Parareal methods and averaged models for solving stiff differential equations – Applications

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Strasbourg, August 2024

Joint work with Laura Grigori, Julien Salomon, Pierre-Henri Tournier

Summer school "New trends in computing", Strasbourg









Outline

- 1 Introduction
- 2 Vlasov equation
- 3 Vlasov-Poisson system

The problems of interest and reduced models Numerical Parareal results

Performance analysis Pipelined version Speedups

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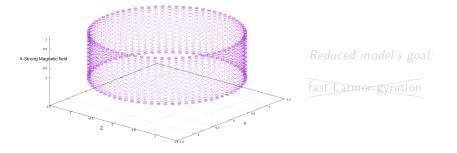
Motivation

Complex dynamics of charged particles (ions and free electrons) in electro-magnetic fields.

→ Plasma confinement under large magnetic and/or electric field.

Multiscale dynamics in time.

Example.



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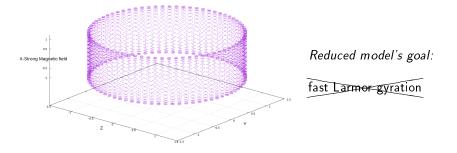
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Multiscale dynamics in time.

Example:

fast Larmor gyration \ll parallel motion \ll drift across field lines.



Motivation

Aim: propose a time stepping for solving <u>accurately</u> and <u>rapidly</u> in times $T_{\rm end} \sim 1/\varepsilon$ stiff equations.

Ingredients:

- Parareal algorithm: A time-stepping scheme for parallel in time computations.
- Reduced models: Zero-order approximations of the multiscale equations.

The parareal strategy

Question: what choice for the coarse solver \mathcal{G} ?

Standard choices:

- G = approximation scheme of F solver but with a larger time step
- G = different approximation scheme than F's, with lower accuracy

 \hookrightarrow Use **reduced (averaged) models** to define the coarse solver.

Reason: Reduced models are not stiff ODEs \leftrightarrow low computational cost.

Some similar approaches

Maday 2007, Haut, Wingate, ... 2014 – 2022, Ariel, Kim, Tsai 2016

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Realistic Penning trap: magnetic bottle

Knapp, Kendl, Koskela, Ostermann, 2015. Solve for $0 < \varepsilon \ll 1$

$$\begin{cases} \frac{\mathrm{d}\mathbf{x}_{\varepsilon}}{\mathrm{d}t} = \mathbf{v}_{\varepsilon}, & \mathbf{x}_{\varepsilon}(s) = \mathbf{x}, \\ \frac{\mathrm{d}\mathbf{v}_{\varepsilon}}{\mathrm{d}t} = \frac{1}{\varepsilon}(\mathbf{v}_{\varepsilon})^{\perp} + \mathbf{v}_{\varepsilon} \times \mathbf{B}(\mathbf{x}_{\varepsilon}) + \mathbf{E}(\mathbf{x}_{\varepsilon}), & \mathbf{v}_{\varepsilon}(s) = \mathbf{v}, \end{cases}$$

where for c > 0, k > 0

$$\mathbf{E}(\mathbf{x}) = c \begin{pmatrix} -x \\ y/2 \\ z/2 \end{pmatrix} \quad \text{and} \quad \mathbf{B}(\mathbf{x}) = k \begin{pmatrix} x^2 - (y^2 + z^2)/2 \\ -xy \\ -xz \end{pmatrix}$$

Device for storing charged particles

- if $1/\varepsilon > \sqrt{2c}$ then stable periodic trajectory.
- otherwise the particle escapes from the trap

No analytic solution; oscillations at three time scales: $2\pi\varepsilon$, 1 and $2\pi/\varepsilon$.

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Averaged models

from two-scale asymptotic expansion theory.

Sanders, Verhulst, 1985, Frénod, 2006, N'Guetseng 1989, Allaire 1990 We develop the solution

$$\mathcal{X}_{\varepsilon}(t) = \mathcal{X}^{0}\left(t, \frac{t-s}{\varepsilon}\right) + \varepsilon \mathcal{X}^{1}\left(t, \frac{t-s}{\varepsilon}\right) + \varepsilon^{2} \mathcal{X}^{2}\left(t, \frac{t-s}{\varepsilon}\right) + \dots$$

when $\varepsilon \to 0$ and where the functions $\mathcal{X}^i(t,\theta)$ are periodic in $\theta, \forall i \in \mathbb{N}$.

