

School "Optimization & Algorithms" - Toulouse 2024

HIGH-DIMENSIONAL RANDOM LANDSCAPES

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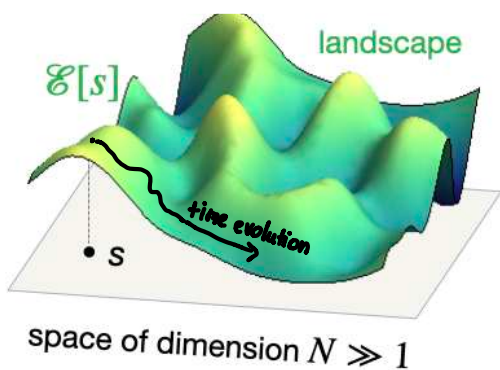


[If you find typos
please let me know!]

Exercises are at the
end of these notes.

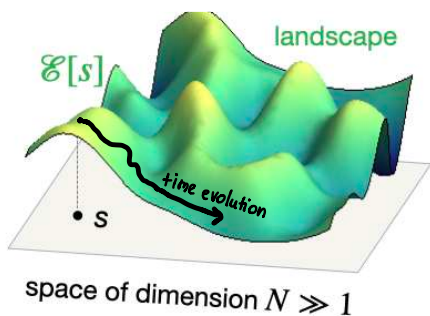
■ **WHAT:** High-D random landscapes are functions of many variables $\mathcal{E}[\vec{s}]$, $\vec{s} = (s_1, \dots, s_N)$ with $N \gg 1$, which are random, with given $\mathcal{P}[\mathcal{E}[\vec{s}]]$ (in the following, Gaussian)

■ **WHY:** Many 'complex systems' are inherently high-dimensional. They evolve trying to optimize some function (fitness, energy, cost...). Function encodes complex interactions between constituents, often modelled with random variables.

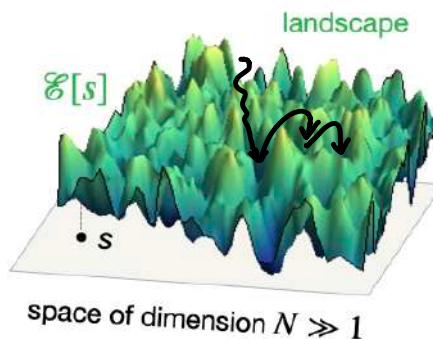


What to expect from this optimization processes in high-D, typically (i.e., with high probability)?

■ **How:** Characterize landscapes structure & its dynamical exploration using tools of Stat physics ($N \gg 1$) of disordered systems: random matrix theory, saddle-point & large- N limits, large-deviations, replica tricks, Kac-Rice counting formulas....



Scenario 1: "smooth" landscape.



Scenario 2: "rugged" landscape.

HIGH-D RANDOM LANDSCAPES

■ PART I: QUADRATIC HIGH-D LANDSCAPES

WHY: an example from high-D inference

An 'easy' inference problem - From denoising to landscapes - Questions & Strategy

HOW: Random Matrix Theory

From landscapes back to random matrices - Basic RMT facts

WHAT: Ground state, landscape, dynamics

Recovering the signal - A landscape of saddles - DMFT & beyond

■ PART II: RUGGED HIGH-D LANDSCAPES

WHY: another example from high-D inference

A 'hard' inference problem: noisy tensors - Landscape problem, & complexity

HOW: Kac-Rice formalism

Averages vs typical values, and replicas - Kac-Rice formula(s) -

Computing the complexity: 3 steps - The annealed complexity

WHAT: Ground state, landscape, dynamics

Recovering the signal - A landscape of minima - DMFT. And beyond?

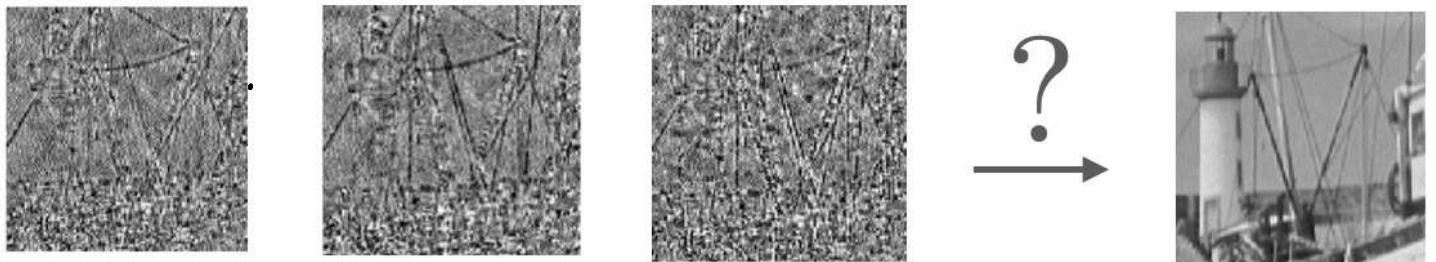
PART I

Quadratic high-D Landscapes

I.1 WHY: AN INFERENCE EXAMPLE

■ An 'easy' inference problem: noisy matrices

Inference problem: measure a "signal" corrupted by noise. Combining measurements, can recover information on signal?



(figure adapted from the web)

Denoising of matrices ("spiked" matrices): JOHNSTONE 2001

$$\hat{M} = r \frac{\vec{U} \vec{U}^T}{N} + \hat{J}$$

↑ signal strength ↑ signal ↓ noise (randomness)

size $N \times N$, $r \geq 0$
 $N \gg 1$

■ SIGNAL \vec{v} : vector of norm $\|\vec{v}\|^2 = N$, $\vec{v} = (v_1, \dots, v_N)$
 Unknown. Quenched (fixed). Independent of $\hat{\mathcal{J}}$.

■ NOISE $\hat{\mathcal{J}}$: matrix with random, symmetric ($\mathcal{J}_{ij} = \mathcal{J}_{ji}$) entries, $N \times N$. Gaussian statistics:

$$\langle \mathcal{J}_{ij} \rangle = 0, \quad \langle \mathcal{J}_{ij}^2 \rangle = \frac{\sigma^2}{N} (1 + \delta_{ij})$$

Probability to observe one instance of $\hat{\mathcal{J}}$:

$$P_N(\hat{\mathcal{J}}) d\hat{\mathcal{J}} = A_N e^{-\frac{N}{2\sigma^2} \sum_{i < j} \mathcal{J}_{ij}^2 - \frac{N}{4\sigma^2} \sum_{i=1}^N \mathcal{J}_{ii}^2} \prod_{i < j} d\mathcal{J}_{ij}$$

$$= A_N e^{-\frac{N}{4\sigma^2} \text{Tr}(\hat{\mathcal{J}}^2)} \prod_{i < j} d\mathcal{J}_{ij} \quad A_N = \frac{1}{2^N} \left(\frac{N}{2\pi\sigma^2} \right)^{\frac{N(N+1)}{2}}$$

"GAUSSIAN ORTHOGONAL ENSEMBLE" = rotationally invariant ensemble. \hat{O} rotation ($\hat{O}\hat{O}^T = \hat{1}$).

Matrix $\hat{\mathcal{J}}$ in new basis: $\hat{\mathcal{J}}_R = \hat{O}\hat{\mathcal{J}}\hat{O}^T$.

Rotationally invariant means: $\hat{\mathcal{J}}$ has same prob. as $\hat{\mathcal{J}}_R = \hat{O}\hat{\mathcal{J}}\hat{O}^T$: $\hat{\mathcal{J}} \stackrel{\text{in law}}{\sim} \hat{\mathcal{J}}_R$

Notice: Same eigenvalues, eigenvectors $\vec{u}_R = \hat{O}\vec{u}$. The evector of $\hat{\mathcal{J}}$ has same distribution as any other vector obtained from it with rotation \Rightarrow uniformly distributed vector on sphere.

From denoising to landscapes

Estimator (guess) of \vec{v} : $\vec{s}_{\text{ML}} = \underset{\|\vec{s}\|^2 = N}{\text{argmax}} \vec{s}^T \hat{M} \vec{s}$

this is "maximum likelihood estimator" of the signal \vec{v} .

Maximum-likelihood

$$\hat{M} = r \frac{\vec{v} \vec{v}^T}{N} + \hat{J}$$

\hat{M} - observation
 \vec{v} - unknown signal
 \hat{J} - iid gaussians

Bayes formula:

$$\underbrace{P(\vec{s} | \hat{M})}_{\text{POSTERIOR}} = \underbrace{P_0(\vec{s})}_{\text{PRIOR}} \underbrace{P(\hat{M} | \vec{s})}_{\text{LIKELIHOOD}} \frac{1}{P(\hat{M})} = P_0(\vec{s}) \frac{e^{-\frac{N}{4\sigma^2} \sum_{i,j} (M_{ij} - \frac{r}{N} s_i s_j)^2}}{Z(\hat{M})}$$

$$\mathcal{L}(\vec{s} | \hat{M}) = \log P(\hat{M} | \vec{s}) = -\frac{N}{2\sigma^2} \sum_{i,j} (M_{ij} - \frac{r}{N} s_i s_j)^2 \left(\frac{1}{1 + \delta_{ij}} \right) + \ell(\hat{M})$$

"log-likelihood"

The maximum-likelihood estimator is the vector that maximizes the log-likelihood.

If we know $\|\vec{u}\|^2 = N$, we can assume $\|\vec{s}\|^2 = N$
 and thus the estimator is minimizing

$$\sim \sum_{i,j=1}^N \left(M_{ij} - \frac{r}{N} s_i s_j \right)^2 = \sum_{i,j=1}^N M_{ij}^2 + \frac{r^2}{N^2} \|\vec{s}\|^4 - \frac{2r}{N} \sum_{i,j} M_{ij} s_i s_j$$

$$\Rightarrow \vec{s}_{\text{gs}} = \underset{\|\vec{s}\|^2 = N}{\text{arg max}} \vec{s} \cdot \hat{M} \vec{s}$$

s_{gs} is also the ground state of the energy landscape:

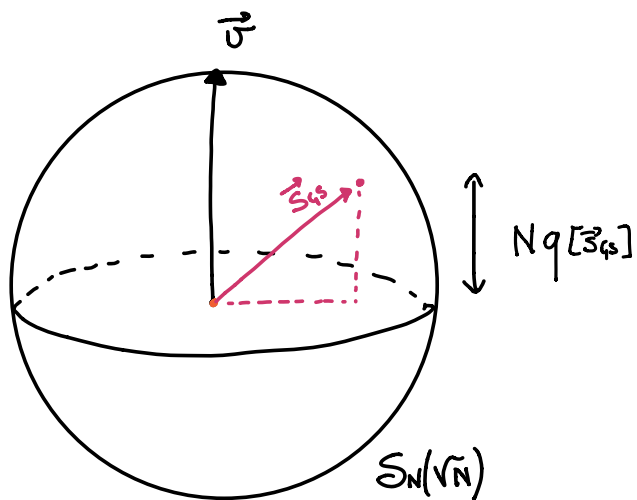
$$\mathcal{E}[\vec{s}] = -\frac{1}{2} \sum_{i,j=1}^N s_i M_{ij} s_j = -\frac{1}{2} \sum_{i,j=1}^N \left[J_{ij} s_i s_j + r N \left(\frac{\vec{u} \cdot \vec{s}}{N} \right)^2 \right]$$

defined on $\mathcal{S}_H(\sqrt{N}) = \{ \vec{s} : \|\vec{s}\|^2 = N \}$

\uparrow random isotropic \uparrow deterministic biased towards \vec{u}

Finding the estimator \iff solving optimization problem for random landscape $\mathcal{E}[\vec{s}]$.

Define the "OVERLAP WITH SIGNAL"



$$q_N[\vec{s}] = \frac{\vec{s} \cdot \vec{v}}{N}$$

$$q[\vec{s}] = \lim_{N \rightarrow \infty} q_N[\vec{s}]$$

$r=0$: random, fully-connected interactions
between s_i : "pure spherical $p=2$ model"
Isotropic statistics

$$\langle \mathcal{E}[\vec{s}] \rangle = 0$$

$$\langle \mathcal{E}[\vec{s}] \mathcal{E}[\vec{s}'] \rangle = \frac{N\sigma^2}{2} \left(\frac{\vec{s} \cdot \vec{s}'}{N} \right)^2$$

by entropy,
 \Rightarrow expect $\vec{s}_{qs} \perp \vec{v}$
for $r=0$ (see below)

$\sigma=0$: the points in the vicinity of \vec{v} are favored
energetically, $\vec{s}_{qs} = \vec{v}$

Competition leads to transitions in r/σ (signal-to-noise ratio) when $N \rightarrow \infty$.

High-D geometry: typical values of overlaps

Let \vec{v} be fixed vector $\|\vec{v}\|^2 = N$. Assume \vec{s} uniformly taken on sphere. Then typical value of $\left(\frac{\vec{v} \cdot \vec{s}}{N}\right) \xrightarrow{N \rightarrow \infty} 0$.
 With overwhelming probability, two vectors are orthogonal when $N \rightarrow \infty$.

Indeed:

Basis-independent. Choose basis in which $\vec{v} = \sqrt{N}(0, 0, \dots, 1)$

$$\left\langle \left(\frac{\vec{v} \cdot \vec{s}}{N}\right)^2 \right\rangle = \frac{1}{|\mathcal{S}_N(\sqrt{N})|} \int_{\mathcal{S}_N(\sqrt{N})} \prod_{i=1}^N d\sigma_i \left(\frac{\vec{v} \cdot \vec{s}}{N}\right)^2 = \frac{1}{|\mathcal{S}_N|} \int_{\mathcal{S}_N(\sqrt{N})} \prod_{i=1}^N d\sigma_i \quad \frac{\mathcal{S}_N^2}{N} \quad \textcircled{=}$$

Surface of $(N-1)$ -dimensional sphere of radius R , in \mathbb{R}^N :

$$|\mathcal{S}_N(R)| = \frac{2\pi^{N/2}}{\Gamma(N/2)} R^{N-1} \quad (*)$$

Rescale: $\vec{\sigma} = \vec{s}/\sqrt{N}$:

$$\textcircled{=} N^{N/2} \int_{\mathcal{S}_N(1)} \prod_{i=1}^N d\sigma_i \sigma_N^2 = N^{N/2-1} \int d\sigma_N \sigma_N^2 \underbrace{\left[\int_{i=1}^{N-1} \prod_{i=1}^{N-1} d\sigma_i \delta\left(\sum_{i=1}^{N-1} \sigma_i^2 - [1 - \sigma_N^2]\right) \right]}_{|\mathcal{S}_{N-1}(\sqrt{1 - \sigma_N^2})|}$$

$$\stackrel{N \gg 1}{\approx} \frac{\int d\sigma_N \sigma_N^2 e^{\frac{N}{2} \log [2\pi e(1 - \sigma_N^2)]} + o(N)}{e^{N/2 \log(2\pi e)}} \xrightarrow[N \rightarrow \infty]{\text{SADDLE POINT: } \sigma_N^{\text{SP}} = 0} 0$$

Notice:

Could do this for all components by rotational invariance: all σ_i^2 are statistically equivalent $\Rightarrow \sum_{i=1}^N \sigma_i^2 \approx N \cdot \langle \sigma_i^2 \rangle = 1 \Rightarrow \langle \sigma_i^2 \rangle \approx 1/N$
 $\Rightarrow \langle \left(\frac{\mathbf{v} \cdot \mathbf{S}}{N} \right)^2 \rangle \approx 1/N$

Indeed, setting $\sigma_N^2 = a/N$ and using (*):

$$\left\langle \left(\frac{\mathbf{S} \cdot \mathbf{J}}{N} \right)^2 \right\rangle = \frac{N^{N/2-1}}{|\mathcal{S}_N(\sqrt{N})| \cdot \Gamma\left(\frac{N-1}{2}\right)} \int \frac{da}{2\sqrt{Na}} \left(\frac{a}{N}\right) \left(1 - \frac{a}{N}\right)^{\frac{N-2}{2}}$$

Since $\left(1 - \frac{a}{N}\right)^{N/2} \xrightarrow{N \rightarrow \infty} e^{-a/2}$,

$$= C_N \frac{N^{N/2} \pi^{N/2}}{\underbrace{\Gamma\left(\frac{N-1}{2}\right) |\mathcal{S}_N(\sqrt{N})|}_{\text{exponential cancel!}}} \int da f_N(a)$$

exponential cancel!

Questions & strategy

▶ Three questions:

[Q1] RECOVERY QUESTION (T=0 EQUILIBRIUM)

for which values of r/σ is \vec{S}_{qs} informative of signal \vec{v} , i.e. "close" to \vec{v} in configuration space?

For $N \rightarrow \infty$, $q[\vec{S}_{qs}] > 0$ ("magnetization")

[Q2] LANDSCAPE QUESTION (METASTABLE STATES)

are there many local minima/stationary points at higher energy? How far from \vec{S}_{qs} ?

How far from \vec{v} ?

In following, "many" = $\mathcal{O}(e^N)$

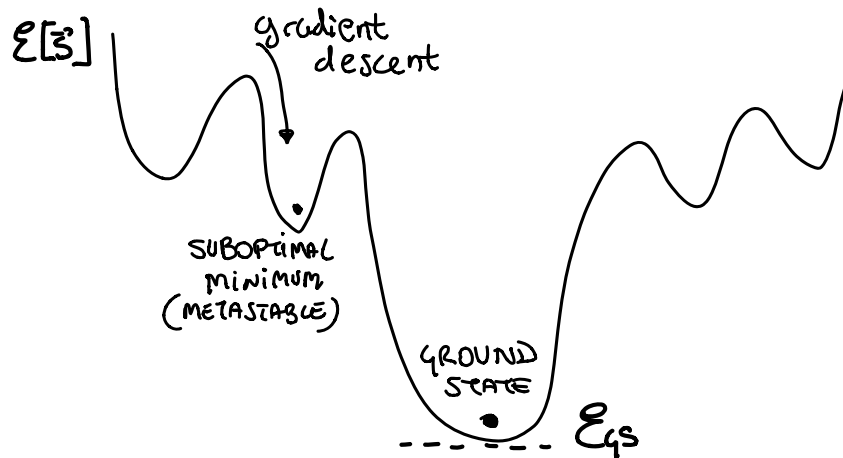
[Q3] ALGORITHMIC QUESTION (DYNAMICS)

finding \vec{S}_{qs} with (local) optimization algorithms (gradient descent / Langevin: $\frac{d\vec{S}(t)}{dt} = -\nabla_{\vec{S}} \mathcal{E}[\vec{S}] + \sqrt{2T} \vec{\eta}(t)$) is

easy: timescales $\tau_{typ} \sim \mathcal{O}(N^\alpha)$, or \nearrow gradient on the sphere
hard: timescales $\tau_{typ} \sim \mathcal{O}(e^N)$?

Q2 and Q3 related: optimization hard when many metastable states/local minima in which system gets stuck!

↳ glassiness



► The strategy:

Study the typical distribution of stationary points \vec{s}^* : $\nabla_{\vec{s}} \mathcal{E}[\vec{s}^*] = 0$ as a function of:

(i) energy density $\epsilon_N[\vec{s}^*] = \mathcal{E}[\vec{s}^*]/N$

(ii) stability / local curvature (Minima, saddles)

curvature = eigenvalues of Hessian $\nabla_{\vec{s}}^2 \mathcal{E}[\vec{s}]$ ($\sim \frac{\partial^2 \mathcal{E}[\vec{s}]}{\partial s_i \partial s_j}$)

index $K_N[\vec{s}] = \{ \# \text{ negative evalues } \nabla_{\vec{s}}^2 \mathcal{E}[\vec{s}] \}$
 (minima: all evalues positive, $K=0$)

(iii) geometry: overlap with signal $q_N[\vec{s}^*] = (\vec{s}^* \cdot \vec{\sigma})/N$

Q1. Properties of global minimum

Q2/Q3. Properties of local minima

Notice: here "typical" means: happening with probability $P \rightarrow 1$ when $N \rightarrow \infty$.

"rare" means happening with $P \xrightarrow{N \rightarrow \infty} 0$.

► We shall see:

Quadratic landscape $E[\vec{z}]$: Can answer all the questions when $N \rightarrow \infty$, using Random matrix theory. Describe what happens typically (= with large probability) when N large.

More complicated landscapes: PART II.

► Comment: Q1 and Q3 depend on the estimator and on the algorithm chosen. Here we discuss maximum likelihood (with spherical prior), and Langevin dynamics, and derive a recovery and algorithmic threshold for them.

"Information-theoretic threshold" (minimal r/σ above which it is information theoretically possible to detect the signal) can be smaller than the recovery threshold predicted by ML.

