

# Numeric-symbolic computation of the separatrix graph of a holomorphic differential equation

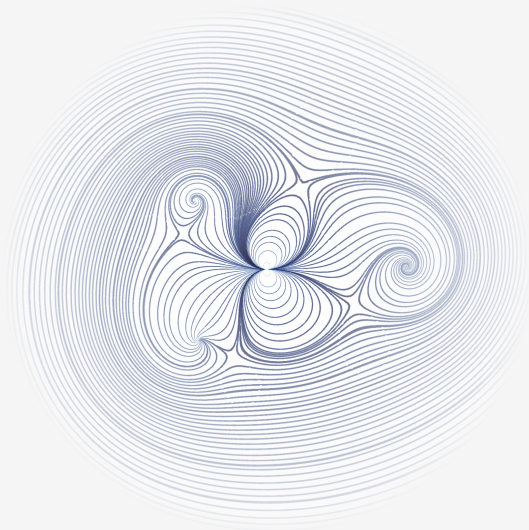
FELim

**Loïc TEYSSIER**

(joint work with R. Schilling, Strasbourg)

March 25, 2024

# Rational flows on $\overline{\mathbb{C}}$



Rational flows on  $\overline{\mathbb{C}}$ 

$$P, Q \in \mathbb{C}[z] , P \wedge Q = 1$$

$$\dot{z}(t) = \frac{P}{Q}(z(t)) , t \in \mathbb{R}$$

Rational flows on  $\overline{\mathbb{C}}$ 

$$P, Q \in \mathbb{C}[z] \text{ , } P \wedge Q = 1$$

$$\dot{z}(t) = \frac{P}{Q}(z(t)) \text{ , } t \in \mathbb{R}$$

## Trajectories

level curves of  $\text{Im}(T)$ , the (multivalued) time function  $dt = \frac{Q}{P} dz$

$$T(z) := \int^z \frac{Q}{P}(x) dx$$

Rational flows on  $\overline{\mathbb{C}}$ 

$$P, Q \in \mathbb{C}[z] \text{ , } P \wedge Q = 1$$

$$\dot{z}(t) = \frac{P}{Q}(z(t)) \text{ , } t \in \mathbb{R}$$

## Trajectories

level curves of  $\text{Im}(T)$ , the (multivalued) time function  $dt = \frac{Q}{P} dz$

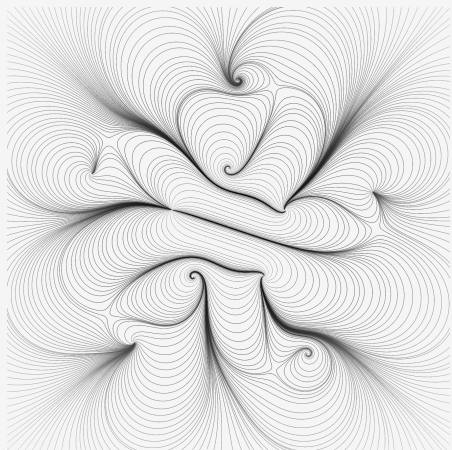
$$T(z) := \int^z \frac{Q}{P}(x) dx$$

Singularities in affine chart  $\mathbb{C} = \{z \neq \infty\}$ 

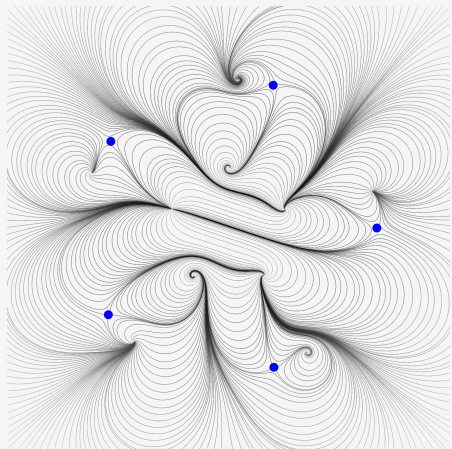
$$PQ = 0$$

- zero-like:  $P^{-1}(0)$
- pole-like:  $Q^{-1}(0)$

## Example (some random degree-10 flow)

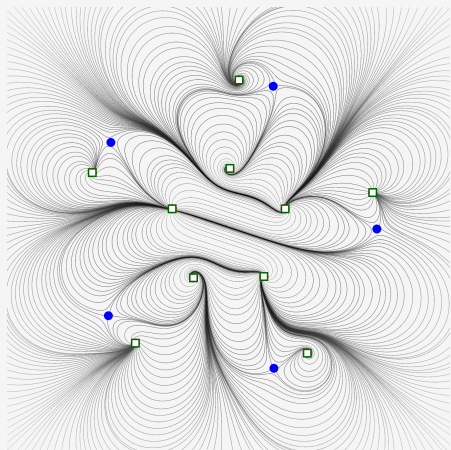


## Example (some random degree-10 flow)



- Saddle points: poles  $Q^{-1}(0)$

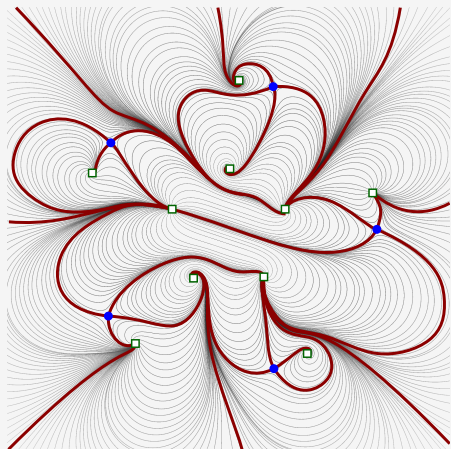
## Example (some random degree-10 flow)



- Saddle points: poles  $Q^{-1}(0)$
- Other stationary points: zeros  $P^{-1}(0)$

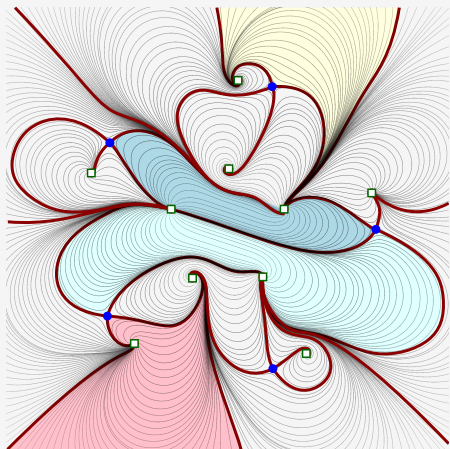


## Example (some random degree-10 flow)



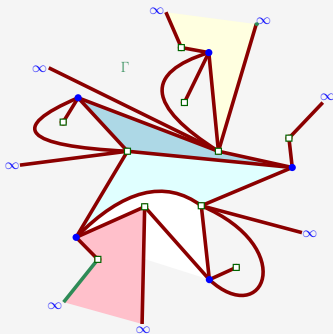
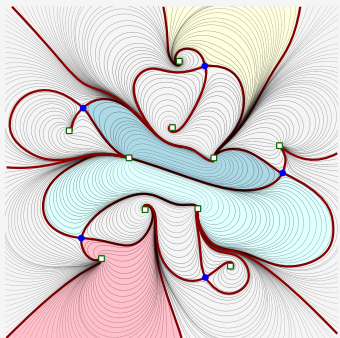
- Saddle points: poles  $Q^{-1}(0)$
- Other stationary points: zeros  $P^{-1}(0)$
- Separatrices  
(= trajectories passing through saddles)

## Example (some random degree-10 flow)



- Saddle points: poles  $Q^{-1}(0)$
- Other stationary points: zeros  $P^{-1}(0)$
- Separatrices  
(= trajectories passing through saddles)
- Zones

## Example (some random degree-10 flow)



### Fact

*Topological class of the flow*  
 = *combinatorial class of the separatrix graph  $\Gamma$*

# Douady's question

Questions

# Douady's question

## Questions

- 1 Direct problem: is there an algorithm computing  $\Gamma$ ?