The limit $\mathcal{Y}^0 = (\mathbf{y}^0, \mathbf{u}^0)$ is solution to the i.v.p.

$$\begin{cases} \frac{\mathrm{d}\mathbf{y}^0}{\mathrm{d}t} = \begin{pmatrix} \mathbf{u}_x^0 \\ 0 \\ 0 \end{pmatrix}, & \frac{\mathrm{d}\mathbf{u}^0}{\mathrm{d}t} = \begin{pmatrix} \mathbf{E}_x(\mathbf{y}^0) \\ 0 \\ 0 \end{pmatrix} + \begin{pmatrix} \mathbf{B}_x(\mathbf{y}^0) \mathbf{u}_z^0 \\ -\mathbf{B}_x(\mathbf{y}^0) \mathbf{u}_y^0 \end{pmatrix} \\ \mathbf{v}^0(s) = \mathbf{x}, & \mathbf{u}^0(s) = \mathbf{v}. \end{cases}$$

More complex equations for $\mathcal{Y}^1 = (\mathbf{y}^1, \mathbf{u}^1)$ coupled with $(\mathbf{y}^0, \mathbf{u}^0)!$

Properties of the reduced models

- both reduced models average the fastest rotation motion.
- the first-order model is more accurate than the zero-order one in the approximation of the **bounce motion**.
- the **electric drift** ${\bf E} \times {\bf e}_1$ is missed by the zero-order model, unlike the first-order one.

The system for $Y=(\mathbf{y}^0,\mathbf{u}^0,\mathbf{y}^1,\mathbf{u}^1)$ is source-free

$$rac{\mathrm{d}Y}{\mathrm{d}t} = F(Y)$$
 where $F: \mathbb{R}^{12} o \mathbb{R}^{12}$ satisfies $\nabla \cdot F = 0$

Volume-preserving scheme: splitting method (which is 4th order, time-symmetric).

Feng, Shang, 1995, Hairer, Lubich, Wanner, 2006

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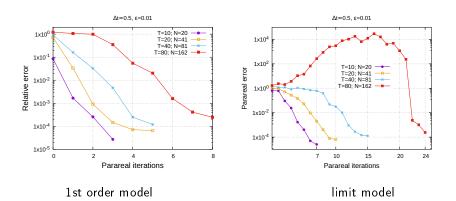
 \hookrightarrow conserves volumes in the enlarged phase space.

Volume-preserving scheme: splitting method (which is 4th order, time-symmetric).

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Parareal numerical results

the **strong** magnetic field is $1/\varepsilon=100$ and the reduced model timestep is $\Delta t=0.5\approx 8$ gyroperiods.



Speedup of Parareal

Computing $(F(T_{n+1},T_n,U_n^k))_{n=0,...,N-1}$ in parallel over N processors. N=162. $\varepsilon\in\{0.01;0.001\}.$

Nb. of points in $P=2\pi arepsilon$	10	20	40
Error(fine solver) at $T=80$	$4.2543 \cdot 10^{-3}$	$2.816 \cdot 10^{-4}$	$1.77 \cdot 10^{-5}$
Nb. of Parareal iterations	7	8	8
Speedup	4.8	6.7	10.0

Nb. of points in $P=2\pi arepsilon$	10	20	40
Error(fine solver) at $T=80$	$4.5956 \cdot 10^{-4}$	$2.989 \cdot 10^{-5}$	$1.89 \cdot 10^{-6}$
Nb. of Parareal iterations	2	3	4
Speedup	47.7	43.4	36.0

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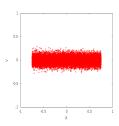
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Vlasov-Poisson equation – beam in a focusing channel

