INTRODUCTION TO DATA ASSIMILATION **Practical session Day 1: elementary tools**

Exercice D1.0.

In this course we will compute the solutions of ODEs or ODE systems using the function scipy.integrate.solve_ivp.

Read the official documentation on this function.

Exercice D1.1. Numerical solution of an ODE: logistic growth

We consider the following ODE that models the logistic growth of a population:

$$\begin{cases} y'(t) = \alpha y(t)(1 - y(t)/K), & t \in [0, T], \\ y(t = 0) = y_0, & t = 0. \end{cases}$$

for some given constants $\alpha > 0$ and K > 0. The initial population is $y_0 > 0$.

- a) implement the numerical solution of this ODE, and plot the solution.
- b) change the values of α , K and y_0 (one parameter at a time !).

Note: an analytical solution of the logistic equation can be calculated. We propose not to use this analytical solution.

Exercice D1.2. Numerical solution of an ODE system: SIR epidemiologic model

We consider the following ODE system (SIR model) that models the spread of an epidemics in a population:

$$S'(t) = -\tau S(t)I(t),$$

$$I'(t) = \tau S(t)I(t) - \nu I(t)$$

$$R'(t) = \nu I(t), \qquad t \in [0,T]$$

together with the initial condition: S(t = 0) = N, I(t = 0) = 1, R(t = 0) = 0.

The given constants $\tau > 0$ and $\nu > 0$ represent respectively the force of the infection and the recovery/death rate. Note that in this simple model a person that was Infected becomes Removed at a rate ν , and the model does not distinguish between people that recovered from the infection and those that died !

- a) Implement the numerical solution of this ODE system on the time interval [0, 250] for the following values: $\tau = 3.10^{-9}$, $\nu = 10^{-1}$ and the initial conditions $N = 6.10^7$, and plot the solution.
- b) Change the values of τ and ν (one parameter at a time !).

We aim at modelling a public intervention to stop the pandemics spread. This public intervention (e.g. lock down) has the effect on the spread force τ that is multiplied by a factor $f \in (0, 1)$ between the dates t_1 and t_2 .

- c) Modify the function that implements the SIR model to incorporate the effect of multiplying τ by the factor f between the dates t_1 and t_2 .
- d) Apply on the previous simulation the spread force reduction by a factor of 10 between $t_1 = 80$ and $t_2 = 130$. Comment the results.

e) Modify the factor f.

Optimization of a quadratic function: gradient method, Gauss-Newton Exercice D1.3. method

We consider a symmetric positive definite (sdp) matrix A of size $n \times n$, and a vector $\mathbf{x}_* \in \mathbf{R}^n$. The objective function that is defined by

$$J(\mathbf{x}) = \frac{1}{2} \|A(\mathbf{x} - \mathbf{x}_*)\|^2$$

attains its minimum value at the point \mathbf{x}_* . Therefore we know the 'exact' minimizer and we will be able to evaluate the performance of methods designed to find this minimizer.

a) Let $\mathbf{h} \in \mathbf{R}^n$. Compute the quantity

 $DJ(\mathbf{x}).\mathbf{h}.$

What is the gradient of J at the point \mathbf{x} ?

- b) One can prove that the Lipschitz constant of the gradient of J is the largest eigenvalue L of the matrix $A^T A$. Propose an implementation of the gradient descent method applied to J with starting point **0**.
- c) Choose a 3×3 sdp matrix A. Implement 100 iterations of the gradient descent method. For each iterate \mathbf{x}^k compute
 - the distance to the true minimizer $\|\mathbf{x}^k \mathbf{x}_*\|$,
 - the value of the cost function $J(\mathbf{x}^k)$,

and plot these quantities vs k in two different graphics. One can use a semi-log scale.

d) Choose the following 2×2 sdp matrix:

$$A = \begin{pmatrix} 4 & 2 \\ 2 & 2 \end{pmatrix}$$

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and perform the same study. Plot in the plane the iterates \mathbf{x}^k together with the level curves of the function J and the true minimizer \mathbf{x}_* .

We aim to minimize the same quadratic function using a Gauss-Newton method. One can note that

$$J(\mathbf{x}) = \frac{1}{2} \|F(\mathbf{x})\|^2$$
, with $F(\mathbf{x}) = A(\mathbf{x} - \mathbf{x}_*)$.

- e) What is the Jacobian matrix DF of F? Propose an implementation of the Gauss-Newton descent method applied to J.
- f) Perform the same studies as questions c) and d) above.

Optimization of a non linear function (Rosenbrock function): gradient Exercice D1.4. method, GN method.

We consider the Rosenbrock function in dimension 2, defined by

$$j(x,y) = (x-1)^2 + 100(y-x^2)^2.$$

The minimizer is the point $\mathbf{x}^* = (x^*, y^*) = (1, 1)$, it is located at the bottom of a valley in the shape of a parabola. This function (and higher dimensional generalizations) is an example of a 'difficult' function to minimize.

- a) What is the gradient of j at the point $\mathbf{x} = (x, y)$?
- b) The gradient of j is not Lipschitz in the whole plane \mathbb{R}^2 but it is in bounded domains. We assume that $x, y \in [-M, M]$. Check that the Lipschitz constant of ∇j in this domain can be bounded by

$$L \le 202 + 800M + 600M^2.$$

- c) Implement 100 iterations of the gradient descent method with fixed step size. Use as a starting point a random point with coordinates between 0 and 1. For each iterate \mathbf{x}^k compute
 - the distance to the true minimizer $\|\mathbf{x}^k \mathbf{x}^*\|$,
 - the value of the cost function $j(\mathbf{x}^k)$,

and plot these quantities vs k in two different graphics. One can use a semi-log scale.

d) Increase the number of iterates to reach the minimizer up to machine precision.

We now aim to implement Gauss-Newton method.

e) Check that one can write

$$j(\mathbf{x}) = \frac{1}{2} \|F(\mathbf{x})\|^2,$$

for a well chosen function F to be determined.

- f) What is the Jacobian matrix DF of F? Propose an implementation of the Gauss-Newton descent method applied to J.
- g) Perform the same studies as questions c) and d) above.