I.2] HOW: RANDOM MATRIX THEORY

From landscapes back to random matrices

Consider a fixed realization of $\hat{M} \rightarrow$ of landscape $\mathcal{E}[\vec{s}]$

KOSTERLITZ, THOULESS, JONES 1976

Implement spherical constraint:

$$\mathcal{E}_\lambda[\vec{s}] = -\frac{1}{2} \sum_{i,j=1}^N M_{ij} s_i s_j + \frac{\lambda}{2} \left(\sum_{i=1}^N s_i^2 - N \right)$$

Stationary points (\vec{s}^*, λ^*) satisfy:

$$\begin{cases} \frac{\partial \mathcal{E}_\lambda[\vec{s}^*]}{\partial s_i} = -\sum_{j=1}^N M_{ij} s_j^* + \lambda^* s_i^* = 0 & \forall i=1, \dots, N \\ \frac{\partial \mathcal{E}_\lambda[\vec{s}^*]}{\partial \lambda} = \sum_i (s_i^*)^2 - N = 0 \end{cases}$$

The first equation is eigenvalue equation for \hat{M} : $\hat{M} \vec{s}^* = \lambda^* \vec{s}^*$

If $\{\vec{u}_\alpha, \lambda_\alpha\}$ are eivectors/eivalues of \hat{M} for $\alpha=1, \dots, N$, then:

$\vec{s}_\alpha = \pm \sqrt{N} \vec{u}_\alpha$ are stationary points of $\mathcal{E}[\vec{s}]$: $2N$ of them!
(notice symmetry bc. quadratic function)

Properties:

(i) Energy. Multiply first equation by s_i^* , sum & use second one:

$$\sum_{i,j} s_i^* M_{ij} s_j^* = \lambda^* \cdot N \Rightarrow \lambda^* = -\frac{2 \mathcal{E}[s^*]}{N} = -2 \underset{\substack{\uparrow \\ \text{energy density}}}{\mathcal{E}[s^*]}$$

\Rightarrow The \vec{s}_α have energy density

$$\underline{\mathcal{E}_N[\vec{s}_\alpha] = -\frac{\lambda_\alpha}{2}}$$

(ii) Stability. minima, saddles?

Hessian: $\nabla^2 \mathcal{E}_\lambda[s^*] = -M_{ij} + \lambda^*$

At stationary point \vec{s}^α : $\nabla^2 \mathcal{E}_\lambda[\vec{s}^\alpha] = -(\hat{M} - \lambda_\alpha \hat{1})$

The eigenvalues of \hat{M} are $\lambda_1 \leq \dots \leq \lambda_N$. The eigenvalues of $\nabla^2 \mathcal{E}_\lambda[\vec{s}^\alpha]$ are $\underbrace{-(\lambda_1 - \lambda_\alpha)}_{\text{positive if } \alpha > 1}, \underbrace{-(\lambda_2 - \lambda_\alpha)}_{\text{positive if } \alpha > 2}, \dots$

One zero eigenvalue (due to spherical constraint), $(d-1)$ positive and $N-d$ negative: stationary points \vec{s}_α are saddles of index $\underline{\kappa_N[s_\alpha] = N-d}$

Ground state: $d=N$. Global minimum ($\kappa=0$)

⇒ For each realization of randomness \hat{J} , $\mathcal{E}[\vec{s}]$ has $2N$ stationary points; their energy distribution is related to eigenvalue distribution of \hat{M} .

Statistical properties when $N \gg 1$ determined by Random Matrix Theory (RMT).

Notation: gradients & Hessians on sphere

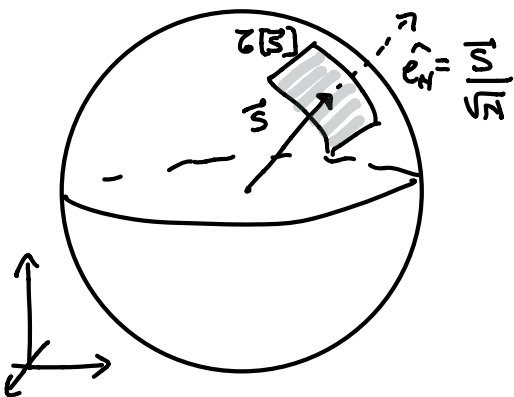
$$\nabla \mathcal{E}[\vec{s}] = \left(\frac{\partial \mathcal{E}}{\partial s_i} \right)_{i=1}^N \text{ gradient in } \mathbb{R}^N$$

Lagrange multiplier λ^* subtracts the radial component:

$$\lambda^* = -\nabla \mathcal{E}[\vec{s}] \cdot \vec{s}, \quad \nabla \mathcal{E}_\lambda[\vec{s}] = \nabla \mathcal{E}[\vec{s}] - \underbrace{\left(\frac{\nabla \mathcal{E}[\vec{s}] \cdot \vec{s}}{N} \right)}_{\text{radial component}} \vec{s}$$

Choose basis vectors such that

$$\vec{e}_\alpha = \begin{cases} \perp \vec{s} & \alpha = 1, \dots, N-1 \\ \vec{e}_N = \vec{s}/\sqrt{N} \end{cases} \leftarrow \text{Spanning tangent plane } \mathcal{C}[\vec{s}]$$



In this basis:

$$\nabla \mathcal{E}_\lambda[\vec{s}] = \begin{pmatrix} \nabla_\perp \mathcal{E}[\vec{s}] \\ 0 \end{pmatrix} \quad \begin{matrix} (N-1)\text{-dim} \\ \text{"gradient} \\ \text{on the} \\ \text{sphere"} \end{matrix}$$

Similarly, Hessian on the sphere $\nabla_\perp^2 \mathcal{E}[\vec{s}]$ is the $(N-1) \times (N-1)$ matrix $\frac{\partial^2 \mathcal{E}[\vec{s}]}{\partial s_i \partial s_j} + \lambda^*[\vec{s}] \hat{1}$ projected on $\mathcal{C}[\vec{s}]$

Some facts in Random Matrix Theory (RMT)

- The results below hold true for rank-1 perturbed GOE matrices of the type:

$$\hat{M} = \hat{J} + \hat{R} = \hat{J} + r \vec{w} \vec{w}^T \quad (\vec{w} = \vec{v}/\sqrt{N}, \|\vec{w}\|=1)$$

\hat{J} = GOE matrix: both a Wigner matrix (real, symmetric, iid entries) & rotationally-invariant ($\hat{J} \stackrel{\text{in law}}{\sim} \mathbf{J}_R = \mathbf{O} \hat{J} \mathbf{O}^T$)
Normalized so that spectrum in bounded interval when $N \rightarrow \infty$.

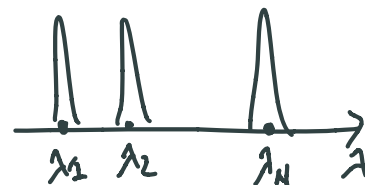
\hat{R} = deterministic, rank-one matrix with 1 eigenvalue equal to r , and $(N-1)$ zero eigenvalues. Independent of \hat{J}
Perturbation to GOE! "Spike".

- Some results have some degree of universality: can be generalized to other matrix ensembles, or perturbations of higher rank (finite in N)

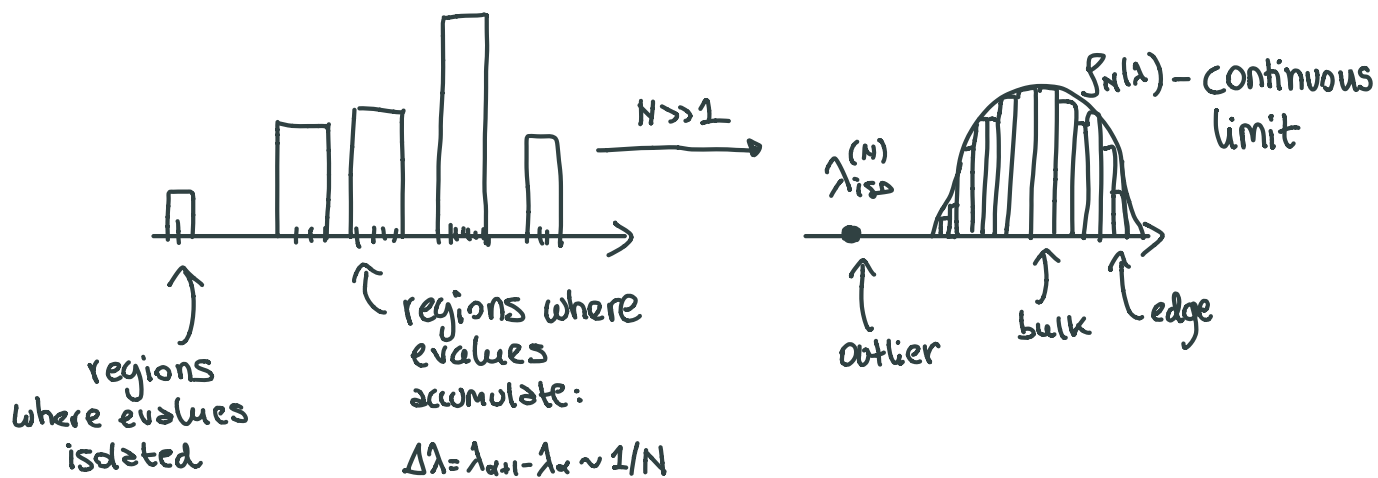
- Eigensystem: $\{\lambda_\alpha, u_\alpha\}_{\alpha=1}^N$. In this section, averages are w.r.t. distribution of \hat{M} : $\langle \cdot \rangle = \int d\hat{M} P(\hat{M})$.
Assume $\lambda_1 \leq \dots \leq \lambda_N$, and $\|u_\alpha\|=1$.

► The eigenvalue distribution: density, & outliers

N finite:
$$V_N(\lambda) = \frac{1}{N} \sum_{\alpha=1}^N \delta(\lambda - \lambda_\alpha)$$



Typical scenario when N increases:



$$V_N(\lambda) \stackrel{N \gg 1}{\approx} \underbrace{\rho_N(\lambda)}_{\text{Density}} + \underbrace{\frac{1}{N} \delta(\lambda - \lambda_{iso}^{(N)})}_{\text{Outliers}}$$

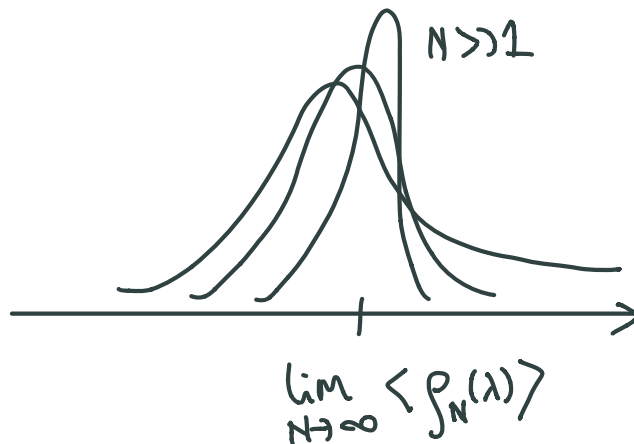
The density. Where values accumulate, distribution described by continuous density: $\rho_N(\lambda)$.

$$P(\lambda_\alpha \in [\lambda, \lambda + \delta\lambda]) \stackrel{N \gg 1}{\approx} \rho_N(\lambda) d\lambda$$

have $\mathcal{O}(N)$ values around λ , separated by $\mathcal{O}(1/N)$ in bulk, or $\mathcal{O}(1/N^\alpha)$ at edges.

Facts: (a) Density $f_N(\lambda)$ is self-averaging

$$\lim_{N \rightarrow \infty} \underbrace{f_N(\lambda)}_{\text{random function}} = \underbrace{f_\infty(\lambda)}_{\text{deterministic}} = \lim_{N \rightarrow \infty} \langle f_N(\lambda) \rangle$$



(b) Can be obtained from Stieltjes transform:

$$g_N(z) = \int \frac{d\nu_N(\lambda)}{z - \lambda} = \frac{1}{N} \sum_{\alpha} \frac{1}{z - \lambda_{\alpha}} = \frac{1}{N} \text{tr} \left(\underbrace{\frac{1}{z - M}}_{\text{resolvent}} \right)$$

This function is singular when $z \rightarrow \lambda_{\alpha}$ (poles)
 Define it away from real axis, e.g. $z \in \mathbb{C}^-$, $z = E - i\eta$
 (then: analytically continue).

$\lim_{N \rightarrow \infty} g_N(z) = g_{\infty}(z)$ also self-averaging

(c) When $N \rightarrow \infty$, poles accumulate into branch-cut.
The discontinuity at the cut is related to $\rho_\infty(\lambda)$:

$$\rho_\infty(\lambda) = \lim_{\eta \downarrow 0} \frac{1}{\pi} \text{Im} \left\{ g_\infty(\lambda - i\eta) \right\}$$

Isolated eigenvalues. Isolated poles of $g_N(z)$, contributing to order $1/N$.

They also "concentrate": $\lim_{N \rightarrow \infty} \lambda_{iso}^{(N)} = \lambda_{iso}^\infty$

Questions:

- ▣ $\rho_\infty(\lambda)$, typical value of $\lambda_{iso}^{(N)}$ when $N \rightarrow \infty$?
- ▣ typical fluctuations at N large & finite?
- ▣ atypical fluctuations: large deviations

Books:

POTTERS, BOUCHAUD - A first course in random matrix theory, 2021
MEHTA - Random Matrices, 2004

► Typical values: the density $\rho_\infty(\lambda)$.

Can be studied with REPLICA METHOD → EXERCISE 1

One finds that:



(1) The finite rank perturbation \hat{R} does not affect the density of \hat{M} , that is the same as the one of \hat{J} .

$$\lim_{N \rightarrow \infty} \rho_N(\lambda; r) = \rho_\infty(\lambda; r=0) \quad (\text{effect of rank-1 perturbation disappears for } N \rightarrow \infty)$$

(2) When \hat{J} is Gaussian, $\langle J_{ij}^2 \rangle = \frac{\sigma^2}{N} (1 + \delta_{ij})$, then:

The Stieltjes transform satisfies a self-consistent

equation:

$$\sigma^2 g_\infty^2(z) - z g_\infty(z) + 1 = 0 \quad z \notin \text{spectrum}$$

(3) This is solved by: $g_{sc}(z) = \frac{z - z\sqrt{1 - 4\sigma^2/z}}{2\sigma^2}$

choice of branch?

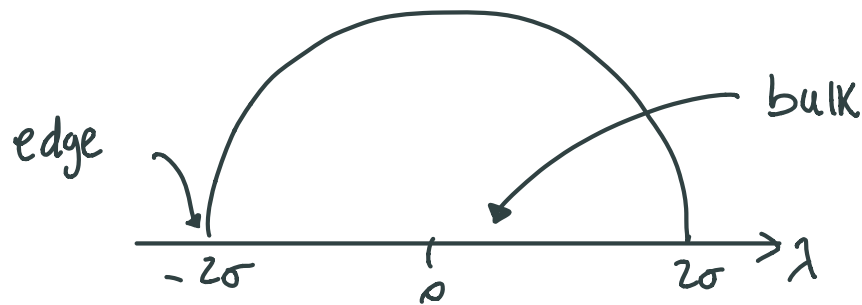
Continuation to real axis: $z \rightarrow \lambda$

$$g_{sc}(\lambda) = \frac{\lambda - \text{sign}(\lambda)\sqrt{\lambda^2 - 4\sigma^2}}{2\sigma^2} \quad \lambda \notin [-2\sigma, 2\sigma]$$

Choice of branch guarantees $\lim_{|\lambda| \rightarrow \infty} g_{sc}(\lambda) = 0$ ($g_{sc}(z) \sim \frac{1}{z}$)

By inversion formula:

$$f_{\infty}(\lambda) = f_{sc}(\lambda) = \frac{1}{2\pi\sigma^2} \sqrt{4\sigma^2 - \lambda^2} \quad \mathbb{1}_{\lambda \in [-2\sigma, 2\sigma]}$$



■ Universality of $f_{sc}(\lambda)$: it is the limiting density for a large class of matrices of the Wigner type: symmetric, with iid entries not necessarily Gaussian, finite second moment.

ERDÖS - Universality of Wigner random matrices: a survey of results, 2010

BENAYCH-GEORGES & KNOWLES - Lectures on the local semicircle law for Wigner matrices, 2019

Also spectrum of Laplacian of random graphs. (adjacency matrix), Burgers equation...

■ \hat{R} can have larger rank, not scaling with N (finite rank)

► Typical values: the isolated value(s) \ evector(s)

The $1/N$ contributions to $g_N(x)$ can be studied in a large- N expansion \rightarrow EXERCISE 2



One finds that:

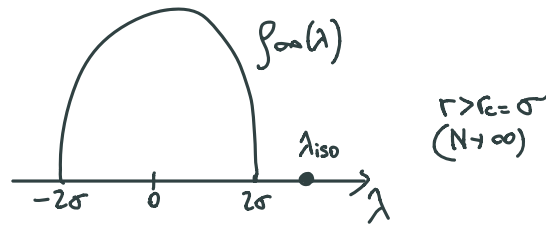
(1) For $\hat{R}=0$, There are no isolated eigenvalues

$$\begin{aligned} \lim_{N \rightarrow \infty} \lambda_1 &= -2\sigma && \text{minimal eigenvalue} \\ \lim_{N \rightarrow \infty} \lambda_N &= 2\sigma && \text{maximal eigenvalue} \end{aligned} \quad (\text{almost surely})$$

(2) When $N \rightarrow \infty$, a transition in maximal value when $r = r_c = \sigma$ (notice: smaller than radius 2σ)

$$\lim_{N \rightarrow \infty} \lambda_N = \begin{cases} 2\sigma & r \leq r_c = \sigma \\ \frac{\sigma^2}{r} + r & r > r_c = \sigma \end{cases} \quad (\text{almost surely})$$

For $r < r_c$, same behavior as for $r=0$: largest value sticks to boundary. For $r > r_c$, the largest eigenvalue is isolated:

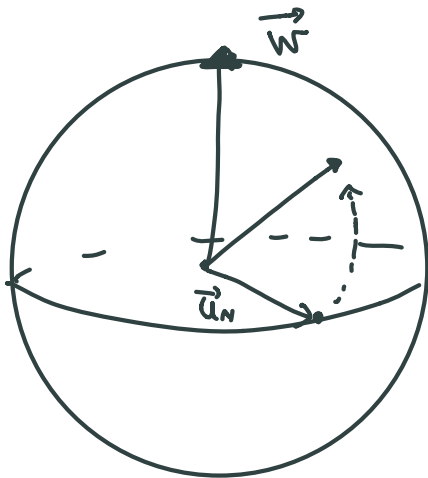


KOSTERLITZ, THOULESS, JONES 1976
PÉCHÉ 2006

(3) The eigenvector \vec{u}_N when $r \geq r_c$ acquires macroscopic projection on $\vec{w} = \vec{v} / \sqrt{N}$

Then:

$$\lim_{N \rightarrow \infty} (\vec{u}_N \cdot \vec{w})^2 = \begin{cases} 0 & \text{if } r \leq r_c \\ 1 - (\sigma/r)^2 & r \geq r_c \end{cases}$$



While all other eigenvectors such that $(\vec{u}_\alpha \cdot \vec{w})^2 = 0$ $\alpha \neq N$

This can be seen as a "LOCALIZATION" transition.

- For $r=0$, consistent with rotational invariance:

eigenvectors of \hat{J} like random vectors on sphere (statistically), and \vec{w} is independent of \hat{J} .

As in calculation above,

$$\langle (\vec{u}_\alpha \cdot \vec{w})^2 \rangle = \int \prod_{i=1}^N du_i \delta(\|\vec{u}\| - 1) (\vec{u}_\alpha \cdot \vec{w})^2 \sim \frac{1}{N} \xrightarrow{N \gg 1} 0$$

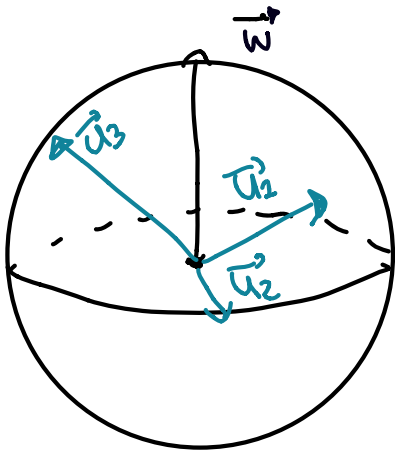
(Use this in Exercise 2): two arbitrary vectors on sphere are typically orthogonal when $N \rightarrow \infty$.

\vec{w} is DELOCALIZED in basis \vec{u}_α : overlap is of same order of magnitude for all α , no special direction.