# Douady's question

## Questions

- 1 Direct problem: is there an algorithm computing  $\Gamma$ ?
- 2 What about the inverse problem?

# Douady's question

## Questions

- 1 Direct problem: is there an algorithm computing  $\Gamma$ ?
- 2 What about the inverse problem?

## Computational model

# Douady's question

## Questions

- 1 Direct problem: is there an algorithm computing  $\Gamma$ ?
- 2 What about the inverse problem?

## Computational model

- 1 Douady asked for a *theoretical* algorithm with full real arithmetic and 0-test available: a BSS-machine



# Douady's question

## Questions

- 1 Direct problem: is there an algorithm computing  $\Gamma$ ?
- 2 What about the inverse problem?

## Computational model

- 1 Douady asked for a *theoretical* algorithm with full real arithmetic and 0-test available: a BSS-machine
- 2 We produce *effective* algorithms for polynomials in  $\mathcal{C}[z]$   
 $\mathcal{C}$  : decidable number field

# Douady's question

## Questions

- 1 Direct problem: is there an algorithm computing  $\Gamma$ ?
- 2 What about the inverse problem?

## Computational model

- 1 Douady asked for a *theoretical* algorithm with full real arithmetic and 0-test available: a BSS-machine
- 2 We produce *effective* algorithms for polynomials in  $\mathcal{C}[z]$   
 $\mathcal{C}$  : decidable number field
- 3 Complexity = arithmetic complexity of the BSS-machine

# Separatrix graph

Let  $\gamma : t \in ]\tau_-, \tau_+[ \subset \mathbb{R} \rightarrow \gamma(t)$  be a maximal trajectory

- Either  $\gamma$  is periodic  $\rightarrow$  **cycle**

# Separatrix graph

Let  $\gamma : t \in ]\tau_-, \tau_+[ \subset \mathbb{R} \rightarrow \gamma(t)$  be a maximal trajectory

- Either  $\gamma$  is periodic  $\rightarrow$  **cycle**
- Either  $|\tau_{\pm}| < \infty$ :  $\gamma(\tau_{\pm})$  pole-like singularity  $\rightarrow$  **separatrix**

# Separatrix graph

Let  $\gamma : t \in ]\tau_-, \tau_+[ \subset \mathbb{R} \rightarrow \gamma(t)$  be a maximal trajectory

- Either  $\gamma$  is periodic  $\rightarrow$  **cycle**
- Either  $|\tau_{\pm}| < \infty$ :  $\gamma(\tau_{\pm})$  pole-like singularity  $\rightarrow$  **separatrix**
- Either  $|\tau_{\pm}| = \infty$ :  $\gamma(\tau_{\pm})$  zero-like singularity  $\rightarrow$  **landing trajectory**

## Separatrix graph

Let  $\gamma : t \in ]\tau_-, \tau_+[ \subset \mathbb{R} \rightarrow \gamma(t)$  be a maximal trajectory

- Either  $\gamma$  is periodic  $\rightarrow$  **cycle**
- Either  $|\tau_{\pm}| < \infty$ :  $\gamma(\tau_{\pm})$  pole-like singularity  $\rightarrow$  **separatrix**
- Either  $|\tau_{\pm}| = \infty$ :  $\gamma(\tau_{\pm})$  zero-like singularity  $\rightarrow$  **landing trajectory**

### Remark

No limit cycles: if  $\gamma$  not a cycle, then  $\gamma(\tau_{\pm}) \in \overline{\mathbb{C}}$

# Separatrix graph

Let  $\gamma : t \in ]\tau_-, \tau_+[ \subset \mathbb{R} \rightarrow \gamma(t)$  be a maximal trajectory

- Either  $\gamma$  is periodic  $\rightarrow$  **cycle**
- Either  $|\tau_{\pm}| < \infty$ :  $\gamma(\tau_{\pm})$  pole-like singularity  $\rightarrow$  **separatrix**
- Either  $|\tau_{\pm}| = \infty$ :  $\gamma(\tau_{\pm})$  zero-like singularity  $\rightarrow$  **landing trajectory**

## Remark

No limit cycles: if  $\gamma$  not a cycle, then  $\gamma(\tau_{\pm}) \in \overline{\mathbb{C}}$

## Definition

**Separatrix graph  $\Gamma$** : edges-ordered graph defined by

## Separatrix graph

Let  $\gamma : t \in ]\tau_-, \tau_+[ \subset \mathbb{R} \rightarrow \gamma(t)$  be a maximal trajectory

- Either  $\gamma$  is periodic  $\rightarrow$  **cycle**
- Either  $|\tau_{\pm}| < \infty$ :  $\gamma(\tau_{\pm})$  pole-like singularity  $\rightarrow$  **separatrix**
- Either  $|\tau_{\pm}| = \infty$ :  $\gamma(\tau_{\pm})$  zero-like singularity  $\rightarrow$  **landing trajectory**

### Remark

No limit cycles: if  $\gamma$  not a cycle, then  $\gamma(\tau_{\pm}) \in \overline{\mathbb{C}}$

### Definition

**Separatrix graph**  $\Gamma$ : edges-ordered graph defined by

- vertices  $P^{-1}(0) \cup Q^{-1}(0) \cup \{\infty\}$



# Separatrix graph

Let  $\gamma : t \in ]\tau_-, \tau_+[ \subset \mathbb{R} \rightarrow \gamma(t)$  be a maximal trajectory

- Either  $\gamma$  is periodic  $\rightarrow$  **cycle**
- Either  $|\tau_{\pm}| < \infty$ :  $\gamma(\tau_{\pm})$  pole-like singularity  $\rightarrow$  **separatrix**
- Either  $|\tau_{\pm}| = \infty$ :  $\gamma(\tau_{\pm})$  zero-like singularity  $\rightarrow$  **landing trajectory**

## Remark

No limit cycles: if  $\gamma$  not a cycle, then  $\gamma(\tau_{\pm}) \in \overline{\mathbb{C}}$

## Definition

**Separatrix graph**  $\Gamma$ : edges-ordered graph defined by

- vertices  $P^{-1}(0) \cup Q^{-1}(0) \cup \{\infty\}$
- edges  $\{\gamma : \tau_- \text{ or } \tau_+ \in \mathbb{R}\}$

# Structure theorem

Theorem (A. Douady-F. Estrada-P. Sentenac / B. Branner-K. Dias)

$$Q = 1$$

# Structure theorem

Theorem (A. Douady-F. Estrada-P. Sentenac / B. Branner-K. Dias)

$$Q = 1$$

1  $\Gamma(P)$  is a tree and  $\Gamma : \mathbb{C}[z] \rightarrow \text{Trees}$  is surjective

