



Phase diagram of extensive-rank symmetric matrix denoising beyond rotational invariance



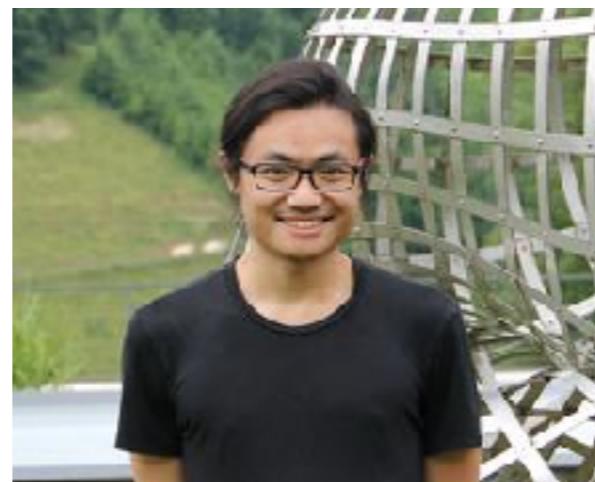
Jean Barbier

International Center for Theoretical Physics
Trieste, Italy

$$\text{Data} = ? + ? + \text{Noise}$$



F. Camilli (ICTP)



J. Ko (Waterloo U)



K. Okajima (Tokyo U)

$$Y = \sqrt{\frac{\lambda}{N}} X X^\top + Z$$

$$Y = \sqrt{\frac{\lambda}{N}} X X^\top + Z \quad Y, Z \in \mathbb{R}^{N \times N} \quad X \in \mathbb{R}^{N \times M}$$

$$Z_{ij} = Z_{ji} \stackrel{i.i.d.}{\sim} \mathcal{N}(0, 1 + \delta_{ij})$$

$$X_{i\mu} \stackrel{i.i.d.}{\sim} P_X \quad \mathbb{E}X = 0, \quad \mathbb{E}X^2 = 1$$

Known (Bayes optimal)

$$\text{Rot. inv. } P_X = \mathcal{N}(0, 1) \text{ VS NOT Rot. inv. } P_X = \frac{1}{2}\delta_{-1} + \frac{1}{2}\delta_{+1}$$

Non-symmetric: dictionary learning

$$Y = \sqrt{\frac{\lambda}{N}} U V^\top + Z$$

Representation learning, signal processing, recommender systems...

Bayesian optimal setting

Posterior

$$\begin{aligned} dP(x|Y) &\propto \exp\left(-\frac{1}{4}\|Y - \sqrt{\frac{\lambda}{N}}xx^\top\|^2\right) \prod_{i,\mu}^{N,M} dP_X(x_{i\mu}) \\ &= \frac{1}{Z} \exp\left(\frac{1}{2}\sqrt{\frac{\lambda}{N}}\text{Tr}Yxx^\top - \frac{\lambda}{4N}\|xx^\top\|^2\right) \prod_{i,\mu}^{N,M} dP_X(x_{i\mu}) \end{aligned}$$

Minimum mean-square error (MMSE)

$$\lim_{N \rightarrow \infty} \frac{1}{MN^2} \mathbb{E} \|XX^\top - \mathbb{E}[xx^\top|Y]\|^2$$

Bayesian optimal setting

Posterior

$$\begin{aligned} dP(x|Y) &\propto \exp\left(-\frac{1}{4}\|Y - \sqrt{\frac{\lambda}{N}}xx^\top\|^2\right) \prod_{i,\mu}^{N,M} dP_X(x_{i\mu}) \\ &= \frac{1}{Z} \exp\left(\frac{1}{2}\sqrt{\frac{\lambda}{N}}\text{Tr}Yxx^\top - \frac{\lambda}{4N}\|xx^\top\|^2\right) \prod_{i,\mu}^{N,M} dP_X(x_{i\mu}) \end{aligned}$$

Mutual information (MI)

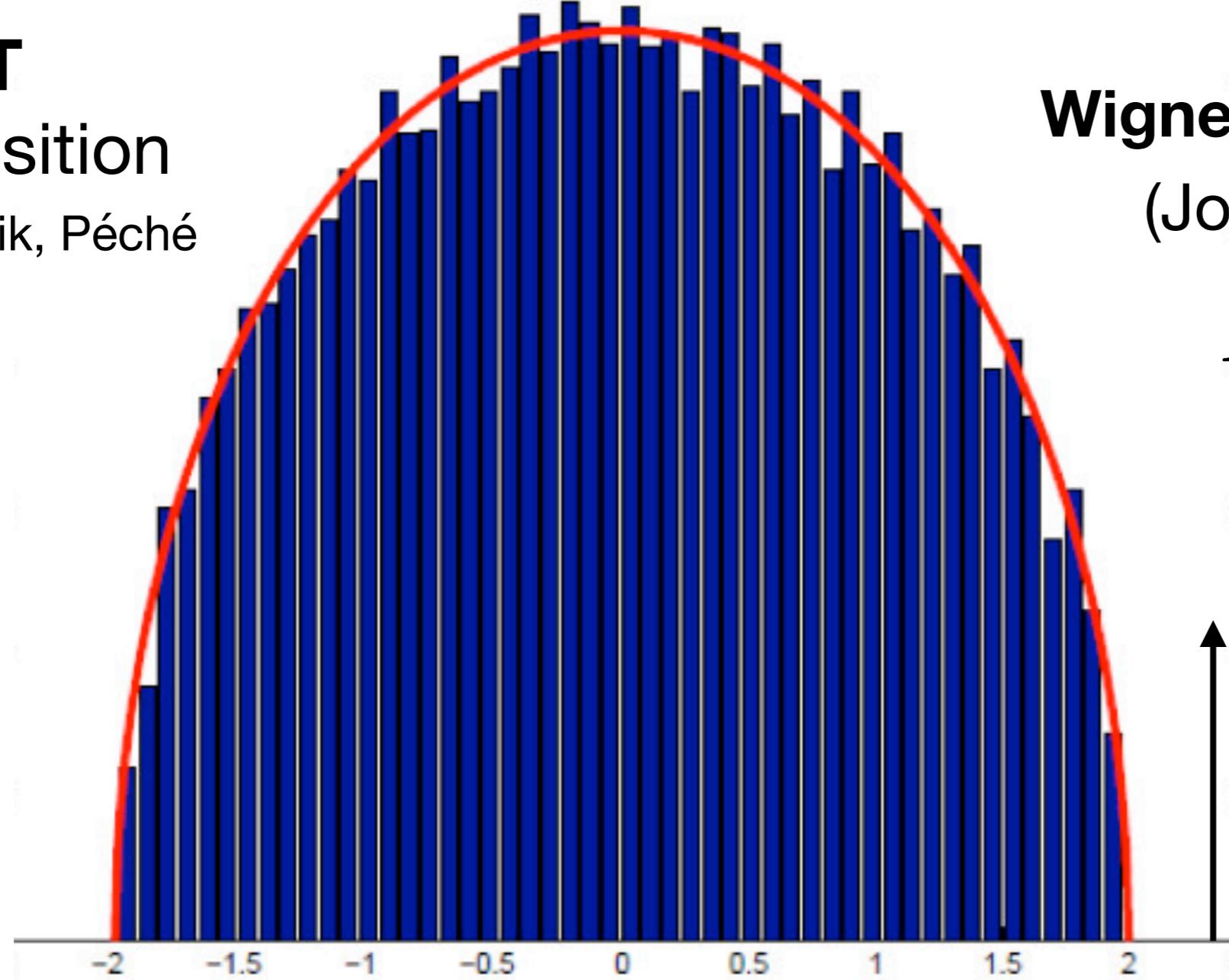
$$\begin{aligned} &\lim_{N \rightarrow \infty} \frac{1}{MN} I(XX^\top; Y) \\ &= \lim \frac{1}{MN} \left(H(Y) - H(Y|XX^\top) \right) \\ &= \frac{\lambda}{4} - \lim \frac{1}{MN} \mathbb{E}_Y \ln Z \\ &= \frac{\lambda}{4} - \lim \frac{1}{MN} \mathbb{E}_Y \ln \int e^{\frac{1}{2}\sqrt{\frac{\lambda}{N}}\text{Tr}Yxx^\top - \frac{\lambda}{4N}\|xx^\top\|^2} \prod_{i,\mu}^{N,M} dP_X(x_{i\mu}) \end{aligned}$$

Free entropy $\phi_{N,M}$

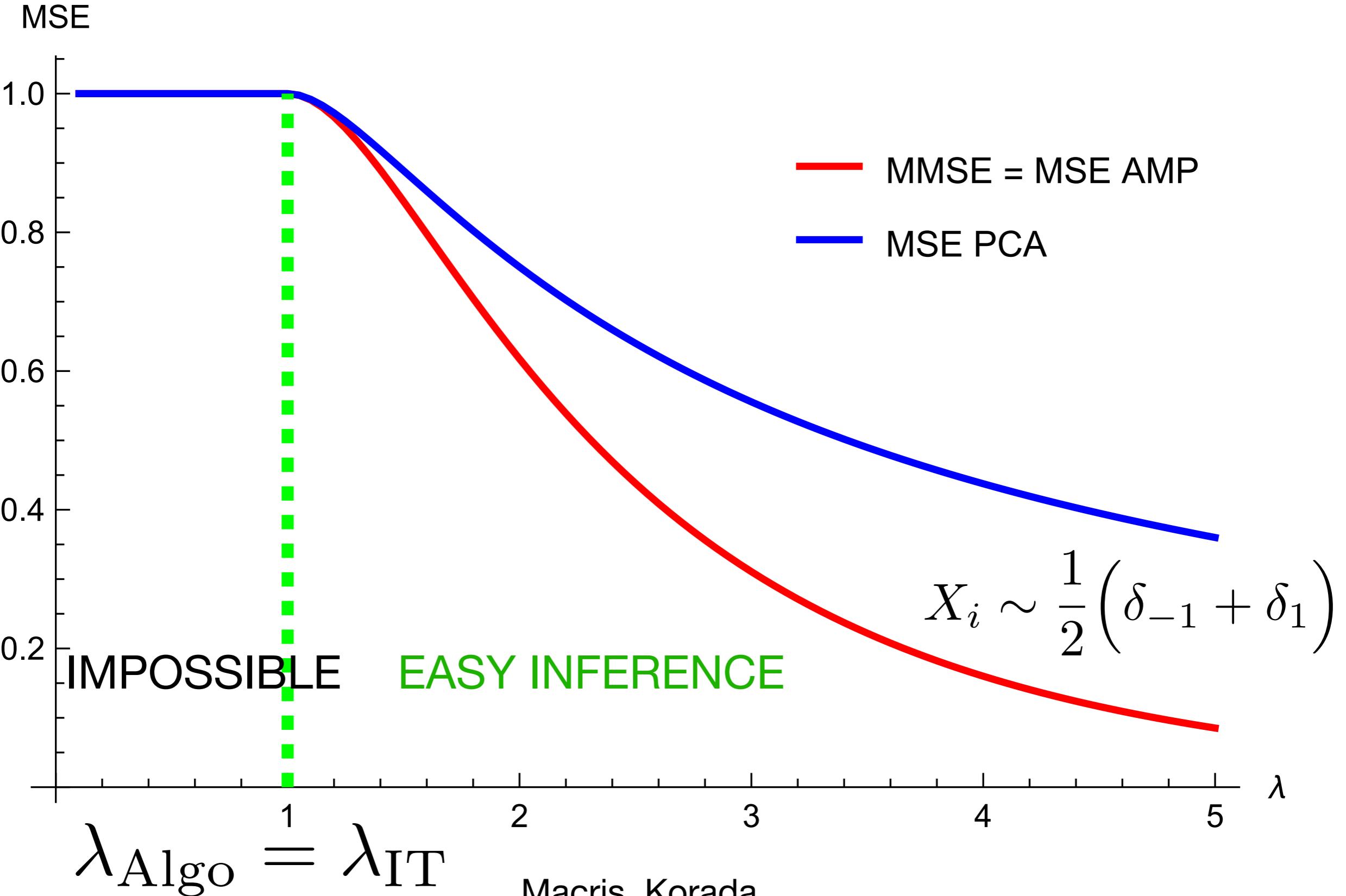
$$Y = \sqrt{\frac{\lambda}{N}} X^T + Z$$