Terminology from quantum problems, where \vec{u}_α and \vec{w} eigenvectors of local operators (QM is linear).

[CONNECTED NOTIONS: QUANTUM CHAOS, FREE PROBABILITY.]

- When $r > 0$, isotropy broken in direction \vec{w} . For $r > r_c$, \vec{w} localized in basis \vec{u}_α !



Measure of localization in a basis \vec{u}_α : IPR, or HERFINDAHL INDEX:

$$\text{IPR} = \frac{\sum_{\alpha=1}^N (\vec{w} \cdot \vec{u}_\alpha)^4}{\sum_{\alpha=1}^N (\vec{w} \cdot \vec{u}_\alpha)^2}$$

non-zero in localized phase

$$\text{IPR} = \begin{cases} \sum_{\alpha=1}^N \left(\frac{1}{N}\right)^2 \sim \frac{1}{N} \xrightarrow{N \rightarrow \infty} 0 & r \leq r_c \\ \sum_{\alpha=1}^{N-1} \left(\frac{1}{N}\right)^2 + \theta(1) \xrightarrow{N \rightarrow \infty} \theta(1) & r > r_c \end{cases}$$

It is also an instance of CONDENSATION (sum over many elements dominated by $\theta(1)$ terms) \rightarrow see EXERCISE 3

Generalizations:

- ① The above is true if $\hat{\mathcal{J}}$ is extracted from a rotationally invariant ensemble (not necessarily Gaussian), with density $g_{\infty}(a)$ supported in $[a, b]$. Then one can show that almost surely:

$$\lim_{N \rightarrow \infty} \lambda_N = \begin{cases} b & r \leq r_c = 1/g_{\infty}(b) \\ g_{\infty}^{-1}\left(\frac{1}{r}\right) & r > r_c = 1/g_{\infty}(b) \end{cases}$$

$$\lim_{N \rightarrow \infty} (\vec{w} \cdot \vec{u}_N)^2 = \begin{cases} 0 & \text{if } r \leq r_c \\ \frac{-1}{r^2 g'_{\infty}(\lambda_{\text{iso}})} & r \geq r_c \end{cases}$$

PÉCHÉ 2006

BENAYCH-GEORGES &

NADAKUDITI 2011

One can recover the GOE expressions from these general ones

Important thing: \hat{R} is independent ("Free") of \hat{J} .

CAPITAINE, DONATI-MARTIN 2016

- can be generalized to perturbations \hat{R} with rank $n > 1$: n transitions, potentially n isolated eigenvalues. One r_c for each of them.

▶ Finite- N fluctuations: small deviations

Above results describe $N \rightarrow \infty$ limit, when things are self-averaging / concentrate.

At finite N : fluctuations. Things are distributed.

Fluctuations of smallest eigenvalue?

▣ Transition at $r=r_c$ becomes a crossover.

Critical regime: $w = N^{2/3}(r-r_c) \Rightarrow r = r_c + N^{-2/3}w$

$\left\{ \begin{array}{l} \text{If } (r_c - r) \gg N^{-1/3} : \text{ subcritical} \end{array} \right.$

$\left\{ \begin{array}{l} \text{If } (r - r_c) \gg N^{-1/3} : \text{ supercritical} \end{array} \right.$

BEN AROUS, BAIK, PECHÉ 2005

PECHÉ 2006

BLOEMENTAL, VIRÁG, 2013

(See example in figure below.)

Scaling $N^{2/3}$ of critical window: BBP 2005 for complex Wishart, but conjectured to be general.

Subcritical regime ($r > 0$)

$$\lambda_N \stackrel{N \gg 1}{\approx} 2\sigma + N^{-2/3} \sigma \mathbb{S}_{TW}$$

\mathbb{S}_{TW} = Variable with Tracy-Widom distribution $P_{TW} (\beta=1)$

This means

$$\lim_{N \rightarrow \infty} P\left(\frac{N^{2/3} (\lambda_N - 2\sigma)}{\sigma}\right) = P_{TW}$$

TRACY, WIDOM 1994

FORRESTER 1993

The gap between eigenvalues at edge is $\mathcal{O}(N^{-2/3})$ in subcritical regime

BAIK, LEE 2017

Supercritical regime:

$$\lambda_N \stackrel{N \gg 1}{\approx} \lambda_{iso}^{\infty} + N^{-2/2} \sqrt{2\sigma^2 \left(1 - \frac{\sigma^2}{r^2}\right)} \mathbb{S}_{Gauss}$$

\mathbb{S}_{Gauss} = random v. with Gaussian distrib.

$$\lim_{N \rightarrow \infty} P\left(\frac{N^{2/2} (\lambda_N - \lambda_{iso}^{\infty})}{\sqrt{2\sigma^2 \left(1 - \frac{\sigma^2}{r^2}\right)}}\right) = P_{Gauss}$$

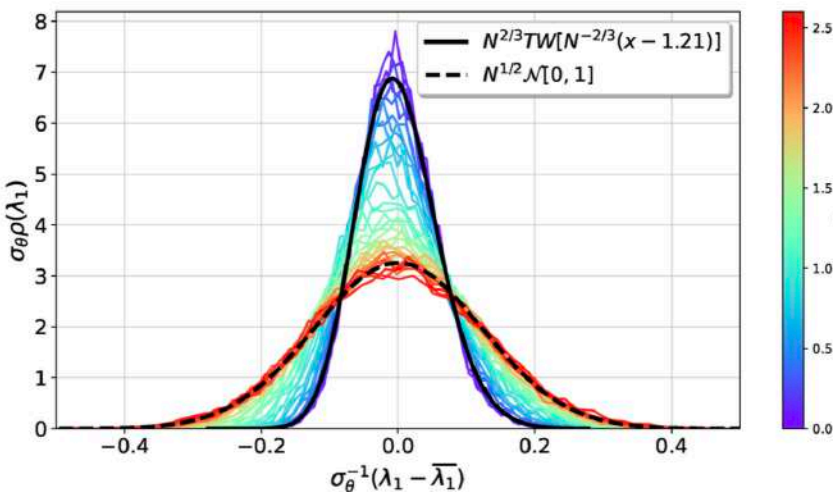
■ Critical regime ($r = r_c + N^{-2/3} \omega$)

$$\lambda_N \stackrel{N \gg 1}{\approx} 2\sigma + N^{-2/3} X_\omega \quad X_\omega \text{ random variable with distribution } p_\omega$$

Such that: $p_\omega \xrightarrow{\omega \rightarrow \infty} \text{gauss}$
 $p_\omega \xrightarrow{\omega \rightarrow -\infty} \text{tracy-widom}$

BLOEMENTAL, VIRÁG, 2013

Figure 1. Scaled probability density distributions of an ensemble of 10^4 spike random matrices with $N = 100$. The distributions are centered relative to the ensemble average λ_1 and σ_θ stands for the predicted standard deviation when $\theta > 1$. The centered TW distribution TW (15) and the normal distribution $\mathcal{N}[0, 1]$ (16) have been scaled similarly to the data.



Crossover in distribution of λ_N , from Tracy-Widom to gaussian [here θ denotes r/σ]

PIMENTA, STARIOLO 2023

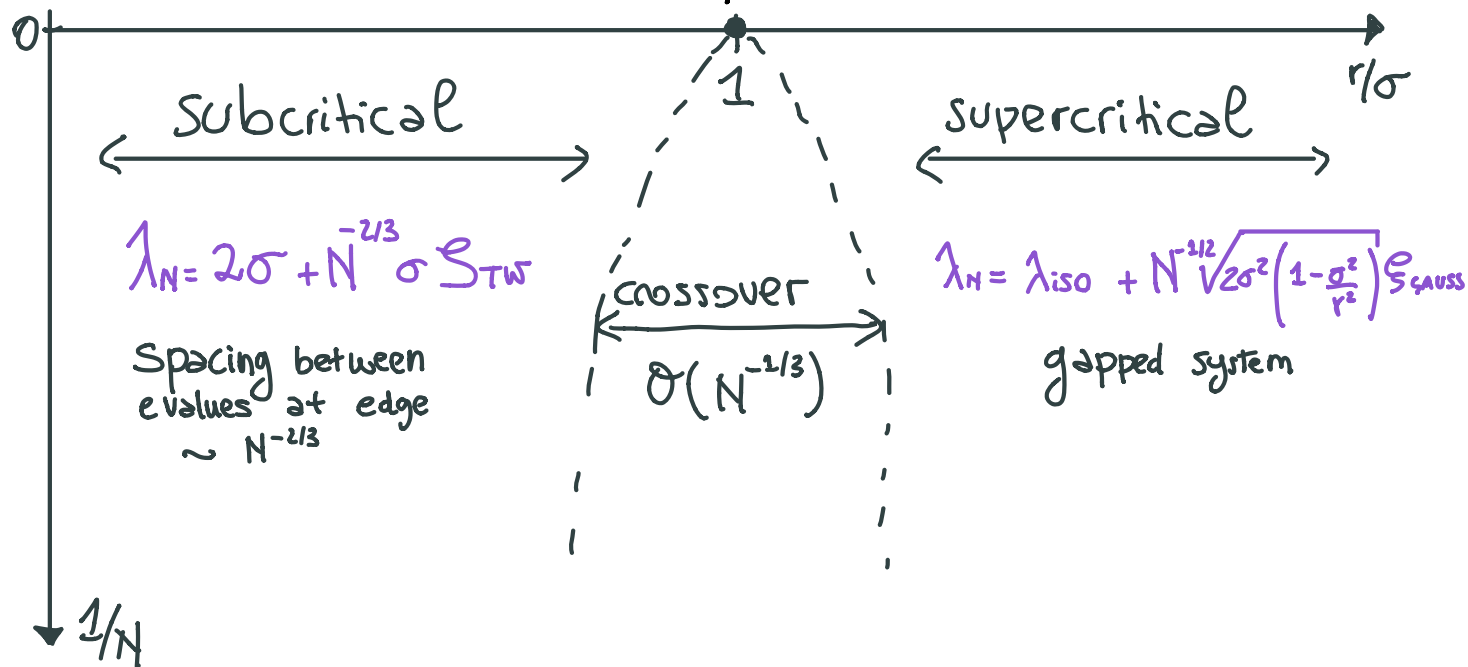
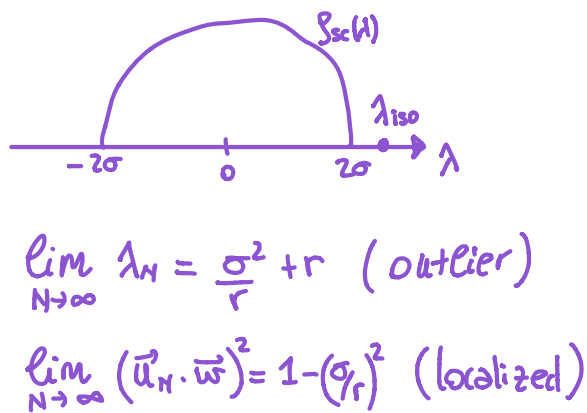
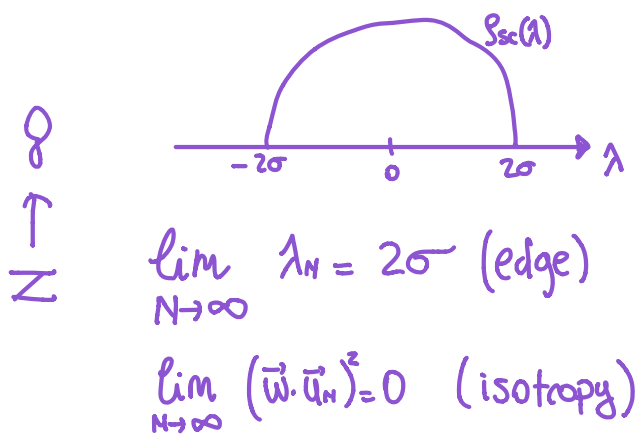
■ The Tracy-Widom distribution appears in a huge variety of contexts: universality.

"KPZ (Karlar, Parisi, Zhang) universality class"

At r_c , also a transition on the scaling of the fluctuations of largest evalue, not just on its typical value \Rightarrow "BBP transition".

BAIK, BEN AROUS, PÉCHÉ 2005

In summary:



► Finite N fluctuations: large deviations

Joint eigenvalue-eigenvector projection distribution

$$\mathcal{P}_N(\{\lambda_\alpha, \xi_\alpha\}) = \frac{e^{-N \sum_\alpha f(\lambda_\alpha, \xi_\alpha)}}{Z_N} \prod_{\alpha=1}^N \theta(\lambda_{\alpha+1} - \lambda_\alpha) \underbrace{\prod_{\alpha < \beta} |\lambda_\beta - \lambda_\alpha|}_\text{Vandermonde} \times \delta\left(\sum_{\alpha=1}^N \xi_\alpha - 1\right) \frac{1}{\sqrt{\xi_\alpha}}$$

where $f(\lambda_\alpha, \xi_\alpha) = \frac{1}{4\sigma^2} (\lambda_\alpha^2 - 2r\lambda_\alpha\xi_\alpha)$

$$\xi_\alpha = \left(\vec{u}_\alpha \cdot \frac{\vec{v}}{\sqrt{N}} \right)^2 = (\vec{u}_\alpha \cdot \vec{w})^2$$

● $r=0$ [spectrum $\hat{\mathcal{J}}$]: decoupling of eigenvalues & eigenvectors proj.

The eigenvalues alone distributed as:

$$\mathcal{P}_N(\{\mu_1 \leq \dots \leq \mu_N\}) = \frac{N!}{Z_N(\sigma)} \prod_{i=1}^N \left(e^{-\frac{N\mu_i^2}{4\sigma^2}} \theta(\mu_{i+1} - \mu_i) \right) \prod_{i < j} |\mu_i - \mu_j|$$

$$Z_N(\sigma) = \sigma^{\frac{N(N+1)}{2}} e^{\frac{3}{2} N \log 2} \left(\frac{2}{N} \right)^{\frac{N(N+1)}{4}} \prod_{i=1}^N \Gamma\left(1 + \frac{i}{2}\right)$$

The eigenvectors have statistics of random unit vectors: setting $q_\alpha = \sqrt{\xi_\alpha}$, then:

$$P_N(\{q_\alpha\}_{\alpha=1}^N) = C_N \delta\left(\sum_{\alpha=1}^N q_\alpha^2 - 1\right) \quad \left| \begin{array}{l} \text{rotational invariance:} \\ \text{eigenvectors of } \hat{J} \text{ and } \hat{J}_R \\ \text{are equally probable} \end{array} \right.$$

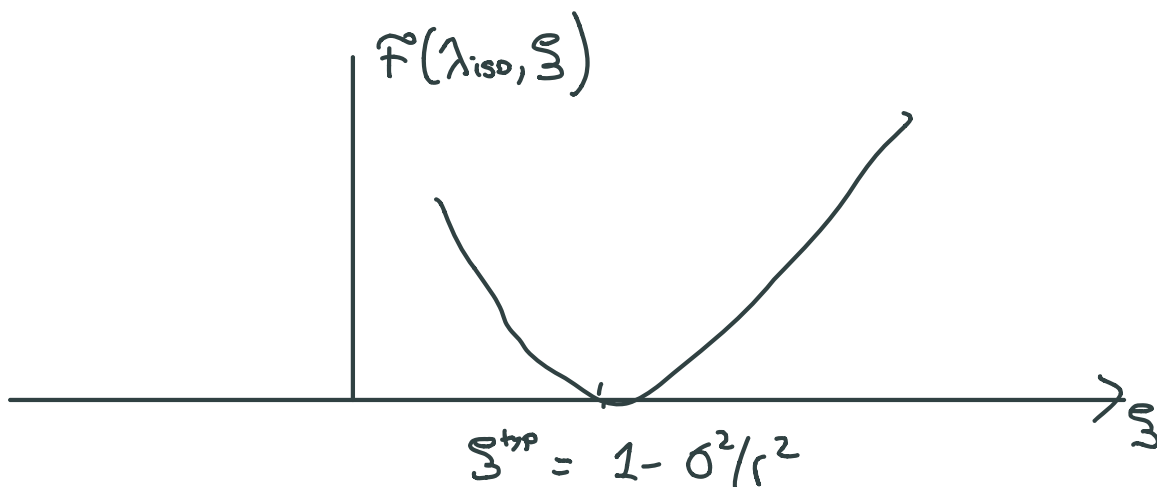
- For $r > 0$: coupling of values & vector projection!

This coupling can "pull" some eigenvector (the extremal) towards \vec{w} when $r > r_c$.

- From $P_N(\{\lambda_n, \xi_n\})$, can get the joint large deviation probability of λ_N, ξ_N - maximal eigenvalue/vector

$$P_{LD}(\lambda_N, \xi_N) \sim e^{-NF(\lambda_N, \xi_N)} \quad \text{BIROLI, GUIONNET 2019}$$

↖ probability of $\mathcal{O}(1)$ deviations
from typical, asymptotic $N \rightarrow \infty$ value.



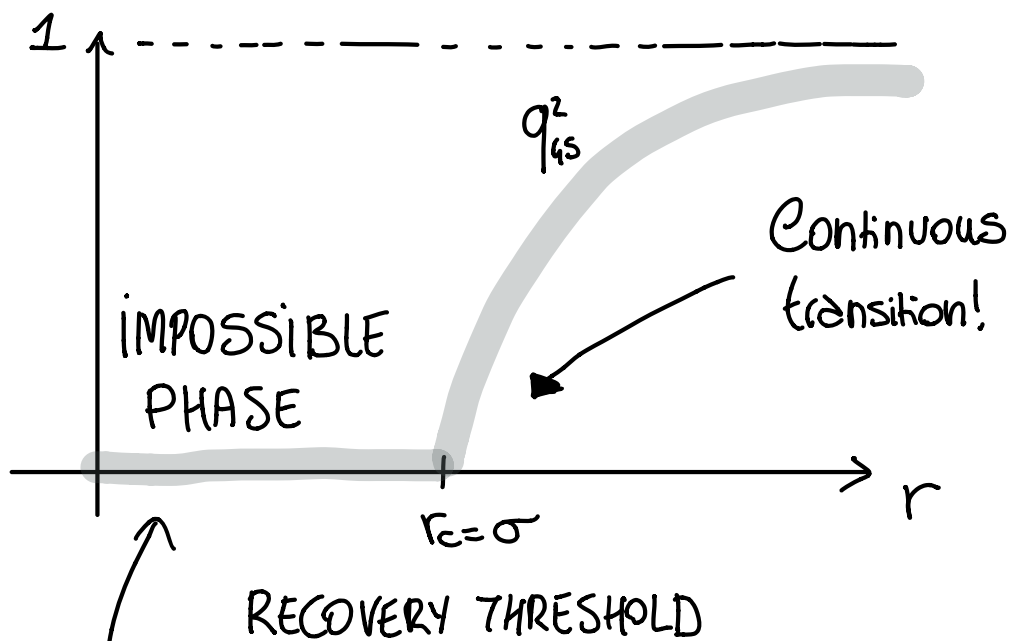
I.3] WHAT: GS, LANDSCAPE, DYNAMICS

Back to the inference problem...

Q1: Recovering the signal

Q1: when is \vec{S}_{4S} informative, i.e. $q_{4S} > 0$?

A sharp transition when $N \rightarrow \infty$: informative for $r > r_c$



here, even if I am able to find \vec{S}_{4S} , I would get no info on \vec{v} because \vec{S}_{4S} is uncorrelated to it.

Comments:

- ① The transition in the ground state could be found also from thermodynamics, studying the $\beta \rightarrow \infty$ limit of:

$$\mathbb{Z}_\beta = \int_{\mathcal{S}_N(\sqrt{N})} d\vec{s} e^{-\beta \mathcal{E}[\vec{s}]} = \int d\vec{s} d\lambda e^{-\beta \mathcal{E}[\vec{s}] - \beta \frac{\lambda}{2} \left(\sum_{i=1}^N s_i^2 - N \right)}$$

Thermodynamically, the zero-temperature transition at $r=r_c=\sigma$ is a transition between a spin-glass phase at $r < r_c$, and a ferromagnetic phase at $r > r_c$.

At $T > 0$: phenomenology of condensation \Rightarrow EXERCISE 3!

KOSTERLITZ, THOULESS, JONES 1976

CUGLIANDOLO LECTURE NOTES CARGESE 2020

- ① Critical threshold for maximum likelihood is also "detection threshold" when \vec{v} has gaussian or rademacher prior: below r_c , no estimator distinguishes between pure noise ($\mathcal{U}(0,1)$) and spiked matrices.

PERRY, WEIN, BANDEIRA, MOITRA 2018

Q2: A landscape of saddles

Stationary points above ground state.

