

13ème Atelier en Évaluation des Performances

Toulouse, Dec 2-4, 2024

Decision-Epoch Matters: Unveiling its Impact on the Stability of Scheduling with Randomly Varying Connectivity

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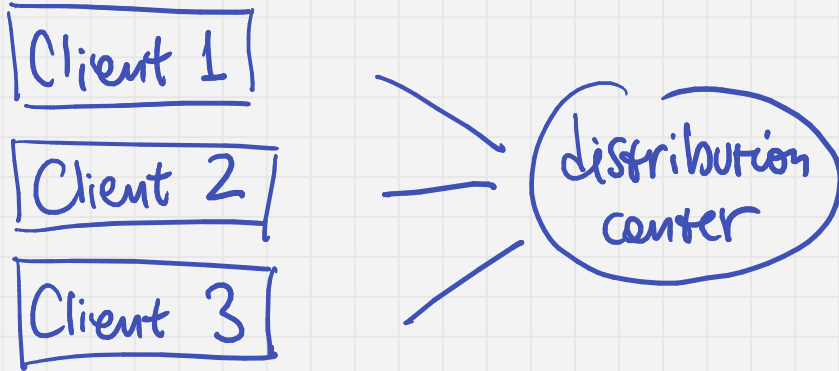
Application example:
supply chains

queuing systems ; random environment ; timing restrictions over decision making

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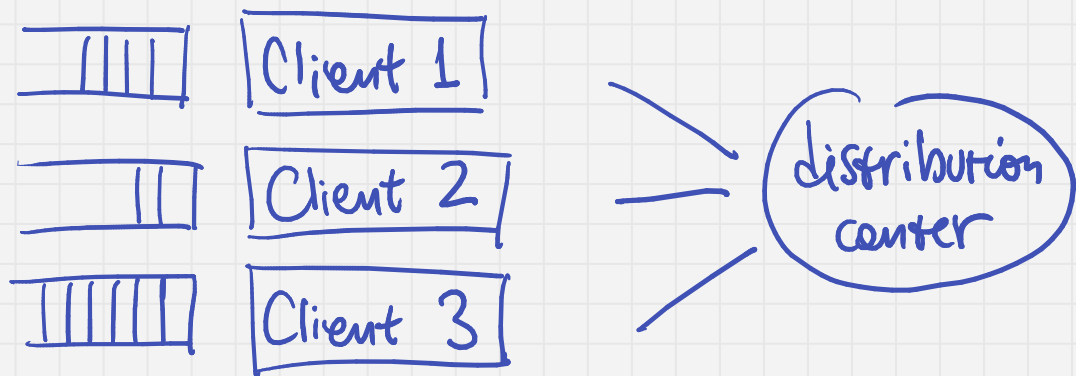
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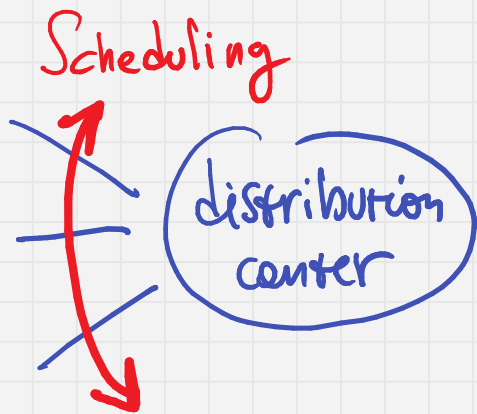
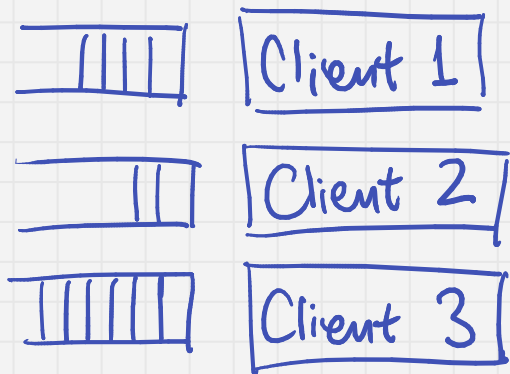


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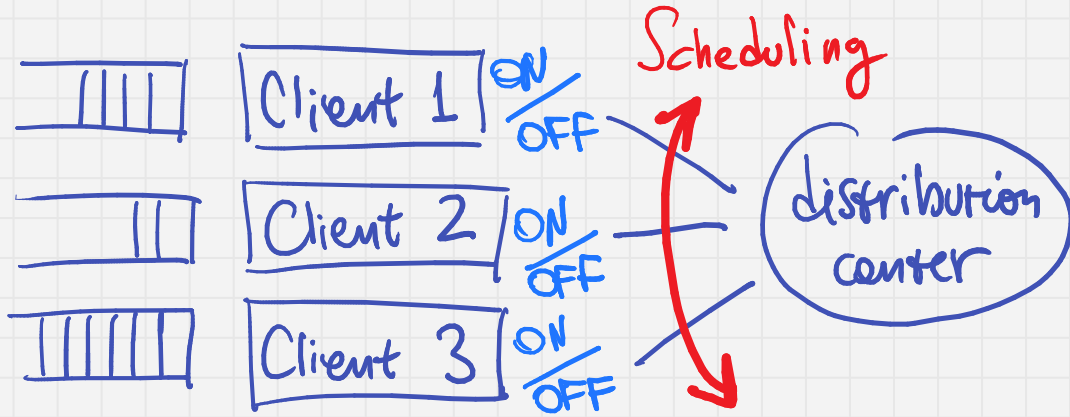


Application example: supply chains

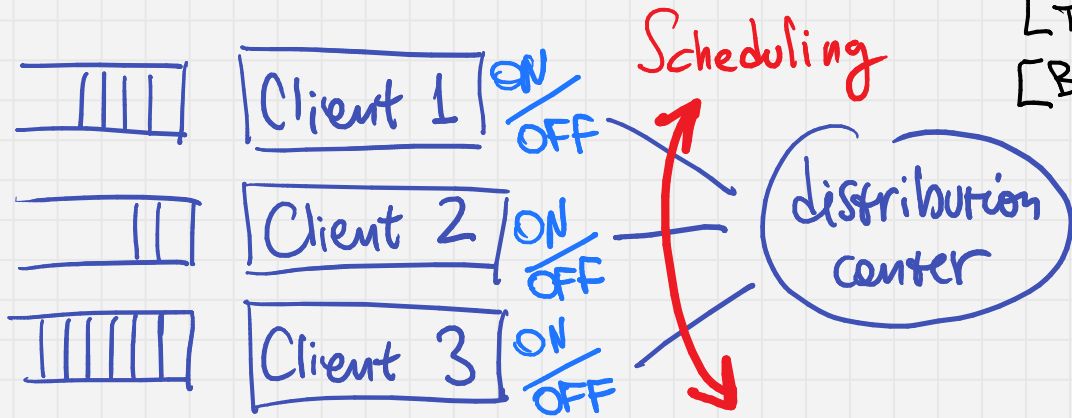
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Application example: supply chains