For $\varepsilon \to 0$ solve numerically

$$\begin{cases} \partial_t f^{\varepsilon} + \frac{v}{\varepsilon} \partial_r f^{\varepsilon} + \left(E^{\varepsilon} - \frac{r}{\varepsilon} + rH\left(\frac{t}{\varepsilon}\right) \right) \partial_v f^{\varepsilon} = 0, \\ \frac{1}{r} \partial_r (r E^{\varepsilon}) = \int f^{\varepsilon}(t, r, v) dv. \\ f^{\varepsilon}(t = 0, r, v) = f_0(r, v). \end{cases}$$

- $f^{\varepsilon} = f^{\varepsilon}(t, r, v)$ particles distrib. function
- Time $t \in [0,T]$, Position r > 0, Velocity $v \in \mathbb{R}$
- $r \mapsto r/\varepsilon$ strong external electric field
- $E^{\varepsilon}(t,r)$ self-consistent electric field
- H is a periodic external function.



Paraxial approximation: Filbet-Sonnendrücker (2006), Frénod-Salvarani-Sonnendrücker (2009), Mouton (2009), Crouseilles-Lemou-Méhats-Zhao (2013, 2017)

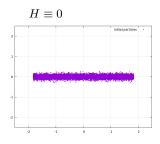
Examples

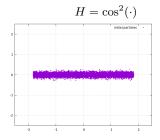
Let the initial distribution

$$f_0(r,v) = \frac{1}{\sqrt{2\pi} v_{\text{th}}} \exp\left(-\frac{v^2}{2v_{\text{th}}^2}\right) \chi_{[r_{\min}, r_{\max}]}(r),$$

where $v_{\rm th}=0.072$, $r_{\rm max}=1.83$ and $r_{\rm min}=-r_{\rm max}$ and $\chi_{[r_{\rm min},r_{\rm max}]}(r)=1$ if $r\in[r_{\rm min},r_{\rm max}]$ and $\chi_{[r_{\rm min},r_{\rm max}]}(r)=0$ otherwise.

$$H(\tau) = \cos^2(\tau) \implies \text{focusing effect}; \quad H(\tau) = \cos(2\tau) \implies \text{defocusing effect}.$$





Two-scale limit model

Frénod, Salvarani, Sonnendrücker (M3AS, 2009).

When $\varepsilon \to 0$, $(f_{\varepsilon}, E_{\varepsilon})$ two-scale converges to (F, \mathcal{E}) over [0, T].

$$F(t,\tau,r,v) = G\big(t,\cos(\tau)r - \sin(\tau)v,\sin(\tau)r + \cos(\tau)v\big),$$

and (G,\mathcal{E}) is the solution of the following model

$$\begin{cases} \frac{\partial G}{\partial t} + \frac{1}{2\pi} \int_0^{2\pi} -\sin(\tau) \Big[\mathcal{E} \Big(t, \tau, \cos(\tau) q + \sin(\tau) u \Big) + \Big(\mathcal{H}(\tau) \Big) \Big(\cos(\tau) q + \sin(\tau) u \Big) \Big] d\tau \, \frac{\partial G}{\partial q} \\ + \frac{1}{2\pi} \int_0^{2\pi} \cos(\tau) \Big[\mathcal{E} \Big(t, \tau, \cos(\tau) q + \sin(\tau) u \Big) + \Big(\mathcal{H}(\tau) \Big) \Big(\cos(\tau) q + \sin(\tau) u \Big) \Big] d\tau \, \frac{\partial G}{\partial u} = 0, \\ G(0, q, u) = f_0(q, u), \\ \frac{1}{r} \frac{\partial (r\mathcal{E})}{\partial r} = \Upsilon, \quad \Upsilon(t, \tau, r) = \int_{\mathbb{R}} G\Big(t, \cos(\tau) r - \sin(\tau) v, \sin(\tau) r + \cos(\tau) v \Big) dv. \end{cases}$$

- When $\varepsilon \to 0$, f_ε is approximated by $f_\varepsilon(t,r,v) \approx F\Big(t,\frac{t}{\varepsilon},r,v\Big)$.
- ullet The transport equation of G is free of high oscillations.