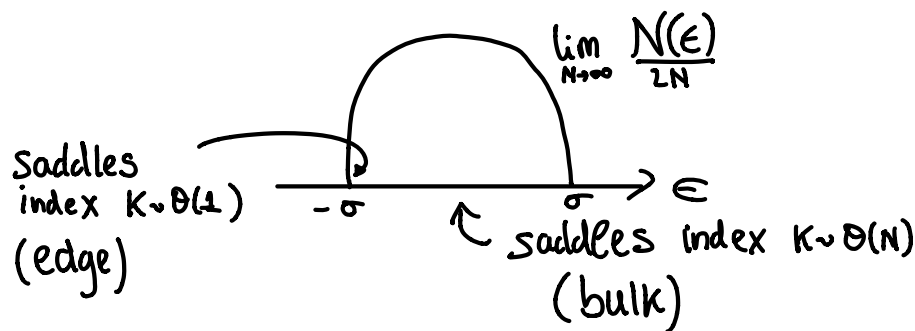
$N_N(\epsilon) = \#$ stationary points with $E_N[s^*] = \epsilon$

is a self-averaging random variable such that:

$$\lim_{N \rightarrow \infty} \frac{N_N(\epsilon)}{2N} = \lim_{N \rightarrow \infty} \left\langle \frac{N_N(\epsilon)}{2N} \right\rangle = \rho_{sc}(2\epsilon)$$

↑
GOE density

All stationary points (except GS) are saddles with negative directions of curvature: most have index $k \sim \Theta(N)$: NO trapping local minima!



All these saddles have $q_N[s_a] = \left(\frac{s_a \cdot W}{\sqrt{N}} \right) \xrightarrow{N \rightarrow \infty} 0$. Can study scaled overlap $\Phi = N \cdot \mathbb{E} \left[\left(\frac{s_a \cdot V}{N} \right)^2 \right]$ BUN, BOUCHAUD, POTTERS 2018

Expect optimization not to be "hard" ($2^N \neq e^N$)

Q3: Dynamics: DMFT, & beyond

Consider simplest algorithm: gradient descent.
(Langevin with $T \rightarrow 0$)

$$\frac{dS_i(t)}{dt} = - \sum_j J_{ij} S_j(t) - \lambda(t) S_i(t) + \sqrt{2T} \eta_i(t)$$

need to enforce to stay on sphere at each time

Gaussian white noise



$\langle \eta_i(t) \eta_j(t') \rangle = \delta_{ij} \delta(t-t')$
Mimics coupling to degrees of freedom equilibrated at T

When $T \rightarrow 0$ (no noise), expect convergence to $T=0$ equilibrium state, the ground state $\vec{S}_{GS} = \pm \sqrt{N} \vec{u}_N$, when $t \rightarrow \infty$; how to take $N \rightarrow \infty$? Relevant timescales?

Large-time and large- N limit: how?

(1) Mean-field dynamics: take $N \rightarrow \infty$ before, then $t \rightarrow \infty$.

Fully-connected models with randomness can be described by DMFT ('Dynamical Mean Field Theory')

Why?

- Dynamics becomes self-averaging when $N \rightarrow \infty$: properties of trajectories for different realizations of $\mathcal{E}[\mathcal{S}]$ become deterministic, converge to average value [can replace average over \mathcal{E} with $N \rightarrow \infty$]

eg. energy density: $\lim_{N \rightarrow \infty} \frac{\mathcal{E}[\mathcal{S}(t)]}{N} = \lim_{N \rightarrow \infty} \left\langle \frac{\mathcal{E}[\mathcal{S}(t)]}{N} \right\rangle$

- These properties are one and two-point functions in time, for which have closed eqs, "DMFT equations"

$\mathcal{E}(t)$ ← time-dependent energy

$$C(t, t') = \frac{1}{N} \sum_{i=1}^N S_i(t) S_i(t') \quad \leftarrow \text{correlation function}$$

$$R(t, t') = \frac{1}{N} \sum_{i=1}^N \left. \frac{\delta S_i(t)}{\delta \mathcal{E}_i(t')} \right|_{z=0} \quad \leftarrow \text{response function}$$

⇒ Used in many contexts: **UGLIANDOLO 2023**
(Annual review of condensed matter physics)

(2) Beyond mean-field: dynamics for N large but finite.

DIFFICULT PROBLEM!

Often, fluctuations matter, no self-averagingness
Quantities are distributed.

Averages & typical values are different.

⇒ This model (for $r=0$) is a rare case
in which dynamics can be studied in both
regimes, using Random Matrix Theory.

● $T=0$. In the eigenbasis $S_\alpha = (\vec{S} \cdot \vec{u}_\alpha)$

$$\frac{dS_\alpha(t)}{dt} = -[\lambda_\alpha + \lambda(t)] S_\alpha(t)$$

↘ couples all different α .
makes the equations non-linear.

● $T=0$, dynamics should converge to $\vec{S}_{qs} = \pm \sqrt{N} \vec{u}_N$.

Study convergence by excess energy:

$$\Delta E_N(t) = \left(\frac{\sum E(t)}{N} - E_{qs} \right) = \frac{1}{2} \frac{\sum_{\alpha \neq N} (\lambda_N - \lambda_\alpha) e^{-2(\lambda_N - \lambda_\alpha)t}}{1 + \sum_{\alpha \neq N} e^{-2(\lambda_N - \lambda_\alpha)t}} = \int (\sum \lambda_N - \lambda_\alpha)$$

for random initial conditions $S_\alpha(t=0) = 1 \quad \forall \alpha$.

Short times, large times, dynamical crossovers

$$\Delta E_N(t) \stackrel{t \gg 1}{\approx} g_N e^{-2t g_N} \quad g_N = \lambda_N - \lambda_{N-1} \text{ 'gap'}$$

Natural time where "probe" finite-N, energy scales where discreteness of spectrum matters:

$$\tau_{\text{dync}} \sim 1/g_N$$

Such that: $\left\{ \begin{array}{l} t \ll \tau_{\text{dync}} : \text{dynamics looks as if } N \rightarrow \infty \text{ (DMFT-like)} \\ t \gg \tau_{\text{dync}} : \text{finite-N dynamics} \end{array} \right.$

The fluctuations of the gap g_N are of the same order as those of maximal eigenvalue. Recall RMT detour:

$1/g_N \sim \left\{ \begin{array}{l} \mathcal{O}(N^{2/3}) \quad \text{subcritical regime } r \lesssim r_c \\ \text{?} \quad \text{critical regime } |r-r_c| \sim \mathcal{O}(N^{-1/3}) \\ \mathcal{O}(N^0) \quad \text{supercritical regime: } r \gtrsim r_c \\ \text{system is GAPPED!} \end{array} \right.$

$\mathcal{O}(N^0)$ is more precisely $\sim \log N$ D'ASCOLI, REFINETTI, BIROLI 2022

■ The mean-field dynamics: $N \rightarrow \infty$

One finds in this time regime:

$$\lim_{N \rightarrow \infty} \langle \Delta E_N(t) \rangle = U_{MF}(t) \stackrel{t \gg 1}{\approx} \begin{cases} \frac{3\sigma}{8t} & r \leq r_c \\ \frac{3\sigma}{8t} + [-\sigma - \epsilon_{gs}] & r \geq r_c \end{cases}$$

Slow, algebraic decay to the energy density of the ground state ($\epsilon_{gs} = -\sigma$) when $r \leq r_c$, and to the same energy (which is no longer the ground state) when $r > r_c$.

(1) Dynamics is always out-of-equilibrium in this regime. It is, in fact, glassy:

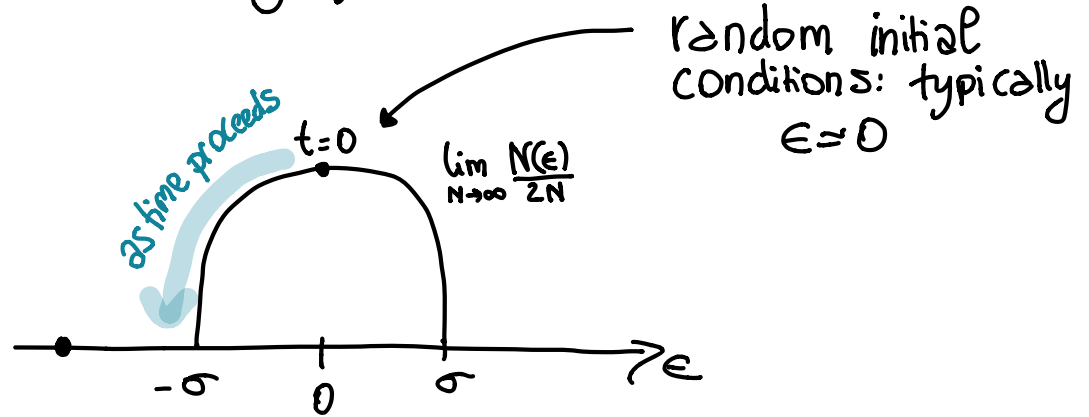
- $C(t, t') \neq c(t-t')$, modified FDT
- separation of timescales in $t-t'$
- aging & weak ergodicity breaking

"Aging": dynamics slower and slower as system becomes older (i.e., as time proceeds)

CUGLIANDOLO & DEAN 1995

BEN AROUS, DEMBO, GUILONNET 2001 (math)

(2) Landscape interpretation: in these timescales, Probe landscape at extensive energies above ϵ_{cs} , $\Delta\epsilon_N(t) \sim \mathcal{O}(1)$. Region of landscape dominated by saddles, with density described by $f_{sc}(-2\epsilon)$:



Why slowing down? no trapping by local minima (there are not!), but slow decay due to decreasing number of negative directions of saddles (decreasing index).

DMFT, $N \rightarrow \infty$ dynamics probes the bulk on $f_{sc}(2\epsilon)$.

▣ The finite- N dynamics, $N \gg 1$

► The subcritical regime ($r \leq r_c$): dynamics as for $r=0$. Crossover time $\tau_{dync} \sim N^{2/3}$.

$$\langle \Delta\epsilon_N(t) \rangle \sim \begin{cases} \mathcal{U}_{MF}(t) & t \ll N^{2/3} = \tau_{dync} \\ N^{-2/3} \mathcal{U}_{NMF}(t N^{-2/3}) & t \gg N^{2/3} = \tau_{dync} \end{cases}$$

For $t \ll N^{2/3}$, the system explores extensive energies above E_{qs} .

Dynamics is self-averaging, captured by mean-field (DMFT)

For $t \gg N^{2/3}$, system explore intensive energies above E_{qs} .

Dynamics not self-averaging, not captured by mean-field.

Consider $t \gg N^{2/3}$

► System explores intensive energies on top of E_{qs} :
Sensitive to statistics of extreme values and gaps g_N .

► Dynamics not self-averaging: $\langle \Delta_{en}(t) \rangle$ dominated by realization where gap atypically small.

► The distribution of g_N is known! PERRET, SCHEHR 2015

$$\begin{cases} P(N^{2/3} g_N) \sim b N^{2/3} g_N & N^{2/3} g_N \rightarrow 0 \quad (\text{small gaps}) \\ P(N^{2/3} g_N) \sim e^{-2/3 (N^{2/3} g_N)^{3/2}} & N^{2/3} g_N \rightarrow \infty \quad (\text{large gaps}) \end{cases}$$

$$\Rightarrow \langle \Delta_{en}(t) \rangle \sim N^{-2/3} f_0(t N^{-2/3})$$

$$f_0(x) \sim \begin{cases} \frac{3\sigma}{8x} & x \rightarrow 0 \\ \frac{a\sigma}{x^3} & x \rightarrow \infty \end{cases}$$

scaling function known!

FYODOROV, PERRET, SCHEHR 2015

BARBIER, PIMENTA, CUGLIANDOLO, STAROIOLO 2021

► The supercritical regime: in this case system is gapped: for $t \gg \tau_{\text{dync}} \sim \log N$, the system is able to reach the vicinity of S_{qs} and to relax to it exponentially (as in ferromagnetic systems):

$$\langle \Delta E_N(t) \rangle \sim \begin{cases} U_{\text{MF}}(t) & t \ll \log N = \tau_{\text{dync}} \\ \frac{C_r}{t^{3/2}} e^{-2t|\frac{\sigma^2}{r} + r - 2\sigma|} & t \gg \log N = \tau_{\text{dync}} \end{cases}$$

↑
gap

► The critical regime ($r - r_c \sim \mathcal{O}(N^{-2/3})$): open problem!

$$\langle \Delta E_N(t) \rangle \stackrel{t \gg 1}{\sim} \int_0^\infty dg_N p(g_N) g_N e^{-2g_N t}$$

λ_n and λ_{n+1} strongly correlated, distribution $p(g_n)$ unknown.

From numerics, $p(g_N) \stackrel{g \ll 1}{\sim} g^{a(r,N)}$ PIMENTA, STARIOLO 2023

giving:

$$\langle \Delta E_N(t) \rangle \stackrel{t \gg 1}{\sim} \begin{cases} U_{\text{MF}}(t) \sim e^{-2t|\lambda_{\text{iso}} - 2\sigma|} & t \ll N^{2/3} \\ N^{2/3} f_a(t N^{-2/3}) & t \gg N^{2/3} \end{cases}$$

PART II

Rugged high-D Landscapes

II.1 WHY: A HIGH-D INFERENCE EXAMPLE

▣ A 'hard' inference problem: noisy tensors

Beyond matrices? Tensors! MONTANARI, RICHARD 2014

$$M_{i_1 i_2 \dots i_p} = \frac{r}{N^{p-1}} U_{i_1} \dots U_{i_p} + J_{i_1 \dots i_p} \quad (p > 2)$$

$J_{i_1 \dots i_p}$ symmetric, iid gaussian $\langle J_{i_1 \dots i_p}^2 \rangle = \frac{p! \tilde{\sigma}^2}{N^{p-1}}$

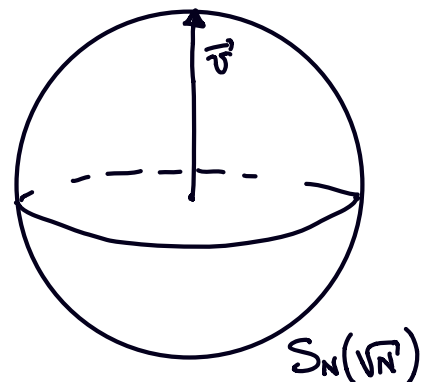
Energy landscape:

$$\mathcal{E}[\vec{S}] = - \sum_{i_1 \leq i_2 \dots \leq i_p} J_{i_1 \dots i_p} S_{i_1} \dots S_{i_p} - r N \left(\frac{\vec{U} \cdot \vec{S}}{N} \right)^p$$

Again, fully-connected random interactions.

$$\langle \mathcal{E}[\vec{S}] \rangle = -r N \left(\frac{\vec{S} \cdot \vec{U}}{N} \right)^p$$

$$\langle \mathcal{E}[\vec{S}] \mathcal{E}[\vec{S}'] \rangle_c = \tilde{\sigma}^2 N \left(\frac{\vec{S} \cdot \vec{S}'}{N} \right)^p$$



Here: no spectrum. Also, landscape at $r=0$ much different...

Landscape problem & complexity

Same questions as above, same approach: study stationary points.

$$E_\lambda[\vec{s}] = - \sum_{i_2 \leq i_3 \dots \leq i_p} M_{i_2 \dots i_p} S_{i_2} \dots S_{i_p} + \frac{\lambda}{2} \left(\sum_{i=1}^N S_i^2 - N \right)$$

$$\begin{cases} \frac{\partial E_\lambda[\vec{s}^*]}{\partial S_i} = - \sum_{i_2 \leq \dots \leq i_p} M_{i i_2 \dots i_p} S_{i_2}^* \dots S_{i_p}^* + \lambda^* S_i^* \\ \frac{\partial E_\lambda[\vec{s}^*]}{\partial \lambda} = \sum_{i=1}^N (S_i^*)^2 - N = 0 \end{cases}$$

As before, multiply first equation by S_i , sum & use second equation:

$$\lambda^* = - \frac{1}{N} \left(\sum_i \frac{\partial E[\vec{s}^*]}{\partial S_i} \cdot S_i \right) = -p \frac{E[\vec{s}^*]}{N} = -p E[\vec{s}^*]$$

However, first equation non-linear: how many solutions?
Introduce the random variable

$$N_n(\epsilon, q) = \# \text{ stationary points } \vec{s}^* \text{ with } E_n[\vec{s}^*] = \epsilon \text{ and } q_n[\vec{s}^*] = \frac{\vec{s} \cdot \vec{v}}{N} = q.$$

▣ Quadratic landscape ($p=2$):

$N_N(\epsilon)$ is $\mathcal{O}(N)$ when $N \gg 1$

Self-averaging: $\lim_{N \rightarrow \infty} \frac{N_N(\epsilon)}{2N} = \lim_{N \rightarrow \infty} \frac{1}{2N} \langle N_N(\epsilon) \rangle = f_{sc}(-2\epsilon)$

▣ Landscape for $p > 2$:

$N_N(\epsilon, q)$ is $\mathcal{O}(e^N)$: $N_N(\epsilon, q) \sim e^{N \Sigma_N(\epsilon, q)}$

$N_N(\epsilon, q)$ not self-averaging

but $\Sigma_N(\epsilon, q)$ is:

$$\lim_{N \rightarrow \infty} \Sigma_N(\epsilon, q) = \lim_{N \rightarrow \infty} \langle \Sigma_N(\epsilon, q) \rangle = \Sigma_\infty(\epsilon, q)$$

$$\Rightarrow \Sigma_\infty(\epsilon, q) = \lim_{N \rightarrow \infty} \frac{1}{N} \langle \log N_N(\epsilon, q) \rangle \quad \text{"COMPLEXITY"}$$

▣ Averages vs typical values, and replicas

Means that typically when $N \rightarrow \infty$ (with probability $\rightarrow 1$):

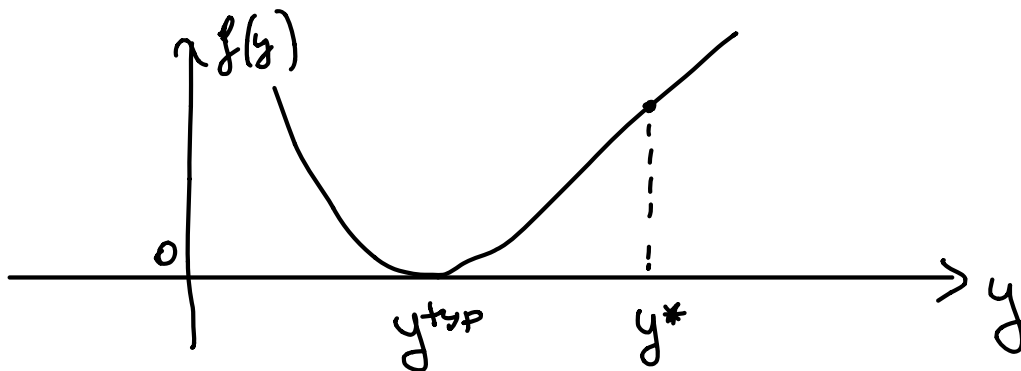
$[N(\epsilon, q)]_{\text{typ}} \sim e^{N \Sigma_\infty(\epsilon, q)}$ (most probable value of N)

But most-probable value is different from the average value: $\langle N(\epsilon, q) \rangle \neq e^{N \Sigma_\infty(\epsilon, q)}$

Average vs typical values: example.

Assume X_N is a random variable scaling as $X_N \sim e^N$: means that $Y_N = \frac{\log X_N}{N}$ has a limiting distribution when $N \rightarrow \infty$.

Assume that when $N \gg 1$, distribution of Y_N takes large-deviation form: $P_{Y_N}(y) \sim e^{-Nf(y) + o(N)}$.



Then, typical value of X_N is:

$$[X_N]^{typ} \sim e^{N y^{typ}} \quad \text{where } y^{typ} \text{ such that } f'(y^{typ}) = 0 = f(y^{typ}).$$

On the other hand:

$$\langle X_N \rangle \approx \int dy P_{Y_N}(y) e^{Ny} = \int dy e^{N[y - f(y)] + o(N)} \underset{\substack{\uparrow \\ \text{saddle point approximation}}}{\approx} e^{N[y^* - f(y^*)]}$$

and y^* such that $f'(y^*) = 1$.

Since $y^* \neq y^{typ}$, $f(y^*) > 0$: y^* is exponentially rare, but controls the average: average "dominated" by rare realizations of random variable!