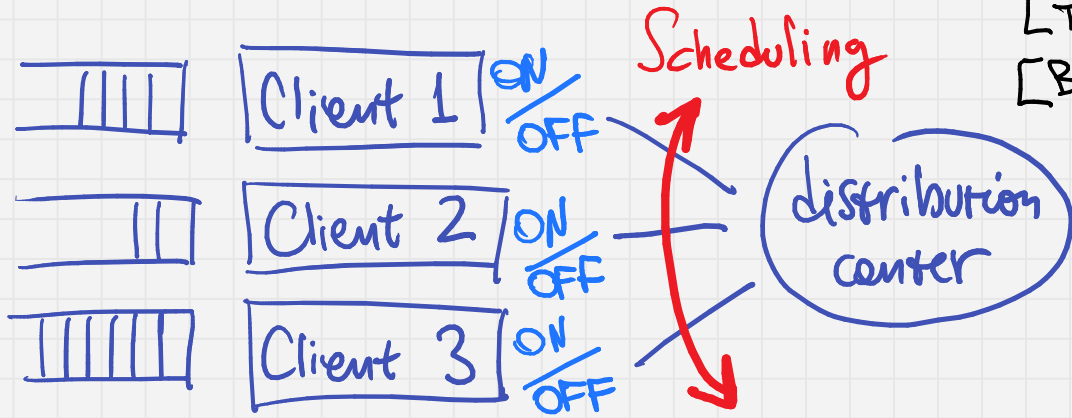


queuing systems ; random environment ;

[Tassiulas, Ephremides; 1993]
[Bambos, Michailidis; 2005]

timing restrictions over decision making

Application example: supply chains



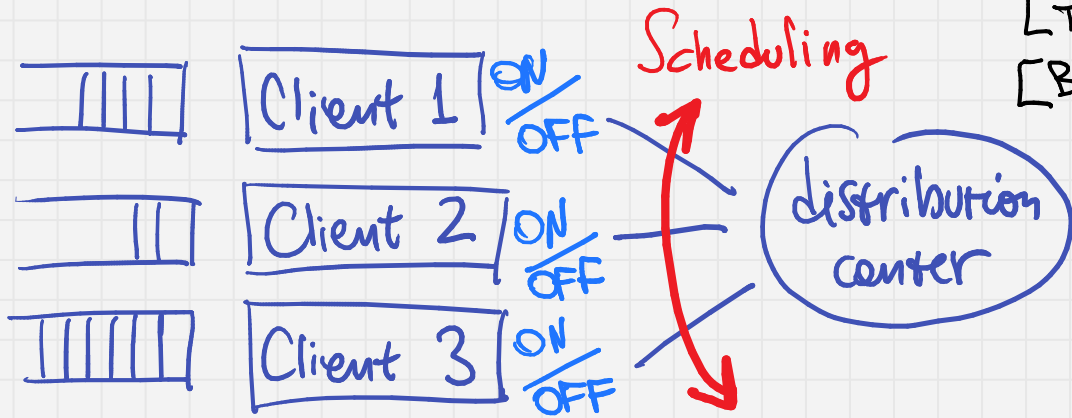
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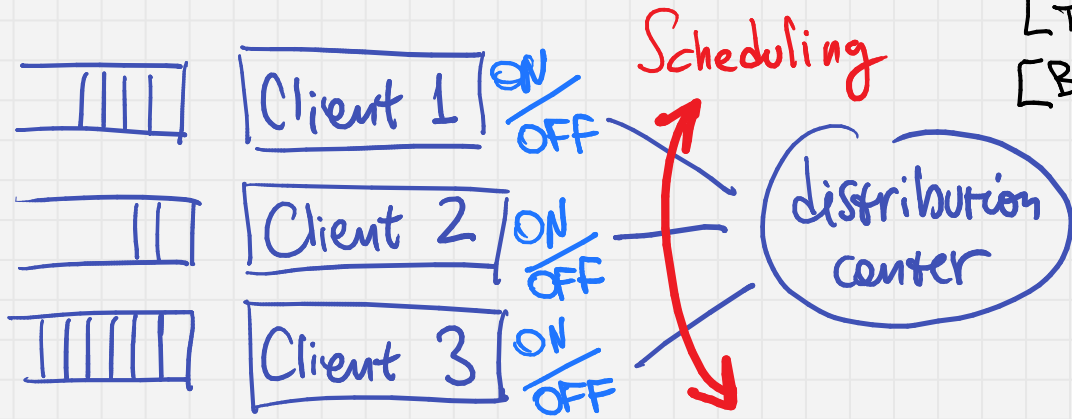
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Application example: supply chains



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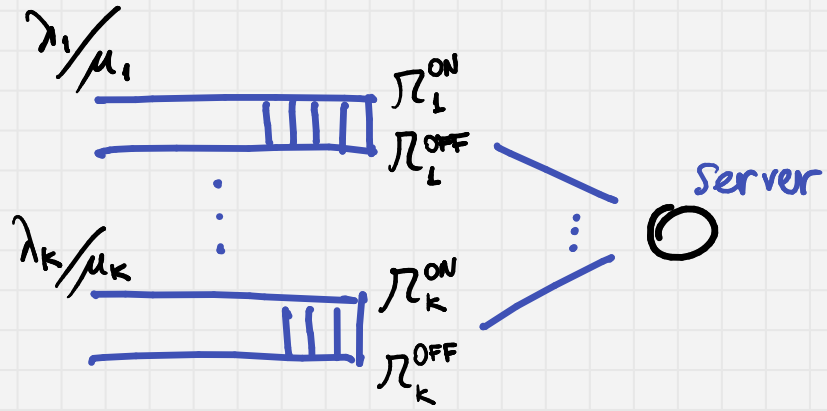
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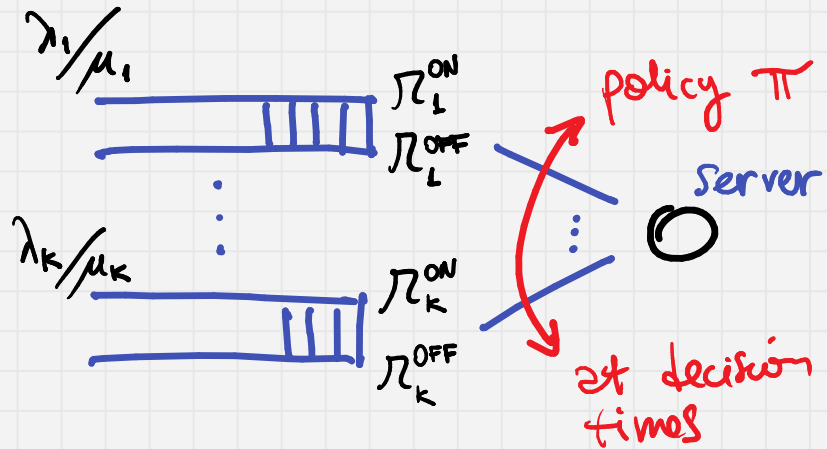
Performance guarantees?

Optional policies?