# Structure theorem

**Theorem** (A. Douady-F. Estrada-P. Sentenac / B. Branner-K. Dias)

$Q = 1$

- 1  $\Gamma(P)$  is a tree and  $\Gamma : \mathbb{C}[z] \rightarrow \text{Trees}$  is surjective
- 2  $\Gamma(P) \simeq \Gamma(\hat{P}) \Leftrightarrow$  topologically equivalent flows

# Structure theorem

**Theorem** (A. Douady-F. Estrada-P. Sentenac / B. Branner-K. Dias)

$Q = 1$

- 1  $\Gamma(P)$  is a tree and  $\Gamma : \mathbb{C}[z] \rightarrow \text{Trees}$  is surjective
- 2  $\Gamma(P) \simeq \Gamma(\hat{P}) \Leftrightarrow$  topologically equivalent flows

**Conjecture**

The mapping  $\Gamma : \mathbb{C}(z) \rightarrow \text{PlanarGraphs}$  is surjective

# Main result

## Main Theorem

$$Q = 1 \quad , \quad P(z) = z^{k+1} + a_{k-1}z^{k-1} + \cdots + a_0 \quad , \quad k \in \mathbb{Z}_{>0}$$

# Main result

## Main Theorem

$$Q = 1 \quad , \quad P(z) = z^{k+1} + a_{k-1}z^{k-1} + \cdots + a_0 \quad , \quad k \in \mathbb{Z}_{>0}$$

- 1 There exists an effective algorithm computing  $\Gamma(P)$

# Main result

## Main Theorem

$Q = 1$  ,  $P(z) = z^{k+1} + a_{k-1}z^{k-1} + \dots + a_0$  ,  $k \in \mathbb{Z}_{>0}$

- 1 There exists an effective algorithm computing  $\Gamma(P)$
- 2 Complexity

$$O\left(\operatorname{Re}(b(P)) \times k^4 \left(\frac{9}{4}|P|_k\right)^k \times \ln^2 \frac{\tan \arg b(P)}{k}\right)$$

where:



# Main result

## Main Theorem

$Q = 1$  ,  $P(z) = z^{k+1} + a_{k-1}z^{k-1} + \dots + a_0$  ,  $k \in \mathbb{Z}_{>0}$

- 1 There exists an effective algorithm computing  $\Gamma(P)$
- 2 Complexity

$$O\left(\operatorname{Re}(b(P)) \times k^4 \left(\frac{9}{4}|P|_k\right)^k \times \ln^2 \frac{\tan \arg b(P)}{k}\right)$$

where:

- $\mathcal{L} = \mathbb{Z}/2\mathbb{Z} \left[ 2i\pi \operatorname{res}\left(\frac{1}{P}; z\right) : z \in P^{-1}(0) \right]$

# Main result

## Main Theorem

$Q = 1$  ,  $P(z) = z^{k+1} + a_{k-1}z^{k-1} + \dots + a_0$  ,  $k \in \mathbb{Z}_{>0}$

- 1 There exists an effective algorithm computing  $\Gamma(P)$
- 2 Complexity

$$O\left(\operatorname{Re}(\mathfrak{b}(P)) \times k^4 \left(\frac{9}{4}|P|_k\right)^k \times \ln^2 \frac{\tan \arg \mathfrak{b}(P)}{k}\right)$$

where:

- $\mathcal{L} = \mathbb{Z}/2\mathbb{Z} \left[ 2i\pi \operatorname{res}\left(\frac{1}{P}; z\right) : z \in P^{-1}(0) \right]$
- $\mathfrak{b}(P) := \max |\mathcal{L}| + i \min |\operatorname{Im}(\mathcal{L} \setminus \mathbb{R})|$

with  $\min \emptyset := +\infty$

# Main result

## Main Theorem

$Q = 1$  ,  $P(z) = z^{k+1} + a_{k-1}z^{k-1} + \dots + a_0$  ,  $k \in \mathbb{Z}_{>0}$

- 1 There exists an effective algorithm computing  $\Gamma(P)$
- 2 Complexity

$$O\left(\operatorname{Re}(\mathfrak{b}(P)) \times k^4 \left(\frac{9}{4}|P|_k\right)^k \times \ln^2 \frac{\tan \arg \mathfrak{b}(P)}{k}\right)$$

where:

- $\mathcal{L} = \mathbb{Z}/2\mathbb{Z} \left[ 2i\pi \operatorname{res}\left(\frac{1}{P}; z\right) : z \in P^{-1}(0) \right]$
- $\mathfrak{b}(P) := \max |\mathcal{L}| + i \min |\operatorname{Im}(\mathcal{L} \setminus \mathbb{R})|$
- $|P|_k := \max \left\{ |ka_\ell|^{k+1-\ell} : 0 \leq \ell < k \right\}$

with  $\min \emptyset := +\infty$

# Main result

## Main Theorem

$Q = 1$  ,  $P(z) = z^{k+1} + a_{k-1}z^{k-1} + \dots + a_0$  ,  $k \in \mathbb{Z}_{>0}$

- 1 There exists an effective algorithm computing  $\Gamma(P)$
- 2 Complexity

$$O\left(\operatorname{Re}(b(P)) \times k^4 \left(\frac{9}{4}|P|_k\right)^k \times \ln^2 \frac{\tan \arg b(P)}{k}\right)$$

where:

- $\mathcal{L} = \mathbb{Z}/2\mathbb{Z} \left[ 2i\pi \operatorname{res}\left(\frac{1}{P}; z\right) : z \in P^{-1}(0) \right]$
- $b(P) := \max |\mathcal{L}| + i \min |\operatorname{Im}(\mathcal{L} \setminus \mathbb{R})|$
- $|P|_k := \max \left\{ |ka_\ell|^{k+1-\ell} : 0 \leq \ell < k \right\}$

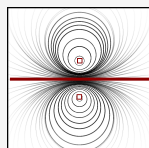
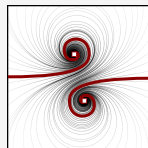
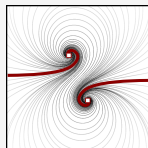
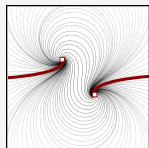
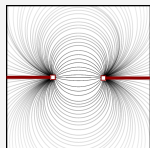
with  $\min \emptyset := +\infty$

- 3 Simple roots:  $k^4 \rightarrow (k \ln k)^2$

# Bifurcation parameter

## Remark

$$P(z) = z^{k+1} + a_{k-1}z^{k-1} + \dots + a_0, \quad k \in \mathbb{Z}_{>0}$$

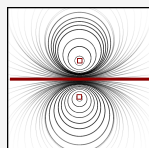
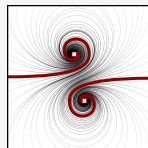
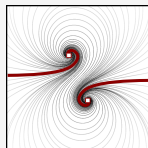
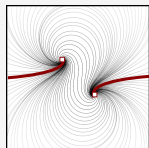
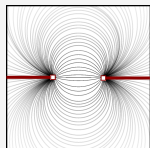


# Bifurcation parameter

## Remark

$$P(z) = z^{k+1} + a_{k-1}z^{k-1} + \dots + a_0, \quad k \in \mathbb{Z}_{>0}$$

$$\blacksquare \mathcal{L} = \mathbb{Z}/2\mathbb{Z} \left[ 2i\pi \operatorname{res} \left( \frac{1}{P}; z \right) : z \in P^{-1}(0) \right]$$