Numerical approximation

• particle in cell algorithm for both models (ε -dependent and the limit). Raviart (1985), Birdsall-Langdon (1985), Hockney-Eastwood (1988), ...

Dirac sum approximation for f_0

$$f_0^{N_p}(r,v) = \sum_{k=1}^{N_p} \omega_k \, \delta(r - r_0) \, \delta(v - v_0)$$

implies a Dirac sum for the solution f^{ε} :

$$f_{\varepsilon}^{N_p}(t,r,v) = \sum_{k=1}^{N_p} \omega_k \, \delta(r - R_k(t)) \, \delta(v - V_k(t))$$

where N_p is the number of **macroparticles** and $\left(R_k(t),V_k(t)\right)$ is the macroparticle k moving along a characteristic curve of Vlasov eq.

$$R'(t) = \frac{1}{\varepsilon}V(t), \qquad R(0) = r_0$$

$$V'(t) = -\frac{1}{\varepsilon}R(t) + E(t, R(t)) + R(t)H\left(\frac{t}{\varepsilon}\right), \qquad V(0) = v_0$$

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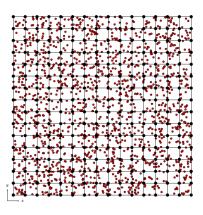
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Particle in Cell method



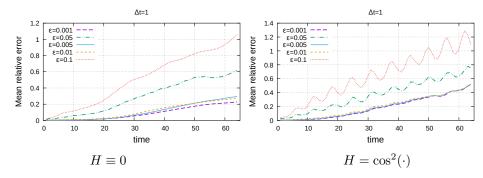
The main time loop:

- deposit particles on the grid \Rightarrow the grid density ρ (RHS of Poisson eq.)
- solve Poisson equation on the grid \Rightarrow the grid electric field E
- ullet interpolate E in each particle
- push particles with this field
 ODEs to solve

Validity of the reduced model

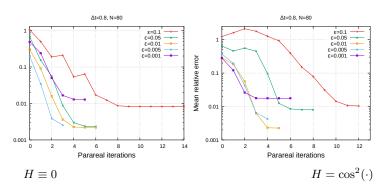
Runge-Kutta 4 scheme for original and reduced models. Fine $\delta t=2\pi\varepsilon/100$. 10000 particles and 128 cells.

Error
$$(t_n) = \frac{1}{N_p} \sum_{j=1}^{N_p} \frac{\|(R_j^n, V_j^n) - (\widetilde{R}_j^n, \widetilde{V}_j^n)\|_2}{\|(\widetilde{R}_j^n, \widetilde{V}_j^n)\|_2}.$$



Convergence of Parareal

Use the two-scale limit model to define \mathcal{G} . K given by the error of the fine solver w.r.t. the very fine solution.



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Theoretic Speedup

Computing $(F(T_{n+1},T_n,U_n^k))_{n=0,\dots,N-1}$ in parallel over N processors.

The total time of the parareal run is

$$T_{\text{par}} = T_{\text{init}} + K \left(\frac{T_{\text{fine}}}{N} + T_{\text{coarse}} \right),$$

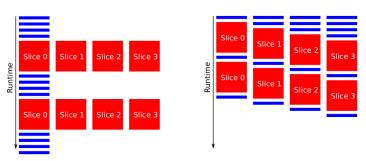
where K is the parareal iterations number.

Thus
$$\mathbf{S}(N) = \frac{1}{\left(1+K\right)\frac{T_c}{T_f} + \frac{K}{N}}$$

where $T_{\text{fine}} = NT_f$, $T_{\text{coarse}} = NT_c$.

Pipelined Parareal

- allows to reduce the time of coarse calculations from NT_c to T_c . Minion (2010), Aubanel (2011), Ruprecht (2017)

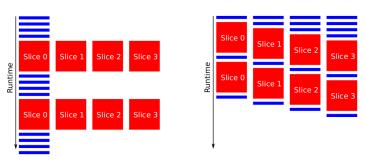


from D. Ruprecht's paper "Shared Memory Pipelined Parareal", Euro-Par 2017.