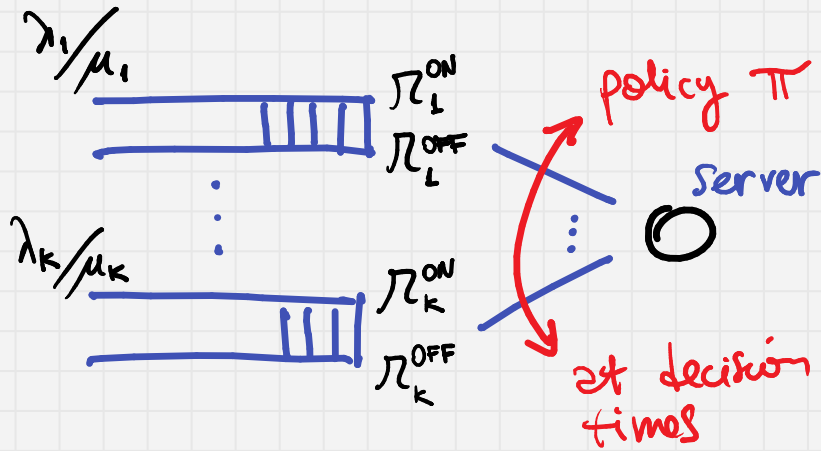
The mathematical model



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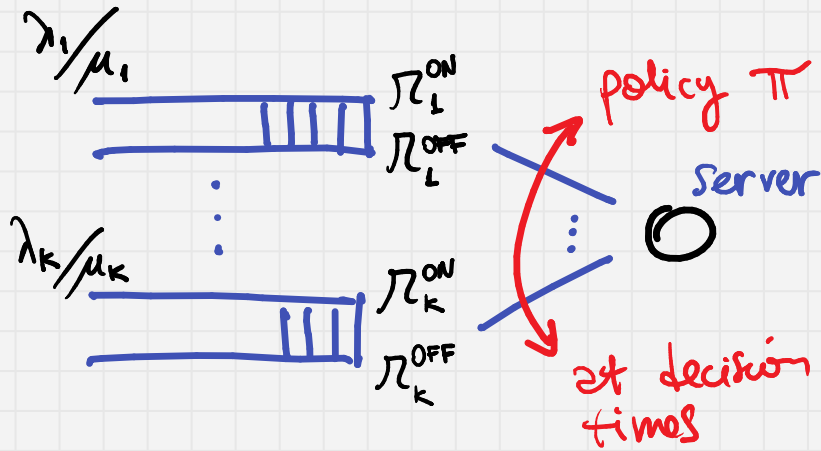
The mathematical model



Model assumptions:

- commutative state-space
- Markovian (observable) policies
- No processor sharing

The mathematical model



Timing restrictions:

Setting 1: unconstrained

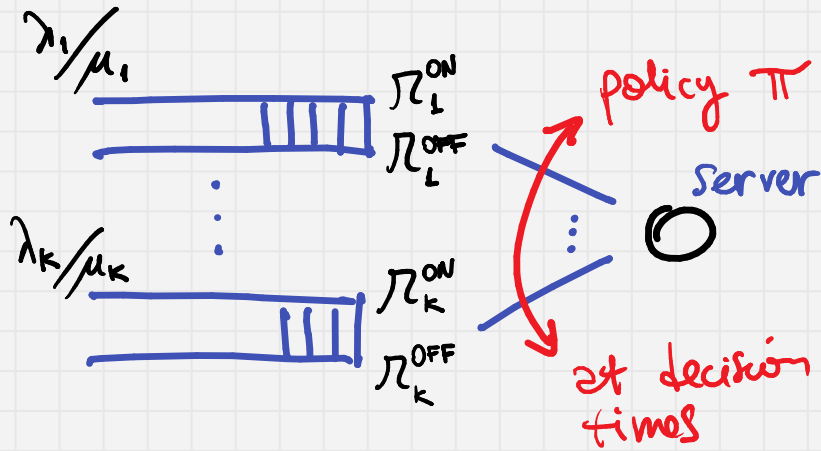
Setting 2: non-preemptive

Setting 3: γ -rate exponentially

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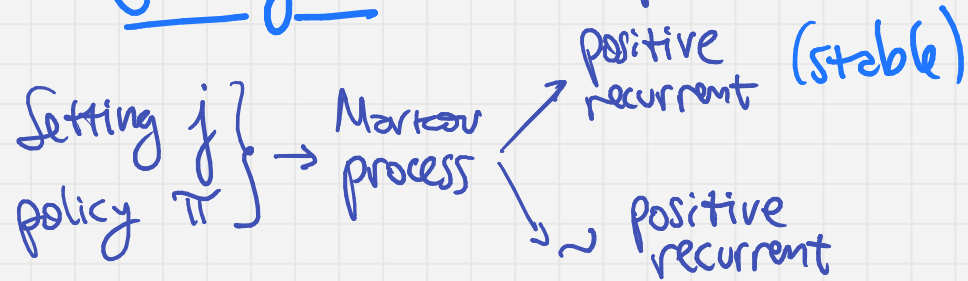
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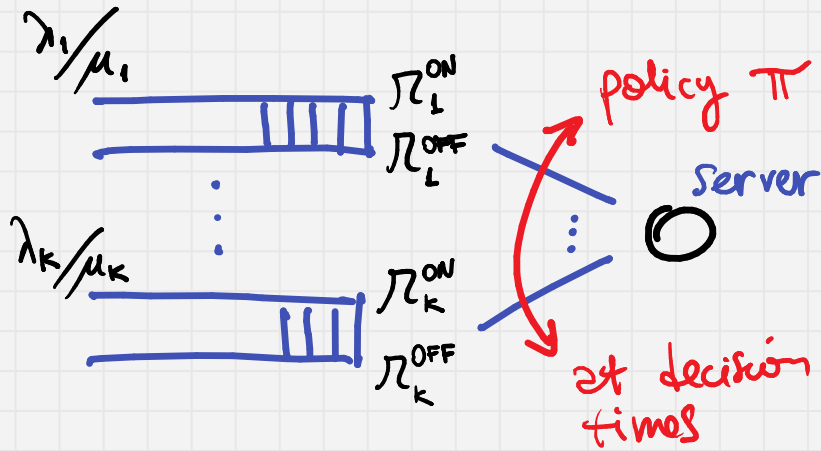
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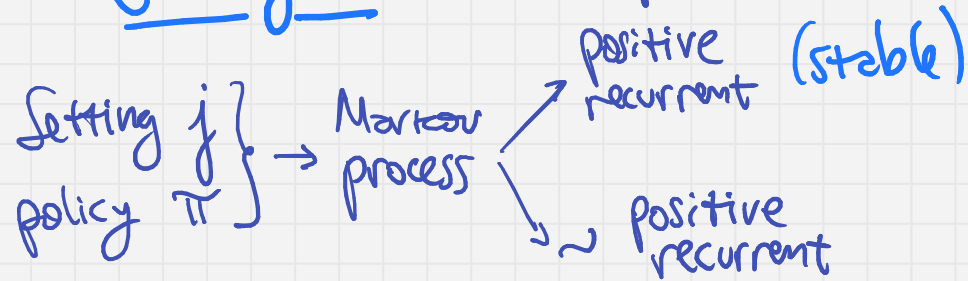
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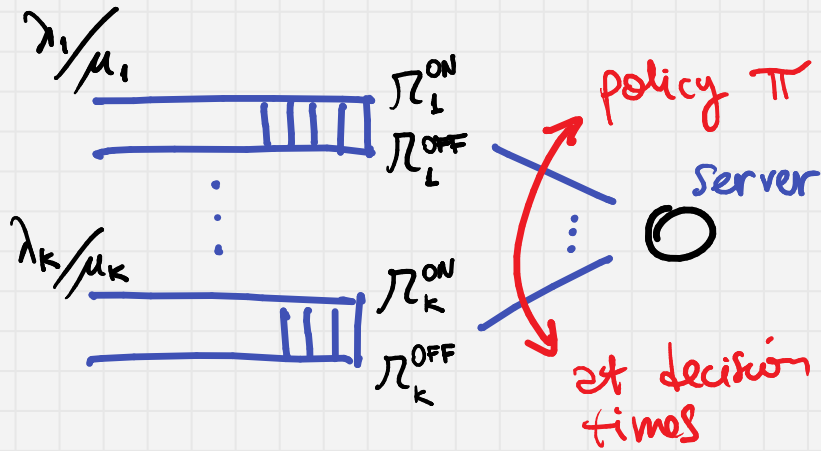
Setting 2: non-preemptive