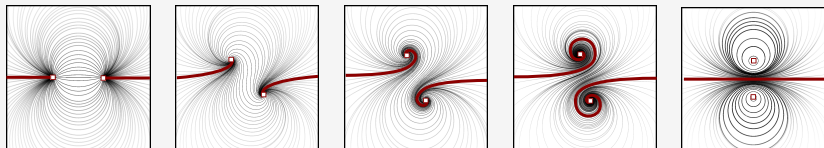
# Bifurcation parameter

## Remark

$$P(z) = z^{k+1} + a_{k-1}z^{k-1} + \dots + a_0, \quad k \in \mathbb{Z}_{>0}$$

- $\mathcal{L} = \mathbb{Z}/2\mathbb{Z} \left[ 2i\pi \operatorname{res} \left( \frac{1}{P}; z \right) : z \in P^{-1}(0) \right]$
- $\mathfrak{b}(P) := \max |\mathcal{L}| + i \min |\operatorname{Im}(\mathcal{L} \setminus \mathbb{R})|$

proximity to bifurcation



# Bifurcation parameter

## Remark

$$P(z) = z^{k+1} + a_{k-1}z^{k-1} + \dots + a_0, \quad k \in \mathbb{Z}_{>0}$$

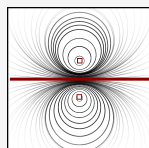
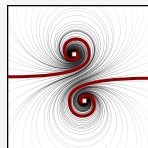
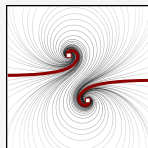
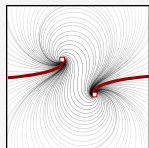
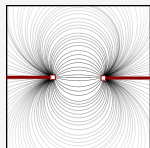
- $\mathcal{L} = \mathbb{Z}/2\mathbb{Z} \left[ 2i\pi \operatorname{res} \left( \frac{1}{P}; z \right) : z \in P^{-1}(0) \right]$

- $b(P) := \max |\mathcal{L}| + i \min |\operatorname{Im}(\mathcal{L} \setminus \mathbb{R})|$

proximity to bifurcation

**1**  $\operatorname{Re}(b(P)) \rightarrow +\infty \iff$  roots collide

saddle-node bifurcation





# Bifurcation parameter

## Remark

$$P(z) = z^{k+1} + a_{k-1}z^{k-1} + \dots + a_0, \quad k \in \mathbb{Z}_{>0}$$

- $\mathcal{L} = \mathbb{Z}/2\mathbb{Z} \left[ 2i\pi \operatorname{res} \left( \frac{1}{P}; z \right) : z \in P^{-1}(0) \right]$

- $b(P) := \max |\mathcal{L}| + i \min |\operatorname{Im}(\mathcal{L} \setminus \mathbb{R})|$

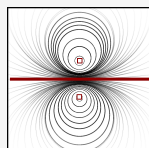
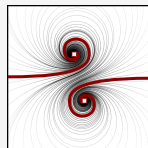
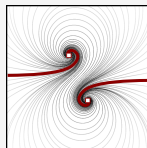
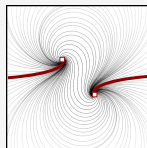
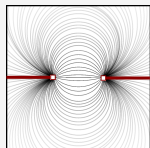
**1**  $\operatorname{Re}(b(P)) \rightarrow +\infty \iff$  roots collide

**2**  $\operatorname{Im}(b(P)) \rightarrow 0 \iff$  loop forms

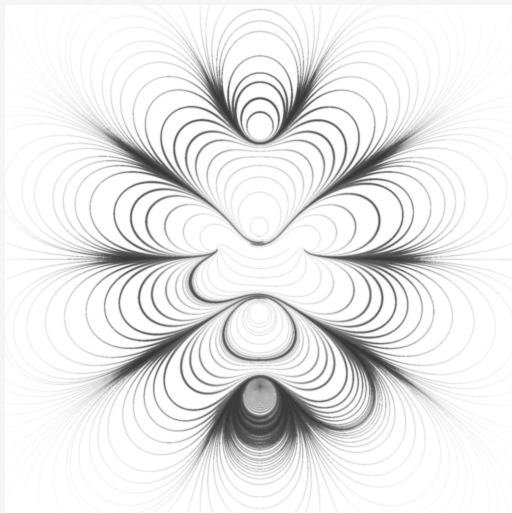
proximity to bifurcation

saddle-node bifurcation

center/focus bifurcation



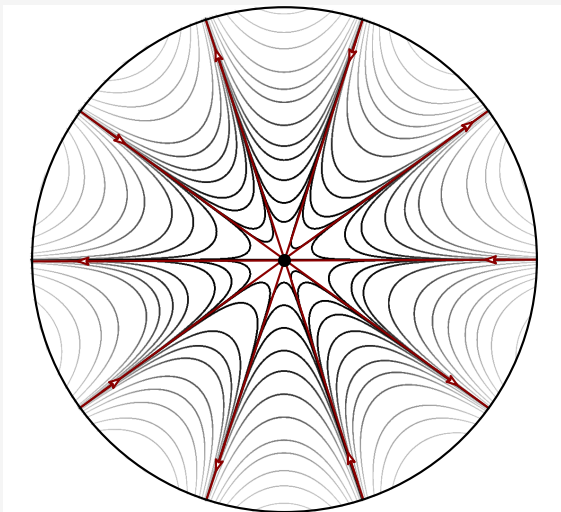
## Example



Where do the separatrices land?

# What is being computed

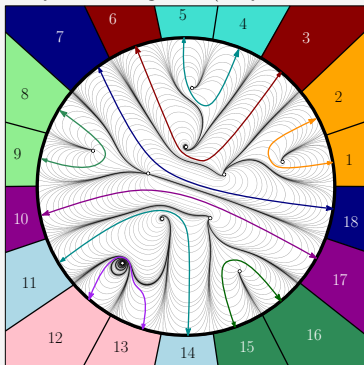
# What is being computed



Near  $\infty$  ( $k = 5$ )

# What is being computed (generic case)

All roots are simple, no cycle (in particular  $\mathcal{L} \cap \mathbb{R} = \{0\}$  )

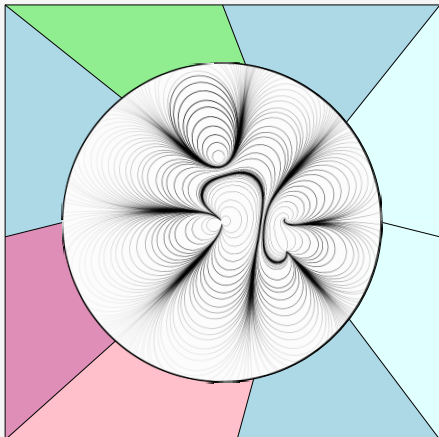
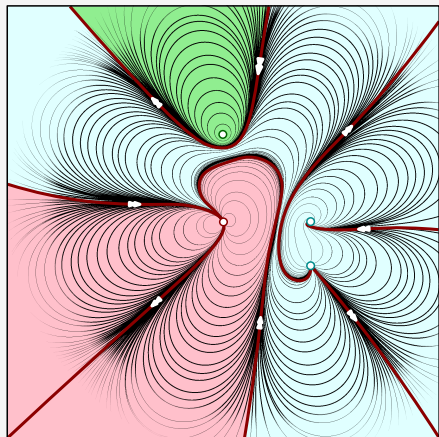