Thus
$$\mathbf{S_p}(N) = \frac{1}{\left(1 + \frac{K}{N}\right)\frac{T_c}{T_f} + \frac{K}{N}}$$

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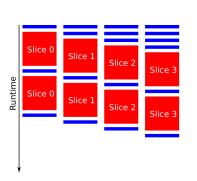


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Thus
$$\mathbf{S_p}(N) = \frac{1}{\left(1 + \frac{K}{N}\right)\frac{T_c}{T_f} + \frac{K}{N}}$$
 > $\mathbf{S}(N)$, since $\frac{K}{N} \ll K$.

Pipelined Parareal

-standard implementation using MPI.

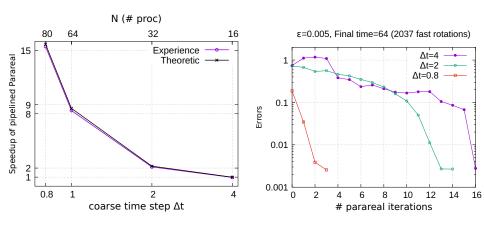


Algorithm 1: Parareal using MPI

```
input: Initial value q_0; number of iterations K
 1.1 q \leftarrow q_0
1.2 p = MPI\_COMM\_RANK()
1.3 q \leftarrow \mathcal{G}_{\Lambda t}(q, t_n, 0)
1.4 q_c \leftarrow \mathcal{G}_{\Delta t}(q, t_{p+1}, t_p)
1.5 for k = 1, K do
           q \leftarrow \mathcal{F}_{\delta t}(q, t_{n+1}, t_n)
 1.7
           \delta a \leftarrow a - a_c
           if Process not first then
1.8
                 MPI_RECV(q, source = p - 1)
1.9
           end
1.10
           else
1.11
1.12
                 q \leftarrow q_0
1.13
           end
           q_c \leftarrow \mathcal{G}_{\Lambda t}(q, t_{n+1}, t_n)
1.14
           q \leftarrow q_c + \delta q
1.15
           if Process not last then
1.16
                 MPI\_SEND(q, target = p + 1)
1.17
           end
1.18
1.19 end
```

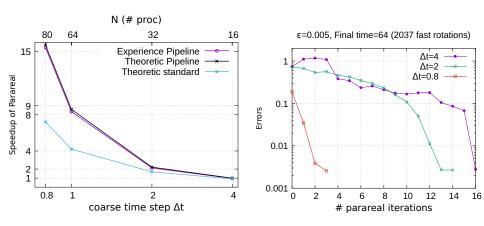
Speedup of the pipelined implementation

simulations on Leto. case $H\equiv 0$ and $\varepsilon=0.005$ (i.e. an accurate coarse solver)

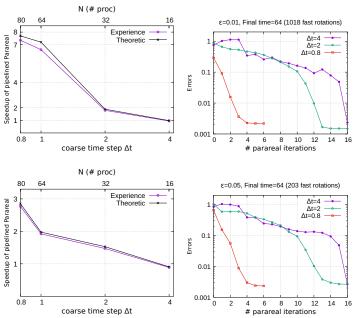


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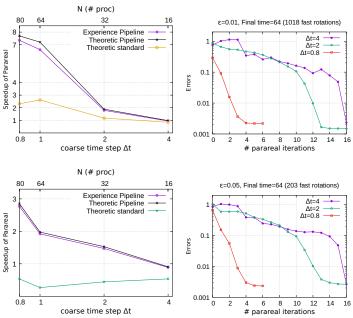
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Speedup for $\varepsilon=0.01$ and $\varepsilon=0.05$



Speedup for $\varepsilon=0.01$ and $\varepsilon=0.05$



Summary and Outlook

Conclusion:

Parareal algorithm provides accurate results at $\underline{\text{any}}\ T_{\mathrm{end}}$ and for $\underline{\text{any}}\ \varepsilon$, with a low computational cost.

The pipelined version speeds up the simulations.

Shared memory parallelism to be added.

Cons:

- need for finding the reduced model (not always an easy task).
- derive estimate for the error of the reduced model.
- parareal does not allow to speed up for $\varepsilon \sim 0.1$.

Thank you!

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