Setting 3: γ -rate exponential



$$SR_j(\pi) = \left\{ (\underline{\lambda}, \underline{\mu}, \underline{\rho}^{ON}, \underline{\rho}^{OFF}) : \pi \text{ is stable} \right\}$$

The mathematical model



Model assumptions:

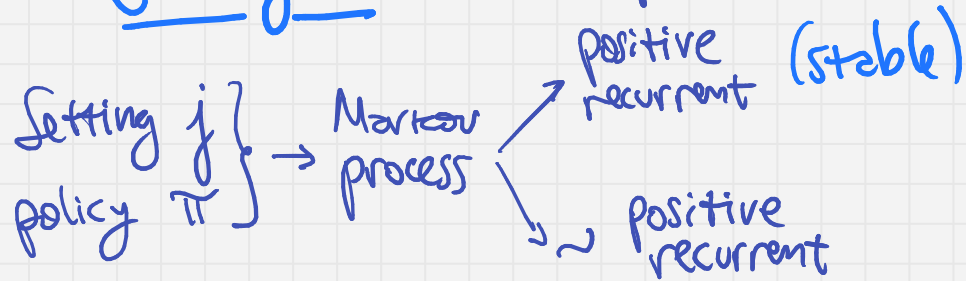
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Timing restrictions:

Setting 1: unconstrained

Setting 2: non-preemptive

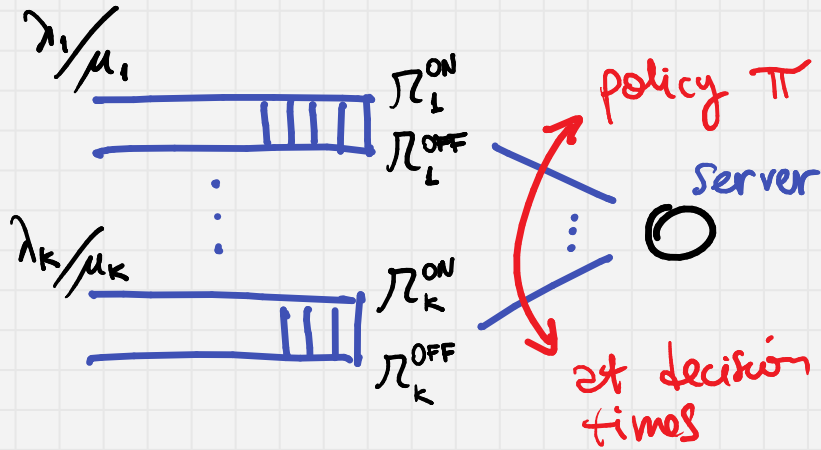
Setting 3: δ -rate exponentially



$$SR_j(\pi) = \{ (\underline{\lambda}, \underline{\mu}, \underline{\rho}^{ON}, \underline{\rho}^{OFF}) : \pi \text{ is stable} \}$$

$$MSR_j = \bigcup_{\pi} SR_j(\pi)$$

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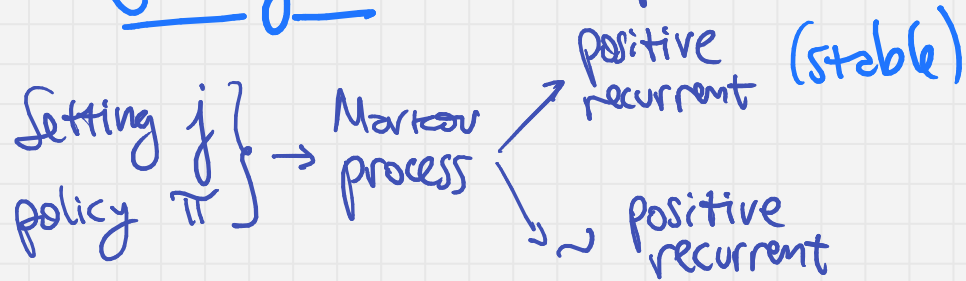
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$$SR_j(\pi) = \{(\underline{\lambda}, \underline{\mu}, \underline{\rho}^{ON}, \underline{\rho}^{OFF}) : \pi \text{ is stable}\}$$

$$MSR_j = \bigcup_{\pi} SR_j(\pi)$$

π^* is throughput optimal if

$$SR_j(\pi^*) = MSR_j$$

Main theorem

$$\rho_i = \frac{\lambda_i}{\mu_i}, \quad p_i^{\text{ON}} = \frac{\% \text{ time ON}}{\text{queue } i} = \frac{\rho_i^{\text{ON}}}{\rho_i^{\text{ON}} + \rho_i^{\text{OFF}}} = 1 - p_i^{\text{OFF}}$$

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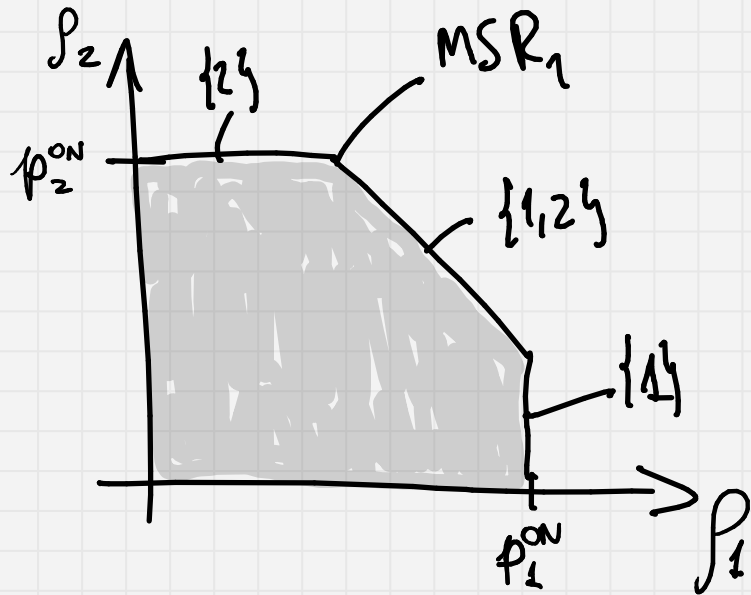
$$\text{MSR}_1: \quad \forall L \subseteq \{1, \dots, K\}, \quad \underbrace{\sum_{i \in L} \rho_i}_{\text{load at } L} < \underbrace{1 - \prod_{i \in L} p_i^{\text{OFF}}}_{\text{maximum capacity}}$$

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MSR₁: $\forall L \subseteq \{1, \dots, K\}, \underbrace{\sum_{i \in L} \rho_i}_{\text{load at } L} < \underbrace{1 - \prod_{i \in L} p_i^{\text{OFF}}}_{\text{maximum capacity}}$
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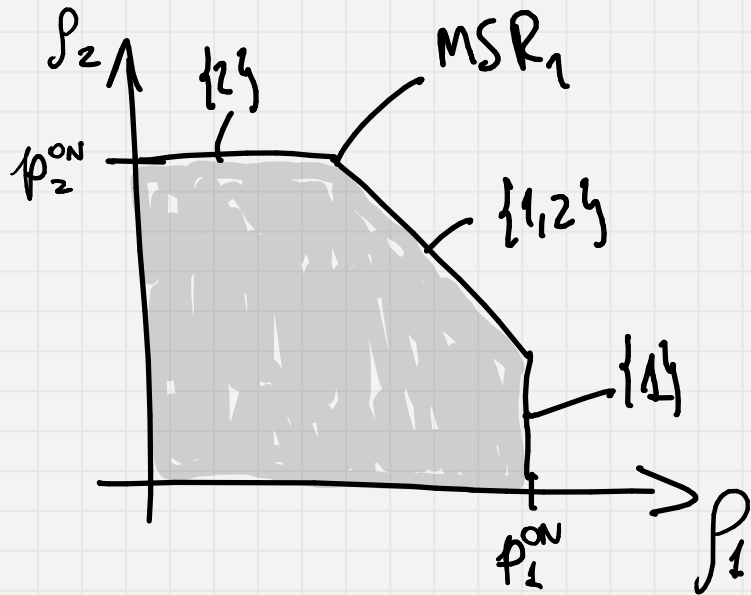


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(unconstrained)
↑ not new



Main theorem

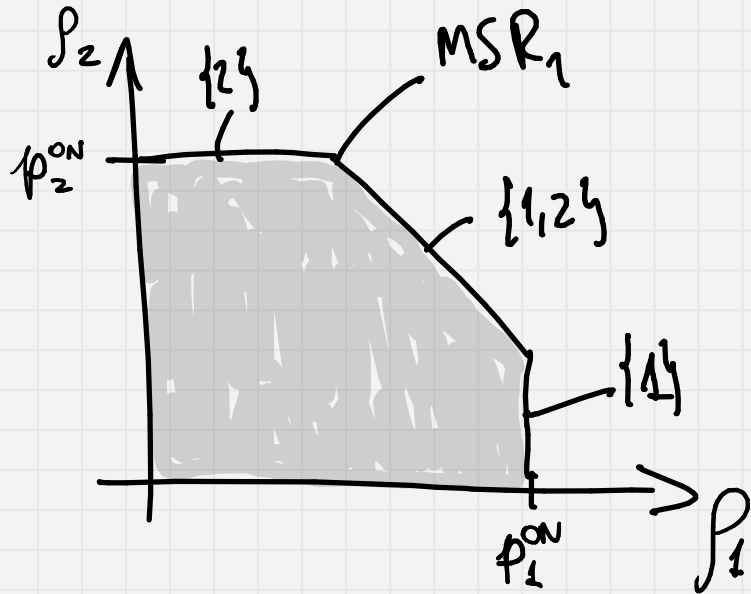
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$$\text{MSR}_2: \sum_{i=1}^K \frac{\rho_i}{p_i^{\text{ON}}} < 1$$

(non-preemptive)



Main theorem

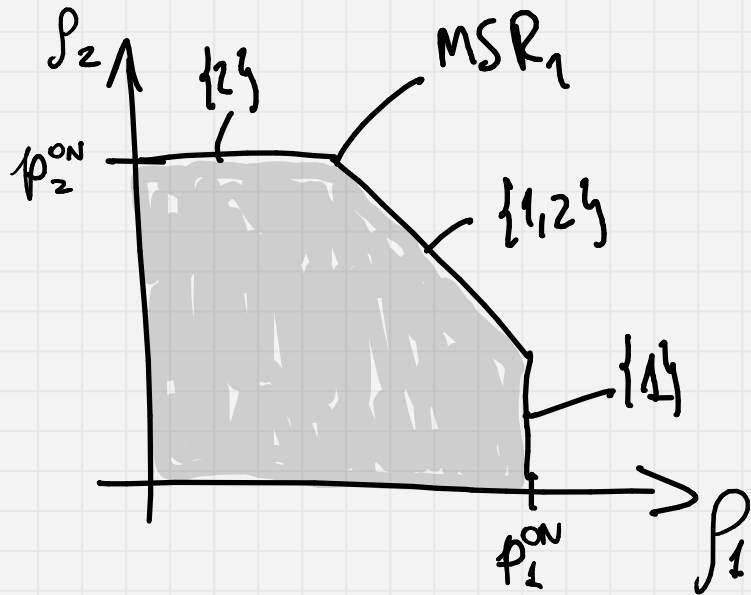
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(unconstrained)
 ↖ not new

$$\text{MSR}_2: \sum_{i=1}^K \frac{\rho_i}{p_i^{\text{ON}}} < 1 \leftarrow \begin{array}{l} \text{multi-class} \\ \text{M/G/1} \end{array}$$

(non-preemptive)



Main theorem

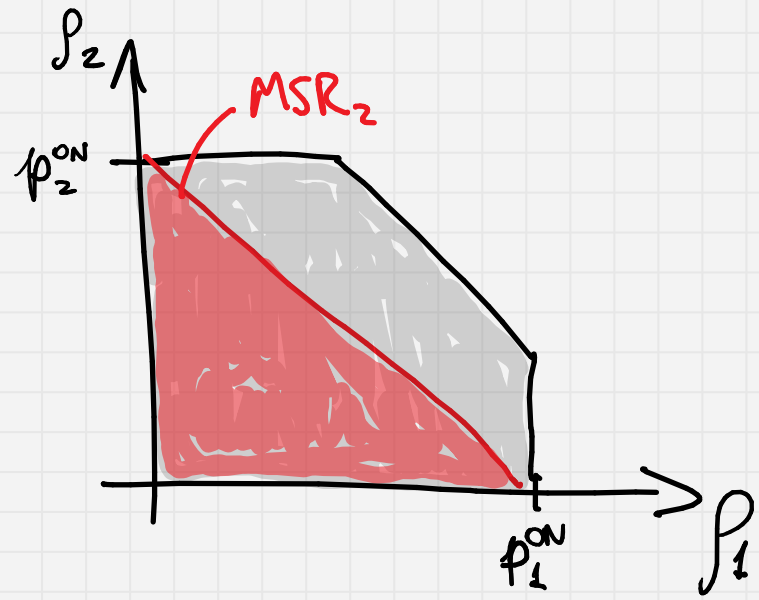
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MSR₁: $\forall L \subseteq \{1, \dots, K\}, \underbrace{\sum_{i \in L} \rho_i}_{\text{load at } L} < \underbrace{1 - \prod_{i \in L} p_i^{\text{OFF}}}_{\text{maximum capacity}}$

(unconstrained)
 ↖ not new

MSR₂: $\sum_{i=1}^K \frac{\rho_i}{p_i^{\text{ON}}} < 1 \leftarrow \text{multi-class M/G/1}$

(non-preemptive)



Main theorem

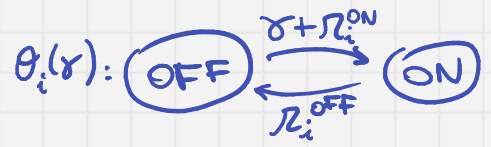
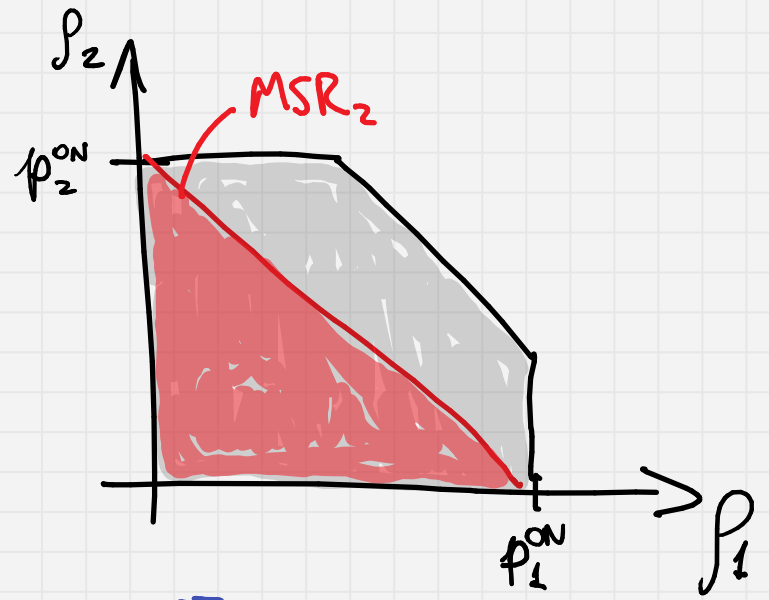
$$\rho_i = \frac{\lambda_i}{\mu_i}, \quad p_i^{\text{ON}} = \frac{\% \text{ time ON}}{\text{queue } i} = \frac{\lambda_i^{\text{ON}}}{\lambda_i^{\text{ON}} + \lambda_i^{\text{OFF}}} = 1 - p_i^{\text{OFF}}$$