Message: to characterize what happens typically (with large probability) when $N \gg 1$ need:

"QUENCHED CALCULATION," $\Sigma_{\infty}(\epsilon, q) = \lim_{N \rightarrow \infty} \frac{1}{N} \langle \log N_n(\epsilon, q) \rangle$

But this is hard; requires tricks like REPLICAS:

$$\langle \log N \rangle = \lim_{\omega \rightarrow 0} \frac{\langle N^{\omega} \rangle - 1}{\omega}$$

ω-th moment of N

analytic continuation

In the following, we perform instead:

"ANNEALED APPROXIMATION," $\Sigma_A(\epsilon, q) = \lim_{N \rightarrow \infty} \frac{1}{N} \log \langle N(\epsilon, q) \rangle$

It holds $\Sigma_A(\epsilon, q) \geq \Sigma_{\infty}(\epsilon, q) \Rightarrow \langle N_n \rangle \gg [N_n]_{typ}$

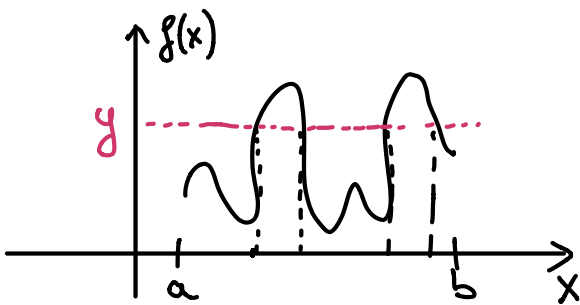
For the quenched calculation of the complexity in this model: ROS, BEN AROUS, BIROLI, CAMMAROTA 2018

II.2. HOW: KAC-RICE FORMALISM

Kac-Rice formula(s)

Kac-Rice formula = formula for average (or higher moments) of number of solutions of random equations.

Counting formulas: example.



$f(x)$ random function in $[a, b]$.
How many solutions of $f(x) = y$?

$$\begin{aligned} N(y) &= \int_a^b dx \delta(x - f^{-1}(y)) = \int_a^b dx \frac{1}{\left| \frac{d}{dy} f^{-1}(y) \right|} \delta(y - f(x)) \\ &= \int_a^b dx |f'(x)| \delta(y - f(x)) \quad |f'(x)| = \text{Jacobian} \end{aligned}$$

In higher dimension: $\vec{x} \in \mathcal{I} \subset \mathbb{R}^d$, $f(\vec{x}) = \vec{y} \in \mathbb{R}^d$

$$N(\vec{y}) = \int_{\mathcal{I}} d\vec{x} \prod_{i=1}^d \delta(f_i(\vec{x}) - y_i) \left| \det \left(\frac{\partial f_i(\vec{x})}{\partial x_j} \right)_{ij} \right|$$

► Kac-Rice formula: stationary points of landscapes

Count solutions of $\nabla_{\perp} \mathcal{E}[\vec{s}] = 0$, $\mathcal{E}[\vec{s}] = N\epsilon$, $\vec{s} \cdot \vec{v} = Nq$

Then:

$$N(\epsilon, q) = \int_{S_N(\sqrt{N})} d\vec{s} |\det \nabla_{\perp}^2 \mathcal{E}[\vec{s}]| \delta(\nabla_{\perp} \mathcal{E}[\vec{s}]) \delta(\mathcal{E}[\vec{s}] - N\epsilon) \delta(\vec{s} \cdot \vec{v} - Nq)$$

Take average \Rightarrow Kac-Rice formula.

$$\langle N(\epsilon, q) \rangle = \int_{S_N(\sqrt{N})} d\vec{s} \delta(\vec{s} \cdot \vec{v} - Nq) \left\langle |\det \nabla_{\perp}^2 \mathcal{E}[\vec{s}]| \right\rangle_{\substack{\nabla_{\perp} \mathcal{E} = 0 \\ \mathcal{E} = N\epsilon}} P_{\nabla_{\perp} \mathcal{E}, \mathcal{E}}(\vec{0}, N\epsilon)$$

average conditioned

to $\nabla_{\perp} \mathcal{E}[\vec{s}] = 0$ and
 $\mathcal{E}[\vec{s}] = N\epsilon$

joint density of
 $(\nabla_{\perp} \mathcal{E}, \mathcal{E})$ evaluated
at $(\vec{0}, N\epsilon)$

BRAY, MOORE 1980

CAVAGNA, GIARDINA, PARISI 1998

FYODOROV 2013

BEN AROUS, AUFFINGER, CERNY 2010 (math)

Computing the complexity: 3 steps

The calculation is done in 3 steps, & uses 3 main ingredients:

(1) GAUSSIANTY

The functions $E[\vec{s}]$, $\frac{\partial E[\vec{s}]}{\partial s_i}$, $\frac{\partial^2 E[\vec{s}]}{\partial s_i \partial s_j}$ are Gaussian: to get

distribution, need only averages & covariances.

Can be computed explicitly (TRY! see below for hints)

Doing so, one finds:

(F1) $\bar{\nabla}_i E[\vec{s}]$ independent of $E[\vec{s}]$ and $\nabla_i^2 E[\vec{s}]$.

Consequences:

$$\blacktriangleright P_{\nabla_i E[\vec{s}], E[\vec{s}]}(\vec{0}, N\epsilon) = P_{\nabla_i E[\vec{s}]}(\vec{0}) P_{E[\vec{s}]}(N\epsilon)$$

factorization: two Gaussians, known explicitly.

$$\blacktriangleright \left\langle |\det \nabla_i^2 E[\vec{s}]| \right\rangle_{\substack{\nabla_i E[\vec{s}]=0 \\ E=N\epsilon}} = \left\langle |\det \nabla_i^2 E[\vec{s}]| \right\rangle_{E=N\epsilon}$$

Statistics of Hessian at stationary point is same as at any point of same energy.

(F2) The $(N-1) \times (N-1)$ matrix $\nabla_1^2 \mathcal{E}$ conditioned to $\mathcal{E} = N\epsilon$ has the same statistics as matrices:

$$\hat{M}[\vec{s}] = \hat{\mathcal{J}} - p\epsilon \hat{\mathbb{1}} - \text{Veff}[q_N[\vec{s}]] \vec{w}_\perp \vec{w}_\perp^T$$

spherical constraint
rank-1 perturbation

Vector \vec{w} is projection of \vec{v} on tangent plane $\mathcal{Z}[\vec{s}]$

where $\hat{\mathcal{J}}$ is a GOE: $\langle \mathcal{J}_{ij} \rangle = 0$, $\langle \mathcal{J}_{ij}^2 \rangle = \frac{p(p-1)}{N} \bar{\sigma}^2 (1 + \delta_{ij})$

$$\text{Veff}(q) = r p(p-1) q^{p-2} (1-q^2), \quad \|\vec{w}_\perp\|^2 = 1.$$

(2) ISOTROPY

There is only one special direction in the sphere, that is \vec{v} . All averages & covariances, and so the joint distribution of $\mathcal{E}[\vec{s}]$, $\nabla_1 \mathcal{E}[\vec{s}]$, $\nabla_1^2 \mathcal{E}[\vec{s}]$ depend on \vec{s} only via $q_N[\vec{s}] = \left(\frac{\vec{s} \cdot \vec{v}}{N} \right) \rightarrow$ (see above!)

Consequences: for all \vec{s} such that $q_N[\vec{s}] = q$

$$P_{\nabla_1 \mathcal{E}[\vec{s}]}(\vec{0}) \rightarrow P_1(q) = (2\pi p \bar{\sigma}^2)^{-\frac{N-1}{2}} e^{-\frac{N}{2\bar{\sigma}^2} p r^2 q^{2p-2} (1-q^2)}$$

$$P_{\mathcal{E}}(N\epsilon) \rightarrow P_2(\epsilon, q) = \sqrt{\frac{N}{2\pi \bar{\sigma}^2}} e^{-\frac{N}{2\bar{\sigma}^2} (\epsilon + r q^p)^2}$$

$$\text{And } \left\langle \left| \det \nabla_{\vec{s}}^2 \mathcal{E}[\vec{s}] \right| \right\rangle_{\mathcal{E}[\vec{s}] = N\epsilon} := \mathcal{D}_N(\epsilon, q)$$

Therefore:

$$\begin{aligned} \langle N(\epsilon, q) \rangle &= \int_{S_N(\sqrt{N})} d\vec{s} \delta(\vec{s} \cdot \vec{v} - Nq) \left\langle \left| \det \nabla_{\vec{s}}^2 \mathcal{E}[\vec{s}] \right| \right\rangle_{\mathcal{E} = N\epsilon} P_{\nabla_{\vec{s}} \mathcal{E}}(\vec{0}) P_{\mathcal{E}}(N\epsilon) \\ &= \mathcal{D}_N(\epsilon, q) p_2(q) p_2(\epsilon, q) V_N(q) \end{aligned}$$

$$\text{where } V_N(q) = \int_{S_N(\sqrt{N})} d\vec{s} \delta(Nq - \vec{s} \cdot \vec{v}) \quad \text{Volume of the sub-sphere}$$

$$\text{Can show that } V_N(q) \stackrel{N \gg 1}{\sim} e^{N/2 \log[2\pi e(1-q^2)] + o(N)}$$

Example: 2d rotationally-invariant function

$$\begin{aligned} I &= \int_{\mathbb{R}^2} ds_1 ds_2 f(\sqrt{s_1^2 + s_2^2}) \delta(\sqrt{s_1^2 + s_2^2} - q) = \int_0^{2\pi} d\theta \int_0^{\infty} dr r f(r) \delta(r - q) \\ &= (2\pi q) f(q) = V(q) \cdot f(q) \end{aligned}$$

(3) LARGE-N AND RANDOM MATRIX THEORY

$$D_N(\epsilon, q) = \left\langle \left| \det \left(\hat{J} - p\epsilon \hat{1} - r_{\text{eff}}(q) \vec{w}_1 \vec{w}_1^T \right) \right| \right\rangle$$

Call $\lambda_2 \leq \dots \leq \lambda_N = \{\lambda_\alpha\}_{\alpha=1}^{M=N-1}$ eigenvalues of $\hat{J} - r_{\text{eff}}(q) \vec{w}_1 \vec{w}_1^T$

Then:

$$\begin{aligned} D_N(\epsilon, q) &= \left\langle \prod_{\alpha=1}^M |\lambda_\alpha - p\epsilon| \right\rangle = \left\langle e^{\sum_{\alpha=1}^M \log |\lambda_\alpha - p\epsilon|} \right\rangle \\ &= \left\langle e^{\int d\nu_M(\lambda) \log |\lambda - p\epsilon|} \right\rangle \end{aligned}$$

where $\nu_M(\lambda) = \frac{1}{M} \sum_{\alpha=1}^M \delta(\lambda - \lambda_\alpha) \quad M = N-1$

Recall facts in RMT (part I):

■ The leading order contribution when $N \gg 1$ is given by the continuous part of $\nu_N(\lambda)$, the density:

$$D_N \approx \left\langle e^{N \int d\lambda \rho_N(\lambda) \log |\lambda - p\epsilon| + o(N)} \right\rangle$$

The average $\langle \cdot \rangle$ becomes average over $\mathcal{P}_N(\{\xi, \rho\}) D\rho$

III The density $f_N(\lambda)$ is self-averaging, and $f_\infty(\lambda)$ does not depend on r and is the semicircular law $f_{sc}(\lambda)$ with $\sigma^2 \rightarrow \tilde{\sigma}^2 p(p-1)$.

$$D_N \stackrel{N \gg 1}{\simeq} e^{N \int d\lambda f_{sc}(\lambda) \log |\lambda - p\epsilon| + o(N)}$$

\Rightarrow This integral can be done explicitly:

$$\int d\lambda \frac{1}{2\pi p(p-1)\tilde{\sigma}^2} \sqrt{4p(p-1)\tilde{\sigma}^2 - \lambda^2} \log |\lambda - p\epsilon| =$$

$$= \int \frac{d\mu}{\pi} \sqrt{2 - \mu^2} \log \left| \sqrt{2p(p-1)\tilde{\sigma}^2} \mu - p\epsilon \right|$$

$$= \log \sqrt{2p(p-1)\tilde{\sigma}^2} + I \left(\frac{p\epsilon}{\sqrt{2p(p-1)\tilde{\sigma}^2}} \right)$$

$$I(y) = \int d\mu \frac{\sqrt{2 - \mu^2}}{\pi} \log |\mu - y|$$

$$= \begin{cases} \frac{y^2 - 1}{2} + \frac{y}{2} \sqrt{y^2 - 2} + \log \left(\frac{-y + \sqrt{y^2 - 2}}{2} \right) & y \leq -\sqrt{2} \\ \frac{y^2}{2} - \frac{1}{2} (1 + \log 2) & y > -\sqrt{2} \end{cases}$$

Computing distributions: example

Consider the unconstrained gradient: $\nabla \mathcal{E}[\vec{s}] = \left(\frac{\partial \mathcal{E}}{\partial s_i} \right)_{i=1}^N$

Then:

$$\left\langle \frac{\partial \mathcal{E}}{\partial s_i} [\vec{s}] \right\rangle = -r N p \left(\frac{v \cdot s}{N} \right)^{p-2} \frac{v_i}{N}$$

while:

$$\left\langle \frac{\partial \mathcal{E}}{\partial s_i} [\vec{s}] \frac{\partial \mathcal{E}}{\partial s'_j} [\vec{s}'] \right\rangle_c \stackrel{\text{c}}{=} \sum_{k_2=1}^p \sum_{k_1=1}^p \sum_{\substack{i_1 \leq \dots \leq i_p \\ j_1 \leq \dots \leq j_p}} \langle J_{i_1 i_2 \dots i_p} J_{j_1 j_2 \dots j_p} \rangle \delta_{i_{k_2} i} \delta_{j_{k_2} j} s_{i_1} \dots \cancel{s_{i_{k_1}}} \dots s_{i_p} \times \\ \times s'_{j_1} \dots \cancel{s'_{j_{k_2}}} \dots s'_{j_p}$$

Using that $\langle J_{i_1 \dots i_p} J_{j_1 \dots j_p} \rangle = \frac{p! \tilde{\sigma}^2}{N^{p-1}} \prod_{n=1}^p \delta_{i_n j_n}$,

$$\stackrel{\text{c}}{=} \sum_{k_1=1}^p \sum_{k_2=1}^p \frac{p! \tilde{\sigma}^2}{N^{p-1}} \frac{1}{p!} \sum_{i_1, \dots, i_p} \delta_{i_{k_2} i} \delta_{i_{k_2} j} s_{i_1} \dots \cancel{s_{i_{k_2}}} \dots s_{i_p} \times \\ \times s'_{i_1} \dots \cancel{s'_{i_{k_2}}} \dots s'_{i_p}$$

Distinguishing the case $k_1=k_2$ (p of them) and $k_1 \neq k_2$ ($p \cdot (p-1)$ of them) one gets:

$$\left\langle \frac{\partial \mathcal{E}}{\partial s_i} [\vec{s}] \frac{\partial \mathcal{E}}{\partial s'_j} [\vec{s}'] \right\rangle_c = \tilde{\sigma}^2 \left\{ p \delta_{ij} \left(\frac{s \cdot s'}{N} \right)^{p-1} + p(p-1) \frac{s_i s_j}{N} \left(\frac{s \cdot s'}{N} \right)^{p-2} \right\}$$

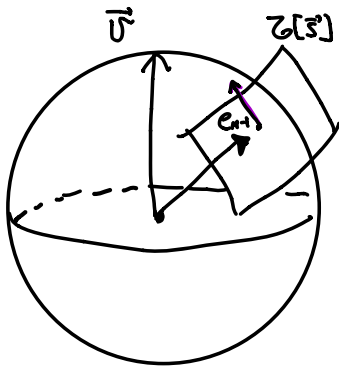
Now, $\nabla_{\perp} \mathcal{E}[\vec{s}]$ is the projections of $\nabla \mathcal{E}[\vec{s}]$ on the space orthogonal to \vec{s} , i.e. on the tangent plane $\mathcal{Z}[\vec{s}]$. Choosing $\vec{e}_\alpha[\vec{s}]$ a basis of $\mathcal{Z}[\vec{s}]$, one has $\vec{e}_\alpha \cdot \vec{s} = 0$. Thus:

$$\langle (\nabla_{\perp} \mathcal{E}[\vec{s}])_\alpha \rangle = \langle (\nabla \mathcal{E}[\vec{s}] \cdot \vec{e}_\alpha) \rangle = -r N p \left(\frac{v \cdot s}{N} \right)^{p-2} \left(\frac{v \cdot \vec{e}_\alpha}{N} \right)$$

And:

$$\begin{aligned} \langle (\nabla_{\perp} \mathcal{E}[\vec{s}])_{\alpha} (\nabla_{\perp} \mathcal{E}[\vec{s}])_{\beta} \rangle_c &= \langle (\nabla \mathcal{E}[\vec{s}] \cdot \vec{e}_{\alpha}[\vec{s}]) (\nabla \mathcal{E}[\vec{s}] \cdot \vec{e}_{\beta}[\vec{s}]) \rangle = \\ &= \bar{\sigma}^2 p \delta_{\alpha\beta} + p(p-1) \underbrace{\left(\frac{\vec{s} \cdot \vec{e}_{\alpha}}{\sqrt{N}} \right)}_{=0} \underbrace{\left(\frac{\vec{s} \cdot \vec{e}_{\beta}}{\sqrt{N}} \right)}_{=0} = p \bar{\sigma}^2 \delta_{\alpha\beta} \end{aligned}$$

In the annealed calculation, all distributions depend on \vec{s} only via $q[\vec{s}] = \frac{\vec{v} \cdot \vec{s}}{N}$: \vec{v} is the only 'special direction' on the sphere, that breaks isotropy. It is convenient to choose, for each \vec{s} , this basis on the tangent plane:



$$\vec{e}_{N+1}[\vec{s}] = \frac{1}{\sqrt{N(1-q^2)}} (\vec{v} - q[\vec{s}] \vec{s})$$

$$\vec{e}_{\alpha}[\vec{s}] \perp \{\vec{v}, \vec{s}\} \quad \alpha = 1, \dots, N-2$$

\Rightarrow only $(\nabla_{\perp} \mathcal{E})_{N+1}$ and $(\nabla_{\perp}^2 \mathcal{E})_{\alpha, N+1}$ or $(\nabla_{\perp}^2 \mathcal{E})_{N+1, \alpha}$ will have a q -dependent distribution

$$\langle \nabla \mathcal{E}[\vec{s}] \cdot \vec{e}_{\alpha} \rangle = r N p \left(\frac{q[\vec{s}]}{N} \right)^{p-1} \left(\frac{\vec{v}}{N} \cdot \vec{e}_{\alpha} \right) = \begin{cases} 0 & \alpha < N+1 \\ \neq 0 & \alpha = N+1 \end{cases}$$

$$\langle (\nabla_{\perp} \mathcal{E}[\vec{s}])_{\alpha} (\nabla_{\perp} \mathcal{E}[\vec{s}])_{\beta} \rangle_c = p \bar{\sigma}^2 \delta_{\alpha\beta}$$

The annealed complexity

Combine all terms:

$$\langle N(\epsilon, q) \rangle = V_N(q) D_N(\epsilon, q) P_1(q) P_2(N\epsilon) = e^{N \Sigma_A(\epsilon, q) + o(N)}$$

$$\Sigma_A(\epsilon, q) = \frac{1}{2} \log [2e(p-1)(1-q^2)] - \frac{p}{2\bar{\sigma}^2} r^2 q^{2p-2} (1-q^2) - \frac{1}{2\bar{\sigma}^2} (\epsilon + r q^p)^2 + \mathcal{I} \left(\sqrt{\frac{p}{2(p-1)\bar{\sigma}^2}} \epsilon \right)$$

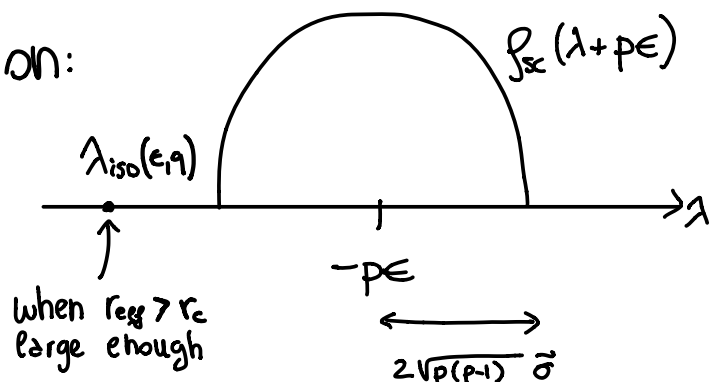
This gives distribution of stationary points in energy and geometry (overlap with $\bar{\sigma}$), on average.

What about stability?