Douady-Estrada-Sentenac non-crossing involution:

$$\begin{bmatrix} 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 & 9 & 10 & 11 & 12 & 13 & 14 & 15 & 16 & 17 & 18 \\ 2 & 1 & 6 & 5 & 4 & 3 & 18 & 9 & 8 & 17 & 14 & 13 & 12 & 11 & 16 & 15 & 10 & 7 \end{bmatrix}$$

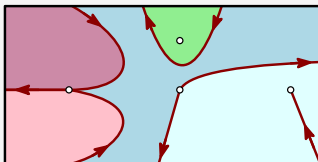
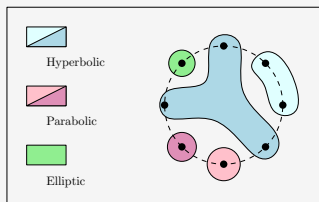
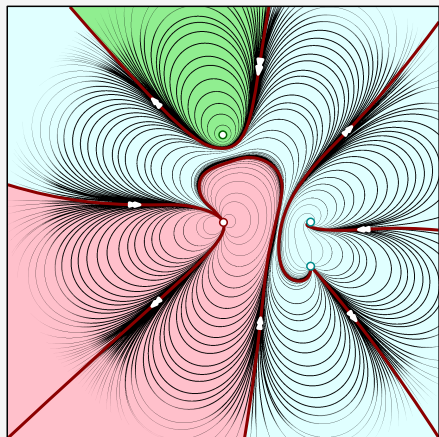
# What is being computed (general case)

## What is being computed (general case)



The zones are of different nature and define a sectors partition near  $\infty$

# What is being computed (general case)



## Lemma

The *polar partition* is a colored non-crossing partition of  $\mathbb{Z}/2k\mathbb{Z}$



# What is being computed (general case)

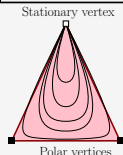
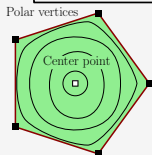
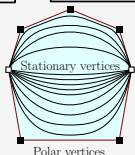
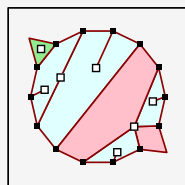
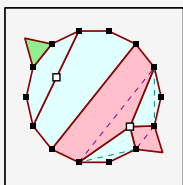
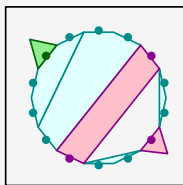
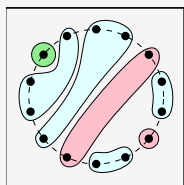
## Definition

Here goes a boring, never ending list of properties defining a **colored non-crossing partition** of  $\mathbb{Z}/2k\mathbb{Z}$ , ascertaining that this is the right concept to state provable theorems. It is a combinatorial counterpart to the dynamical properties of holomorphic flows that have previously been discussed

# What is being computed (general case)

## Main Proposition

There is a 1-1 correspondence between classes of non-crossing colored partitions (up to cyclic action of  $\mathbb{Z}/2k\mathbb{Z}$ ) and topological classes of flows

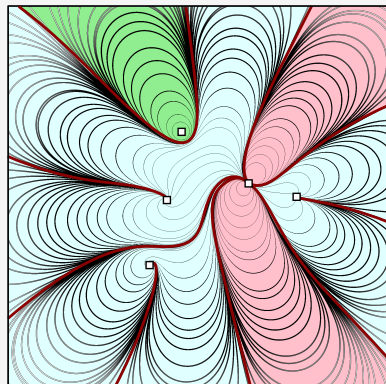
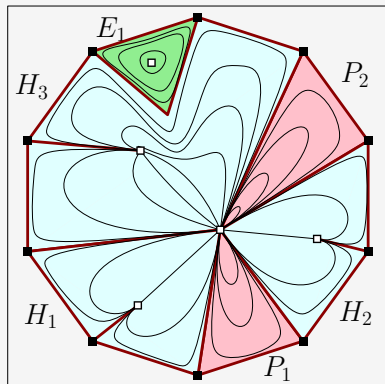


3 colors:

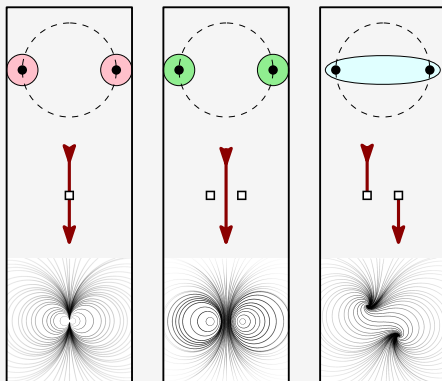
# What is being computed (general case)

## Main Proposition

There is a 1-1 correspondence between classes of polar partitions (up to cyclic action of  $\mathbb{Z}/2k\mathbb{Z}$ ) and topological classes of flows

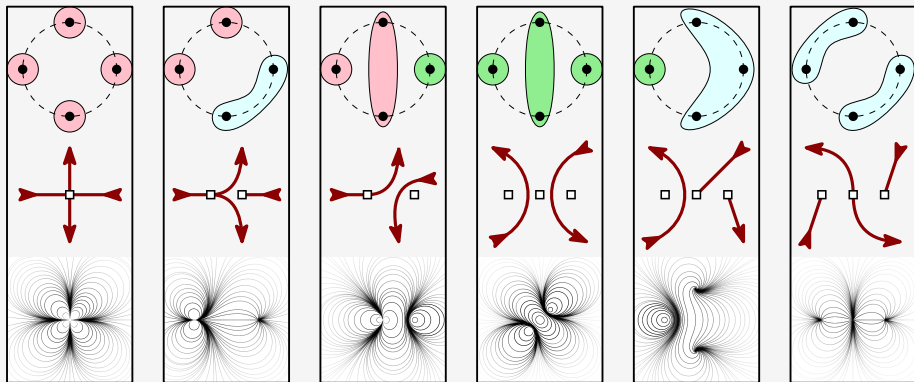


# Examples



$k = 1$

# Examples

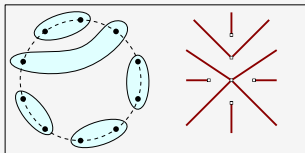


$k = 2$

# Examples

## Definition

Generic = structurally stable flows (open condition)  
 = hyperbolic blocks with 2 elements

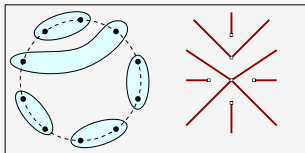


Generic polar partition = non-crossing involution

# Examples

## Definition

Generic = structurally stable flows (open condition)  
 = hyperbolic blocks with 2 elements

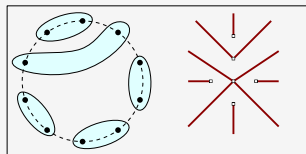


Generic polar partition = non-crossing involution

# Examples

## Definition

Generic = structurally stable flows (open condition)  
 = hyperbolic blocks with 2 elements



Generic polar partition = non-crossing involution

$k$	1	2	3	4	5	6	7
$\#NCInv(k)$	1	1	2	3	6	14	34
$\#NonCrossing(k)$	3	6	26	123	801	5686	43 846

(Computations by T. Tomasini)