MSR₁: $\forall L \subseteq \{1, \dots, K\}, \underbrace{\sum_{i \in L} \rho_i}_{\text{load at } L} < \underbrace{1 - \prod_{i \in L} p_i^{\text{OFF}}}_{\text{maximum capacity}}$

(unconstrained)
 ↖ not new

MSR₂: $\sum_{i=1}^K \frac{\rho_i}{p_i^{\text{ON}}} < 1$ ← multi-class M/G/1
 (non-preemptive)

MSR₃(γ) — CONNECTED POLICIES: $\forall L \subseteq \{1, \dots, K\}, \sum_{i \in L} \frac{\rho_i}{\theta_i(\gamma)} < 1 - \prod_{i \in L} p_i^{\text{OFF}}$
 (γ -exponentials)



Main theorem

$$\rho_i = \frac{\lambda_i}{\mu_i}, \quad p_i^{\text{ON}} = \frac{\% \text{ time ON}}{\text{queue } i} = \frac{\lambda_i^{\text{ON}}}{\lambda_i^{\text{ON}} + \lambda_i^{\text{OFF}}} = 1 - p_i^{\text{OFF}}$$

$$\text{MSR}_1: \forall L \subseteq \{1, \dots, K\}, \underbrace{\sum_{i \in L} \rho_i}_{\text{load at } L} < \underbrace{1 - \prod_{i \in L} p_i^{\text{OFF}}}_{\text{maximum capacity}}$$

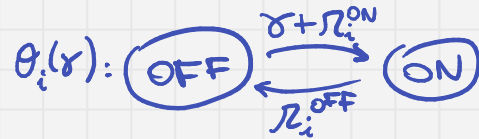
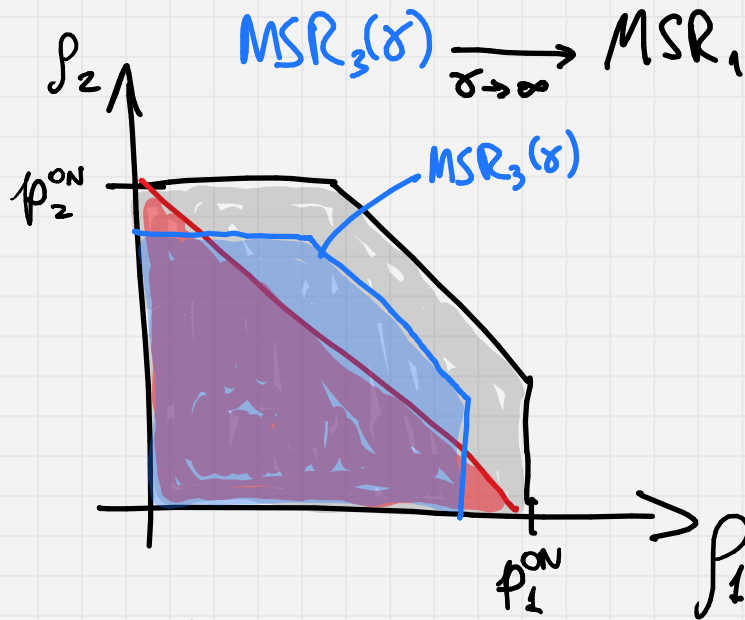
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$$\text{MSR}_2: \sum_{i=1}^K \frac{\rho_i}{p_i^{\text{ON}}} < 1 \leftarrow \text{multi-class M/G/1}$$

(non-preemptive)

$$\text{MSR}_3(\gamma) \text{ — CONNECTED POLICIES: } \forall L \subseteq \{1, \dots, K\}, \sum_{i \in L} \frac{\rho_i}{\theta_i(\gamma)} < 1 - \prod_{i \in L} p_i^{\text{OFF}}$$

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Main theorem

$$\rho_i = \frac{\lambda_i}{\mu_i}, \quad p_i^{\text{ON}} = \frac{\% \text{ time ON}}{\text{queue } i} = \frac{\lambda_i^{\text{ON}}}{\lambda_i^{\text{ON}} + \lambda_i^{\text{OFF}}} = 1 - p_i^{\text{OFF}}$$

$$\text{MSR}_1: \forall L \subseteq \{1, \dots, K\}, \underbrace{\sum_{i \in L} \rho_i}_{\text{load at } L} < \underbrace{1 - \prod_{i \in L} p_i^{\text{OFF}}}_{\text{maximum capacity}}$$

(unconstrained)
 \leftarrow not new

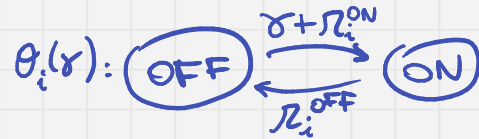
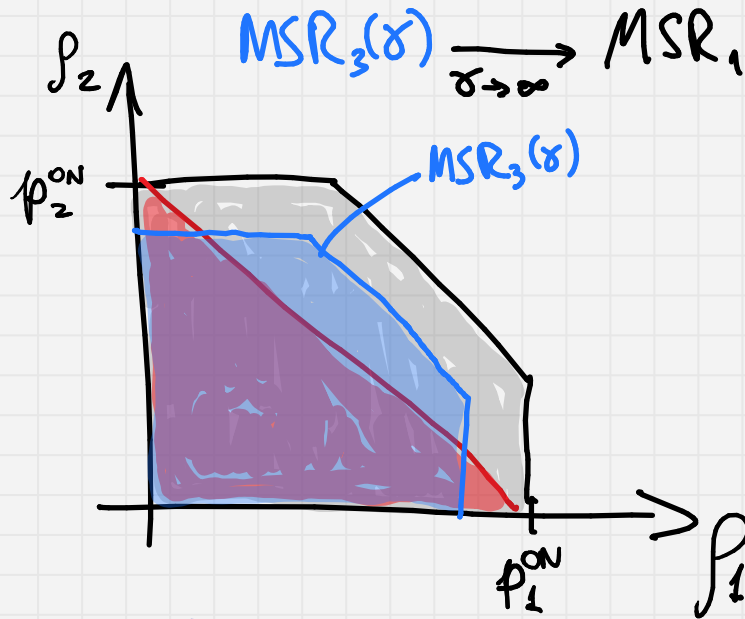
$$\text{MSR}_2: \sum_{i=1}^K \frac{\rho_i}{p_i^{\text{ON}}} < 1 \leftarrow \text{multi-class M/G/1}$$

(non-preemptive)

$$\text{MSR}_3(\gamma) \text{ — CONNECTED POLICIES: } \forall L \subseteq \{1, \dots, K\}, \sum_{i \in L} \frac{\rho_i}{\theta_i(\gamma)} < 1 - \prod_{i \in L} p_i^{\text{OFF}}$$

(γ -exponentials)

$\forall c_1, \dots, c_K > 0$, arg max $c_i Q_i$ s.t. $\{E_i = \text{ON}\}$ is optimal.



Main theorem

$$\rho_i = \frac{\lambda_i}{\mu_i}, \quad p_i^{\text{ON}} = \frac{\% \text{ time ON}}{\text{queue } i} = \frac{\lambda_i^{\text{ON}}}{\lambda_i^{\text{ON}} + \lambda_i^{\text{OFF}}} = 1 - p_i^{\text{OFF}}$$

$$\text{MSR}_1: \forall L \subseteq \{1, \dots, K\}, \underbrace{\sum_{i \in L} \rho_i}_{\text{load at } L} < \underbrace{1 - \prod_{i \in L} p_i^{\text{OFF}}}_{\text{maximum capacity}}$$

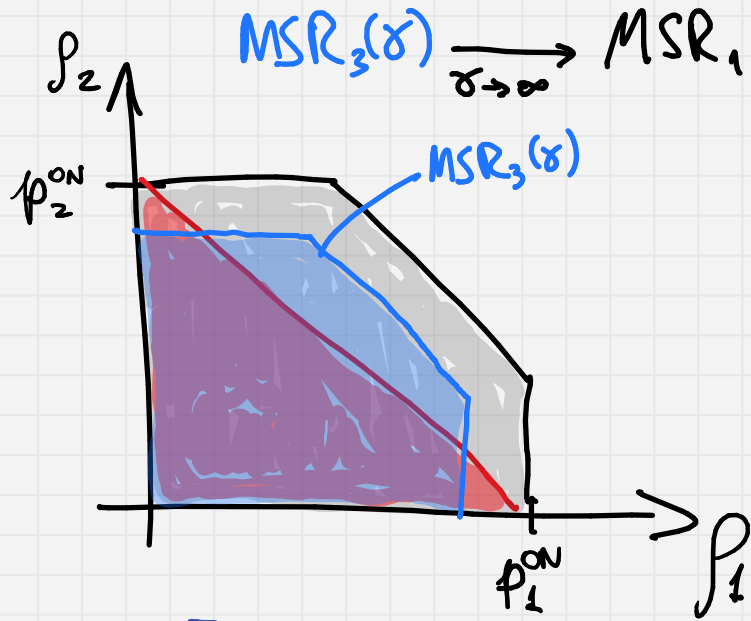
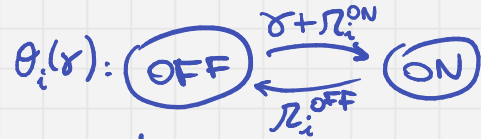
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$$\text{MSR}_2: \sum_{i=1}^K \frac{\rho_i}{p_i^{\text{ON}}} < 1 \leftarrow \text{multi-class M/G/1}$$

(non-preemptive)

$$\text{MSR}_3(\delta) \text{ — CONNECTED POLICIES: } \forall L \subseteq \{1, \dots, K\}, \sum_{i \in L} \frac{\rho_i}{\theta_i(\delta)} < 1 - \prod_{i \in L} p_i^{\text{OFF}}$$

(δ -exponentials)



$\forall c_1, \dots, c_K > 0$, $\arg \max_{i \in \{1, \dots, K\}} c_i Q_i \cdot \mathbb{1}\{E_i = \text{ON}\}$ is optimal. In particular, SLCQ is optimal.

Main theorem

$$p_i = \frac{\lambda_i}{\mu_i}, \quad p_i^{\text{ON}} = \frac{\% \text{ time ON}}{\text{queue } i} = \frac{\lambda_i^{\text{ON}}}{\lambda_i^{\text{ON}} + \lambda_i^{\text{OFF}}} = 1 - p_i^{\text{OFF}}$$

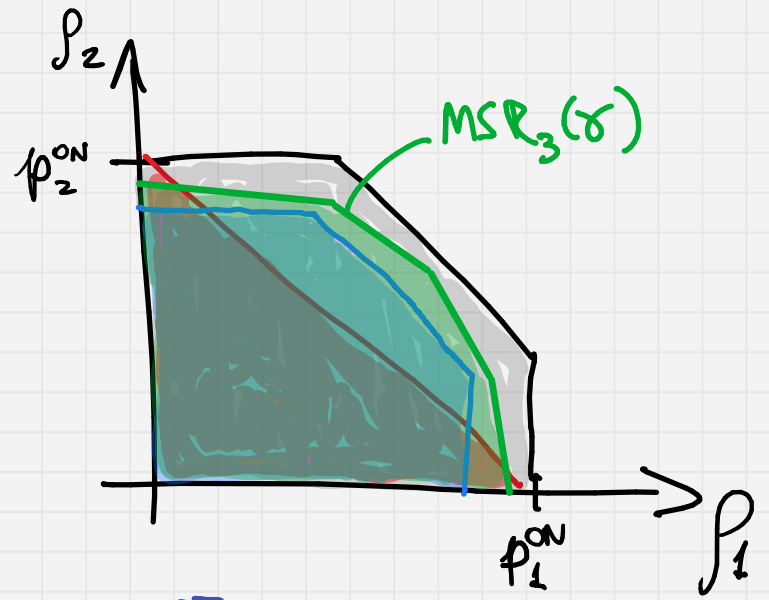
MSR₁: $\forall L \subseteq \{1, \dots, K\}, \underbrace{\sum_{i \in L} p_i}_{\text{load at } L} < \underbrace{1 - \prod_{i \in L} p_i^{\text{OFF}}}_{\text{maximum capacity}}$
 (unconstrained)
 ↖ not new

MSR₂: $\sum_{i=1}^K \frac{p_i}{p_i^{\text{ON}}} < 1$ ← multi-class M/G/1
 (non-preemptive)

MSR₃(δ) — CONNECTED POLICIES: $\forall L \subseteq \{1, \dots, K\}, \sum_{i \in L} \frac{p_i}{\theta_i(\delta)} < 1 - \prod_{i \in L} p_i^{\text{OFF}}$
 (δ -exponentials)
 $\theta_i(\delta): \text{OFF} \xrightleftharpoons[\lambda_i^{\text{OFF}}]{\delta + \lambda_i^{\text{ON}}} \text{ON}$

$\forall c_1, \dots, c_K > 0$, $\arg \max_{i \in \{1, \dots, K\}} c_i Q_i \mathbb{1}\{E_i = \text{ON}\}$ is optimal. In particular, SLCQ is optimal.

MSR₃(δ) — NON-CONNECTED POLICIES: Minkowski sum of triangles — optimal policies: $\arg \max_{i \in \{1, \dots, K\}} c_i Q_i (\underbrace{\mathbb{1}\{E_i = \text{ON}\}}_{\in (0,1)} + K_i \mathbb{1}\{E_i = \text{OFF}\})$



[Andreas, Kumaran, Ramaman, Stolyer, Vijayakumar, Whiting; 2004]

Main theorem

$$\rho_i = \frac{\lambda_i}{\mu_i}, \quad p_i^{\text{ON}} = \frac{\% \text{ time ON}}{\text{queue } i} = \frac{\lambda_i^{\text{ON}}}{\lambda_i^{\text{ON}} + \lambda_i^{\text{OFF}}} = 1 - p_i^{\text{OFF}}$$

$$\text{MSR}_1: \forall L \subseteq \{1, \dots, K\}, \underbrace{\sum_{i \in L} \rho_i}_{\text{load at } L} < \underbrace{1 - \prod_{i \in L} p_i^{\text{OFF}}}_{\text{maximum capacity}}$$