The Hessian at a stationary point with (ϵ, q) is a rank-1 perturbed, shifted GOE:

$$\nabla_{\mathbf{1}}^2 \mathcal{E} \Big|_{\epsilon, q} \stackrel{\text{law}}{\sim} \hat{\mathcal{J}} - p\epsilon \hat{\mathbf{1}} - r_{\text{eff}}(q) \vec{w}_1 \vec{w}_1^T$$

The eigenvalue distribution:



Local minima have all eigenvalues positive. For bulk, need:

$$-p\epsilon > 2\sqrt{p(p-1)}\tilde{\sigma} \Rightarrow \epsilon < \epsilon_{th} = -2\tilde{\sigma}\sqrt{\frac{p-1}{p}}$$

ϵ_{th} = "threshold energy". Also, $\lambda_{iso}(\epsilon, q) > 0$.

The $p \rightarrow 2$ limit of $\Sigma_A(\epsilon, q)$

The annealed complexity is maximal at $q=0$.

We set $\Sigma_A(\epsilon) = \Sigma_A(\epsilon, q=0)$.

Recall that $\langle j_{i_1 \dots i_p}^2 \rangle = \frac{p! \tilde{\sigma}^2}{N}$ while in PART I

we set $\langle j_{ij}^2 \rangle = \frac{\sigma^2}{2}(1 + \delta_{ij})$. To be consistent, $\tilde{\sigma}^2 = \frac{\sigma^2}{2}$

$$\Sigma_A(\epsilon) \xrightarrow{p=2} \frac{1}{2} \log(2e) - \frac{\epsilon^2}{\sigma^2} + \mathbb{I}(\sqrt{2/\sigma^2} \epsilon)$$

Then, given that $\epsilon > -\sigma$:

$$\longrightarrow \frac{1}{2} \log(2e) - \frac{\epsilon^2}{\sigma^2} + \frac{\epsilon^2}{\sigma^2} - \frac{1}{2} - \frac{\log 2}{2} = 0$$

Consistently with the fact that for $p=2$ there are not exponentially-many stationary points.

One can use the Kac-Rice formula to get the results of PART I: exercise 4!

■ The quenched calculation: what would change?

One needs to compute higher moments $\langle N_N^w(\epsilon, q) \rangle$

with $w=2,3,4,\dots$ and $w \rightarrow 0!$

One can use Kac-Rice formulas, too, for higher moments: need to consider w points on sphere:

\vec{z}^a with $a=1,\dots,w$. The fields $\epsilon[\vec{z}^a], \nabla_1 \epsilon[\vec{z}^a], \nabla_1^2 \epsilon[\vec{z}^a]$ are correlated.

$$\langle N_N^w(\epsilon, q) \rangle = \int \prod_{a=1}^w d\vec{z}^a \delta(\vec{z}^a \cdot \vec{v} - Nq) \underbrace{P(\vec{0}, N\epsilon)}_{\substack{\nabla_1 \epsilon[\vec{z}^a], \epsilon[\vec{z}^a] \\ \uparrow \\ \text{joint distribution of } w \\ (N-1)\text{-dim vectors } \nabla_1 \epsilon[\vec{z}^a] \\ \text{and } w \text{ scalars } \epsilon[\vec{z}^a]}} \left\langle \prod_{a=1}^w |\det \nabla_1^2 \epsilon[\vec{z}^a]| \right\rangle_{\substack{\nabla_1 \epsilon[\vec{z}^a]=0 \\ \epsilon[\vec{z}^a]=N\epsilon \\ \uparrow \\ \text{joint expectation} \\ \text{value, conditioned} \\ \text{to } w \text{ vectors and} \\ \text{functions}}}$$

Some consequences of correlations:

(i) No decoupling: $\nabla_1 \epsilon[\vec{z}^a]$ for fixed a is independent of $\epsilon[\vec{z}^a], \nabla_1^2 \epsilon[\vec{z}^a]$, but not of $\epsilon[\vec{z}^b], \nabla_1^2 \epsilon[\vec{z}^b]$ at $b \neq a$.

Consequences: (1) need to compute joint distributions, (2) the expectation of Hessians is a problem of coupled random matrices.

What helps: still Gaussian for (1), and large- N for (2).

(ii) Distributions depend not only on $q_N[\vec{z}^a] = \left(\frac{\vec{z}^a \cdot \vec{v}^a}{N}\right)$,
but also on mutual overlaps $Q_N[\vec{z}^a, \vec{z}^b] = \left(\frac{\vec{z}^a \cdot \vec{z}^b}{N}\right)$:

Consequence: no longer 1 special direction, but w of them.

What helps: Still, huge dimensionality reduction!

From $N \cdot w$ variables S_i^a to $\frac{w(w-1)}{2} + w$ ones,
the $Q_N[\vec{z}^a, \vec{z}^b]$ and $q_N[\vec{z}^a]$. Because fully-connected.

(iii) The conditional distribution of the Hessian at one
point \vec{z}^a is still that of a perturbed GOE,
but finite-rank perturbations are more
complicated: both additive & multiplicative, and not
"free" (in the sense of free probability).

Why: multiplicative perturbations due to conditioning to
 $\nabla_{\perp} \xi[\vec{z}^b]$ with $b \neq a$.

Consequence: calculation of isolated values is more
involved; what helps: perturbation is still of finite-rank.

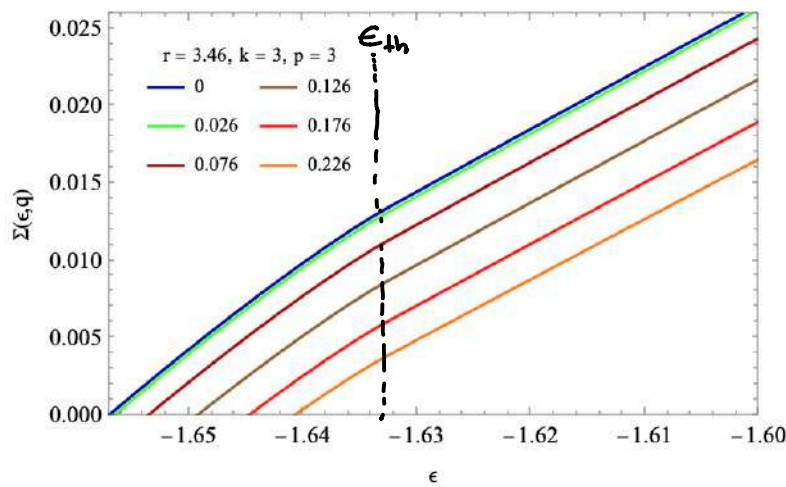
To see comparisons between quenched & annealed, see

ROS, BEN AROUS, BIROLI, CAMMAROTA 2018

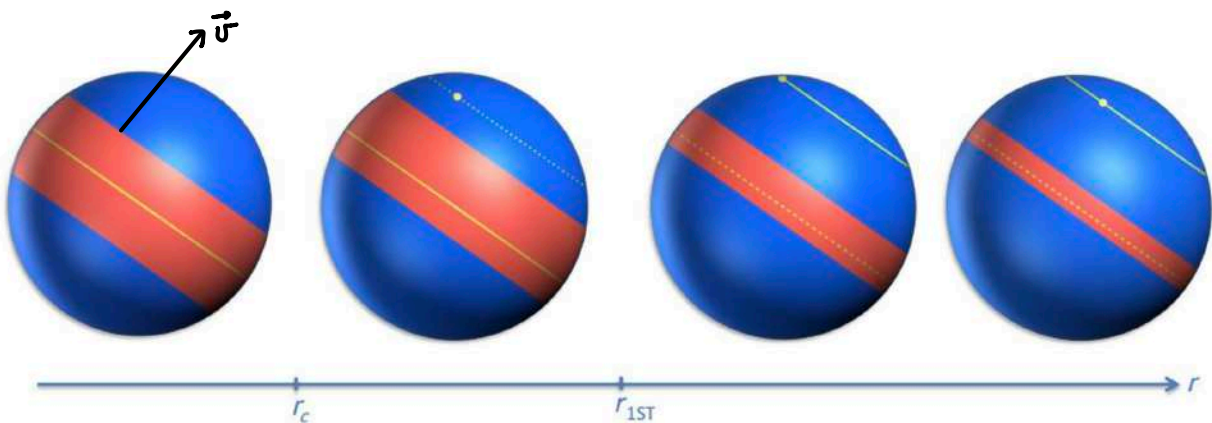
II 3. WHAT: GS, LANDSCAPE, DYNAMICS

Back to the inference problem. Here, summarize results of quenched calculation:

▣ Quenched complexity curves ($\alpha=1$) fixed r



▣ Landscape's evolution with r : regions where $\Sigma_\infty(\epsilon, q) > 0$ for some ϵ (in red), and $q[S_{qs}]$ (yellow).

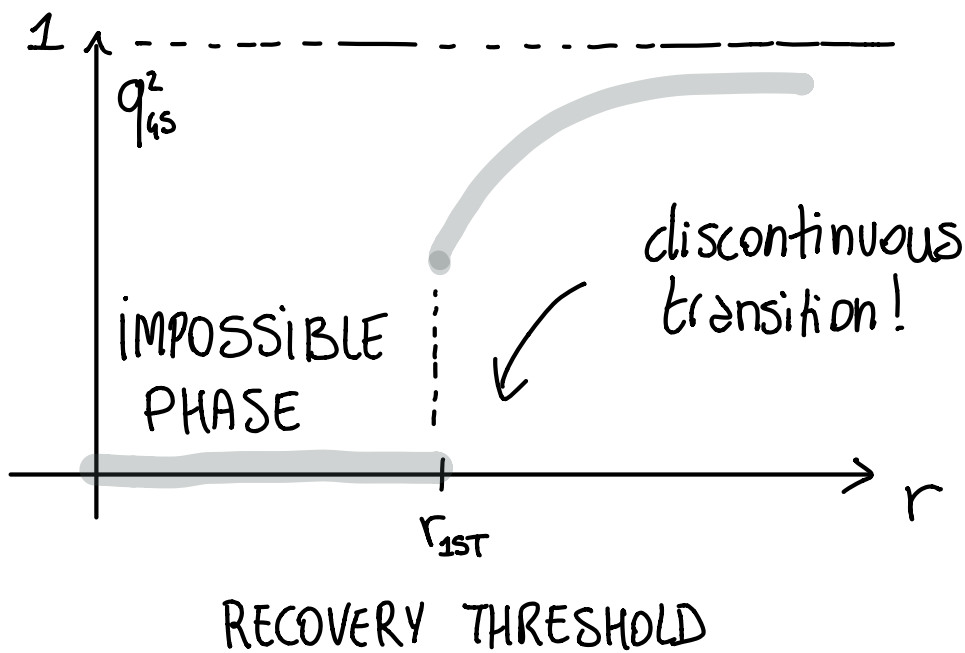


↙ an isolated (local) minimum appears close to signal \vec{u} .

Recovering the signal

Q1: when is \bar{S}_{qs} informative, i.e. $q_{qs} > 0$?

A sharp transition when $N \rightarrow \infty$ at some $r = r_{1st}$



Differences with respect to $p=2$: the transition is discontinuous, first order!

As for $p=2$: could be obtained with thermodynamic calculation for $\beta \rightarrow \infty$

GILLIN SHERRINGTON 2000

A Landscape of minima

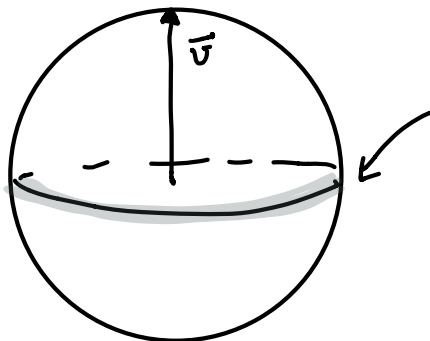
- Most stationary points are un-informative of \vec{v} :

(Neglecting isolated minimum at high overlap)

Optimize over q : $\Sigma_{\infty}(\epsilon, q)$ maximal at $q=0$:

$$\Sigma_{\infty}(\epsilon) = \max_q \Sigma_{\infty}(\epsilon, q) = \frac{1}{2} \log[\bar{z}e(r-1)] - \frac{\epsilon^2}{2\bar{\sigma}^2} + \mathbb{I}\left(\sqrt{\frac{p}{2(p-1)\bar{\sigma}^2}} \epsilon\right)$$

does not depend on r ! Also, $\Sigma_{\infty}(\epsilon, q=0) = \Sigma_A(\epsilon, q=0)$



exponential majority
of stationary points is
orthogonal to the signal!
(Not informative)

- Exponentially many local minima!

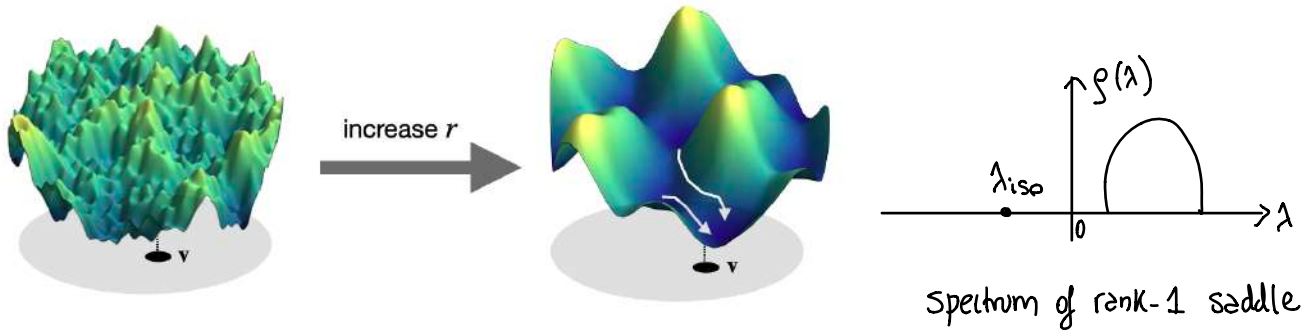
Recall Hessian (annealed calculation)

$$\nabla_{\epsilon, q}^2 \mathcal{E} \Big|_{\epsilon, q} \stackrel{\text{law}}{\sim} \hat{\mathcal{J}} - p\epsilon \hat{\mathbf{1}} - r_{\text{eff}}(q) \vec{w}_{\perp} \vec{w}_{\perp}^T$$

Local minima: $\epsilon < \epsilon_{th}$, $\lambda_{iso}(\epsilon, q) > 0$.

$q=0$: $\text{regg}(q=0)=0$. No isolated evalue. Exponentially-many local minima $\in \epsilon < \epsilon_+$: trapping states for dynamics!

$q>0$: when r large enough, generate isolated evalue, that can become negative: minima \rightarrow saddle transitions



● "Topological trivialization?" How strong should r be to destabilize also minima at equator? Need $r \sim N^\alpha$:

$$r_{\text{eff}} = r p(p-1) \left(\frac{\bar{s} \cdot \bar{u}}{N} \right)^{p-2} \left(1 - \left(\frac{\bar{s} \cdot \bar{u}}{N} \right)^2 \right) \sim r \left(\frac{1}{\sqrt{N}} \right)^{p-2}$$

$$\Rightarrow \alpha = \frac{p-2}{2}$$

▣ Dynamics: DMFT. And beyond?

'Easy' phase: for $r \sim N^\alpha$ with $\alpha > d_c = \frac{p-2}{2}$, gradient descent converges to \vec{S}_{GS} in times $\mathcal{O}(N^0)$.

BEN AROUS, GHEISSARI, JAGANNATH 2020

'Hard' phase $r \sim \mathcal{O}(1)$: dynamics from random initial conditions stuck in high-entropy $q=0$ region, the equator. Here landscape is as if $r=0$.

► The dynamics at $r=0$: "short times".

Described by DMFT ($N \rightarrow \infty$ before $t \rightarrow \infty$)

Excess energy does not decay to zero as for $p=2$, but converges to finite value:

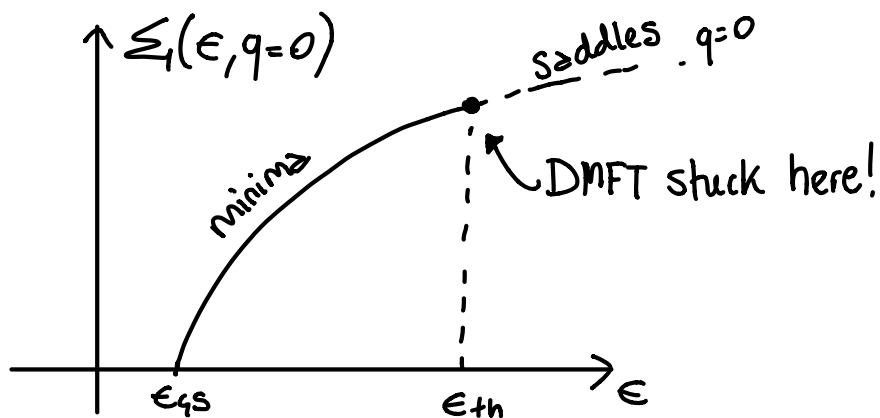
$$\lim_{N \rightarrow \infty} \Delta_N E(t) = \lim_{N \rightarrow \infty} (E_N(t) - E_{GS}) = -\tilde{\sigma}^2 p \int_0^t C^{p-1}(t,s) R(t,s) ds - E_{GS}$$

When $t \rightarrow \infty$, converges to finite value:

$$\lim_{t \rightarrow \infty} \lim_{N \rightarrow \infty} \Delta_N E(t) = E_{th} - E_{GS} > 0$$

Never reach the GS energy density in these timescales. Out-of-equilibrium glassy dynamics, aging. COGLIANDOLO, KURCHAN 1993

Landscape interpretation?



⇒ gradient descent gets stuck at energies of the highest-energy minima, that are exponentially numerous.

COGLIANDOLO, KURCHAN 1993

SELLKE 2024 (math)

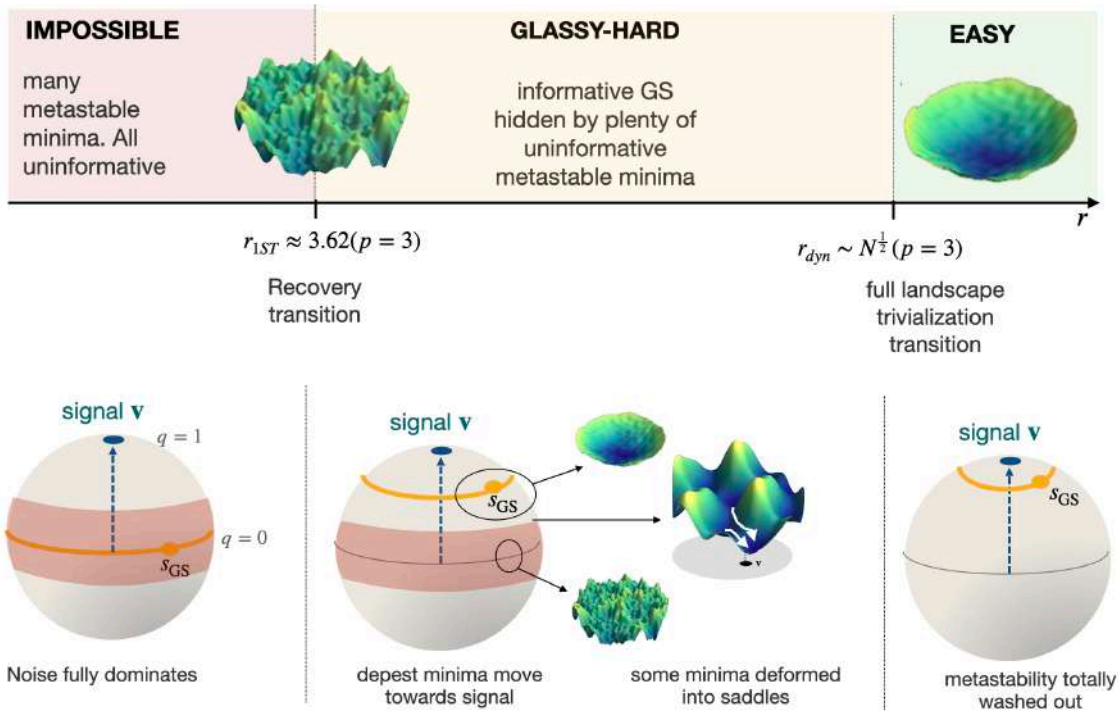
► The dynamics at $r=0$: "long times".

For $p=2$, equilibration timescales $\sim \Theta(N^{2/3})$.

For $p \geq 3$, expect timescales $\sim \Theta(e^N)$: system has to escape from trapping minima crossing energy barriers $\Delta E \sim \Theta(N) \Rightarrow$ ACTIVATED DYNAMICS.

This regime of the dynamics is open problem!