# How to compute a polar partition

## Aim

To compute the polar connections near  $\infty$  without going there

# How to compute a polar partition

## Aim

To compute the polar connections near  $\infty$  without going there

## Method

# How to compute a polar partition

## Aim

To compute the polar connections near  $\infty$  without going there

## Method

- 1 Take  $P \in \mathcal{C}[z]$ , prepare it in the form  $z^{k+1} + *z^{k-1} + \dots$  and compute  $\mathfrak{b}(P)$  and  $|P|_k$

# How to compute a polar partition

## Aim

To compute the polar connections near  $\infty$  without going there

## Method

- 1 Take  $P \in \mathcal{C}[z]$ , prepare it in the form  $z^{k+1} + *z^{k-1} + \dots$  and compute  $\mathfrak{b}(P)$  and  $|P|_k$
- 2 Determine the computation parameters (*a priori* bounds)

# How to compute a polar partition

## Aim

To compute the polar connections near  $\infty$  without going there

## Method

- 1 Take  $P \in \mathcal{C}[z]$ , prepare it in the form  $z^{k+1} + *z^{k-1} + \dots$  and compute  $\mathfrak{b}(P)$  and  $|P|_k$
- 2 Determine the computation parameters (*a priori* bounds)
- 3 Find  $2k$  convenient initial values, each one close to a separatrix

# How to compute a polar partition

## Aim

To compute the polar connections near  $\infty$  without going there

## Method

- 1 Take  $P \in \mathcal{C}[z]$ , prepare it in the form  $z^{k+1} + *z^{k-1} + \dots$  and compute  $\mathfrak{b}(P)$  and  $|P|_k$
- 2 Determine the computation parameters (*a priori* bounds)
- 3 Find  $2k$  convenient initial values, each one close to a separatrix
- 4 Compute the partial trajectories (Taylor series method)

# How to compute a polar partition

## Aim

To compute the polar connections near  $\infty$  without going there

## Method

- 1 Take  $P \in \mathcal{C}[z]$ , prepare it in the form  $z^{k+1} + *z^{k-1} + \dots$  and compute  $\mathfrak{b}(P)$  and  $|P|_k$
- 2 Determine the computation parameters (*a priori* bounds)
- 3 Find  $2k$  convenient initial values, each one close to a separatrix
- 4 Compute the partial trajectories (Taylor series method)
- 5 Stop when the trajectory has “almost landed”

# How to compute a polar partition

## Aim

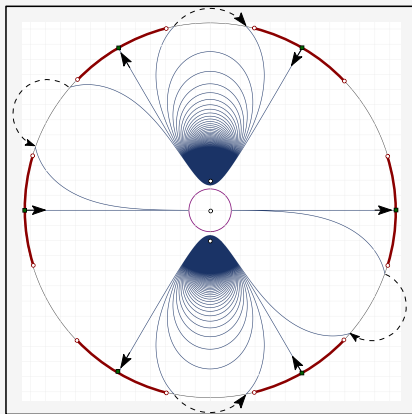
To compute the polar connections near  $\infty$  without going there

## Method

- 1 Take  $P \in \mathcal{C}[z]$ , prepare it in the form  $z^{k+1} + *z^{k-1} + \dots$  and compute  $\mathfrak{b}(P)$  and  $|P|_k$
- 2 Determine the computation parameters (*a priori* bounds)
- 3 Find  $2k$  convenient initial values, each one close to a separatrix
- 4 Compute the partial trajectories (Taylor series method)
- 5 Stop when the trajectory has “almost landed”
- 6 We end up with the incidence matrix of  $\Gamma$

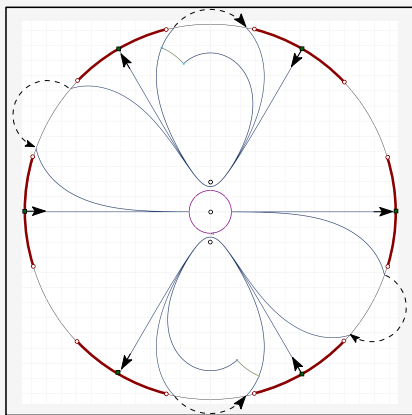


## Simple example



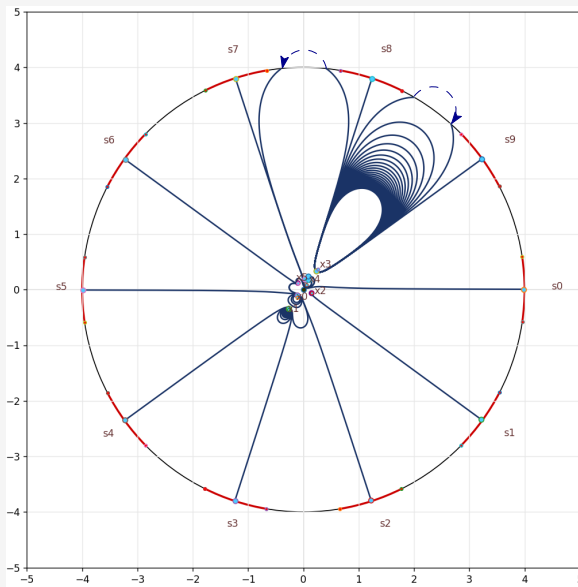
Naive approach

## Computational shortcut: root-traps

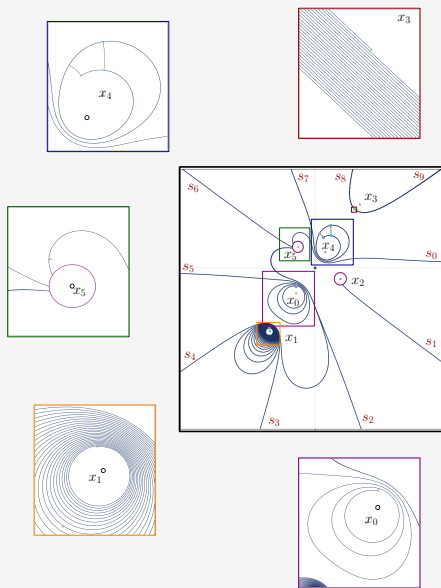


Root-trapping is not a crime

# A typical computation



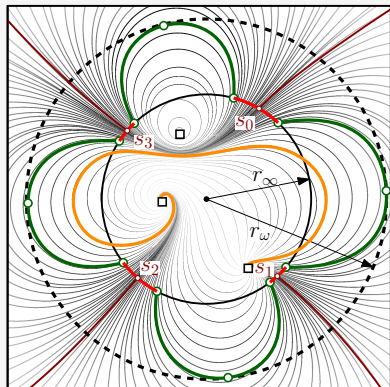
# A typical computation



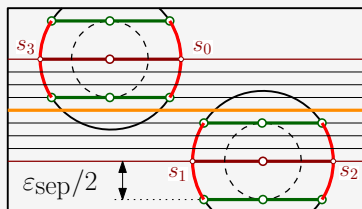
# Determining the parameters: separatrix arcs