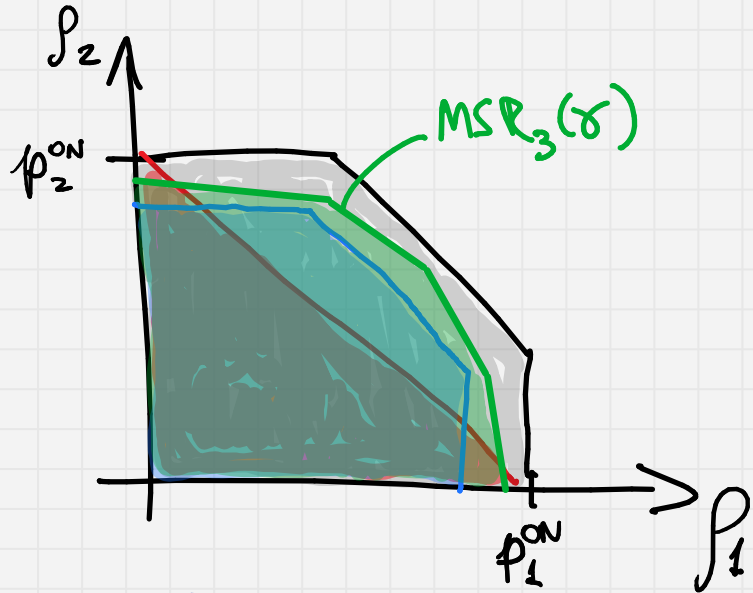
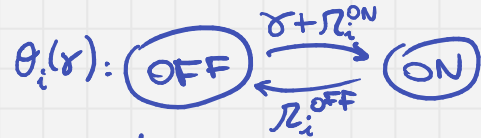
(unconstrained)
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$$\text{MSR}_2: \sum_{i=1}^K \frac{\rho_i}{p_i^{\text{ON}}} < 1 \leftarrow \text{multi-class M/G/1}$$

(non-preemptive)

$$\text{MSR}_3(\delta) \text{ — CONNECTED POLICIES: } \forall L \subseteq \{1, \dots, K\}, \sum_{i \in L} \frac{\rho_i}{\theta_i(\delta)} < 1 - \prod_{i \in L} p_i^{\text{OFF}}$$

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$\forall c_1, \dots, c_k > 0$, $\arg \max_{i \in \{1, \dots, K\}} c_i Q_i \mathbb{1}\{E_i = \text{ON}\}$ is optimal. In particular, SLCQ is optimal.

$\text{MSR}_3(\delta)$ — NON-CONNECTED POLICIES: Minkowski sum of triangles — optimal policies: $\arg \max_{i \in \{1, \dots, K\}} c_i Q_i (\mathbb{1}\{E_i = \text{ON}\} + \underbrace{K_i}_{\in (0,1)} \mathbb{1}\{E_i = \text{OFF}\})$

Obs.: they're all agnostic policies.

[Andrews, Kumar, Ramanan, Stolyar, Vijayakumar, Whiting; 2004]

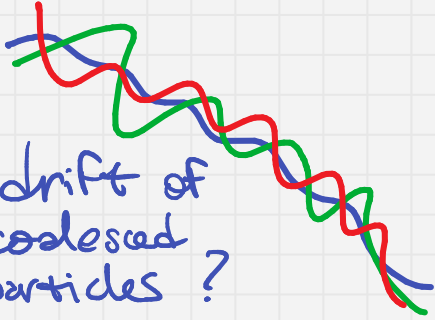
Proof: test for fluid limits (TFL)

Classical result
(Dai, Rybko-Stolyar) : ^{stable} Fluid model \Rightarrow ^{stable} stochastic model

Proof: test for fluid limits (TFL)

Classical result
(Dai, Rybko-Stolyar) : $\begin{matrix} \text{stable} \\ \text{Fluid} \\ \text{model} \end{matrix} \Rightarrow \begin{matrix} \text{stable} \\ \text{stochastic} \\ \text{model} \end{matrix}$

drift of
coalesced
particles?



Proof: test for fluid limits (TFL)

Classical result
(Dai, Rybko-Stolyar)

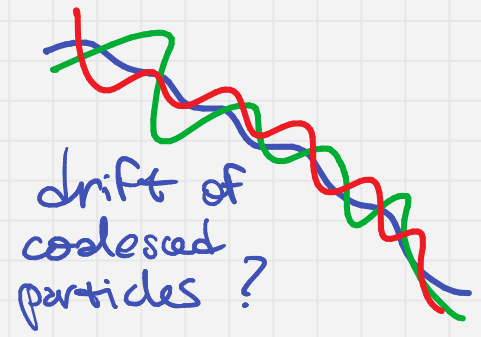
stable
: Fluid
model



stable
stochastic
model



Maximum
queue length
fluid Lyapunov



Proof: test for fluid limits (TFL)

Classical result
(Dai, Rybko-Stolyar)

stable
: Fluid
model



stable
stochastic
model

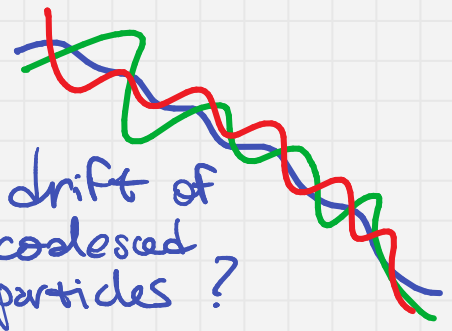


Maximum
queue length
fluid by zpunov

$$\frac{M(t_2) - M(t_1)}{t_2 - t_1} \leq -\delta$$

$\forall t_1 < t_2$

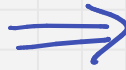
drift of
coalesced
particles?



Proof: test for fluid limits (TFL)

Classical result
(Dai, Rybko-Stolyar)

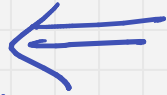
stable
Fluid
model



stable
stochastic
model



Maximum
queue length
fluid by zipper

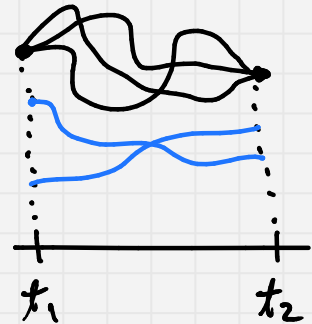


$$\frac{M(t_2) - M(t_1)}{t_2 - t_1} \leq -\delta$$

~~$t_1 < t_2$~~

TFL

for $t_1 < t_2$ s.t.



drift of
condensed
particles?



Proof: test for fluid limits (TFL)

Classical result
(Dai, Rybko-Stolyar)

stable
Fluid
model



stable
stochastic
model



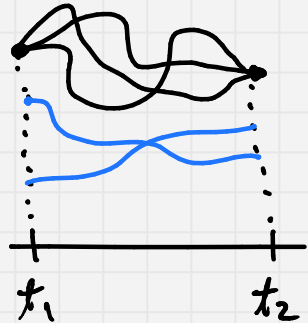
Maximum
queue length
fluid by zipper

$$\frac{M(t_2) - M(t_1)}{t_2 - t_1} \leq -\delta$$

~~$t_1 < t_2$~~

TFL

for $t_1 < t_2$ s.t.



drift of
condensed
particles?



Under the formal assumption,
the control of the slope follows easily!

Conclusions

- In a queuing network with a random environment, we studied how timing restrictions on decision making affect the stability of the system.
More precisely, for different timing restriction settings,
 - we explicitly described the MRSs,
 - and we provided a family of MW optimal policies.
- We developed a found test for fluid limits (TFL) which, if passed, it guarantees the stability of the model.

Thanks!