▣ In summary



- ▶ The ground-state becomes correlated with \vec{v} for $r > r_{1ST}$
- ▶ Exponentially-many local minima for all values of r . Those closer to \vec{v} become saddles when r increases, those at equator remain minima.
- ▶ Optimization is hard: system trapped by metastable states. Mean-field dynamics studied a lot for $r=0$. Dynamics at finite N is open problem.

Key Tools

- ✓ RMT: Stieltjes transform, expansion resolvent in $1/N$, density & isolated evalues
- ✓ BBP transition, typical values, finite- N fluctuations, scaling
- ✓ mean-field dynamics, DMFT, crossovers
- ✓ Landscape complexity, quenched vs annealed, replica trick, Kac-Rice formalism

Spiked GOE: eigenvalues density and outliers

[Ref: Bouchaud, Potters, A First Course in Random Matrix Theory, Cambridge University Press 2020].

Take the $N \times N$ matrix $\hat{M} = \hat{J} + \hat{R}$, where \hat{J} is a GOE matrix with $\langle J_{ij} \rangle = 0$ and $\langle J_{ij}^2 \rangle = \frac{\sigma^2}{N}(1 + \delta_{ij})$, while $\hat{R} = r\vec{w}\vec{w}^T$ is a rank-1 perturbation, with $\|\vec{w}\|^2 = 1$. Call λ_α with $\alpha = 1, \dots, N$ the eigenvalues of \hat{M} , and call \vec{u}_α the corresponding eigenvectors. The resolvent of \hat{M} is

$$\hat{G}_{\hat{M}}(z) = \frac{1}{z\hat{1} - \hat{M}} = \sum_{\alpha=1}^N \frac{\vec{u}_\alpha \vec{u}_\alpha^T}{z - \lambda_\alpha}$$

The goal of these two exercises is to derive the self-consistent equations for the Stieltjes transform of \hat{M} , and for its isolated eigenvalue.

Exercise 1. Replica calculation of the Stieltjes transform.

The starting point of the calculation is the Gaussian identity :

$$\left(\frac{1}{z\hat{1} - \hat{M}} \right)_{ij} = \frac{1}{\mathcal{Z}} \int \prod_{i=1}^N \frac{d\psi_i}{\sqrt{2\pi}} \psi_i \psi_j e^{-\frac{1}{2} \sum_{i,j=1}^N \psi_i (z\hat{1} - \hat{M})_{ij} \psi_j}, \quad \mathcal{Z} = \int \prod_{i=1}^N \frac{d\psi_i}{\sqrt{2\pi}} e^{-\frac{1}{2} \sum_{i,j=1}^N \psi_i (z\hat{1} - \hat{M})_{ij} \psi_j}$$

We wish to take the average of this expression with respect to the matrix \hat{M} . However, averaging the partition function in the denominator makes the calculation potentially difficult; to proceed, we make use of the replica trick to write

$$\mathcal{Z}^{-1} = \lim_{n \rightarrow 0} \mathcal{Z}^{n-1}.$$

We then follow the standard steps of replica calculations, see below.

- (i) **From randomness to coupled replicas.** Using the replica trick, justify why $(z\hat{1} - \hat{M})^{-1} = \lim_{n \rightarrow 0} I_{ij}^{(n)}$ where

$$I_{ij}^{(n)} = \int \prod_{a=1}^n \prod_{i=1}^N \frac{d\psi_i^a}{\sqrt{2\pi}} \psi_i^1 \psi_j^1 e^{-\frac{1}{2} \sum_{a=1}^n \sum_{i,j=1}^N \psi_i^a (z\hat{1} - \hat{J} - r\vec{w}\vec{w}^T)_{ij} \psi_j^a}$$

Take the average of this expression with respect to J_{ij} , and show that

$$\langle I_{ij}^{(n)} \rangle = \int \prod_{a=1}^n \prod_{i=1}^N \frac{d\psi_i^a}{\sqrt{2\pi}} \psi_i^1 \psi_j^1 e^{-\frac{1}{2} \sum_{a=1}^n \sum_{i,j=1}^N \psi_i^a (z\delta_{ij} - r w_i w_j) \psi_j^a} e^{\frac{\sigma^2}{4N} \sum_{a,b} (\sum_{i=1}^N \psi_i^a \psi_i^b)^2}.$$

Now one has an expression without randomness, in which the replicated variables ψ^a are coupled with each others.

- (ii) **Hubbard–Stratonovich.** We would like now to perform the integral over the variables ψ_i^a ; however, this integral contains quartic terms in the exponent; in order to turn such an integral into a Gaussian one, we perform a Hubbard-Stratonovich transformation: we introduce the order parameters

$$Q_{ab}[\psi] = \frac{1}{N} \sum_{i=1}^N \psi_i^a \psi_i^b \quad a \leq b$$

and write the integral as

$$\int \prod_{a=1}^n \prod_{i=1}^N \frac{d\psi_i^a}{\sqrt{2\pi}} \dots \rightarrow N^{\frac{n(n+1)}{2}} \int \prod_{a \leq b} dQ_{ab} \int \prod_{a=1}^n \prod_{i=1}^N \frac{d\psi_i^a}{\sqrt{2\pi}} \prod_{a \leq b} \delta \left(N Q_{ab} - \sum_{i=1}^N \psi_i^a \psi_i^b \right) \dots$$

Show that using the integral representation of the delta distributions

$$\delta\left(NQ_{ab} - \sum_{i=1}^N \psi_i^a \psi_i^b\right) = \int \frac{d\lambda_{ab}}{2\pi} e^{i\lambda_{ab}[NQ_{ab} - \sum_{i=1}^N \psi_i^a \psi_i^b]}$$

and introducing the $n \times n$ matrix Λ with components $\Lambda_{ab} = 2\lambda_{aa}\delta_{ab} + \lambda_{ab}(1 - \delta_{ab})$ and the $N \times N$ matrix A with components $A_{ij} = z\delta_{ij} + rw_i w_j$, the average can be cast in the following form:

$$\langle I_{ij}^{(n)} \rangle = N^{\frac{n(n+1)}{2}} \int \prod_{a \leq b} dQ_{ab} d\lambda_{ab} e^{\frac{N\sigma^2}{4} \text{Tr}_n[Q^2] + \frac{N}{2} \text{Tr}_n[i\Lambda Q]} f_N[Q, \vec{w}] \quad (1)$$

with

$$f_N[Q, \vec{w}] = \int \prod_{a=1}^n \prod_{i=1}^N \frac{d\psi_i^a}{\sqrt{2\pi}} \psi_i^1 \psi_j^1 e^{-\frac{1}{2} \sum_{a,b} \sum_{i,j} \psi_i^a [\hat{1}_N \otimes i\Lambda + A \otimes \hat{1}_n]_{ij}^{ab} \psi_j^b}.$$

(iii) **Gaussian integration.** Performing the Gaussian integral, show that

$$\langle I_{ij}^{(n)} \rangle = \delta_{ij} \int \prod_{a \leq b} dQ_{ab} d\lambda_{ab} e^{\frac{N}{2} A_N[Q, i\Lambda]} \left[(A \otimes 1_n + 1_N \otimes i\Lambda)^{-1} \right]_{ij}^{11}$$

$$A_N[Q, i\Lambda] = \frac{\sigma^2}{2} \text{Tr}_n[Q^2] + \text{Tr}_n[i\Lambda Q] - \frac{1}{N} \text{Tr}_{nN}[\log(A \otimes 1_n + 1_N \otimes i\Lambda)]$$

Hint. Use that $\int \prod_{i=1}^d \frac{dx_i}{\sqrt{2\pi}} x_l x_m e^{-\frac{1}{2} \vec{x} \cdot \hat{K} \vec{x}} = \hat{K}_{lm}^{-1} |\det K|^{-1}$ and that $\log |\det K| = \text{Tr} \log K$.

(iv) **Saddle point.** The integral can now be computed with a saddle point approximation. Show that the saddle point equations for the matrices Q and $i\Lambda$ read

$$i\Lambda = -\sigma^2 Q, \quad Q = \frac{1}{N} \text{Tr}_{nN} \left[\frac{1}{A \otimes 1_n + 1_N \otimes i\Lambda} \right]$$

Show that, plugging the first into the second and assuming that the matrices Λ, Q are diagonal and replica symmetric, i.e. $Q_{ab} = \delta_{ab}g$ and $\lambda_{ab} = \delta_{ab}\lambda$, one reduces to a single equation for g which reads

$$g = \frac{1}{N} \text{Tr}_N \left[\frac{1}{(z - \sigma^2 g) \hat{1}_N - r \vec{w} \vec{w}^T} \right]$$

Using that

$$\langle (z \hat{1} - \hat{M})^{-1} \rangle = \lim_{n \rightarrow 0} \langle I_{ij}^{(n)} \rangle = \left[(A \otimes 1_n - \sigma^2 g 1_N \otimes 1_n)^{-1} \right]_{ij}^{11},$$

justify why g is the Stieljes transform of the matrix M . Show that expanding $g = g_\infty + g_1/N + \dots$, the leading order term satisfies the equation

$$g_\infty^{-1} = z - \sigma^2 g_\infty.$$

Exercise 2. The isolated eigenvalue and eigenvector.

(i) Show that if \hat{A} is a matrix and \vec{v}, \vec{u} are vectors, then

$$(\hat{A} + \vec{u} \vec{v}^T)^{-1} = \hat{A}^{-1} - \frac{A^{-1} \vec{u} \vec{v}^T A^{-1}}{1 + \vec{v} \cdot A^{-1} \vec{u}}.$$

Use this formula (Shermann-Morrison formula) to get an expression for $\hat{G}_{\hat{M}}(z)$.

(ii) The isolated eigenvalue is a pole of the resolvent operator $\hat{G}_{\hat{M}}(z)$, which is real and such that $\lambda_{\text{iso}} > 2\sigma$. Using that λ_{iso} does not belong to the spectrum of the unperturbed matrix \hat{J} , show that it solves the equation

$$r \vec{w} \cdot G_j(\lambda_{\text{iso}}) \vec{w} = 1.$$

- (iii) Using that \hat{J} and \vec{w} are independent and that typically \vec{w} is *delocalized* in the eigenbasis of \hat{J} , show that

$$\vec{w} \cdot G_{\hat{J}}(\lambda_{\text{iso}}) \vec{w} \xrightarrow{N \rightarrow \infty} g_{\text{sc}}(\lambda_{\text{iso}})$$

where $g_{\text{sc}}(\lambda)$ is the Stieltjes transform of the GOE matrix \hat{J} .

- (iv) Using the self-consistent equation satisfied by $g_{\text{sc}}(\lambda)$, derive the expression of the inverse function g_{sc}^{-1} and determine its domain; use it to show that

$$\lambda_{\text{iso}} = \frac{\sigma^2}{r} + r \quad r \geq \sigma.$$

- (v) The eigenvectors projections $\xi_\alpha = (\vec{w} \cdot \vec{u}_\alpha)^2$ can be obtained from the resolvent as residues of the poles:

$$\xi_\alpha = \lim_{\lambda \rightarrow \lambda_\alpha} (\lambda - \lambda_\alpha) \vec{w} \cdot G_{\hat{M}}(\lambda) \vec{w}$$

Use this to show that if $\alpha = N$ labels the isolated eigenvalue, then

$$\xi_N = -\frac{1}{r^2 g'_{\text{sc}}(\lambda_{\text{iso}})} = 1 - \frac{\sigma^2}{r^2}.$$

Hint. Use that if $\lim_{\lambda \rightarrow \lambda_0} f(\lambda) = 0 = \lim_{\lambda \rightarrow \lambda_0} g(\lambda)$, then $\lim_{\lambda \rightarrow \lambda_0} \frac{f(\lambda)}{g(\lambda)} = \lim_{\lambda \rightarrow \lambda_0} \frac{f'(\lambda)}{g'(\lambda)}$.

Condensation transition

[Ref: Kosterlitz, Thouless, Jones, *Spherical Model of a Spin-Glass*, PRL 36 (1976)].

The matrix denoising problem is formulated in terms of the ground state of the energy landscape:

$$\mathcal{E}[\vec{s}] = -\frac{1}{2} \sum_{ij} s_i (J_{ij} + r v_i v_j) s_j, \quad \|\vec{s}\|^2 = N = \|\vec{v}\|^2, \quad \hat{J} \sim \text{GOE}$$

The behavior of the ground state can be characterized by studying the thermodynamics of the system in the limit $\beta \rightarrow \infty$, through the partition function:

$$\mathcal{Z}_\beta = \int_{S_N(\sqrt{N})} d\vec{s} e^{-\beta \mathcal{E}[\vec{s}]}, \quad S_N(\sqrt{N}) = \{\vec{s} : \|\vec{s}\|^2 = N\}$$

As a function of temperature, this model exhibits a transition at a critical temperature $T_c(r)$, which can be interpreted as a *condensation transition* (like in BEC physics).

Exercise 3. Thermodynamics of the model

- (i) Call λ_α ($\lambda_1 \leq \lambda_2 \leq \dots \leq \lambda_N$) the eigenvalues of $\hat{M} = \hat{J} + \hat{R}$, and \vec{u}_α the corresponding eigenvectors. Call $s_\alpha = \vec{s} \cdot \vec{u}_\alpha$. Show that the partition function can be written as

$$\mathcal{Z}_\beta = \int d\lambda \int \prod_{\alpha=1}^N ds_\alpha e^{\frac{\beta}{2} [\sum_\alpha \lambda_\alpha s_\alpha^2 - \lambda (\sum_\alpha s_\alpha^2 - N)]}$$

- (ii) Show that the thermal expectation value of the mode occupations is

$$\langle s_\gamma^2 \rangle = \frac{1}{\mathcal{Z}_\beta} \int d\lambda \int \prod_{\alpha=1}^N ds_\alpha s_\gamma^2 e^{-\frac{\beta}{2} [-\sum_\alpha \lambda_\alpha s_\alpha^2 + \lambda (\sum_\alpha s_\alpha^2 - N)]} = \frac{1}{\beta(\lambda^* - \lambda_\gamma)}$$

where $\lambda^* > \lambda_\gamma$ for all γ is fixed by the equation

$$\sum_{\gamma=1}^N \langle s_\gamma^2 \rangle = N = \sum_{\gamma=1}^N \frac{1}{\beta(\lambda^* - \lambda_\gamma)}$$

- (iii) The matrix \hat{M} is a spiked GOE. Take $r < r_c = \sigma$. Justify why for large N the equation for λ^* becomes:

$$\beta = g_{\text{sc}}(\lambda^*) \quad \lambda^* > 2\sigma$$

where $g_{\text{sc}}(\lambda^*)$ is the Stieltjes transform of the GOE; show that there is a critical temperature $\beta_c = \sigma^{-1}$ and compute the solution λ^* for $\beta < \beta_c$. Show that at β_c , λ^* attains its maximal possible value. Show that at low temperature $\beta > \beta_c$ the equation can be solved assuming *condensation* of the fluctuations in the lowest-energy mode:

$$\frac{1}{N} \langle s_N^2 \rangle = 1 - \frac{1}{\beta\sigma}$$

This condensation transition corresponds also to a transition between a paramagnet at high temperature, and a spin-glass at low temperature.

- (iv) Consider now $r > r_c = \sigma$, when the maximal eigenvalue is $\lambda_N = \lambda_{\text{iso}} = \frac{\sigma^2}{r} + r$; justify why now the critical temperature is $\beta_c = 1/r$, and a solution of the equation for λ^* (with $\lambda^* > \lambda_\gamma$) exists for $\beta < \beta_c$. Show that for $\beta > \beta_c$ it must hold

$$\frac{1}{N} \langle s_N^2 \rangle = \frac{1}{N} \langle s_{\text{iso}}^2 \rangle = 1 - \frac{1}{\beta r}$$

In this regime, the condensation transition coincides with a transition between a paramagnet at high temperature, and a ferromagnet at low temperature.

Exercise 1 - solution

Stieltjes transform with replica method

(i) The normalization Z is an integral over the variables ψ_i . Writing:

$$Z^{n-1} = \left[\int \prod_{i=1}^N \frac{d\psi_i}{\sqrt{2\pi}} \dots \right]^{n-1} = \left[\int \prod_{i=1}^N \frac{d\psi_i^{(2)}}{\sqrt{2\pi}} \dots \right] \dots \left[\int \prod_{i=1}^N \frac{d\psi_i^{(n)}}{\sqrt{2\pi}} \dots \right]$$

we can set:

$$\lim_{n \rightarrow 0} Z^{n-1} \int \prod_{i=1}^N \frac{d\psi_i}{\sqrt{2\pi}} \psi_i \psi_j e^{-\frac{1}{2} \sum_{ij} \psi_i (z-M)_{ij} \psi_j} =$$

$$= \lim_{n \rightarrow 0} \int \prod_{i=1}^N \frac{d\psi_i}{\sqrt{2\pi}} \psi_i \psi_j e^{-\frac{1}{2} \sum_{ij} \psi_i (z-M)_{ij} \psi_j} \int \prod_{a=2}^n \prod_{i=1}^N \frac{d\psi_i^{(a)}}{\sqrt{2\pi}} \dots$$

label these variables as $\psi_i^{(2)}$

$$= \lim_{n \rightarrow 0} \int \prod_{a=1}^n \prod_{i=1}^N \frac{d\psi_i^{(a)}}{\sqrt{2\pi}} \psi_i^{(1)} \psi_j^{(1)} e^{-\frac{1}{2} \sum_{a=1}^n \sum_{ij} \psi_i^{(a)} (z-M)_{ij} \psi_j^{(a)}}$$

$$\stackrel{!}{=} \lim_{n \rightarrow 0} I_{ij}^{(n)}$$

(ii) Using the integral representation of $\delta(\cdot)$, we obtain:

$$\langle I_{ij}^{(n)} \rangle = \int \prod_{a=1}^n \prod_{i=1}^N \frac{d\psi_i^a}{\sqrt{2\pi}} \cdot N^{\frac{n(n+1)}{2}} \int \prod_{a \leq b} dQ_{ab} \int \prod_{a \leq b} \frac{d\lambda_{ab}}{2\pi} e^{i \sum_{a \leq b} \lambda_{ab} (N Q_{ab} - \sum_i \psi_i^a \psi_i^b)} \times$$

$$\times \psi_i^1 \psi_j^1 e^{-\frac{1}{2} \sum_{a \leq b} \sum_{ij} \psi_i^a (\underbrace{\pm \delta_{ij} - r_{ab} w_{ij}}_{A_{ij}}) \psi_j^a} \times$$

$$\times e^{\frac{\sigma^2 N}{4} \sum_{a,b} \left(\sum_i \psi_i^a \psi_j^b \right)^2} \underbrace{\hspace{10em}}_{N Q_{ab}}$$

← exchange order integration

$$\textcircled{=} N^{\frac{n(n+1)}{2}} \int \prod_{a \leq b} dQ_{ab} \int \prod_{a \leq b} \frac{d\lambda_{ab}}{2\pi} e^{i N \left(\frac{1}{2} \sum_{a \neq b} Q_{ab} \lambda_{ab} + \sum_a Q_{aa} \lambda_{aa} \right)} \times$$

$$\times e^{\frac{\sigma^2 N}{4} \sum_{a,b} Q_{ab}^2} \times \int \prod_{a=1}^n \prod_{i=1}^N \frac{d\psi_i^a}{\sqrt{2\pi}} \psi_i^1 \psi_j^1$$

$$e^{-i \left(\frac{1}{2} \sum_{a \neq b} \lambda_{ab} \sum_i \psi_i^a \psi_i^b + \sum_a \lambda_{aa} \sum_i \psi_i^a \psi_i^a \right)} e^{-\frac{1}{2} \sum_{a \leq b} \sum_{ij} \psi_i^a A_{ij} \psi_j^a}$$

(**)

Introducing $\Lambda_{ab} = 2\lambda_{aa} \delta_{ab} + \lambda_{ab} (1 - \delta_{ab})$ and the trace

$$\text{tr}_n [O] = \sum_{a=1}^n O_{aa}, \text{ we can rewrite}$$

$$(*) = \frac{N}{2} \text{tr}_n [Q \cdot i \Lambda]$$

and

$$(\ast\ast) = -\frac{1}{2} \sum_{ij} \sum_{ab} \psi_i^a \left[\mathbb{1}_N \otimes i\Lambda \right]_{ij}^{ab} \psi_j^b \quad \text{where } \mathbb{1}_N = \begin{pmatrix} \mathbb{1}_{N \times N} & 0 \\ 0 & \mathbb{1}_{N \times N} \end{pmatrix}$$

Moreover, $\sum_{a,b} Q_{ab}^2 = \text{tr}_n [Q^2]$.

(iii) The integral over the ψ_i^a is now gaussian.

