \int_0^1 \beta(s) \sin(n\pi s) \sinh(\lambda_{1,n} s) ds$ (continuous and dense embeddings)

Theorem (Lhachemi Prieur Trélat 2025)

If T > 2 and $\gamma_n \neq 0 \quad \forall n \in \mathbb{N}^*$ then:

 \bigcirc Exact controllability in time T in V.

(but solutions live in \mathcal{H}^0)

- 2 Exact null controllability in time T in V_0 .
- Approximate controllability in time T in \mathcal{H}^0 (or in any other Hilbert space s.t. $H \subset \mathcal{H}^0$ or $\mathcal{H}^0 \subset H$ with continuous and dense embeddings).

If T<2 or if $\gamma_n=0$ for some $n\in \mathbb{N}^*$ then no exact / exact null / approximate controllability in any time T>0, in any Hilbert space s.t. $H\subset \mathcal{H}^0$ or $\mathcal{H}^0\subset H$ with continuous and dense embeddings.

$$V = \left\{ \sum_{n \in \mathbb{N}^*} a_n \phi_{1,n} + \sum_{m \in \mathbb{Z}} b_m \phi_{2,m} \ | \ \sum_{n \in \mathbb{N}^*} |a_n|^2 \frac{n^4}{\gamma_n^2} e^{\nu n^2} + \sum_{m \in \mathbb{Z}} |b_m|^2 < +\infty \right\} \\ \qquad \gamma_n = \int_0^1 \beta(s) \sin\left(n\pi s\right) \sinh(\lambda_{1,n} s) \, \mathrm{d}s$$

Comments:

- Compared with $\mathcal{H}^0 = L^2(0,1) \times H^1_{(0)}(0,1) \times L^2(0,1)$, the spaces V and V_0 are much smaller than \mathcal{H}^0 in the a_n components, but they coincide with \mathcal{H}^0 in the b_m components.
- The controllability spaces V and V_0 are "almost sharp".
- These are non-conventional Hilbert spaces: depending on the coupling function β , the coefficient γ_n may wildly oscillate.

The subset \hat{S} of $S = \{(a,b) \mid 0 \le a < b \le 1\}$ such that $\gamma_n \ne 0$ for any $n \in \mathbb{N}^*$ is dense and of full Lebesgue measure in S.

Feedback stabilization:

Exact null controllability \Rightarrow (complete) stabilizability in V_0 , with a linear feedback

BUT how to define such a feedback in practice?

Actually, thanks to the spectral analysis done, we obtain:

Theorem (Lhachemi Prieur Trélat 2025)

Given any $\delta >$ 0, there exists an output-feedback control

based on the two measurements

$$y_o(t) = \int_0^1 c_o(x)y(t,x) dx$$
 for some (generic) $c_o \in L^2(0,1)$
 $c_o(t) = \partial_t z(t,1)$

• explicitly built from a finite number of spectral modes (depending on δ) making the system exponentially stable in $H_0^1(0,1) \times H_{(0)}^1(0,1) \times L^2(0,1)$ with the decay rate δ .

And for heat-wave?

We have obtained a sharp controllability result for:

(1D) Wave-heat cascade

$$\partial_t y = \partial_{xx} y + c y + \beta z,$$
 $y(t,0) = y(t,1) = 0$
 $\partial_{tt} z = \partial_{xx} z,$ $z(t,0) = 0, \quad \partial_x z(t,1) = u(t)$

Now let us "switch":

(1D) Heat-wave cascade

$$\partial_t y = \partial_{xx} y + c y,$$
 $y(t,0) = y(t,1) = u(t)$
 $\partial_t z = \partial_{xx} z + \beta y,$ $z(t,0) = 0, \quad \partial_x z(t,1) = 0$

Similar eigenelements computations

 $\Rightarrow \forall T > 2$ controllability in some spectrally defined (unconventional) Hilbert space

BUT when $\mathrm{supp}(\beta)=[0,1]$ (e.g., $\beta=1$) we may expect to have controllability $\forall T>0$!! How to do?

And for heat-wave?

Let me mention:

(Multi-D) Heat-wave cascade in Ω

$$\partial_t y = \triangle y + \chi_{\omega_1} u$$

$$y(t,\cdot)_{|\partial\Omega}=0$$

$$\partial_{tt}z = \partial_{xx}z + \chi_{\omega_2}y$$

$$z(t,\cdot)_{|\partial\Omega}=0$$

Fernandez-Cara, de Teresa, DCDS 2004

If $\omega_1 \cap \omega_2$ satisfies "the multiplier domain condition" (stronger than GCC), then exact null controllability in $H^{-1}(\Omega) \times H^1_0(\Omega) \times L^2(\Omega)$ in time $T > T_0$.