# Determining the parameters: separatrix arcs

In  $z$ -space

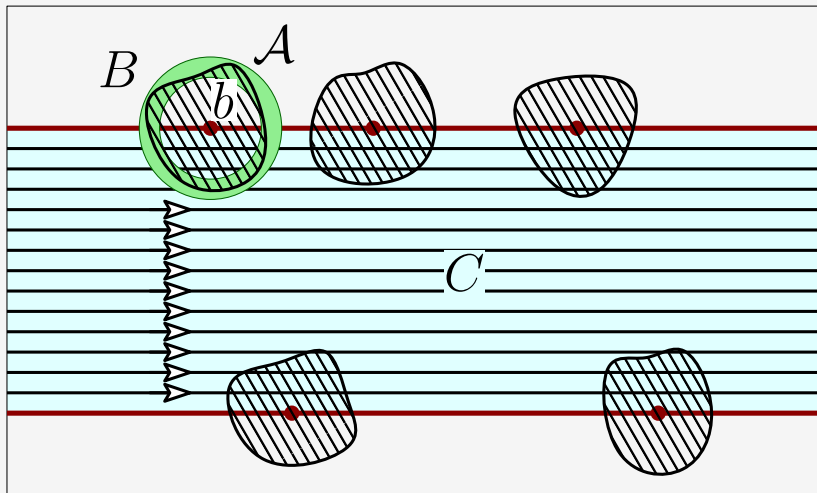


In  $t$ -space



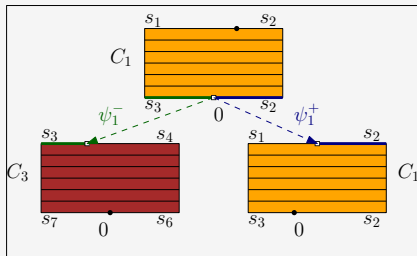
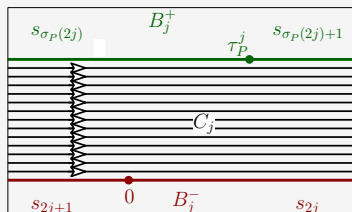
Trajectories in different coordinates, 
$$\begin{cases} P(z) & \simeq z^{k+1} \\ t = T(z) & \simeq \frac{-1}{kz^k} \end{cases} \text{ if } r > r_\infty$$

## Determining the parameters: staying away



Safety annulus around the polar neighborhoods

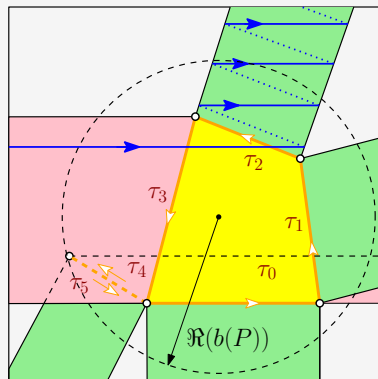
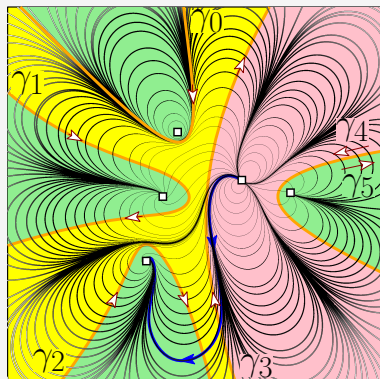
# Determining the parameters: time-strips



Zone in  $t$ -space (left) and atlas of the time surface (right)



# Determining the parameters: periodgon



Periodgon in  $t$ -space (A. Chéritat, M. Klimes, C. Rousseau)

Its edges belong to  $\mathcal{L} = \mathbb{Z}/2\mathbb{Z} \left[ \text{residues of } \frac{1}{P} \right]$

# Determining the parameters

## Main Lemma

We can compute *a priori* bounds on:

for correct computation of  $\Gamma$

# Determining the parameters

## Main Lemma

We can compute *a priori* bounds on:

- 1 safety radius  $r_\infty$  around  $\infty$   
 $P(z) \simeq z^{k+1}$  and  $T(z) \simeq \frac{-1}{kz^k}$

for correct computation of  $\Gamma$

# Determining the parameters

## Main Lemma

We can compute *a priori* bounds on:

- 1 safety radius  $r_\infty$  around  $\infty$   
 $P(z) \simeq z^{k+1}$  and  $T(z) \simeq \frac{-1}{kz^k}$
- 2 width of separatrix arcs

for correct computation of  $\Gamma$

# Determining the parameters

## Main Lemma

We can compute *a priori* bounds on:

- 1 safety radius  $r_\infty$  around  $\infty$   
 $P(z) \simeq z^{k+1}$  and  $T(z) \simeq \frac{-1}{kz^k}$
- 2 width of separatrix arcs
- 3 maximum ODE-solving time before

for correct computation of  $\Gamma$

# Determining the parameters

## Main Lemma

We can compute *a priori* bounds on:

- 1 safety radius  $r_\infty$  around  $\infty$   
 $P(z) \simeq z^{k+1}$  and  $T(z) \simeq \frac{-1}{kz^k}$
- 2 width of separatrix arcs
- 3 maximum ODE-solving time before
  - 1 getting close to a stationary point, or

for correct computation of  $\Gamma$

# Determining the parameters

## Main Lemma

We can compute *a priori* bounds on:

- 1 safety radius  $r_\infty$  around  $\infty$   
 $P(z) \simeq z^{k+1}$  and  $T(z) \simeq \frac{-1}{kz^k}$
- 2 width of separatrix arcs
- 3 maximum ODE-solving time before
  - 1 getting close to a stationary point, or
  - 2 root-trapping a stationary point, or

for correct computation of  $\Gamma$

# Determining the parameters

## Main Lemma

We can compute *a priori* bounds on:

- 1 safety radius  $r_\infty$  around  $\infty$   
 $P(z) \simeq z^{k+1}$  and  $T(z) \simeq \frac{-1}{kz^k}$
- 2 width of separatrix arcs
- 3 maximum ODE-solving time before
  - 1 getting close to a stationary point, or
  - 2 root-trapping a stationary point, or
  - 3 reaching a separatrix arc (homoclinic loop)

for correct computation of  $\Gamma$



# Determining the parameters

## Main Lemma

We can compute *a priori* bounds on:

- 1 safety radius  $r_\infty$  around  $\infty$   
 $P(z) \simeq z^{k+1}$  and  $T(z) \simeq \frac{-1}{kz^k}$
- 2 width of separatrix arcs
- 3 maximum ODE-solving time before
  - 1 getting close to a stationary point, or
  - 2 root-trapping a stationary point, or
  - 3 reaching a separatrix arc (homoclinic loop)
- 4 Taylor solver order and time-step

for correct computation of  $\Gamma$

# Applications

# Applications

- 1 Atlas of Riemann surfaces of certain logarithmic sums

# Applications

- 1 Atlas of Riemann surfaces of certain logarithmic sums
- 2 Computing periodgons: complete analytic invariant of the flow

# Applications

- 1 Atlas of Riemann surfaces of certain logarithmic sums
- 2 Computing periodgons: complete analytic invariant of the flow
- 3 Certified ODE solver: once the periodgon is known, better constants

# Applications

- 1 Atlas of Riemann surfaces of certain logarithmic sums
- 2 Computing periodgons: complete analytic invariant of the flow
- 3 Certified ODE solver: once the periodgon is known, better constants
- 4 Use of machine learning (with D. Vlah, Zagreb)

# Applications

- 1 Atlas of Riemann surfaces of certain logarithmic sums
- 2 Computing periodgons: complete analytic invariant of the flow
- 3 Certified ODE solver: once the periodgon is known, better constants
- 4 Use of machine learning (with D. Vlah, Zagreb)
  - 1 for fast determination of polar partitions ( $k \leq 10$  or more?)