RMT
BBP transition
 Ben-Arous, Baik, Péché

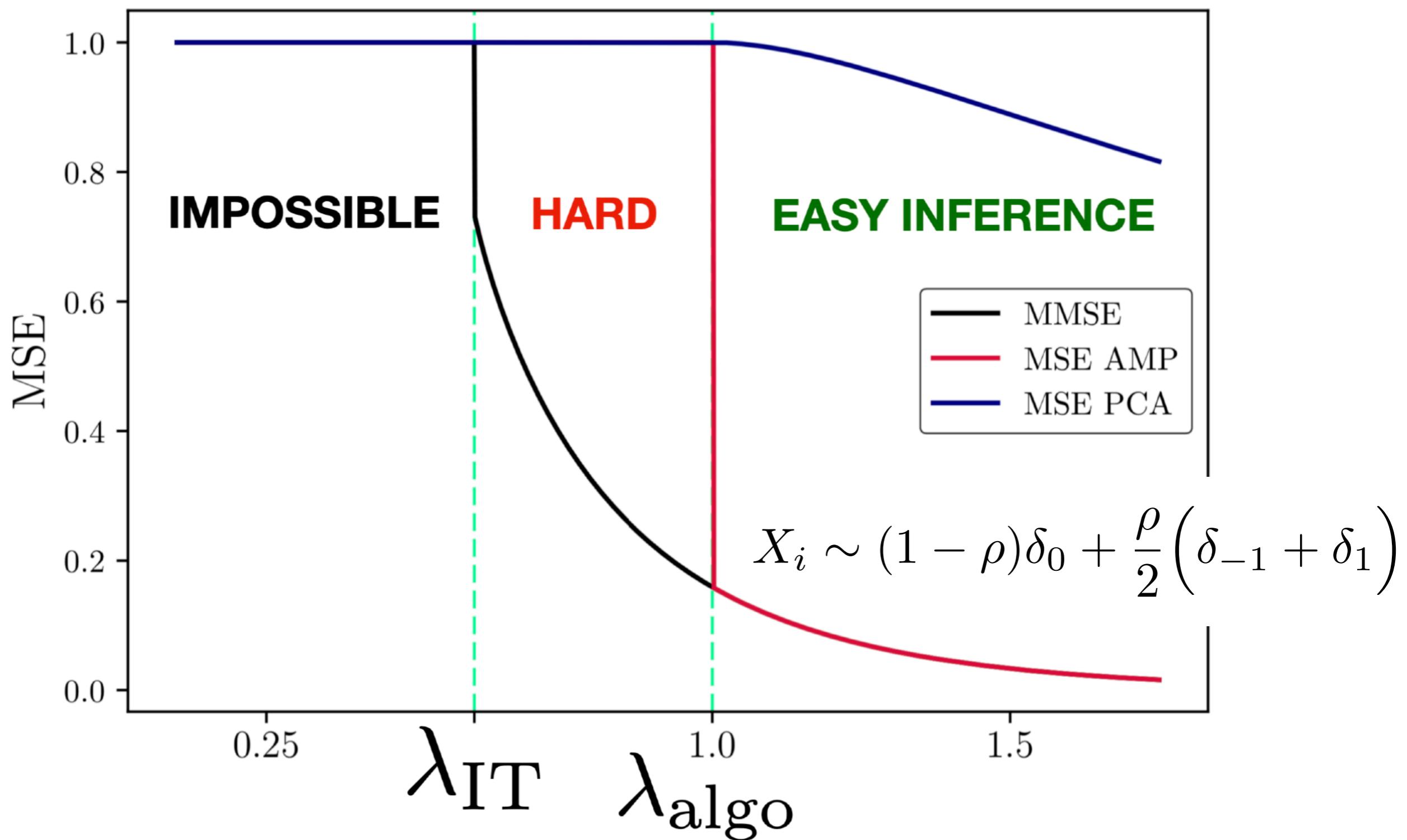
Wigner spiked model
 (Johnstone 10')
 $M = 1$



Bayesian Inference / Information theory



Bayesian Inference / Information theory

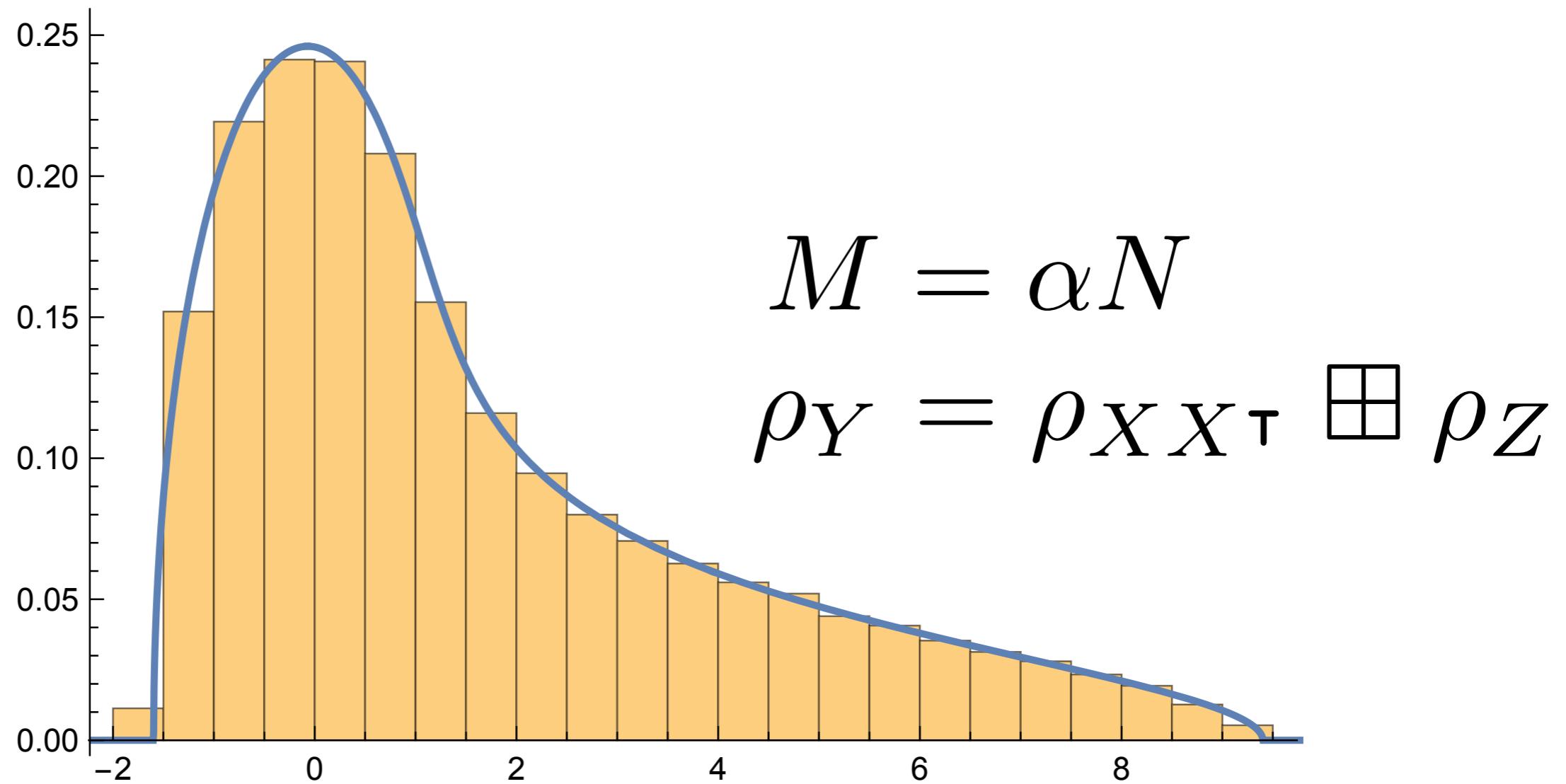


Macris, Korada

Montanari, Abbe, Deshpande

Macris, Barbier, Dia, Krzakala, Zdeborova, Lesieur

$$Y = \sqrt{\frac{\lambda}{N}} X^T + Z$$



Spectrum (and other statistics) are **universal** in law of X entries, but...

$$Y = \sqrt{\frac{\lambda}{N}} X X^\top + Z$$

Difficulty →

$$N \rightarrow \infty$$

$$M = O(1)$$

Physics analysis

(Lesieur, Krzakala, Zdeborova)

Rigorous analysis

(Korada, Macris, Montanari, Deshpande, Dia, Barbier, Krzakala, Zdeborova, Lelarge, Miolane, El Alaoui, Fan,.....)

Optimal algorithm (AMP)

(Same as above)

$$N \rightarrow \infty$$

$$M = o(N)$$

Physics analysis

(Pourkamali, Barbier, Macris)

Rigorous analysis

(Barbier, Ko, Rahman, Husson)

Optimal algorithm (AMP)

(Pourkamali, Barbier, Macris)

$$N \rightarrow \infty$$

$$M \propto N$$

$$P_X = \mathcal{N}(0, 1)$$

HCIZ integral

(Matytsin, Guionnet, Zeitouni)

Physics analysis

(Barbier, Macris, Maillard, Mezard, Camilli, Krzakala, Zdeborova)

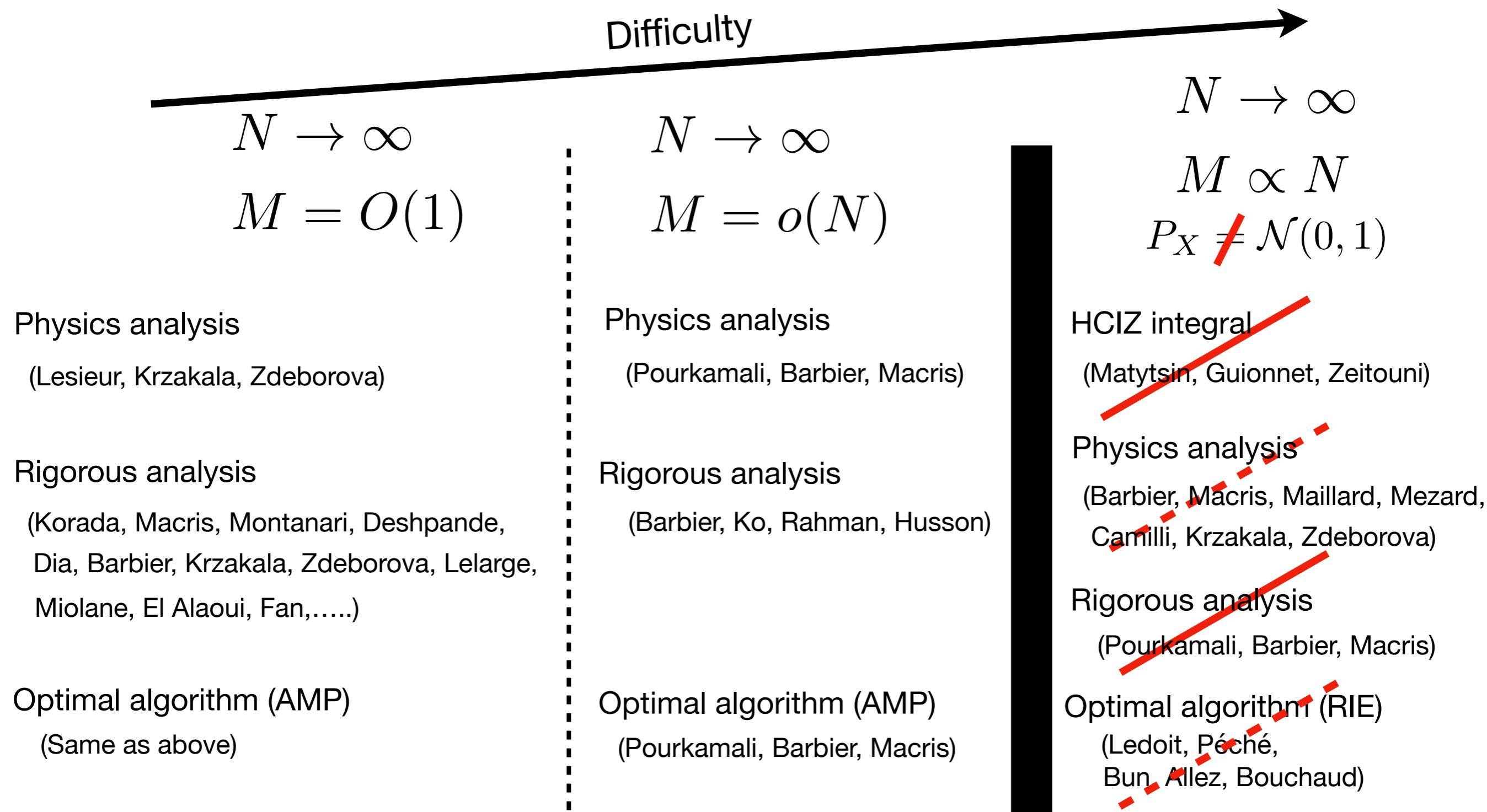
Rigorous analysis

(Pourkamali, Barbier, Macris)

Optimal algorithm (RIE)

(Ledoit, Péché, Bun, Allez, Bouchaud)

$$Y = \sqrt{\frac{\lambda}{N}} X X^\top + Z$$



Cross-breeding a matrix model with an Hopfield model



(Not really) a matrix model

$$\mathcal{Z} = \int_{\mathbb{R}^{N \times M}}$$

$$e^{\frac{1}{2} \sqrt{\frac{\lambda}{N}} \text{Tr} Y x x^\top - \frac{\lambda}{4N} \|x x^\top\|^2}$$

$$\prod_{i,\mu}^{N,M} dP_X(x_{i\mu})$$

Matrix model WITHOUT rotational invariance (so not really one...)

$$\mathcal{Z}_{\text{MM}} = \int$$

$$e^{\frac{1}{2} \sqrt{\frac{\lambda}{N}} \text{Tr} Y x x^\top - \frac{\lambda}{4N} \|x x^\top\|^2}$$

$$\prod_{i,\mu}^{N,M} dx_{i\mu}$$

$$= \int e^{-\frac{\lambda}{4N} \|\Sigma\|^2} \left(\int e^{\frac{1}{2} \sqrt{\frac{\lambda}{N}} \text{Tr} Y O \Sigma O^\top} d\mu(O) \right) d\Sigma$$

$$x x^\top \rightarrow O \Sigma O^\top$$

HCIZ / spherical integral +
saddle point over spectrum

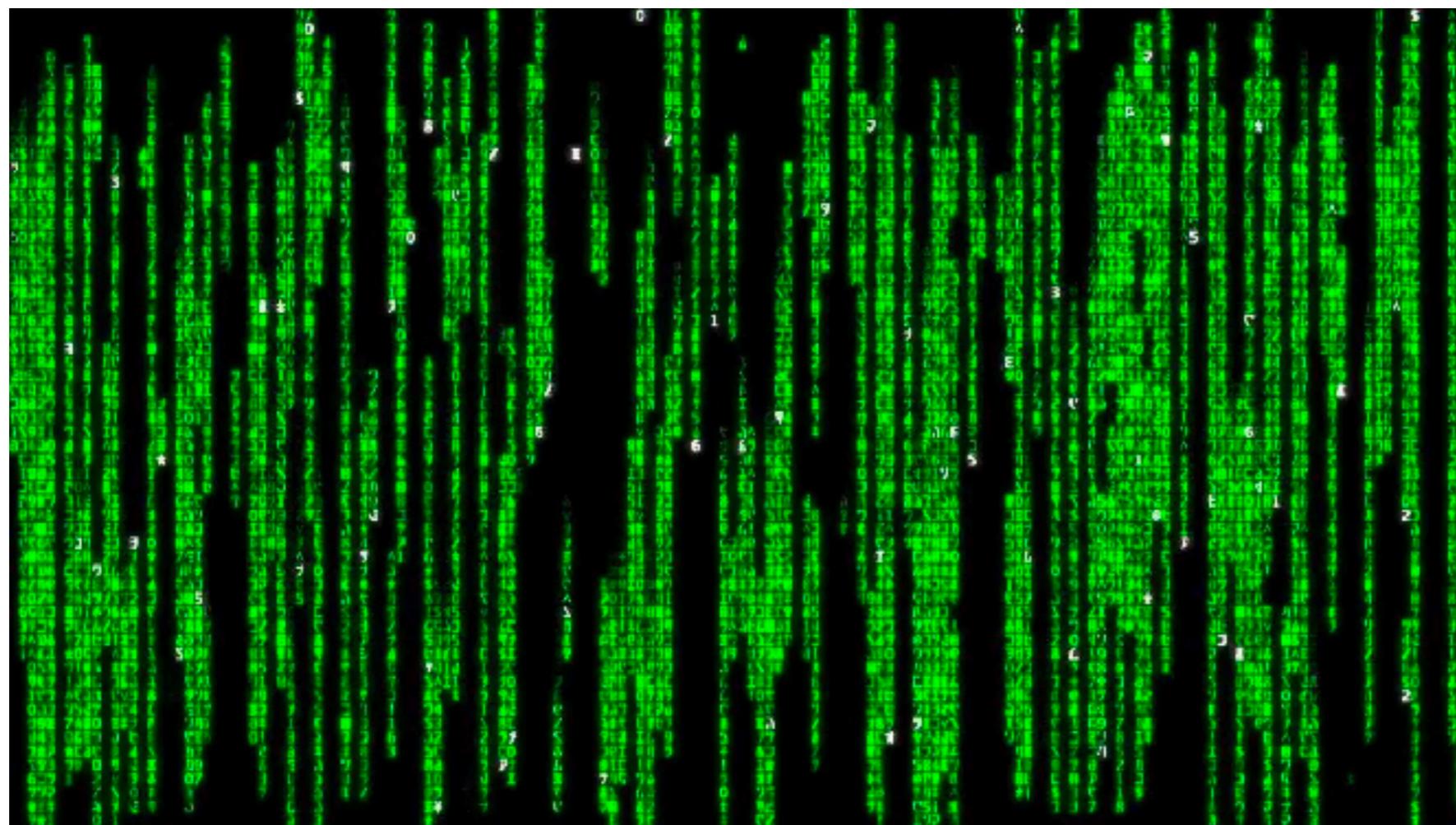
A more complicated Hopfield model

$$\mathcal{Z} = \int_{\mathbb{R}^{N \times M}} e^{\frac{1}{2} \sqrt{\frac{\lambda}{N}} \sum_{\mu \leq M} x_\mu^\top Y x_\mu - \frac{\lambda}{4N} \sum_{\mu, \nu} (x_\mu^\top x_\nu)^2} \prod_{i, \mu}^{N, M} dP_X(x_{i\mu})$$
$$Y = \sqrt{\frac{\lambda}{N}} \sum_{\mu \leq M} X_\mu X_\mu^\top + Z$$

An Hopfield model where ALL patterns must be recovered JOINTLY

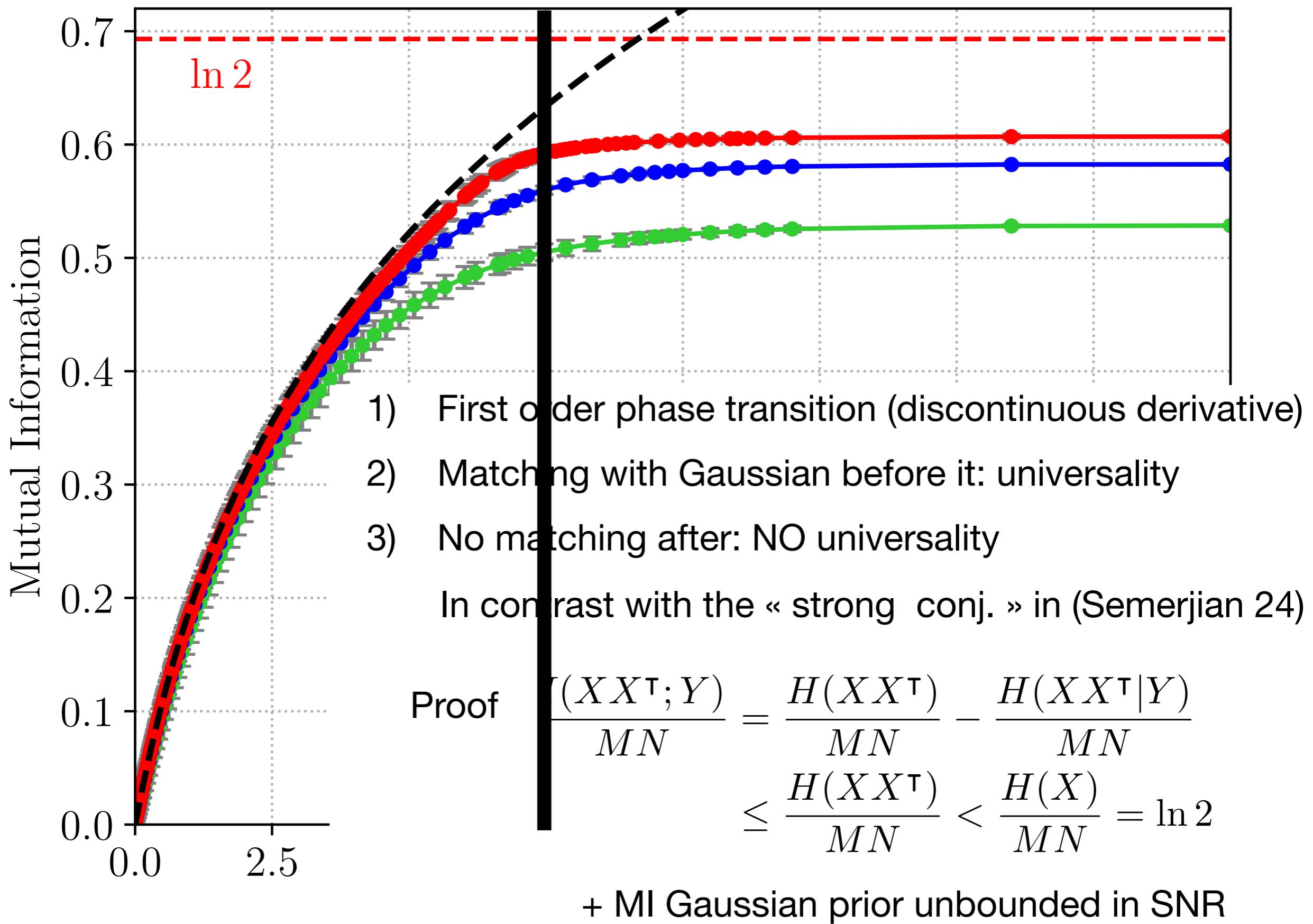
$$\mathcal{Z}_{\text{Hopfield}} = \int_{\mathbb{R}^N} e^{\frac{1}{2} \sqrt{\frac{\lambda}{N}} x^\top J x} \prod_i^N dP_X(x_i)$$
$$J = \frac{1}{\sqrt{N}} \sum_{\mu \leq M} X_\mu X_\mu^\top$$

Numerical insights



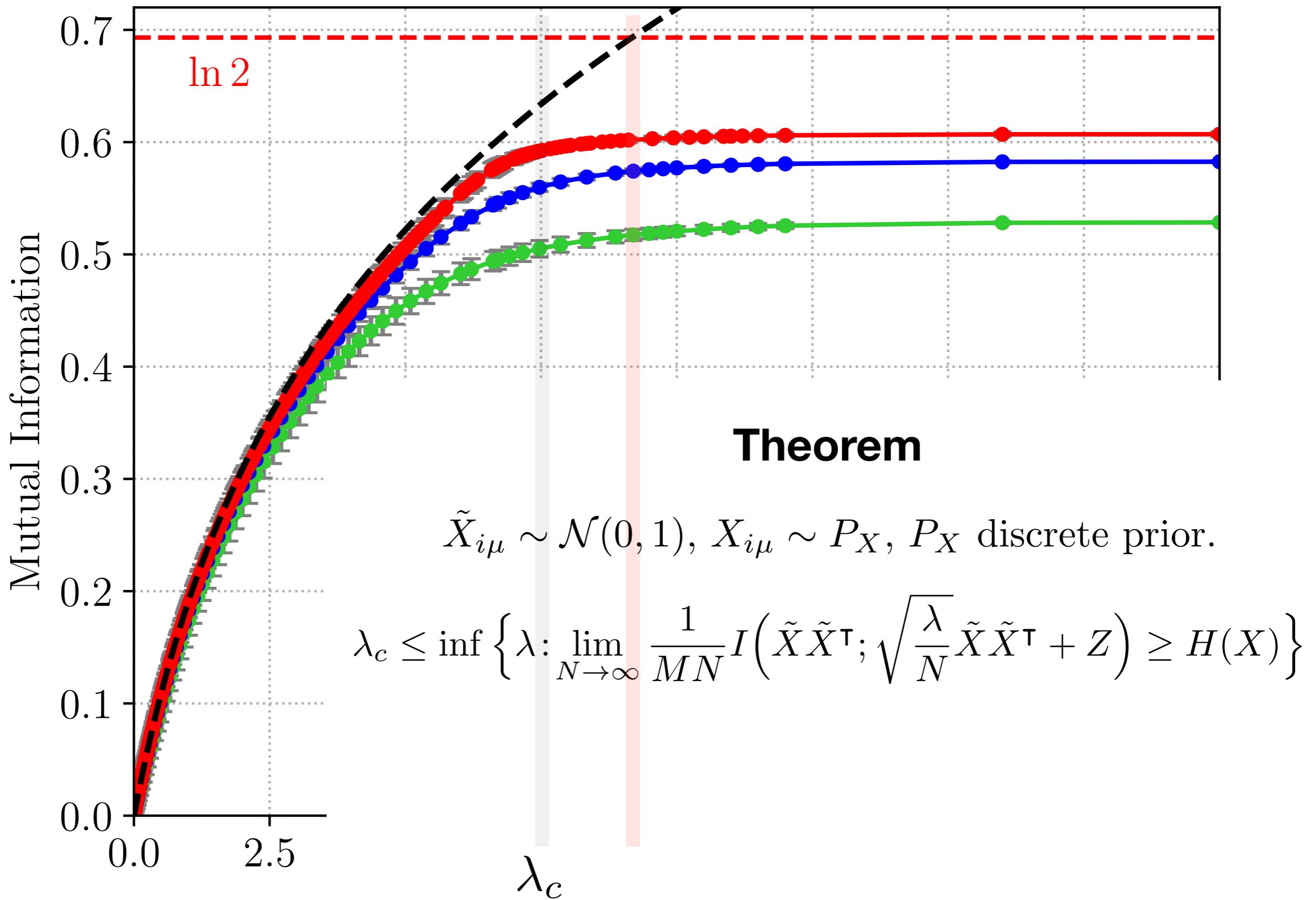
$$P_X = \frac{1}{2}\delta_{-1} + \frac{1}{2}\delta_{+1}$$

$$M = \alpha N = N/2$$



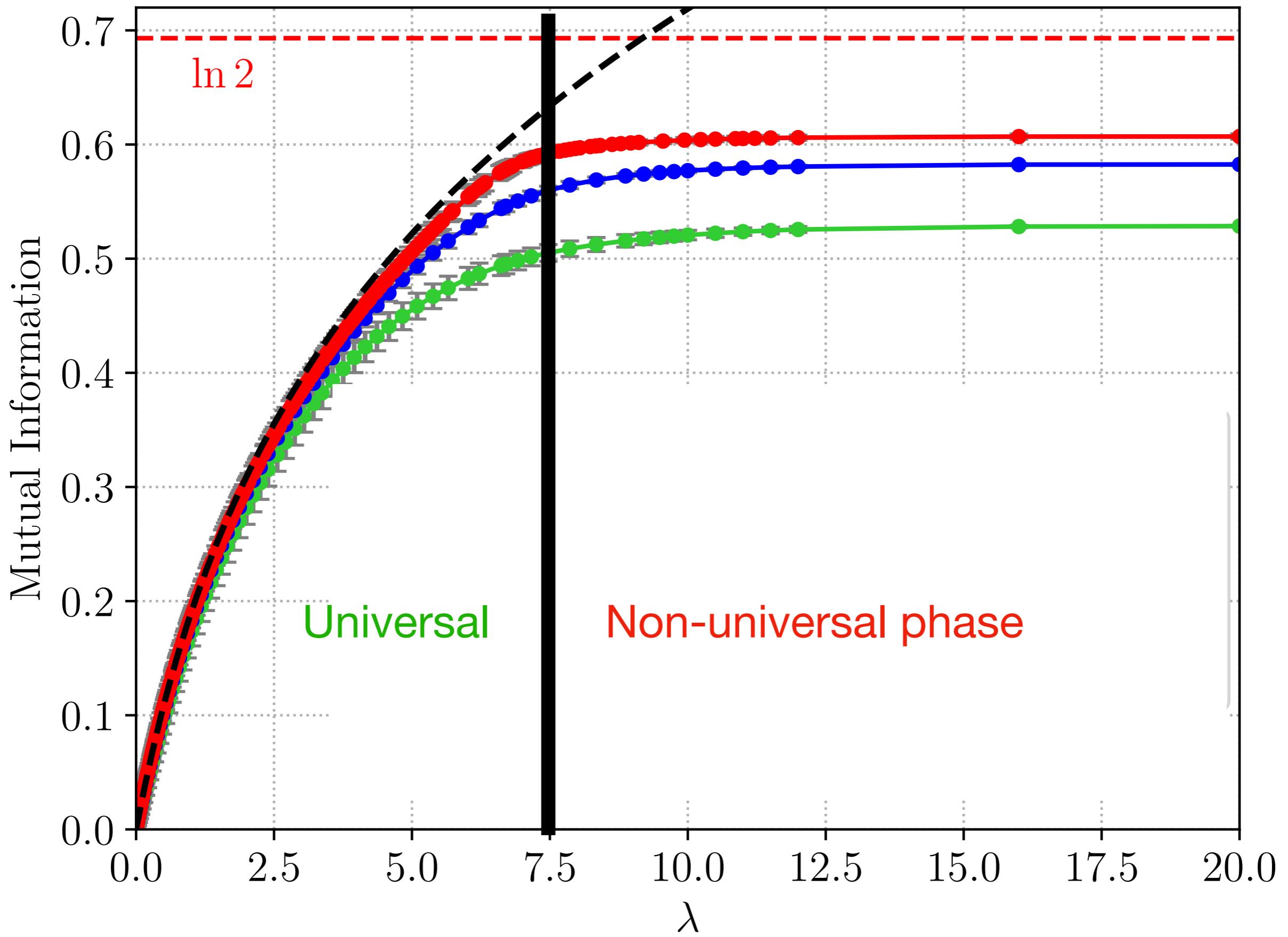
$$P_X = \frac{1}{2}\delta_{-1} + \frac{1}{2}\delta_{+1}$$

$$M = \alpha N = N/2$$

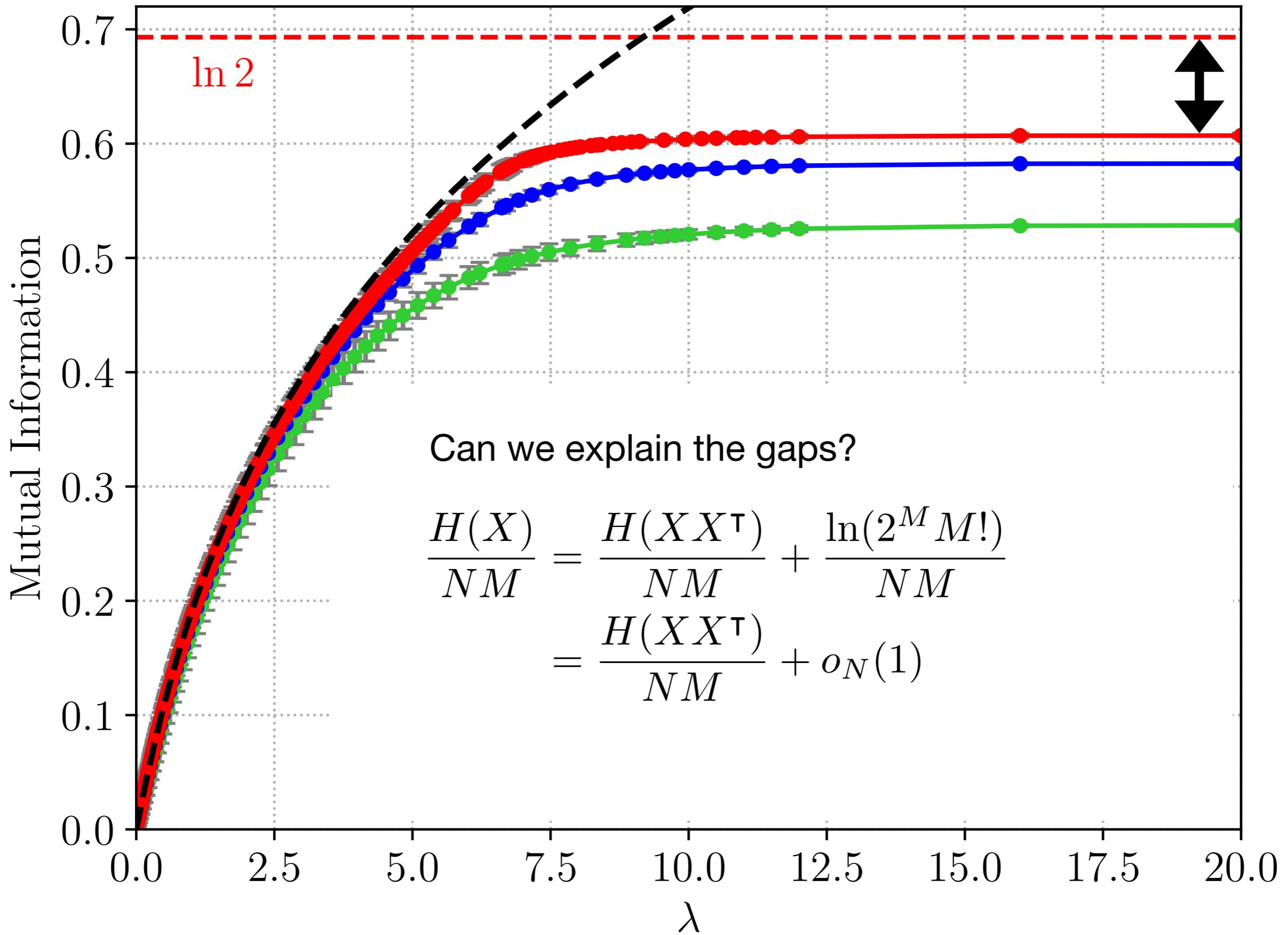


$$P_X = \frac{1}{2}\delta_{-1} + \frac{1}{2}\delta_{+1}$$

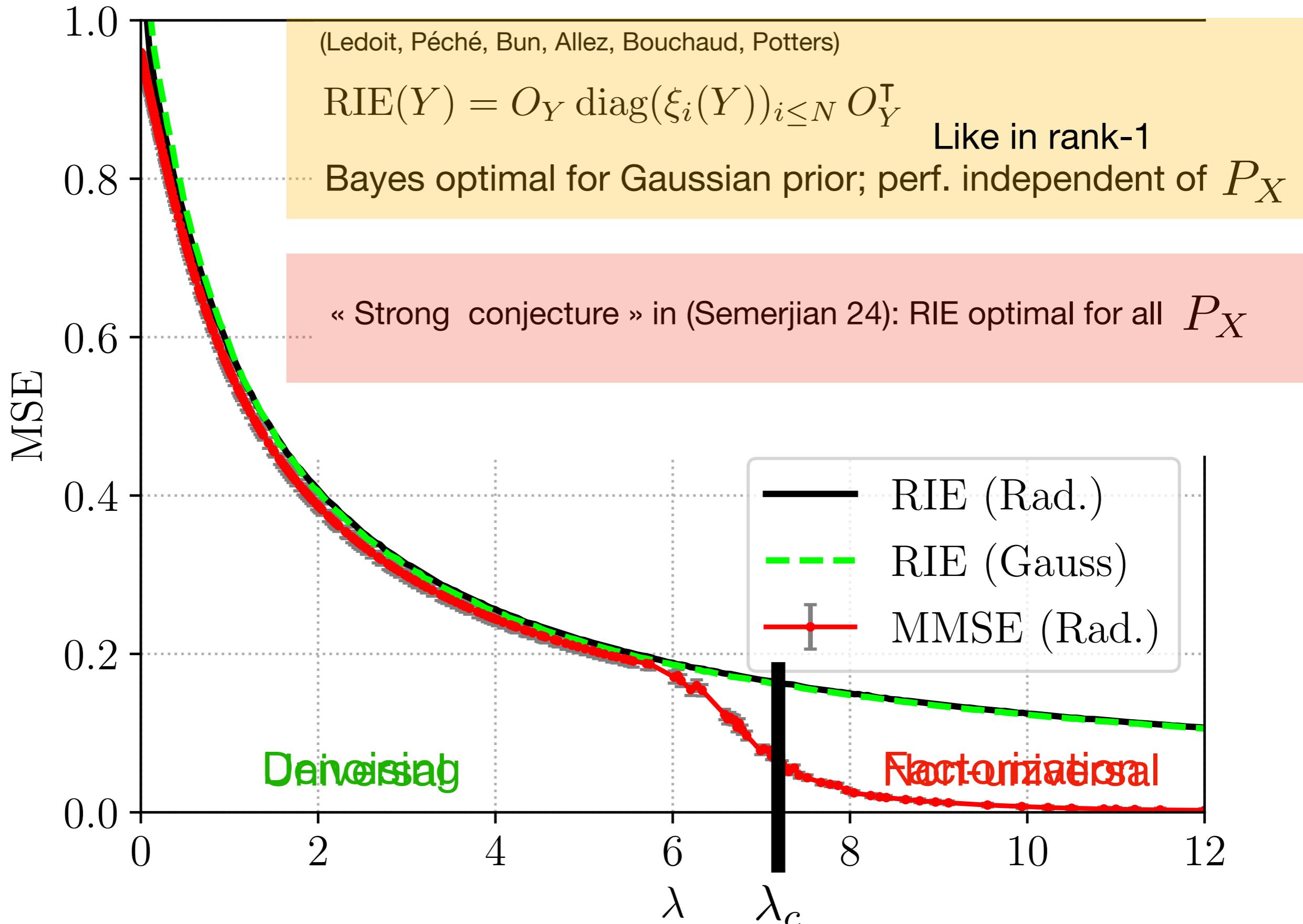
$$M = \alpha N = N/2$$



$$P_X = \frac{1}{2}\delta_{-1} + \frac{1}{2}\delta_{+1} \quad M = \alpha N = N/2$$

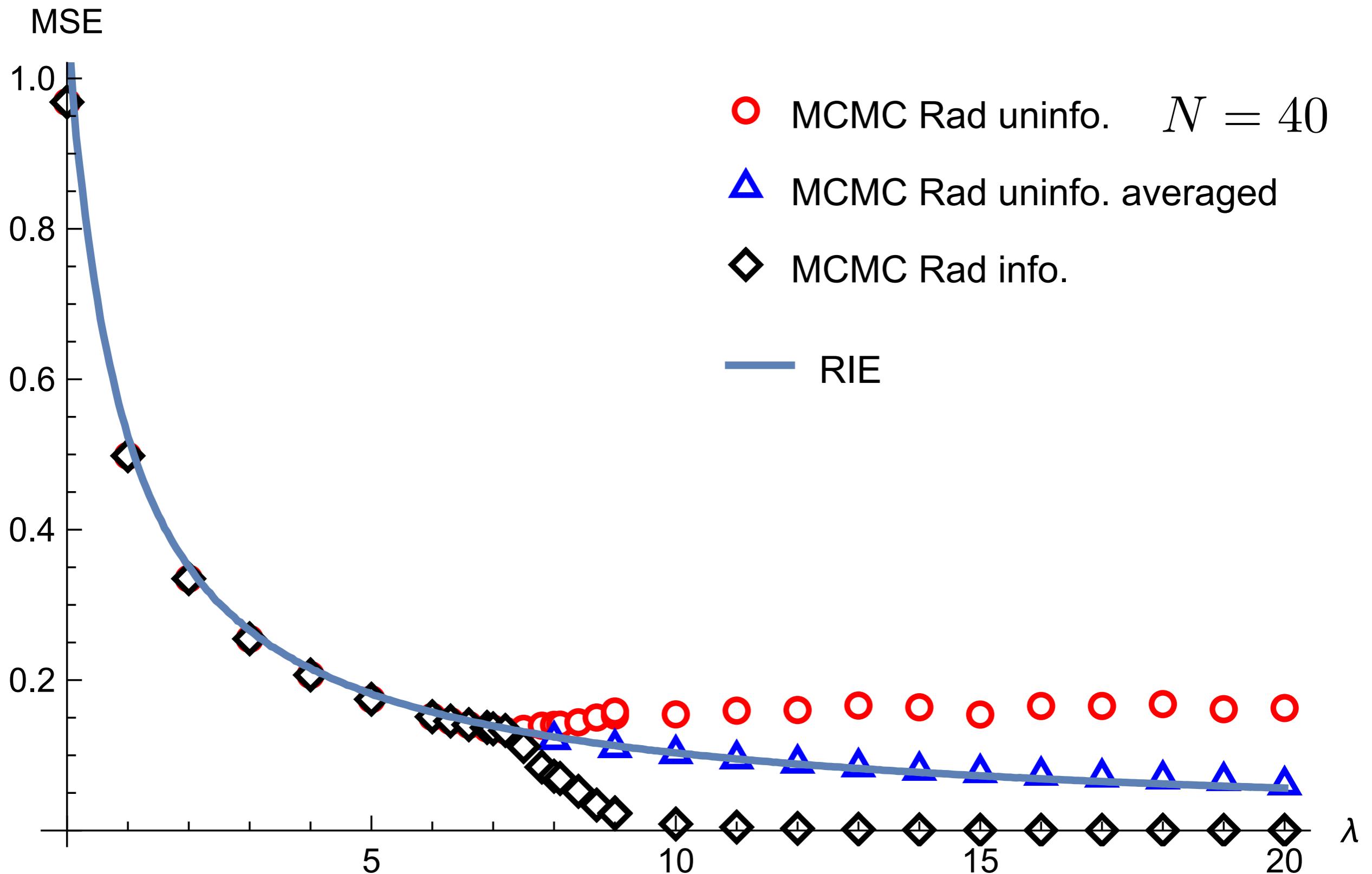


$$\frac{1}{MN^2} \mathbb{E} \|XX^\top - \mathbb{E}[xx^\top | Y]\|^2 = 4 \frac{1}{MN} \frac{d}{d\lambda} I(XX^\top; Y)$$

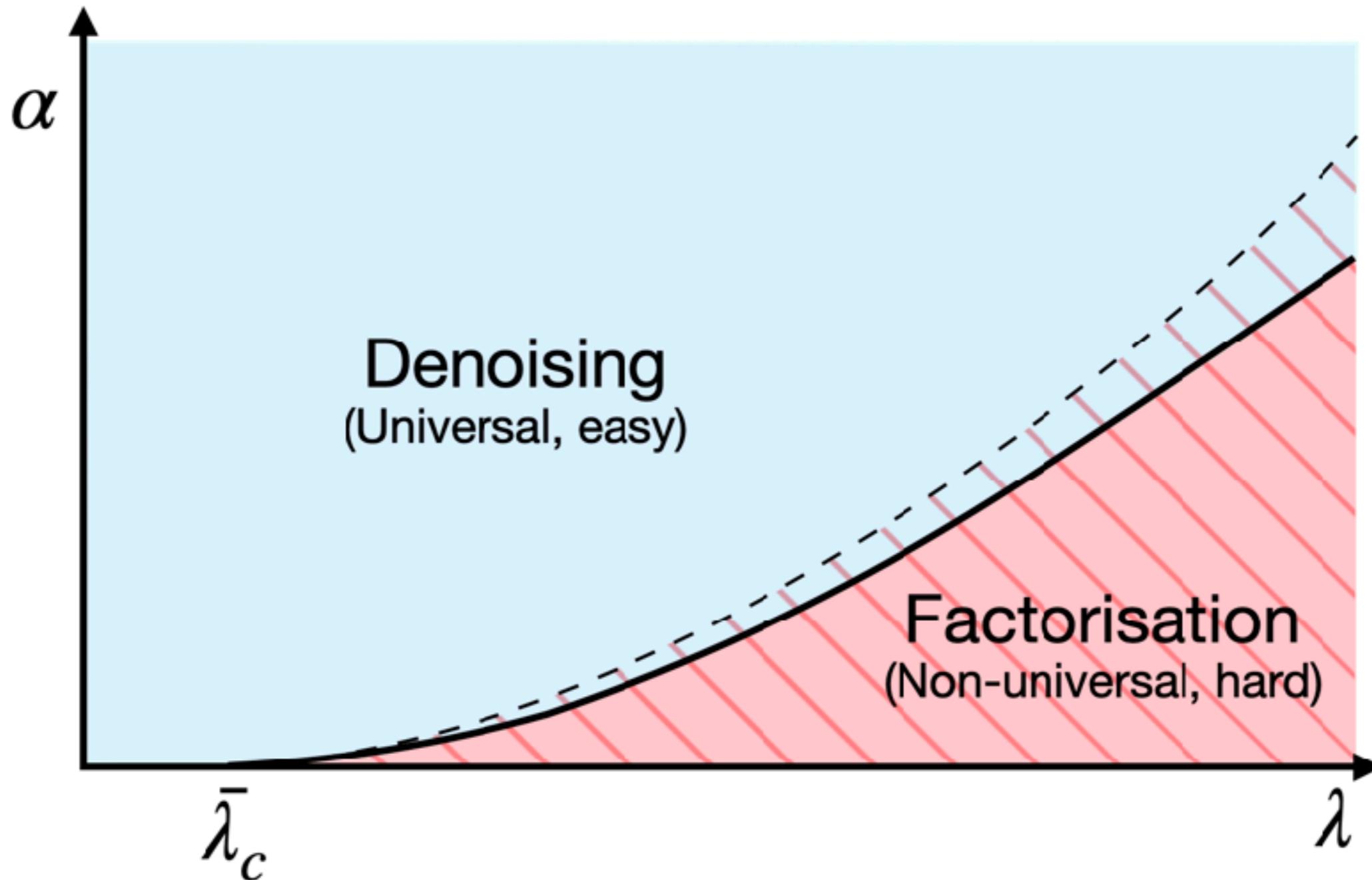


Hard phase

$\alpha=0.7$



Phase diagram



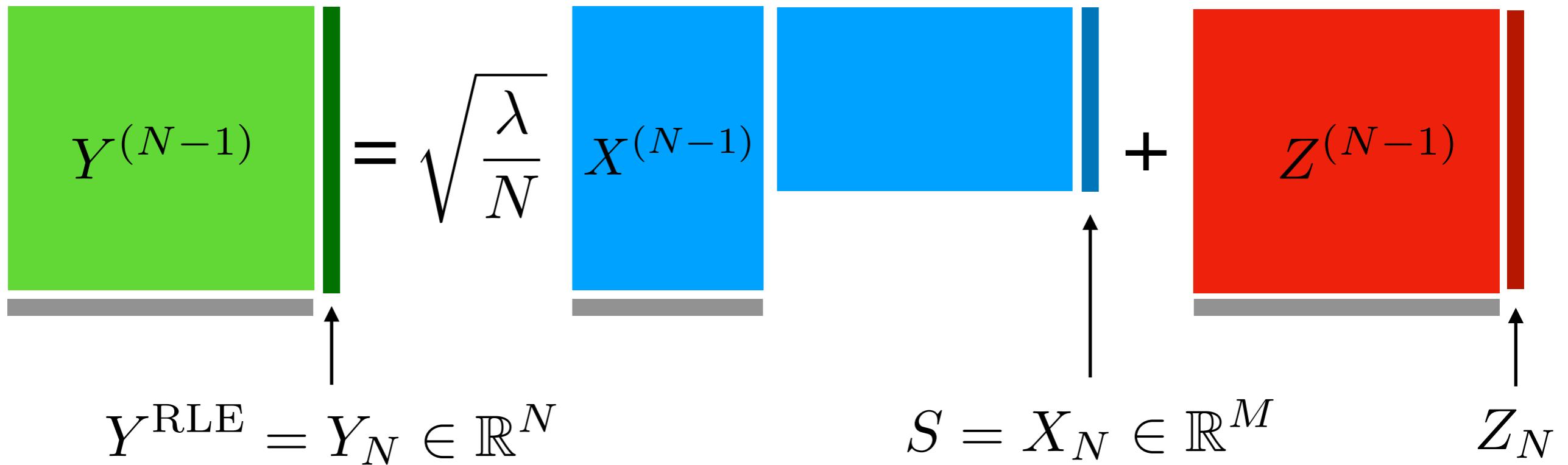
Information-theoretically, recovering ALL “patterns” at once is roughly equally hard as recovering just one (rank-one problem).

Algorithmically it is a very different story...

Multiscale mean-field theory

$$O(MN) \xrightarrow{\text{Multiscale mean-field theory}} O(1)$$

$O(MN) \longrightarrow O(M)$ cavity method



Effective M-dim pb: random linear estimation with uncertain design

$$Y_N = \sqrt{\frac{\lambda}{N}} X^{(N-1)} S + Z_N \quad Y^{(N-1)}(X^{(N-1)})$$

$$(s, x^{(N-1)}) \sim P(s|Y_N, x^{(N-1)}) \times P(x^{(N-1)}|Y^{(N-1)})$$

$$Y_N = \sqrt{\frac{\lambda'}{N}} X^{(N-1)} S + Z_N \quad Y^{(N-1)}(X^{(N-1)})$$

$$\frac{1}{MN^2} \mathbb{E} \|XX^\top - \mathbb{E}[xx^\top|Y]\|^2 = \frac{1}{MN^2} \sum_{i,j=1}^N \left(\mathbb{E}(X_i^\top X_j)^2 - \mathbb{E}\langle x_i^\top x_j \rangle^2 \right)$$

Measurement MMSE

(Barbier, Macris, Dia et al. 17')

$$Y_N = \sqrt{\frac{\lambda'}{N}} X^{(N-1)} S + Z_N \quad Y^{(N-1)}(X^{(N-1)})$$

$$(s, x^{(N-1)}) \sim P(s|Y_N, x^{(N-1)}) \times P(x^{(N-1)}|Y^{(N-1)})$$

Bulk measure simplification: mean-field ansatz

$$P(x^{(N-1)}|Y^{(N-1)})$$

$$\Rightarrow P(x^{(N-1)}|Y_\sigma^{\text{eff,bulk}}) = \prod_{i,\mu} P(x_{i\mu}|Y_{i\mu}^{\text{eff,bulk}} = \sqrt{\sigma} X_{i\mu} + Z_{i\mu}^{\text{eff,bulk}})$$

A bit of work + Barbier, Macris, Miolane et al. PNAS 19'

$\Rightarrow I((X^{(N-1)}, S); Y_N | Y_\sigma^{\text{eff,bulk}})$ Low-dim. "Replica symmetric formula"

$$O(M) \longrightarrow O(1)$$

$\sigma?$

Consistency between cavity and bulk (random) marginals
-> Exchangeability among rows

$$s_\mu \sim P(s_\mu | Y_\mu^{\text{eff,cavity}} = \sqrt{r(\sigma, \lambda)} S_\mu + Z_\mu^{\text{eff,cavity}})$$

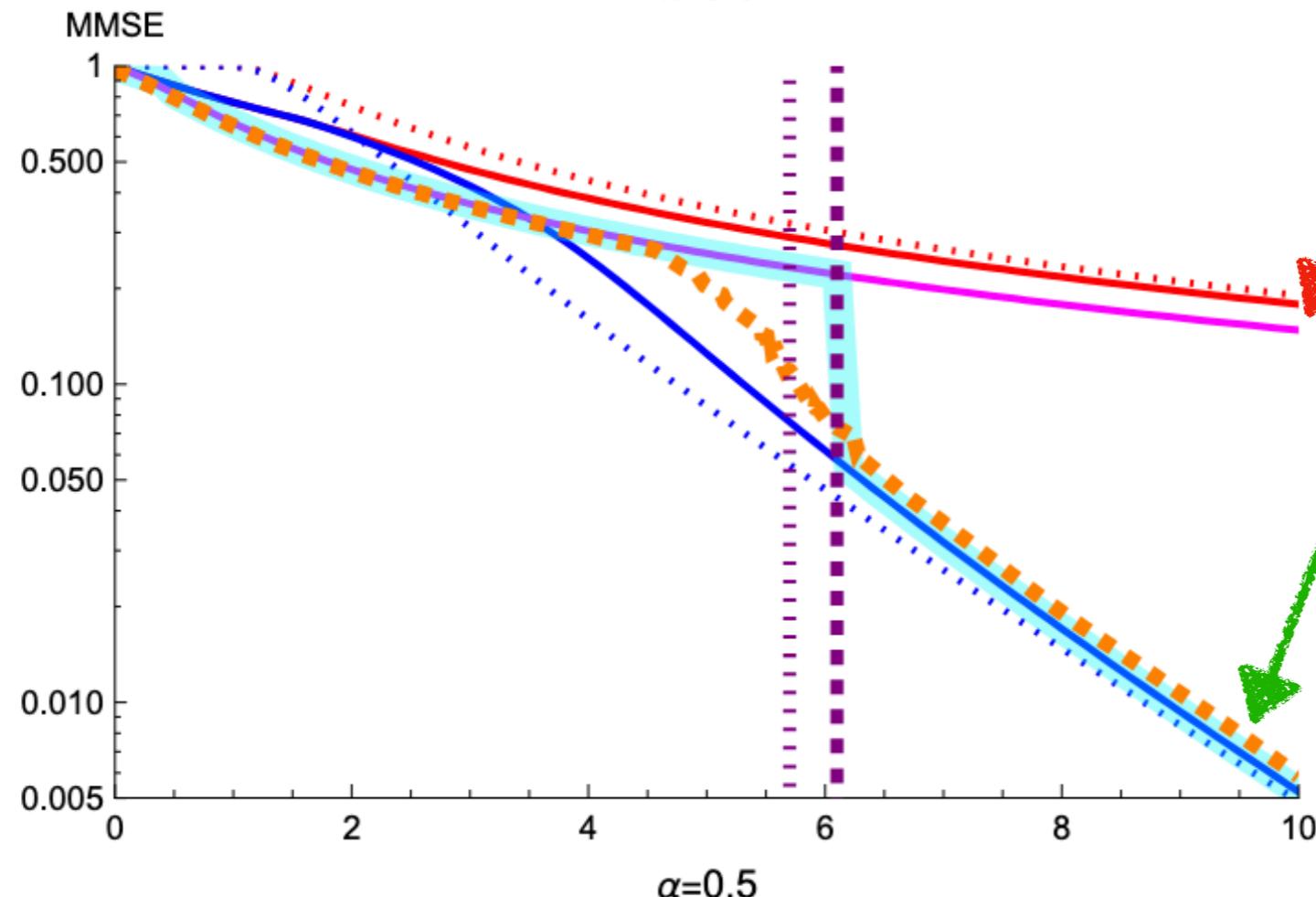
$$x_{i\mu} \sim P(x_{i\mu} | Y_{i\mu}^{\text{eff,bulk}} = \sqrt{\sigma} X_{i\mu} + Z_{i\mu}^{\text{eff,bulk}})$$

$$\Rightarrow \sigma(\lambda) = r(\sigma, \lambda)$$

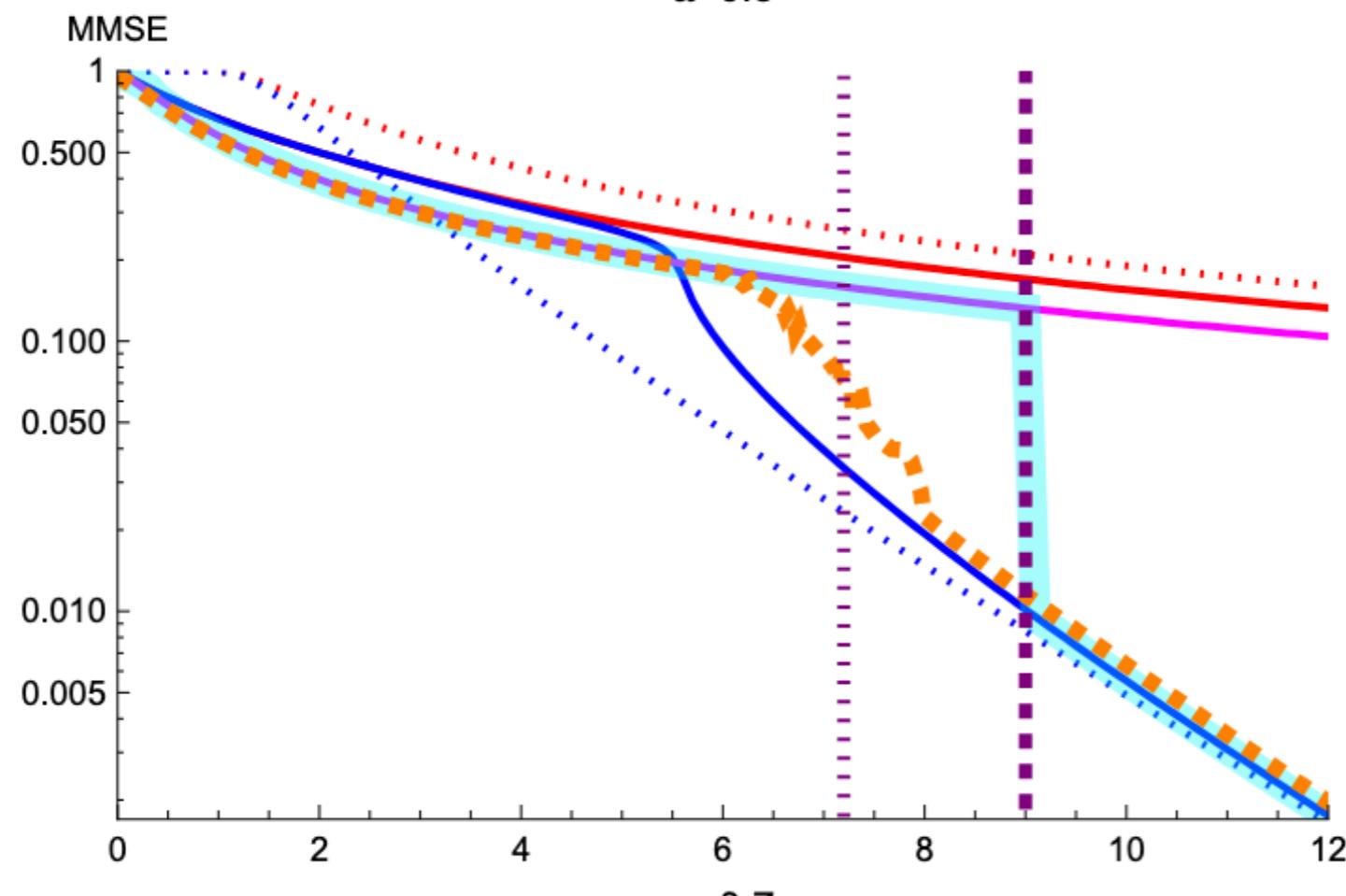
$$\Rightarrow I((X^{(N-1)}, S); Y_N | Y_\sigma^{\text{eff}})$$

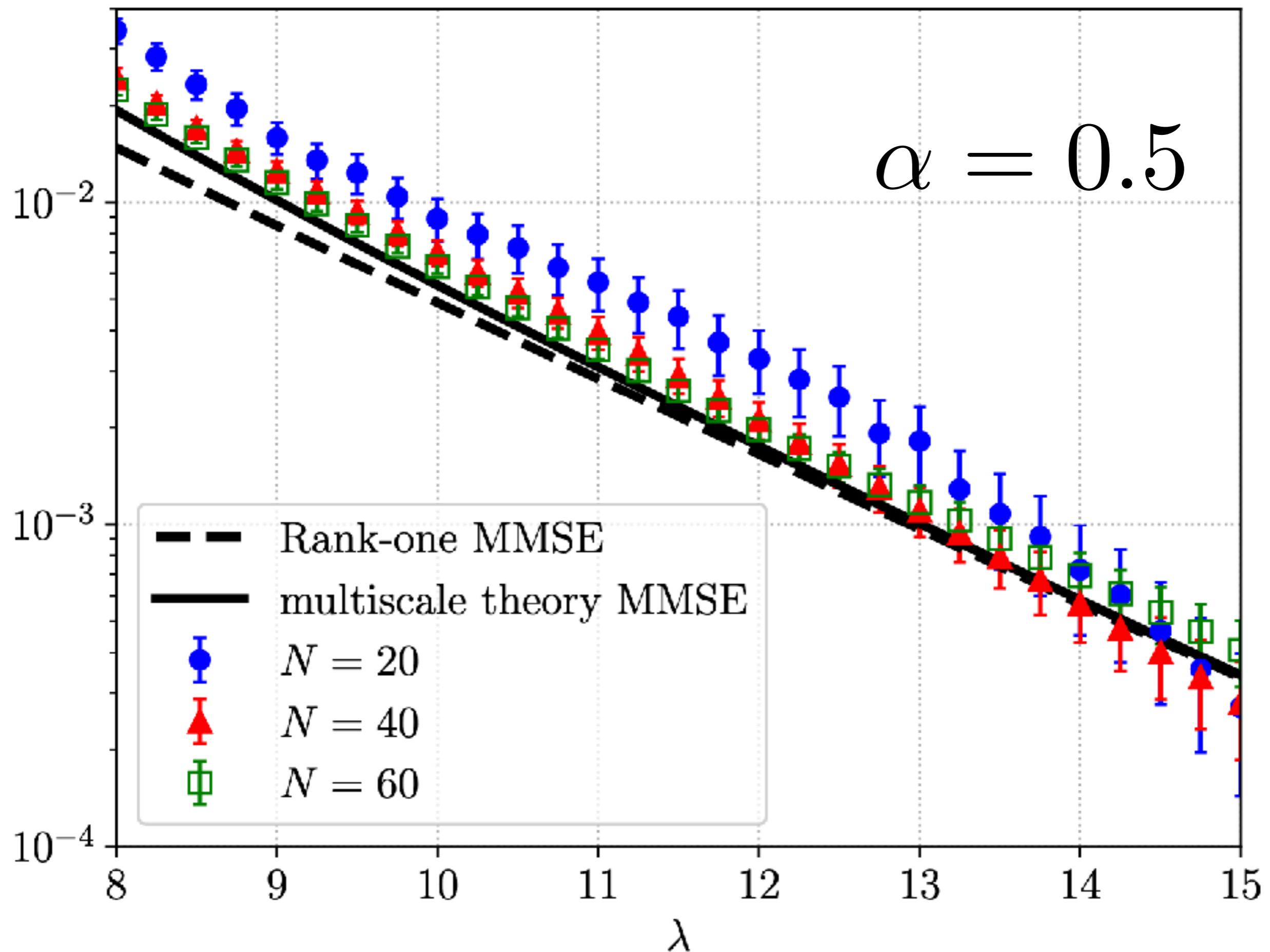
Matches Sakata and
Kabashima replica
prediction 13'

$$\Rightarrow \frac{1}{MN^2} \mathbb{E} \|XX^\top - \mathbb{E}[xx^\top | Y]\|^2$$

$\alpha=0.3$ 

Sakata and Kabashima 13'
thought wrong but...

 $\alpha=0.5$ 



Nature of the phase transition

λ_c

Matrix overlap: is factorisation possible?

MMSE not enough to probe everything

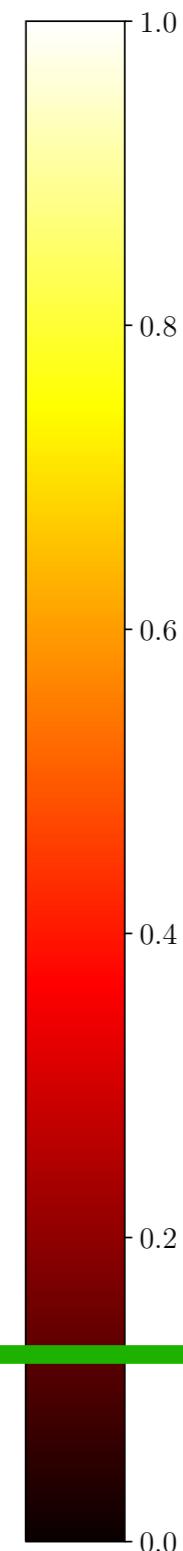
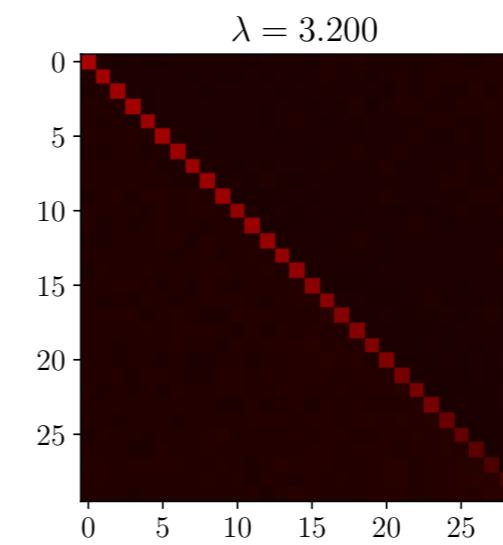
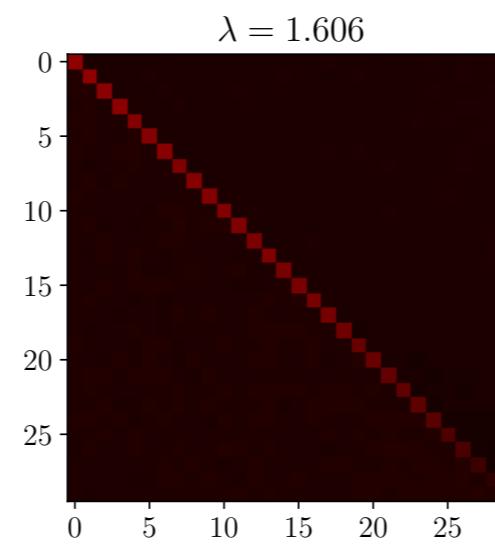
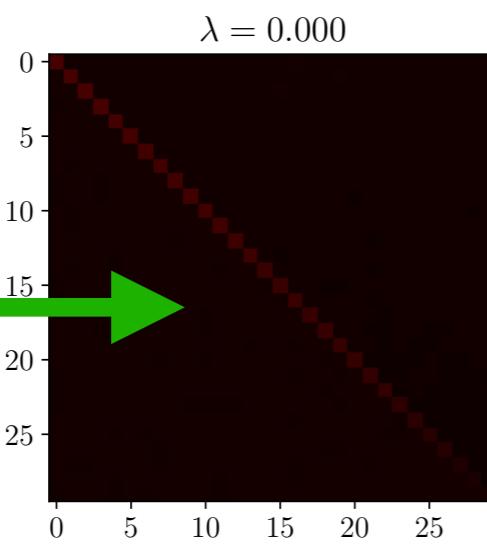
Optimally column-permuted

Overlap $Q = \frac{X^\top x}{N} = \left(\frac{X_\mu^\top x_\nu}{N} \right)_{\mu, \nu \leq M} \in \mathbb{R}^{M \times M} \quad x \sim P(\cdot | Y)$

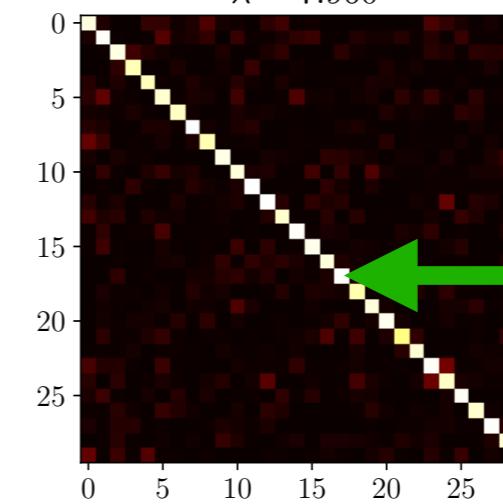
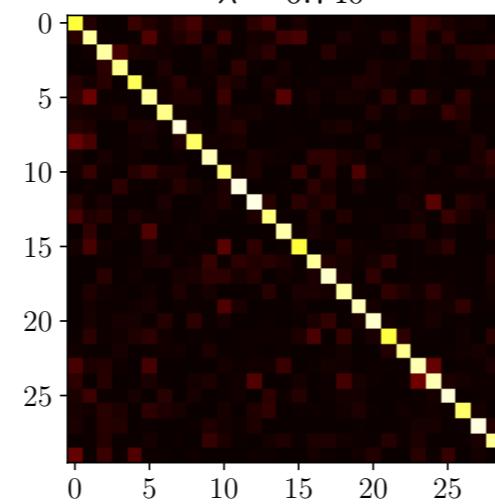
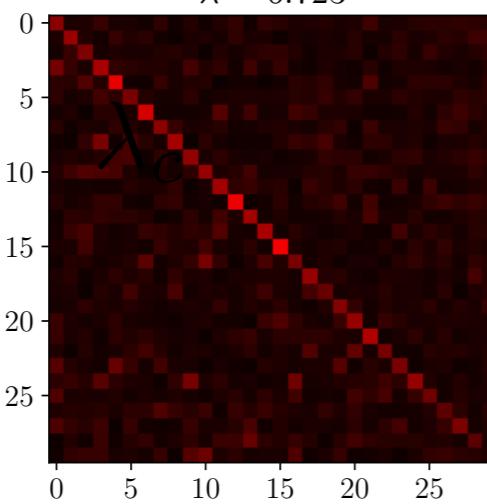
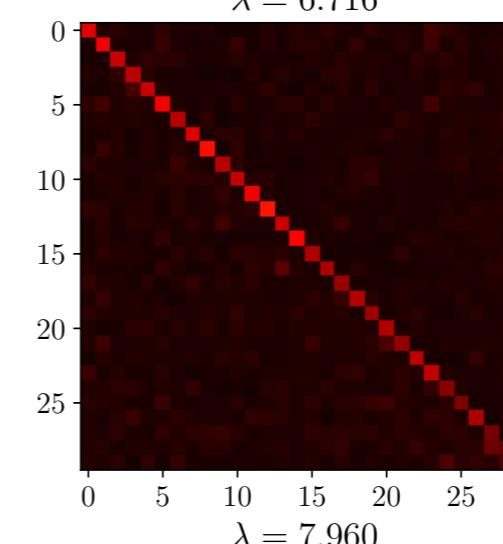
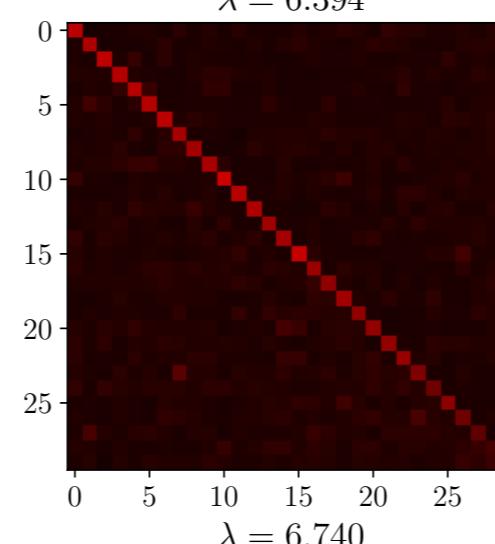
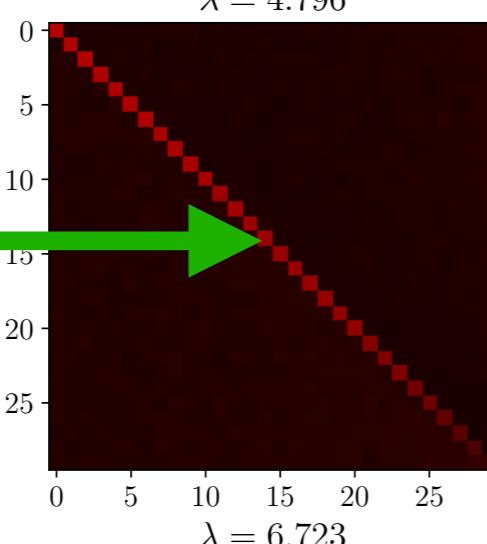
$$\frac{1}{MN^2} \mathbb{E} \|XX^\top - \langle xx^\top \rangle\|^2 = \frac{1}{M} \left(\mathbb{E} \left\| \frac{X^\top X}{N} \right\|^2 - \mathbb{E} \langle \|Q\|^2 \rangle \right)$$

$$N^{-2} \langle (X^\top x)^{\odot 2} \rangle$$

$O(1/N)$



Artefact from
permutation
breaking



$O(1)$

Nature of the phase transition

Universal

Information-theoretic quantities (MI and MMSE)
asymptotically independent of $P_X, \mathbb{E}X = 0, \mathbb{E}X^2 = 1$

Denoising

“Effective rotational invariance” -> RIE is optimal.

XX^\top can be estimated by RIE, X cannot

Mixed

Posterior patterns $(x_\mu)_{\mu \leq M}$ have $O(1/\sqrt{N})$
projections on planted patterns (X_μ)
but larger than in random case -> Information mixed.

Delocalised

Posterior patterns $(x_\mu)_{\mu \leq M}$ have $O(1/\sqrt{N})$
projections in the “quasi basis” (X_μ)

No feature learning

The internal features (factorised, discrete) of
 $S = XX^\top$ are not seen.

Non-universal

... dependent of prior.

Factorisation

Breaking of invariance -> RIE is NOT optimal.

Better strategy exists, which allows to reconstruct X

Ferromagnetic Retrieval

Each posterior pattern has $O(1)$
overlap with one planted one.

Localised

... $O(1)$...

Feature learning

The internal features are exploited.

$$\lambda_c$$

Conclusion

- Numerical insights on the phase diagram of matrix denoising with extensive rank: a model that “interpolates” between an RMT-like matrix model at low SNR and a mean-field spin model at high SNR
- Denoising/Universality -> Factorisation/Non-universality: 1st order transition. Extensive-rank generalisation of the BBP transition and its Bayesian counterpart
- Simple and versatile multiscale mean-field theory
- Predicts that factorisation is hard but possible: RIE best poly algorithm?
- Paves the way for the analysis of more complex inference, spin and matrix models

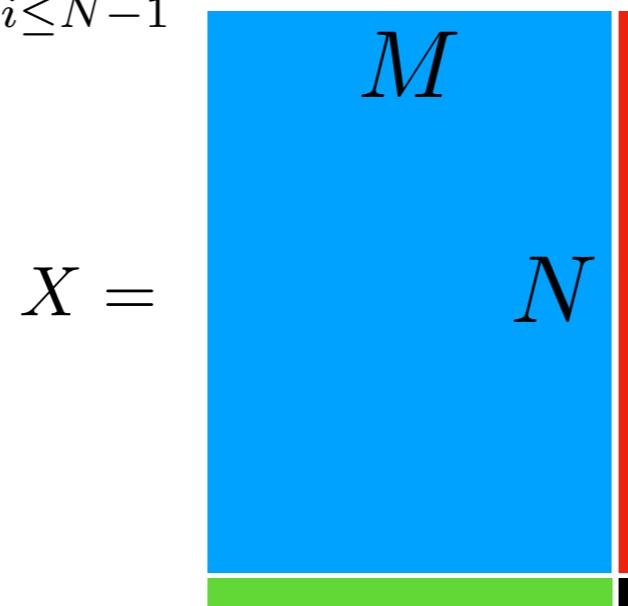
Work in progress

- More rigorous control
- Other extensive-rank models (Hopfield, Bayesian neural networks,...)

In addition

$O(MN) \longrightarrow O(M)$ cavity method

Usually $\frac{1}{N} \mathbb{E} \ln \mathcal{Z}_N = \frac{1}{N} \sum_{i \leq N-1} (\mathbb{E} \ln \mathcal{Z}_{i+1} - \mathbb{E} \ln \mathcal{Z}_i) \approx \lim_{N \rightarrow \infty} (\mathbb{E} \ln \mathcal{Z}_{N+1} - \mathbb{E} \ln \mathcal{Z}_N)$



Theorem 1 (Multiscale Aizenman–Sims–Starr identity). *Let $M = M_N = \alpha N$. We have*

$$\lim_{N \rightarrow \infty} \phi_{N,M} = \frac{1}{2} \lim_{N \rightarrow \infty} \frac{\Delta_{\text{row}}(N)}{M} + \frac{1}{2} \lim_{N \rightarrow \infty} \frac{\Delta_{\text{col}}(N)}{N}$$

where

$$\Delta_{\text{row}}(N) := \mathbb{E} \ln \mathcal{Z}_{N+1, M_{N+1}} - \mathbb{E} \ln \mathcal{Z}_{N, M_{N+1}},$$

$$\Delta_{\text{col}}(N) := \mathbb{E} \ln \mathcal{Z}_{N, M_N+1} - \mathbb{E} \ln \mathcal{Z}_{N, M_N}.$$

Proposition 2 (Equivalence of cavity representations).

Suppose that $\lim_{N \rightarrow \infty} \frac{\Delta_{\text{row}}(N)}{M_N}$ and $\lim_{N \rightarrow \infty} \frac{\Delta_{\text{col}}(N)}{N}$ exist and they are respectively equal to L_{row} and L_{col} . Then $L_{\text{row}} = L_{\text{col}}$.