- Expected because on $\omega_1 \cap \omega_2$ we can choose y as we want and control the wave equation in time $T > T_0$.
- The difficult case would be when ω₁ ∩ ω₂ = ∅...
 (or when the heat equation is controlled at the boundary)
 Conjecture:

Controllability in some unconventional Hilbert space, at least if $T>T_0$. For $T< T_0$, I do not know.

Heat-heat cascade system

Heat-heat cascade

$$\partial_t y = \partial_{xx} y + ay$$
 $a, b \in \mathbb{R}, \quad s \neq 0$
 $\partial_t z = \partial_{xx} z + bz$
 $\partial_x y(t, 0) = sz(t, 0), \quad y(t, 1) = \partial_x z(t, 1) = 0$
 $\partial_x z(t, 0) = u(t)$

studied by Tang Wang Kang (SCL 2024 and Automatica 2025)

Theorem (Lhachemi Prieur Trélat 2025)

Exact null controllability in any time T > 0 in

$$\begin{split} V_0 \ / \ V &= \bigg\{ \sum_{n \in \mathbb{N}} a_n \phi_{1,n} + \sum_{m \in \mathbb{N}} b_m \phi_{2,m} \quad | \quad a_n, b_n \in \mathbb{R}, \\ &\qquad \sum_{n \in \mathbb{N}} \Big(1 + \frac{n^4}{s^2 (a - b)^2} \Big) e^{2T(n + 1/2)^2 \pi^2} |a_n|^2 + \sum_{m \in \mathbb{N}} |b_m|^2 e^{2Tm^2 \pi^2} < + \infty \bigg\}. \end{split}$$

Under (explicit, necessary and sufficient) controllability and observability conditions, the system can be exponentially stabilized at any decay rate in $H^1(0,1) \times H^1(0,1)$, with an explicit output-feedback control.

N-heat cascade system

Generalization to:

N-heat cascade

$$\begin{aligned} y_t^j &= y_{xx}^j + a_j y^j & 1 \leqslant j \leqslant N & a_1, \dots, a_N \in \mathbb{R} \\ y_x^j(t,0) &= y^{j+1}(t,1), & y_x^j(t,1) &= 0 & 1 \leqslant j \leqslant N-1 \\ y_x^N(t,0) &= u(t), & y_x^N(t,1) &= 0 & \end{aligned}$$

either with two-by-two distinct eigenvalues, or with $a_1 = \cdots = a_N$.

Minimal time for parabolic systems

Coupled parabolic system

$$\partial_t y = \partial_{xx} y + \beta z$$

$$y(t,0)=y(t,1)=0$$

 $\partial_t z = \partial_{xx} z + \chi_\omega u$

$$z(t,0)=z(t,1)=0$$

with

$$\operatorname{supp}(\beta)\cap\omega=\emptyset$$

Well-posed in $L^{2}(0,1) \times L^{2}(0,1)$ (with $u \in L^{2}(0,T)$).

Ammar Khodja, Benabdallah, Gonzalez-Burgos, de Teresa (JMAA 2016)

Under a spectral condition on β , there exists $T_0(\beta)$ (explicit) such that the system is

- exactly null controllable in time $T > T_0(\beta)$,
- not exactly null controllable in time $T < T_0(\beta)$.

(proof by moment method)

Minimal time for parabolic systems

Coupled parabolic system

$$\partial_t y = \partial_{xx} y + \beta z$$
 $y(t,0) = y(t,1) = 0$

$$\partial_t z = \partial_{xx} z + \chi_\omega u$$
 $z(t,0) = z(t,1) = 0$

with

$$\operatorname{supp}(\beta)\cap\omega=\emptyset$$

Well-posed in $L^2(0,1) \times L^2(0,1)$ (with $u \in L^2(0,T)$).

We make their statement more precise:

Lhachemi Prieur Trélat, ongoing

Under a spectral condition on β , the system is **always** exactly null controllable, but the controllability space V_T depends on T:

$$V_T = \left\{ \begin{array}{ll} L^2(0,1) \times L^2(0,1) & \text{if } T > T_0(\beta) \\ \text{much smaller, spectrally defined} & \text{if } T < T_0(\beta) \\ \text{(thanks to Müntz-Sász)} \end{array} \right.$$

Generalization to a larger number of coupled parabolic equations, with more "bifurcation" times (ongoing work).

Conclusion

- Ingham-Müntz as an instrumental tool for coupled 1D PDEs.
- Unconventional controllability spaces for internal couplings.

Many questions:

- Coupled 1D PDEs with time-varying coefficients?
- Multi-D case?
 - → combine Carleman with microlocal analysis?
 - \rightarrow "Ingham-Lebeau-Robbiano" inequalities?
- Plenty of other cascade or coupled systems.
- Semilinear case.