# Applications

- 1 Atlas of Riemann surfaces of certain logarithmic sums
- 2 Computing periodgons: complete analytic invariant of the flow
- 3 Certified ODE solver: once the periodgon is known, better constants
- 4 Use of machine learning (with D. Vlah, Zagreb)
  - 1 for fast determination of polar partitions ( $k \leq 10$  or more?)
  - 2 for the inverse problem



# Applications

- 1 Atlas of Riemann surfaces of certain logarithmic sums
- 2 Computing periodgons: complete analytic invariant of the flow
- 3 Certified ODE solver: once the periodgon is known, better constants
- 4 Use of machine learning (with D. Vlah, Zagreb)
  - 1 for fast determination of polar partitions ( $k \leq 10$  or more?)
  - 2 for the inverse problem
- 5 If the inverse problem is solved:

# Applications

- 1 Atlas of Riemann surfaces of certain logarithmic sums
- 2 Computing periodgons: complete analytic invariant of the flow
- 3 Certified ODE solver: once the periodgon is known, better constants
- 4 Use of machine learning (with D. Vlah, Zagreb)
  - 1 for fast determination of polar partitions ( $k \leq 10$  or more?)
  - 2 for the inverse problem
- 5 If the inverse problem is solved:
  - 1 *dessins d'enfants*

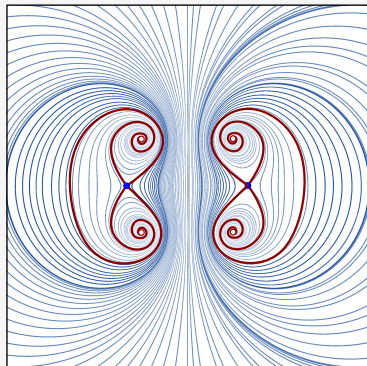
# Applications

- 1 Atlas of Riemann surfaces of certain logarithmic sums
- 2 Computing periodgons: complete analytic invariant of the flow
- 3 Certified ODE solver: once the periodgon is known, better constants
- 4 Use of machine learning (with D. Vlah, Zagreb)
  - 1 for fast determination of polar partitions ( $k \leq 10$  or more?)
  - 2 for the inverse problem
- 5 If the inverse problem is solved:
  - 1 *dessins d'enfants*
  - 2 explicitly embedding finite graphs

## Further work

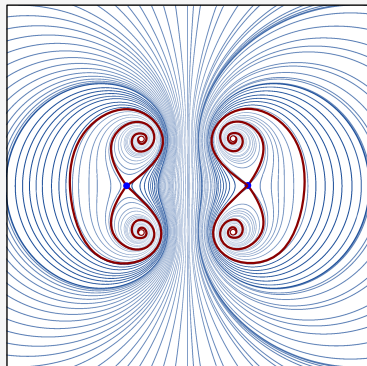
## Further work

- 1 Atlas/periodogon of finitely determined translation surfaces



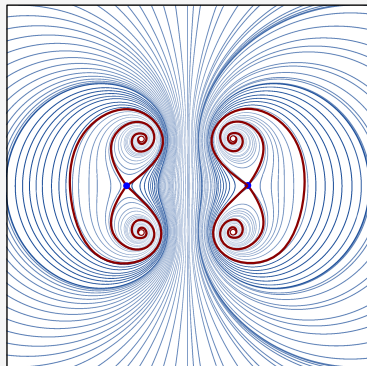
## Further work

- 1 Atlas/periodogon of finitely determined translation surfaces
  - 1 Rational flows and periodogon (on a sphere)



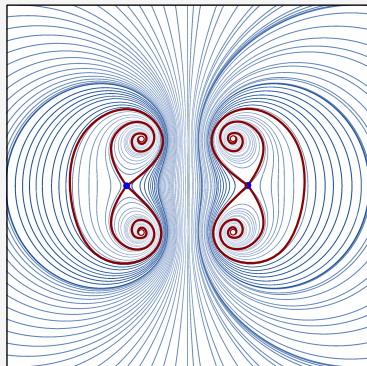
## Further work

- 1 Atlas/periodogon of finitely determined translation surfaces
  - 1 Rational flows and periodogon (on a sphere)
  - 2 Algebraic flows and periodogon (on a genus- $g$  Riemann surface)



## Further work

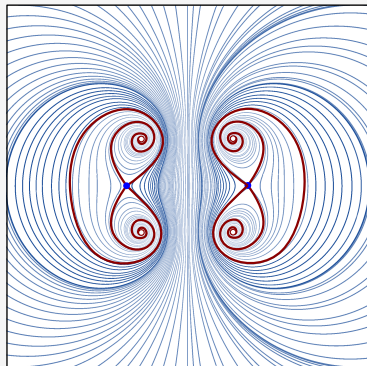
- 1 Atlas/periodgon of finitely determined translation surfaces
  - 1 Rational flows and periodgon (on a sphere)
  - 2 Algebraic flows and periodgon (on a genus- $g$  Riemann surface)
  - 3 Transcendent flows





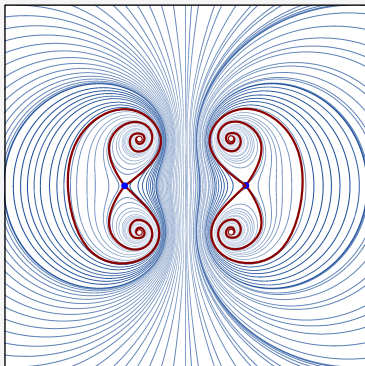
## Further work

- 1 Atlas/periodgon of finitely determined translation surfaces
  - 1 Rational flows and periodgon (on a sphere)
  - 2 Algebraic flows and periodgon (on a genus- $g$  Riemann surface)
  - 3 Transcendent flows
- 2 Inverse problem



## Further work

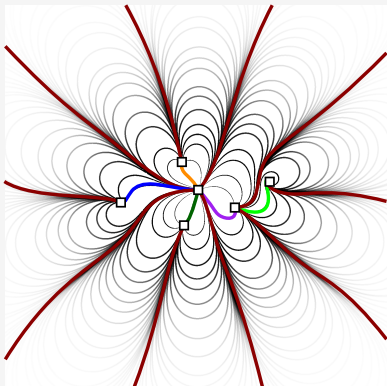
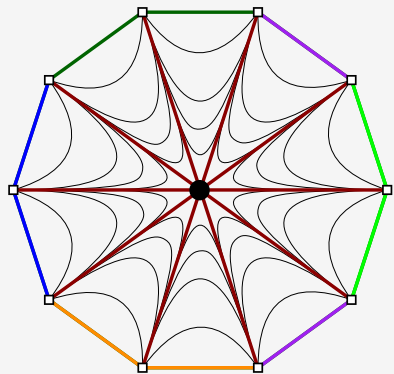
- 1 Atlas/periodgon of finitely determined translation surfaces
  - 1 Rational flows and periodgon (on a sphere)
  - 2 Algebraic flows and periodgon (on a genus- $g$  Riemann surface)
  - 3 Transcendent flows
- 2 Inverse problem



### Conjecture

*Any finite graph can be obtained as the separatrix graph of an algebraic flow*

# Thank you for your attention



(and enjoy a nice meal!)