Using that for an arbitrary (positive-definite) matrix K_{ij} it holds

$$\int \prod_{i=1}^n dx_i e^{-\frac{1}{2} \sum_{ij} x_i K_{ij} x_j} = \frac{(\det K)^{-1/2} (2\pi)^{n/2}}{|\det K|}$$

and that $\log |\det K| = \text{tr} \log K$,

We get:

$$\int \prod_{a=1}^n \prod_{i=1}^N \frac{d\psi_i^a}{\sqrt{2\pi}} \psi_i^a \psi_j^a e^{-\frac{1}{2} \sum_{a,b} \sum_{ij} \psi_i^a \left[A_{ij} \delta_{ab} + \delta_{ij} (i\Lambda)_{ab} \right] \psi_j^b} =$$

$$= (K^{-1})_{ij}^{aa} e^{-\text{tr} \log K} \quad \text{where } K = A \otimes \mathbb{1}_N + \mathbb{1}_N \otimes i\Lambda$$

Combining everything, one gets the final expression

(iv) The saddle point equations are obtained taking the variation of

$$A_N[Q, i\Lambda] = \frac{\sigma^2}{2} \sum_{a,b} Q_{ab}^2 + \sum_{a,b} (i\Lambda)_{ab} Q_{ab} - \frac{1}{N} \text{Tr} \log (A \otimes 1_n + 1_N \otimes i\Lambda)$$

$$\frac{\delta A_N}{\delta Q_{ab}} = \sigma^2 Q_{ab} + i\Lambda_{ab} = 0 \quad \Rightarrow \quad i\Lambda = -\sigma^2 Q$$

$$\frac{\delta A_N}{\delta \Lambda_{ab}} = Q_{ab} - \frac{1}{N} \text{tr}_N \left(\frac{1}{A \otimes 1_n + 1_N \otimes i\Lambda} \right)_{ab} = 0$$

$$\Rightarrow Q = \frac{1}{N} \text{tr}_N \left(\frac{1}{A \otimes 1_n + 1_N \otimes i\Lambda} \right) = \frac{1}{N} \text{tr}_N \left(\frac{1}{A \otimes 1_n - \sigma^2 1_N \otimes Q} \right)$$

If $Q = \begin{pmatrix} g & & \\ & \ddots & \\ & & g \end{pmatrix}$, then componentwise:

$$g = \frac{1}{N} \text{tr}_N \left(\frac{1}{z - r_{\text{WWT}} - \sigma^2 g} \right)$$

To compute the trace, one can choose a basis e_α such that $e_1 = w$, $e_\alpha \perp w \quad \forall \alpha = 2, \dots, N$. Then:

$$g = \frac{1}{N} (N-1) \frac{1}{z - \sigma^2 g} + \frac{1}{N} \frac{1}{z - r - \sigma^2 g} = \frac{1}{z - \sigma^2 g} + \mathcal{O}(1/N)$$

$$\Rightarrow g_\infty = \frac{1}{z - \sigma^2 g_\infty} \Rightarrow \sigma^2 g_\infty - z g_\infty + 1 = 0.$$

Exercise 2 - solution

isolated value/evector of spiked GOE matrix

(i) One has $(A + uv^T)^{-1} = (A [1 + A^{-1} uv^T])^{-1} = (1 + A^{-1} uv^T)^{-1} A^{-1}$

Using the formal expansion:

$$(1 + A^{-1} uv^T)^{-1} = 1 - A^{-1} uv^T + A^{-2} uv^T A^{-1} uv^T + \dots$$

leads to

$$(A + uv^T)^{-1} = A^{-1} - A^{-1} uv^T A^{-1} + A^{-1} u \underbrace{(v^T A^{-1} u)}_{\text{number}} v^T A^{-1} + \dots$$

Calling $X = v^T A^{-1} u$ and resumming the series:

$$(A + uv^T)^{-1} = A^{-1} - \frac{A^{-1} uv^T A^{-1}}{1 + X}$$

In the case of the rank-1 perturbation with $\vec{u} = \frac{r}{N} \vec{w}$, $\vec{v} = \vec{w}$ and $\hat{A} = z\hat{1} - \hat{\mathfrak{A}}$ we get

$$\hat{G}_M(z) = (z - \hat{M})^{-1} = \hat{G}_2(z) + r \frac{\hat{G}_2(z) \vec{w} \vec{w}^T \hat{G}_2(z)}{1 - r \vec{w} \cdot \hat{G}_2(z) \vec{w}} \quad (*)$$

(ii) The eigenvalues of \hat{M} are poles of $\hat{G}_M(z)$.

If λ_{iso} is an outlier, it is not a pole of $\hat{G}_2(z)$, because it does not belong to the spectrum of $\hat{\mathfrak{A}}$ that is the semicircle in $[-2\sigma, 2\sigma]$.

To be a pole of $\hat{G}_M(z)$ and not of $\hat{G}_2(z)$, λ_{iso} must be a zero of the denominator of the second term in (*):

$$1 - \tau \vec{w} \cdot \hat{G}_2(\lambda_{iso}) \vec{w} = 0$$

(iii) The fact that \vec{w} is "delocalized" in the basis of eigenstates of \hat{J} , which I call \vec{e}_α , implies that typically $(\vec{w} \cdot \vec{e}_\alpha)^2 \sim 1/N$ $N \gg 1$.

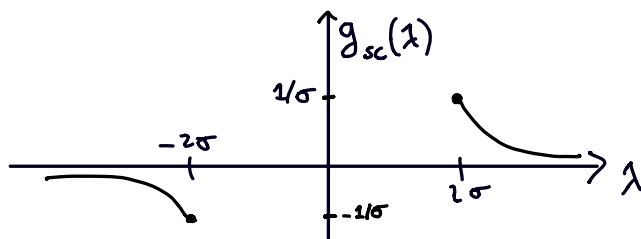
The scalar product $\vec{w} \cdot \hat{G}_2(\lambda) \vec{w}$ can be expanded in the eigenbasis of \hat{J} , and one gets:

$$\vec{w} \cdot \hat{G}_2(\lambda) \vec{w} = \sum_{\beta=1}^N (\vec{e}_\beta \cdot \vec{w})^2 [\hat{G}_2(z)]_{\beta\beta} \stackrel{N \gg 1}{\sim} \frac{1}{N} \sum_{\beta=1}^N [\hat{G}_2(z)]_{\beta\beta}$$

The last term is the normalized trace of the resolvent, i.e. the Stieltjes transform. Therefore:

$$\lim_{N \rightarrow \infty} \vec{w} \cdot \hat{G}_2(\lambda) \vec{w} = g_{sc}(\lambda)$$

(iv) The function $g_{sc}(\lambda)$ has the following behavior on the real axis:



The function is invertible only if $y \in [-1/\sigma, 1/\sigma]$.

The expression for g_{sc}^{-1} can be more easily obtained from the self-consistent equation:

$$\sigma^2 g_{sc}^2(z) - z g_{sc}(z) - 1 = 0$$

$$\Rightarrow z = \sigma^2 g_{sc}(z) + \frac{1}{g_{sc}(z)} \Rightarrow g_{sc}^{-1}(y) = \sigma^2 y + 1/y$$

The equation for λ_{iso} reads: $g_{sc}(\lambda_{iso}) = 1/r$.

It admits a solution only for $1/r \in [-1/\sigma, 1/\sigma]$.

meaning that $r \geq \sigma$ for $r > 0$.

In this case, $\lambda_{iso} = g_{sc}^{-1}(1/r) = \frac{\sigma^2}{r} + r$

(v) Using the decomposition of G_M in its eigenbasis $(\lambda_\alpha, \bar{u}_\alpha)_{\alpha=1}^N$

$$\hat{G}_M(z) = \sum_{\beta=1}^N \frac{\bar{u}_\beta \bar{u}_\beta^T}{z - \lambda_\beta} \Rightarrow \bar{w}^T \hat{G}_M \bar{w} = \sum_{\beta=1}^N \frac{\sum_{\beta}^2}{z - \lambda_\beta}$$

Then obviously if $z \rightarrow \lambda_\alpha$ is an isolated pole,

$$\sum_{\alpha}^2 = \lim_{\lambda \rightarrow \lambda_\alpha} \sum_{\beta=1}^N \frac{(1 - \lambda_\alpha)}{(1 - \lambda_\beta)} \sum_{\beta}^2$$

We use again the expression (*). Since λ_{iso} is not a pole of \hat{g} , the first term will not contribute to the residue and so:

$$\begin{aligned} \xi_N &= \lim_{\lambda \rightarrow \lambda_{iso}} r \frac{(\vec{w}^T \hat{g}_{\partial\partial}(\lambda) \vec{w})^2}{1 - r \vec{w} \cdot \hat{g}_{\partial}(\lambda) \vec{w}} (\lambda - \lambda_{iso}) \\ N \gg 1 & \quad \approx \lim_{\lambda \rightarrow \lambda_{iso}} (\lambda - \lambda_{iso}) \frac{r g_{sc}^2(\lambda)}{1 - r g_{sc}(\lambda)} \\ &= \lim_{\lambda \rightarrow \lambda_{iso}} \frac{(\lambda - \lambda_{iso})}{1 - r g_{sc}(\lambda)} \cdot g_{sc}(\lambda_{iso}) \end{aligned}$$

When $\lambda \rightarrow \lambda_{iso}$, $1 - r g_{sc}(\lambda) \rightarrow 0$ and thus the limit gives 0/0: One has to compute it by taking the derivative of both numerator & denominator

$$\lim_{\lambda \rightarrow \lambda_{iso}} \frac{(\lambda - \lambda_{iso})}{1 - r g_{sc}(\lambda)} g_{sc}(\lambda_{iso}) = g_{sc}(\lambda_{iso}) \lim_{\lambda \rightarrow \lambda_{iso}} \frac{-1}{r g'_{sc}(\lambda)}$$

Using that $g_{sc}(\lambda_{iso}) = 1/r$, one gets: $\xi_N = -\frac{1}{r^2 g'_{sc}(\lambda_{iso})}$

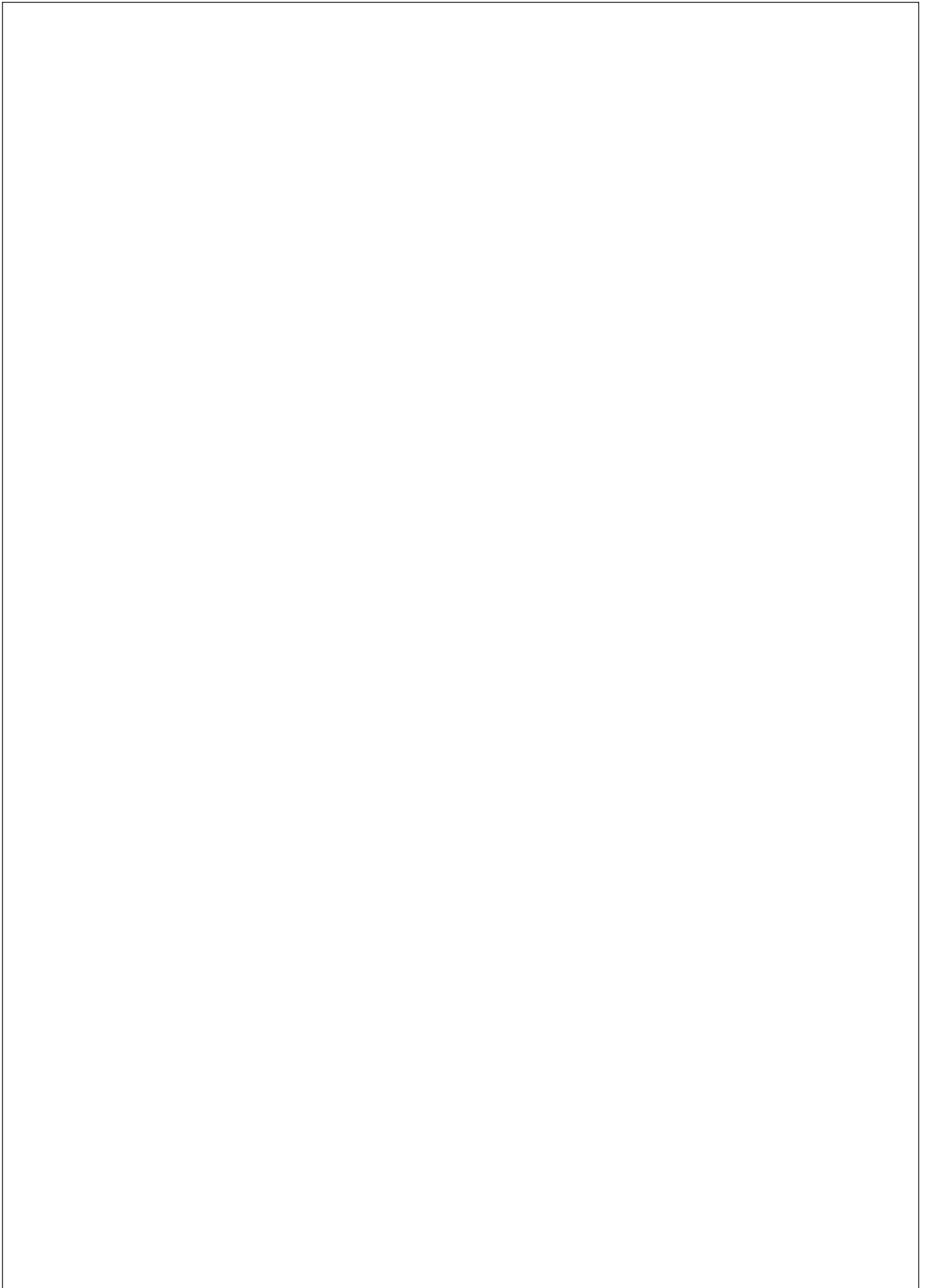
To make this more explicit, convenient to take the self-consistent eq. for $g_{sc}(\lambda)$ and derive it:

$$2\sigma^2 g'_{sc}(z) g_{sc}(z) - g_{sc}(z) - z g'_{sc}(z) = 0$$

$$(2\sigma^2 g_{sc} - z) g'_{sc} = g_{sc} \Rightarrow \frac{g_{sc}}{g'_{sc}} = 2\sigma^2 g_{sc} - z$$

At $z = \lambda_{iso}$,

$$\begin{aligned} \xi_H &= -\frac{1}{r} \left(\frac{g_{sc}}{g'_{sc}} \right) = -\frac{1}{r} \left(2\sigma^2 g_{sc}(\lambda_{iso}) - \lambda_{iso} \right) \\ &= \frac{-2\sigma^2}{r^2} + \frac{1}{r} \left(\frac{\sigma^2}{r^2} + r \right) = 1 - \frac{\sigma^2}{r^2} \end{aligned}$$



Exercise 3 - solution

Thermodynamics and the condensation transition

(i) One has:

$$Z_{\beta} = \int_{S^N(N)} d\vec{s} e^{\frac{\beta}{2} \sum_{i,j=1}^N s_i (\tau_{ij} + r v_i v_j) s_j} = \int d\vec{s} d\lambda e^{\frac{\beta}{2} \sum_{i,j} s_i M_{ij} s_j - \frac{\beta\lambda}{2} \left(\sum_i s_i^2 - N \right)}$$

↑
implement spherical constraint.

Performing the change of basis, one gets:

$$Z_{\beta} = \int d\lambda \int \prod_{\alpha=1}^N ds_{\alpha} e^{\frac{\beta}{2} \sum_{\alpha} \lambda_{\alpha} s_{\alpha}^2 - \frac{\beta\lambda}{2} \left(\sum_{\alpha} s_{\alpha}^2 - N \right)}$$

(ii) The average:

$$\begin{aligned} \langle s_{\gamma}^2 \rangle &= \frac{1}{Z_{\beta}} \int d\lambda e^{\frac{\beta\lambda N}{2}} \int \prod_{\alpha \neq \gamma} ds_{\alpha} e^{\frac{\beta\lambda_{\alpha} s_{\alpha}^2 - \beta\lambda s_{\alpha}^2}{2}} \int ds_{\gamma} s_{\gamma}^2 e^{\frac{\beta\lambda_{\gamma} s_{\gamma}^2 - \beta\lambda s_{\gamma}^2}{2}} \\ &= \frac{1}{Z_{\beta}} \int d\lambda e^{\frac{\beta\lambda N}{2}} \left(\frac{2\pi}{\beta} \right)^{N/2} \left(\prod_{\alpha=1}^N \frac{1}{\lambda - \lambda_{\alpha}} \right)^{1/2} \frac{1}{\beta(\lambda - \lambda_{\gamma})} \quad (*) \end{aligned}$$

Assuming $\lambda > \lambda_{\alpha} \forall \alpha$.

The integral over λ can be performed with a saddle point when $N \gg 1$, optimizing

$$f(\lambda) = \lambda \beta - \frac{1}{N} \sum_{\alpha=1}^N \log(\lambda - \lambda_{\alpha})$$

$$f'(\lambda) \Big|_{\lambda=\lambda^*} = 0 \Rightarrow \beta = \frac{1}{N} \sum_{\alpha=1}^N \frac{1}{\lambda^* - \lambda_{\alpha}}$$

Plugging this in (*) and simplifying the exponential terms in numerator with those in Z_{β} , one gets

$$\langle S_{\gamma}^2 \rangle = \frac{1}{\beta(\lambda^* - \lambda_{\gamma})}$$

with λ^* solving:

$$N = \sum_{\gamma=1}^N \frac{1}{\beta(\lambda^* - \lambda_{\gamma})} = \sum_{\gamma=1}^N \langle S_{\gamma}^2 \rangle$$

(iii) For $r < r_c = \sigma$, there is no isolated eigenvalue and the spectrum of \hat{M} has an eigenvalue density that tends to the semicircle $\rho_{sc}(\lambda)$ when $N \rightarrow \infty$.

Thus:

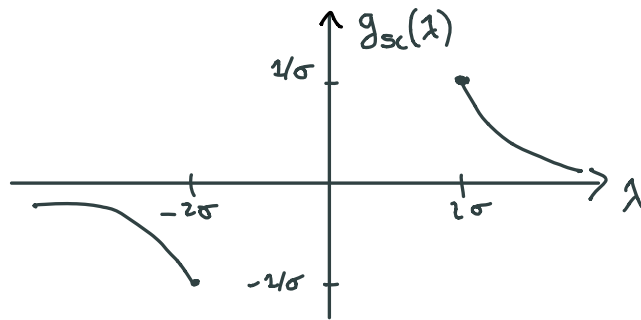
$$\frac{1}{N} \sum_{\gamma} \frac{1}{\lambda^* - \lambda_{\gamma}} \stackrel{N \gg 1}{\sim} \int d\lambda \frac{\rho_{sc}(\lambda)}{\lambda^* - \lambda} = g_{sc}(\lambda^*)$$

The equation for λ^* becomes:

$$g_{sc}(\lambda^*) = \beta \quad \text{for } \lambda^* > \lambda_N = 2\sigma$$

This can be solved only for $\beta < \beta_c = 1/\sigma$, and in this case

$$\lambda^* = \frac{1}{\beta} + \sigma^2 \beta$$



At $\beta \rightarrow \beta_c$, $\lambda^* \rightarrow 2\sigma$, that is the boundary value of the domain where the saddle point can be taken. For $\beta > \beta_c$, the saddle point sticks to the boundary: $\lambda^* = 2\sigma$

This is a freezing transition: it signals the transition to a glass phase.

Then the equation for λ^* is solved assuming condensation in the lowest energy mode

$$\langle S_N^2 \rangle \sim O(N)$$

In particular: $1 = \frac{1}{\beta} \underbrace{g_{sc}(\lambda^* = 2\sigma)}_{1/\sigma} + \frac{1}{N} \langle S_N^2 \rangle$

$\implies \frac{1}{N} \langle S_N^2 \rangle = 1 - 1/\sigma\beta.$

(iv) For $r > r_c = \sigma$, $\lambda_N = \lambda_{iso} = \frac{\sigma^2}{r} + r > 2\sigma$ is the maximal value that λ^* can take. Since $g_{sc}(\lambda)$ is monotonically decreasing, the maximal β for which a solution to $\beta = g_{sc}(\lambda^*)$ can be found is the β such that: $\beta = g_{sc}(\lambda_{iso})$

Recalling that $g_{sc}(\lambda_{iso}) = 1/r$, one has $\beta_c = 1/r$.

For $\beta > \beta_c$, it must hold:

$1 = \frac{1}{\beta} g_{sc}(\lambda_{iso}) + \frac{1}{N} \langle S_N^2 \rangle \implies \frac{1}{N} \langle S_N^2 \rangle = 1 - 1/\beta r.$

Phase transitions in temperature:

