

New higher-spin topological systems in 3D

Strange higher-spins are wild quivers ?

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[to appear soon]

- ① Introduction
- ② Higher dualisations of linearised gravity and Maxwell's
- ③ First-order reformulation of the spin 2 - spin 3 systems
- ④ Generalisations

① Introduction

- Fierz-Pauli programme \rightarrow all possible off-shell descriptions of spin- s massless field ?

\hookrightarrow Interactions may not choose the most economical description

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Higher-spin Gravity

Hidden symmetries of Gravity

Non-linear realisation of $e_{11} \times \ell_1$

Higher, or "exotic" descriptions

• Electric-magnetic duality, perhaps as fundamental as Lorentz symmetry.

In non-Abelian theory, relates **strong** and **weak** coupling regimes. [Long story: Heaviside, Dirac, ...]

• For spin-2 (linearized), studied by P. West, Hull (2001). Previous attempts

in the massive case by Curtright & Freund in 80's. Further studied in 2002,

on-shell, by X. Bekaert & N.B.

• First, review for spin (better, helicity) one.

• On-shell duality in electromagnetism in vacuum

Maxwell's equations $\partial^\mu F_{\mu\nu} = 0$ $(-\mu_0 J_\nu \text{ when sources})$ (Field equations)

$\partial_{[\mu} F_{\nu\lambda]} = 0$ (Bianchi identities) $F_{\mu\nu} := \partial_\mu A_\nu - \partial_\nu A_\mu = 2 \partial_{[\mu} A_{\nu]}$

Rewritten as

$*d*F_{[2]} = 0$ & $dF_{[2]} = 0$

- where $F_{[2]} = \frac{1}{2} dx^\mu \wedge dx^\nu F_{\mu\nu}$ Faraday 2-form, $dx^\mu \wedge dx^\nu = -dx^\nu \wedge dx^\mu$
 $= dx^\mu \otimes dx^\nu - dx^\nu \otimes dx^\mu \in T^*M \otimes T^*M$
- $d : \Omega^p(M) \rightarrow \Omega^{p+1}(M)$ exterior derivative, $d^2 = 0$
- $*d* : \Omega^{p+1}(M) \rightarrow \Omega^p(M)$ co-differential

Hodge dual : $*(dx^{\mu_1} \wedge \dots \wedge dx^{\mu_p}) = \frac{1}{(n-p)!} \epsilon^{\mu_1 \dots \mu_p \nu_1 \dots \nu_{n-p}} dx^{\nu_1} \wedge \dots \wedge dx^{\nu_{n-p}}$, $*^2|_{\Omega^p} = (-1)^{p(n-p)+1} \text{Id}|_{\Omega^p}$

where $\epsilon^{\mu_1 \dots \mu_p \nu_1 \dots \nu_{n-p}} = \eta_{\nu_1 \epsilon_1} \dots \eta_{\nu_{n-p} \epsilon_{n-p}} \epsilon^{\mu_1 \dots \mu_p \epsilon_1 \dots \epsilon_{n-p}}$ (in Minkowski space M)

Duality :

$F_{[2]} \mapsto *F_{[2]}$

i.e. $\begin{pmatrix} \vec{E} \\ c\vec{B} \end{pmatrix} \mapsto \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} \begin{pmatrix} \vec{E} \\ c\vec{B} \end{pmatrix}$

Bianchi identity \leftrightarrow Field equations

On-shell duality for massless spin-2 field

Use condensed notation (X. Bekaert & N.B., 2002)

$$\underline{EI}: \quad \text{Tr } K \approx 0 \quad \Leftrightarrow \quad K^\mu{}_{\alpha\mu\nu} \approx 0 \quad , \quad \text{where } K = d^{(1)} d^{(2)} h \quad ,$$

$$\underline{BI}: \quad \text{Tr}_{12} * K \equiv 0 \quad \Leftrightarrow \quad K_{[\mu\nu]e\sigma} \equiv 0 \quad ,$$

$$\underline{EII}: \quad d^\dagger K \approx 0 \quad \Leftrightarrow \quad \partial^\mu K_{\mu\nu e\sigma} \approx 0 \quad ,$$

$$\underline{BII}: \quad dK \equiv 0 \quad \Leftrightarrow \quad \partial_{[\mu} K_{\nu e] \alpha\beta} \equiv 0 \quad .$$

$$\bullet \quad K \equiv K_{[2,2]} = \frac{1}{4} d^{(1)} x^\mu d^{(1)} x^\nu d^{(2)} x^\alpha d^{(2)} x^\beta K_{\mu\nu\alpha\beta}$$

$$\bullet \quad \text{dual } d_{(i)}^\dagger x^\mu \quad \text{s.t.} \quad \boxed{\{d^{(i)} x^\mu, d_{(i)}^\dagger x^\nu\} = \eta^{\mu\nu}} \quad ,$$

$$\bullet \quad d^{(i)} := d^{(i)} x^\mu \frac{\partial}{\partial x^\mu} \quad , \quad d_{(i)}^\dagger := d_{(i)}^\dagger x^\mu \frac{\partial}{\partial x^\mu} \quad ,$$

$$\bullet \quad \text{Tr}_{ij} = \eta_{\mu\nu} d_{(i)}^\dagger x^\mu d_{(j)}^\dagger x^\nu$$

As operators : $|K_{[2,2]} \rangle = \frac{1}{4} d^{(1)} x^\mu d^{(1)} x^\nu d^{(2)} x^\alpha d^{(2)} x^\beta |0\rangle$

$d_{(i)}^+ x^\mu |0\rangle \stackrel{!}{=} 0$ destruction .

$$[d^{(i)} x^\mu, d^{(j)} x^\nu]_{\mathbb{Z}_2} = 0, \quad [d^{(i)} x^\mu, d_{(j)}^+ x^\nu]_{\mathbb{Z}_2} = \delta_j^i \eta^{\mu\nu}.$$

Twisted-duality relations $K \mapsto *_1 K, \quad *_1 K \mapsto -K$

$$\vec{K} := \begin{pmatrix} K \\ *_1 K \end{pmatrix} \mapsto \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} \begin{pmatrix} K \\ *_1 K \end{pmatrix} = J \vec{K}, \quad J = \pi/2 \text{ rotation}.$$

$$\rightsquigarrow \begin{pmatrix} \text{BI} \\ \text{EII} \end{pmatrix} \leftrightarrow \begin{pmatrix} \text{BII} \\ \text{BI} \end{pmatrix} \text{ under duality.}$$

Example, $n=5$:

$$\left. \begin{array}{l} \text{BI} : \text{Tr}_{12} *_1 K \equiv 0 \\ \text{BII} : d K \equiv 0 \end{array} \right\} \Rightarrow K_{[2,2]} = d^{(1)} d^{(2)} h_{[1,1]}, \quad h \sim \begin{array}{|c|c|} \hline & \\ \hline \end{array}$$

$\tilde{K} := *_1 K$

$$(\text{EI}) : \text{Tr} K = 0 \stackrel{\text{duality}}{\Leftrightarrow} \text{Tr} *_1 \tilde{K} = 0 \text{ (BI)} \Leftrightarrow \tilde{K} \sim \begin{array}{|c|c|} \hline & \\ \hline \end{array}$$

$$(\text{EII}) : d^+ K = 0 \Leftrightarrow d \tilde{K} = 0 \text{ (BII)} \Leftrightarrow \tilde{K} \sim \begin{array}{|c|c|} \hline & \\ \hline \end{array} \begin{array}{|c|} \hline a \\ \hline \end{array}, \quad c \sim \begin{array}{|c|c|} \hline & \\ \hline \end{array} \equiv \tilde{h}$$

② (Higher) dualisations of linearised gravity and Maxwell's : OFF-SHELL

An off-shell dualisation was initiated in 2001 by P. West, completed in 2003 by N.B., S. Cnockaert and M. Henneaux.

In [N.B., P. Cook, D. Ponomarev-2012] \Rightarrow Other off-shell dualisations schemes proposed

First, review the dualisation of [West, N.B.-Cnockaert-Henneaux]

Parent action $S[\gamma^{ab}{}_{cd}, \omega_{abc}] = \int d^n x (\text{"}\omega\omega\text{"} + \partial_a \omega_{bc}{}^d \gamma^{ab}{}_{cd})$

$$Z = \int \mathcal{D}\omega \mathcal{D}\gamma \exp \frac{i}{\hbar} S[\omega, \gamma]$$

enforces $\omega_{abc} = \partial_{[a} e_{b]c}$

semi-classical $S[e_{ab}] = \text{Fierz-Pauli}$

with local Lorentz $\delta e_{ab} = \lambda_{ab}$

Field ω_{abc} auxiliary

$$\frac{\delta S}{\delta \omega} \approx 0 \Rightarrow \omega_{abc} \sim \partial^d \gamma_{abd}{}^c$$

$$S[\gamma^{ab}{}_{cd}] = \int d^n x (\partial^a \gamma_{ab}{}^0{}^c \partial_a \gamma^{ab}{}^0{}^c + \dots)$$

$$\gamma^{ab}{}_{cd}{}^e = \frac{1}{(n-3)!} \epsilon^{abcd_1 \dots d_{n-3}} C_{d[n-3]1e}$$

$$\text{Gauge inv. } \delta_\lambda \gamma^{ab}{}_{cd}{}^e = \delta_{[a}^e \lambda_{bc]} \Rightarrow \delta_\lambda C_{a[n-3]1b} = \epsilon_{a[n-3]bcd} \lambda^{cd}$$

$$C_{[n-3,1]} \rightsquigarrow C_{a_1 \dots a_{n-3}, b} = C_{[a_1 \dots a_{n-3}], b} \quad \text{s.t.} \quad C_{[a_1 \dots a_{n-3}, b]} \equiv 0$$

i.e. $C_{[n-3,1]} \sim \begin{array}{|c|} \hline \square \\ \hline \text{n-3} \\ \hline \end{array}$ of $GL(n)$ appears in Minkowski spacetime $\mathbb{R}^{1, n-1}$

that propagates the d.o.f. of Fierz-Pauli's graviton h_{ab} with $\eta^{bd} K_{ab, cd}(h) = 0$.

. We discussed: Hull's [2001] twisted *on-shell* duality

relating

$$K_{a_1 \dots a_{n-2}, b_1 b_2}(C) := \partial_{[a_1} \partial^{[b_1} C_{a_2 \dots a_{n-2}], b_2]}$$

to

$$K_{ab, cd}(h) := -\frac{1}{2} \partial_{[a} \partial^c h^{d]}_{b]}$$

via

$$K_{[n-2, 2]}(C) = *_1 K_{[2, 2]}(h)$$

2.1) Higher dual of vector field in dimensions 4 & 3

Idea : A_b viewed as a $A_{[0,1]}$ bi-form

$$A_{[0,1]} \xrightarrow{\text{higher dualise}} C_{[n-0-2,1]} \stackrel{n=4}{=} C_{[2,1]} \sim \begin{array}{|c|c|} \hline & \\ \hline \end{array}$$

$$\stackrel{n=3}{=} h_{[1,1]} \sim \begin{array}{|c|c|} \hline & \\ \hline \end{array}$$

• Starts from Maxwell and IBP : $S[A_a] = -\frac{1}{2} \int d^n x (\partial_a A_b \partial^a A^b - \partial_a A^a \partial_b A^b)$

• Parent action $S[Y^{ab}_c, P_{a,b}] = \int d^n x (P_{a,b} \partial_c Y^{cab} - \frac{1}{2} P_{a,b} P^{a,b} + \frac{1}{2} P^a_a P_b^b)$

$$\frac{\delta S[Y,P]}{\delta P_{a,b}} \approx 0 \Leftrightarrow P^{a,b} \approx \partial_c Y^{cab} - \eta^{ab} \frac{1}{n-1} \partial_c Y^{cd}_d$$

substitute to get

$$S[Y^{ab}_c] = \int d^n x \left[\frac{1}{2} \partial_c Y^{cab} \partial_d Y^d_{a,b} - \frac{1}{2(n-1)} \partial_a Y^{ab}_b \right]$$

. From

$$S[Y^{abc}] = \int d^n x \left[\frac{1}{2} \partial_c Y^{cab} \partial_d Y^d{}_{a1b} - \frac{1}{2(n-1)} \partial_a Y^{ab}{}_b \right]$$

invariant under $\delta Y^{abc} = \delta_c^{[a} \partial^{b]} \lambda + \partial_d \psi^{abd}{}_c$,

one decomposes

$$Y^{abc} = X^{abc} + \delta_c^{[a} Z^{b]} , \quad X^{ab}{}_b \equiv 0$$

irreducibly under $GL(n)$.

Ⓐ Hodge-dualise in 4D : $X^{abc} \xleftrightarrow{*} T_{abc} \sim \begin{array}{|c|c|} \hline a & b \\ \hline \end{array}$ that gauge transforms as

$$\delta \begin{array}{|c|c|} \hline & \\ \hline \end{array} = \begin{array}{|c|c|} \hline S & \\ \hline \end{array} + \begin{array}{|c|} \hline A \\ \hline \end{array}$$

with

$$\delta Z_a = \partial_a \lambda + \partial^b A_{ab} \quad \text{for the vector .}$$

Perform some change of field variables and dualize $Z_a \leftrightarrow \tilde{A}_a$ to get

$$S [T_{ab|c}, \tilde{A}_a] = \int d^4x \left[\mathcal{L}^{\text{curt.}}(T_{ab,c}) + \frac{1}{4} F^{ab}(\tilde{A}) F_{ab}(\tilde{A}) + \frac{1}{2} \tilde{A}^a K_a{}^b(T) \right]$$

where $K^{a[33]}{}_{b[22]} := 6 \partial^{[a} \partial_b T^{aa]}{}_{,b]}$ curvature, $K^{ab} := \text{Tr}^2 K$.

The gauge invariances are the ones expected for a Curtright field and a vector.

The field equations give $-\partial_a F^{ab}(\tilde{A}) + \frac{1}{2} K^{ab} = 0$ (1)

$$K^{,ab|c} + \delta_c^{[a} K^{,b]} - \frac{1}{2} \partial_c F^{ab} - \delta_c^{[a} \partial_d F^{b]d} = 0$$
 (2)

Take the trace of (2), combine with (1) to get the equations of motion and

duality relation $d^+ F_{[2]} = 0 = \text{Tr}^2 K_{[3,2]}$ & $\text{Tr} K_{[3,2]} = d_2 F_{[2,0]} \Rightarrow$ no doubling of d.o.f. !

③ Hodge-dualise in 3D

$S[\gamma^{ab}]$ with $\gamma^{ab}{}_c = \epsilon^{abd} h_{cd} + 2 \delta_c^{[a} z^{b]}$, $h_{ab} = h_{ba}$, giving an action $S[h_{ab}, z_a]$

$$S[h_{ab}, z_a] = \int d^3x \left[-\frac{1}{2} \partial_a h_{bc} \partial^a h^{bc} + \frac{1}{2} \partial_a h_{bc} \partial^b h^{ac} + \frac{1}{2} \epsilon^{bcd} \partial^a h_{ab} F_c(z) + \frac{1}{4} F^{ab}(z) F_{ab}(z) \right]$$

invariant under $\delta h_{ab} = 2 \partial_a \epsilon_b$, $\delta z_a = \partial_a \lambda + \epsilon_{abc} \partial^b \epsilon^c$

- Dualise the vector z_a in 3D to a scalar. After a field redefinition, one finds

$$S[h_{ab}, \phi] = \int d^3x \left[-\frac{1}{2} \partial_a h_{bc} \partial^a h^{bc} + \frac{1}{2} \partial_a h \partial^a h - \partial_a h \partial_b h^{ab} + \partial_a h^{ab} \partial^a h_{bc} + \frac{1}{2} \partial_a \phi \partial^a \phi + \partial_a \phi (\partial_b h^{ab} - \partial^a h) \right]$$

As consequence of field equations:

$$\square \phi \approx 0 \approx R(h) \quad \& \quad R_{ab}(h) \approx \partial_a \partial_b \phi$$

Field equations for propagation & duality relation = no doubling

2.2) Higher dualisations of Maxwell's in 3D

- Maxwell in 3D \sim massless scalar in 3D: 1 propagating d.o.f.
- Start from the dual action obtained by the second higher dualisation of scalar theory, i.e. the first higher dualisation of Maxwell's vector reviewed above

$$S[h_{ab}, Z_a] = \int d^3x \left[-\frac{1}{2} \partial_a h_{bc} \partial^a h^{bc} + \frac{1}{3} \partial_a h_{bc} \partial^b h^{ac} + \frac{1}{2} \epsilon^{bcd} \partial^a h_{ab} F_{cd}(Z) + \frac{1}{4} F^{ab}(Z) F_{ab}(Z) \right]$$

We perform the higher dualisation \mathcal{D} of h_{ab} via parent action $S[G_{a|bc}, D_{ab|}{}^{cd}, A_a]$,

eliminate the auxiliary field $G_{a|bc}$ to obtain $S[D_{ab|}{}^{cd}, A_a]$. As before, $\tilde{D}^{a|ij} := -\frac{1}{2} \epsilon^{abc} D_{bc|}{}^{ij}$.

Perform a field redefinition $\{ \underbrace{\tilde{D}_{a|cd}}_{15}, \underbrace{A_a}_{3} \} \longleftrightarrow \{ \underbrace{\phi_{abc}}_{10}, \underbrace{f_{ab}}_{5}, \underbrace{U_a}_{3}, \underbrace{A_a}_{3} \}$ where $f_{ab} \sim \square$ of $SO(3)$.

s.t. U_a enters the action only via $F_{ab}(U) = 2 \partial_{[a} U_{b]}$. Dualise U_a in 3D to a scalar σ that one adds

to $f_{ab} \rightarrow h_{ab}$ traceful.

The final action is invariant under

$$\left\{ \begin{array}{l} \delta \phi_{abc} = 3 \partial_{[a} \zeta_{bc)} \\ \delta h_{ab} = 2 \partial_{[a} \epsilon_{b)} + 2 \epsilon_{[a} \eta_{b)} \partial^p \zeta^p \\ \delta A_a = \frac{2}{3} \partial_a \zeta + \epsilon_{abc} \partial^b \epsilon^c \end{array} \right.$$

Rem: $\delta(\underbrace{\phi_{abc} - \frac{2}{3} \eta_{[ab} A_{c)}}_{\varphi_{abc}}) = 3 \partial_{[a} \zeta_{bc)} - \frac{2}{3} \eta_{[ab} \epsilon_{c]pq} \partial^p \epsilon^q$.

Field equations: seemingly too many propagating d.o.f. since one finds that

- $\bar{K}_{ab}(\phi) \approx 0$ where $\bar{K}_{ab} := \eta^{cd} \eta^{ij} K_{abicciddj}$ and $K_{abicediej} := \mathfrak{R} \begin{array}{|c|c|c|} \hline a & c & e \\ \hline b & d & f \\ \hline \end{array}$ curvature of ϕ_{abc} .
- $\bar{R}^{ab}{}_{ab} \approx 0$ where $\bar{R}{}_{ab}{}^{cd} = K_{ab}{}^{cd}(h) - 2(\epsilon_{abm} \partial^{[c} \psi^{d]m} + \epsilon^{cdm} \partial_{[a} \psi_{b]m})$, $\psi^a{}_b := \partial_b \phi^a - \partial^c \phi^a{}_{bc}$
 \hookrightarrow Riemann-like curvature for h_{ab} .
- $\partial_a \tilde{F}^{ob} \approx 0$ where $\tilde{F}_{ab} := F_{ab}(A) + \partial_{[a} \phi_{b]c}{}^c + \epsilon_{abc}(\partial_d h^{cd} - \mathcal{L} h)$ field strength for A_a .

However, combining the field equation, one finds the duality relations

$$K_{abcd}(\phi) \approx -\frac{8}{21} \epsilon_{efg} \partial^g \tilde{R}_{abcd}$$

$$\tilde{R}{}^{ab}{}_{cd} \approx \frac{7}{4} \epsilon_{cdm} \partial^m \tilde{F}{}^{ab}$$

$$\Rightarrow K_{abcd}(\phi) \approx -\frac{2}{3} \epsilon_{cdp} \epsilon_{efg} \partial^p \partial^g \tilde{F}{}^{ab} \quad ,$$

All the duality relations and E.o.M come out of the action.

2.3) Higher dualisation of the graviton in 3D

Gravity in 3D is topological. Dual formulation thereof by higher dualisation \rightarrow higher spin

$$\bullet S[G_{a|bc}, D_{ab|}{}^{cd}] = \int d^3x \left[-\frac{1}{2} G_{a|bc} G^{a|bc} + \frac{1}{2} G_{a|c}{}^c G^{a|b}{}_b - G_{a|}{}^{ab} G_{b|c}{}^c + G_{a|}{}^{ab} G^{c|}{}_c{}_b + G^{d|}{}_{bc} \partial^a D_{ad|}{}^{bc} \right]$$

$$G_{a|bc} = G_{a|c|b} \quad , \quad D_{ab|}{}^{cd} = -D_{ba|}{}^{cd} = -D_{ba|}{}^{dc}$$

Gauge-invariant under

$$\delta G^a{}_{|bc} = 2 \partial^a \partial_{[b} \epsilon_{c]} \quad , \quad \delta D_{ab|}{}^{cd} = \epsilon_{abp} \partial^p \nu^{cd} + 2 \eta^{cd} \partial_{[a} \epsilon_{b]} + 4 \delta_{[a}^{[c} \partial_{b]} \epsilon^{d]}$$

$$\bullet \frac{\delta S}{\delta D} \approx 0 \Rightarrow G_{a|bc} \approx \partial_a h_{bc} \quad \text{with} \quad h_{ab} = h_{ba} \quad \text{symmetric}$$

$$\hookrightarrow S[\partial_a h_{bc}, D_{ab|}{}^{cd}] = \int d^3x \left[-\frac{1}{2} \partial_a h_{bc} \partial^a h^{bc} + \frac{1}{2} \partial_a h \partial^a h - \partial_a h^{ab} \partial_b h + \partial_a h^{ab} \partial^c h_{bc} \right]$$

Fierz-Pauli

$$\bullet \frac{\delta S}{\delta G_{a|bc}} \approx 0 \Rightarrow G_{a|bc} \approx \partial^d D_{da|bc} + \partial D =: G_{a|bc}(\partial D)$$

$$\hookrightarrow S[G_{a|bc}(\partial D), D_{ab|}{}^{cd}] =: S[D_{ab|}{}^{cd}] \quad \text{Dual action}$$

$$D_{ab}{}^{pq} =: \epsilon_{abm} \tilde{D}^{m1pq} \quad , \quad \tilde{D}{}^{abcd} = \tilde{\varphi}{}^{acd} + 2 \epsilon^{abc} Z_{b1}{}^d \quad , \quad Z_{a1}{}^a \equiv 0$$

Gl(3) decomposition

- Further decompose under SO(3):

$$\tilde{D}{}^{abc} \sim \square \otimes (\square \oplus \bullet) \simeq \square \oplus \square \oplus \square \oplus \square \in \text{SO}(3)$$

- A linear combination of the two vectors can be dualised to a scalar, in 3D.
- Combining the scalar with $\square \rightarrow$ traceful $h_{ab} \sim \square \in \text{Gl}(3)$
- Traceless rank-3 with remaining vector \rightarrow traceful $\varphi_{abc} \sim \square \in \text{Gl}(3)$
- Final spectrum : $\{ \varphi_{abc}, h_{ab} \}$.

- Gauge transformations :

$$\begin{cases} \delta \varphi_{abc} = 3 \partial_{[a} \hat{\xi}_{bc]} - \frac{2}{3} \varepsilon_{[a}{}^{pq} \eta_{bc]} \partial_p \varepsilon_q \\ \delta h_{ab} = 2 \partial_{[a} \varepsilon_{b]} + 2 \varepsilon_{pq[a} \partial^p \hat{\xi}^q{}_{b]} \end{cases} ,$$

- Action :

$$\begin{aligned} S[\varphi_{abc}, h_{ab}] = \frac{1}{2} \int d^3x & \left[-\partial_a \varphi_{bcd} \partial^a \varphi^{bcd} + \partial^a \varphi^b \partial^c \varphi_{abc} + \partial_a \varphi^{abc} \partial^d \varphi_{bcd} - \frac{1}{7} \partial_a \varphi_b \partial^a \varphi^b - \frac{31}{28} \partial_a \varphi^a \partial^b \varphi_b \right. \\ & + \frac{1}{2} \partial_a h_{bc} \partial^a h^{bc} + \frac{1}{14} \partial_a h \partial^a h - \frac{3}{7} \partial^a h_{ab} \partial^b h^{bc} - \frac{1}{7} \partial_a h \partial_c h^{ac} \\ & \left. + \frac{10}{7} \varepsilon_{apq} \partial^b h_b{}^a \partial^p \varphi^q - 2 \varepsilon_{apq} \partial^b h^{ac} \partial^p \varphi^q{}_{bc} \right] \end{aligned}$$

- Gauge transformations entangled
- "Wrong" relative kinetic term

2.4) Relation with the triplet spin-2

The action $S[h_{ab}, z_a]$ derived above is a member of the 1-parameter family

$$S[h_{ab}, A_a] = \frac{1}{2} \int d^3x \left[-\partial_a h_{bc} \partial^a h^{bc} + (\alpha+2) \partial_a h_a \partial^a h^a - (\alpha+1) \partial^a h (2 \partial_a h_a - \partial_a h) \right. \\ \left. - \frac{\alpha}{2} F_{ab}(A) F^{ab}(A) - \alpha \epsilon_{abc} \partial_a h^a F^{bc}(A) \right]$$

invariant under

$$\delta h_{ab} = 2 \partial_{[a} \epsilon_{b]}, \quad \delta A_a = \partial_a \lambda + \epsilon_{abc} \partial^b \epsilon^c .$$

The case obtained by off-shell dualisation corresponds to $\alpha = -1$.

. As above, one dualises the vector $A_a \rightarrow \varphi$ scalar in 3D:

$$S[h_{ab}, \varphi] = \frac{1}{2} \int d^3x \left[-\partial_a h_{bc} \partial^a h^{bc} + 2 \partial_a h_a \partial^a h^a - (\alpha+1) \partial^a h (2 \partial_a h_a - \partial_a h) \right. \\ \left. - 4\alpha (\partial_a \varphi \partial^a \varphi - \varphi \partial^a \partial^b h_{ab}) \right]$$

$$S[h_{ab}, \varphi] = \frac{1}{2} \int d^n x \left[-2 h_{bc} \partial^a h^{bc} + 2 \partial_a h_a \partial \cdot h^a - (\alpha+1) \partial^2 h (2 \partial \cdot h_a - \partial_a h) \right. \\ \left. - 4\alpha (\partial_a \varphi \partial^a \varphi - \varphi \partial^a \partial^a h_{ab}) \right] \quad (*)$$

Invariant under $\delta h_{ab} = 2 \partial_{(a} \epsilon_{b)}$, $\delta \varphi = -\partial^a \epsilon_a$

This is equivalent, when $\alpha=1$, to the *triplet* system

$$S[h_{ab}, C_a, \mathcal{D}] = \int d^n x \left[-\frac{1}{2} \partial_a h_{bc} \partial^a h^{bc} + 2 C^a \partial_a h_a + 2 \partial \cdot C \mathcal{D} + \partial_a \mathcal{D} \partial^a \mathcal{D} - C^a C_a \right]$$

Invariant under $\delta h_{ab} = 2 \partial_{(a} \epsilon_{b)}$, $\delta C_a = \square \epsilon_a$, $\delta \mathcal{D} = \partial \cdot \epsilon$

The field C_a is auxiliary, its e.o.m. give $C_a = \partial_a h_a - \partial_a \mathcal{D}$.

Substituting inside the *triplet* action $S[h_{ab}, C_a, \mathcal{D}]$ reproduces the action (*)

for $n=3$, $\alpha=-1$ and $\mathcal{D} = -\varphi$

2.5) Spin 3 / Spin 2 system

The action shown above

$$\begin{aligned}
 S[\varphi_{abc}, h_{ab}] = \frac{1}{2} \int d^3x & \left[-\partial_a \varphi_{bcd} \partial^a \varphi^{bcd} + \partial^a \varphi^b \partial^c \varphi_{abc} + \partial_a \varphi^{abc} \partial^d \varphi_{bcd} - \frac{1}{7} \partial_a \varphi_b \partial^a \varphi^b - \frac{3!}{28} \partial_a \varphi^a \partial^b \varphi_b \right. \\
 & + \frac{1}{2} \partial_a h_{bc} \partial^a h^{bc} + \frac{1}{14} \partial_a h \partial^a h - \frac{3}{7} \partial^a h_{ab} \partial^b h^{bc} - \frac{1}{7} \partial_a h \partial_c h^{ac} \\
 & \left. + \frac{10}{7} \varepsilon_{apq} \partial^b h_b^a \partial^p \varphi^q - 2 \varepsilon_{apq} \partial^b h^{ac} \partial^p \varphi^q_{bc} \right]
 \end{aligned}$$

invariant under $\delta \varphi_{abc} = 3 \partial_{[a} \hat{\xi}_{bc)}$, $-\frac{2}{3} \varepsilon_{[a}{}^{pq} \eta_{bc)} \partial_p \varepsilon_q$, $\delta h_{ab} = 2 \partial_{[a} \varepsilon_{b)}$, $+ 2 \varepsilon_{pq(a} \partial^p \hat{\xi}^q_{b)}$

is a member of the family

$$\begin{aligned}
 S[\varphi_{abc}, h_{ab}] = \frac{1}{2} \int d^3x & \left[a_0 \partial_a \varphi_{bcd} \partial^a \varphi^{bcd} + a_1 \partial^a \varphi^b \partial^c \varphi_{abc} + a_2 \partial_a \varphi^{abc} \partial^d \varphi_{bcd} + a_3 \partial_a \varphi_b \partial^a \varphi^b + a_4 \partial_a \varphi^a \partial^b \varphi_b \right. \\
 & + b_0 \partial_a h_{bc} \partial^a h^{bc} + b_1 \partial_a h \partial^a h + b_2 \partial^a h_{ab} \partial^b h^{bc} + b_3 \partial_a h \partial_c h^{ac} \\
 & \left. + c_1 \varepsilon_{apq} \partial^b h_b^a \partial^p \varphi^q + c_2 \varepsilon_{apq} \partial^b h^{ac} \partial^p \varphi^q_{bc} \right]
 \end{aligned}$$

invariant under

$$\delta \varphi_{abc} = 3 \partial_{[a} \hat{\xi}_{bc)}, -3 \varepsilon_{[a}{}^{pq} \eta_{bc)} \partial_p \varepsilon_q, \delta h_{ab} = 2 \partial_{[a} \varepsilon_{b)} - 2 \varepsilon_{pq(a} \partial^p \hat{\xi}^q_{b)}$$

- We find that $\bar{z} = 0$ iff $x = 0$.

In that case, $c_1 = 0 = c_2$.

The action is the sum or difference of Frensdal and Fierz-Pauli actions

↳ We reject that case, hence $x \neq 0$ and $\bar{z} \neq 0$

- For the traceless part $\hat{\Phi}_{abc}$ to appear in the action,

a_0, a_1, a_2 and c_2 cannot all vanish

and as a result we find the $b_0 \neq 0$.

- Finally, the parameters are fixed uniquely in terms of z and $\gamma = \text{sign}(b_0)$

in the case $a_0 = -1$ that one reaches by rescaling φ_{abc} .

One parameter and one sign:
$$\alpha = -\frac{z\gamma z}{9(3\gamma z^2 - z)}, \quad \gamma = \pm 1.$$

For $\gamma = +1$, $z = \pm \sqrt{\frac{2}{3}}$ rejected since it amounts to removing the piece $\partial_{(a} \epsilon_{b)}$ in δh_{ab} .

Rem. :

- There is an isolated point where $a_0 = 0$.

By rescaling φ_{abc} so that $a_2 = -1$, all the other coefficients are fixed uniquely.

- One shows that these systems are *not* equivalent to any known indecomposable (triplet-like) systems.
- The original system obtained by higher dualisation of the Fierz-Pauli action is recovered for

$$\gamma = +1, \quad z = -1 \quad \Rightarrow \quad \alpha = \frac{2}{9}.$$

③ First-order reformulation of the spin 2 - spin 3 systems & Deformations

3.1) In flat space

A theorem [M. Grigoriev, K. Martchyan, E. Skvortsov 2005] states that all topological systems in 3D are equivalent to Chern-Simons-like models.

We find that, with the Lorentz-valued one-forms $(e^a, \omega^a, E^{aa}, \Omega^{aa})$,

the action

$$S = \int_{M_3} \left[\omega_a (de^a - \frac{1}{2} \varepsilon^{apq} h_p \omega_q) + 2z \omega_a h_b \Omega^{ab} + \frac{2z}{3x} \Omega_{aa} (dE^{aa} + \frac{2}{3} \varepsilon^{abc} h_b \Omega_c^a) \right]$$

invariant under

$$x = -\frac{2\gamma z}{3(3\gamma^2 - 2)}$$

$$\delta e^a = de^a - \varepsilon^{abc} h_b \tilde{\lambda}_c + 2z h_b \tilde{\alpha}^{ab}, \quad \delta \omega^a = d\tilde{\lambda}^a,$$

$$\delta E^{aa} = d\tilde{\xi}^{aa} + \frac{4}{3} h_b \varepsilon^{abc} \tilde{\alpha}_c^a - 3x (h^a \tilde{\lambda}^a - \frac{1}{3} \eta^{aa} h^b \tilde{\lambda}_b), \quad \delta \Omega^{aa} = d\tilde{\alpha}^{aa}$$

• This action exactly reproduces the 2nd order action $S[h_{ab}, \varphi_{abc}]$

presented above upon (i) eliminating the auxiliary fields (ω^a, Ω^{aa}) .

(ii) fixing the Lorentz gauges where $e_{[a,b]}^{(*)} = 0$ & $E_{a,bc} \Big|_{\widehat{\begin{smallmatrix} b \\ a \end{smallmatrix}}}^{(*)} = 0$

• Recall

$$\delta E_{a,b} = \partial_a \epsilon_b - \Lambda_{ab} + 2z \tilde{\alpha}_{ab}$$

$$\delta E_{a,bc} = \partial_a \xi_{bc} - \alpha_{bc,a} + \alpha (\eta_{bc} \tilde{\lambda}_a - 3 \eta_{a(b} \tilde{\lambda}_{c)})$$

where

$$\tilde{\alpha}_{ab} := \frac{1}{2} \epsilon_{apq} \alpha_b^{p,q}, \quad \tilde{\lambda}_a := \frac{1}{2} \epsilon_{abc} \Lambda^{bc}, \quad \alpha_{bc,a} \sim \widehat{\begin{smallmatrix} b & c \\ a \end{smallmatrix}}$$

• The residual gauge transformations are $\alpha_{a,bc}^{res} = \partial_a \xi_{bc} \Big|_{\widehat{\begin{smallmatrix} b \\ a \end{smallmatrix}}}$, $\Lambda_{ab}^{res} = \partial_{[a} \epsilon_{b]}$

In this gauge, the fields $\varphi_{abc} := 3 E_{(a,bc)}$ and $h_{ab} = z E_{(a,b)}$ transform as

$$\delta \varphi_{abc} = 3 \partial_{(a} \xi_{bc)}, -3 \alpha \epsilon_{(a}^{pq} \eta_{bc)} \partial_p \epsilon_q, \quad \delta h_{ab} = z \partial_{(a} \epsilon_{b)} - z z \epsilon_{pq(a} \partial^p \xi^q_{b)}$$

- One can express the action as

$$S = \int_{M_3} [\omega_a R^a(e) + e_a R^a(\omega) + \frac{2z}{3\alpha} (\Omega_{ab} R^{ab}(E) + E_{ab} R^{ab}(\Omega))] \quad (*)$$

where $R^a(e) := de^a - \varepsilon^{apq} h_p \omega_q + 2z h_b \Omega^{ab}$, $R^a(\omega) := d\omega^a$,

$$\alpha = -\frac{2\gamma z}{3(3\gamma^2 - 2)}$$

$$R^{ab}(E) := dE^{ab} + \frac{4}{3} h_p \varepsilon^{pqa} \Omega_q^b - 3\alpha (h^a \omega^a - \frac{1}{3} \eta^{ab} h^b \omega_b)$$
 , $R^{ab}(\Omega) = d\Omega^{ab}$.

3.2) There is no non-Abelian extension (alas)

Search for $S[e^a, \omega^a, E^{ab}, \Omega^{ab}] = \int_{M_3} \text{Tr} (A dA + \frac{1}{3} A^3)$,

• $A = \omega^a J_a + (h^a + e^a) P_a + \frac{1}{2} \Omega^{ab} J_{ab} + E^{ab} P_{ab}$,

• $\text{Tr}(J_a P_b) = \eta_{ab}$ • $\text{Tr}(J_{ab} P_{cd}) = \frac{2}{3\alpha} (\eta_{ac} \eta_{bd} + \eta_{ad} \eta_{bc} - \frac{2}{3} \eta_{ab} \eta_{cd})$.

Initial data for a possible non-Abelian algebra: $[P_a, J_b] = -\varepsilon_{abc} P^c - 3\alpha P_{ab}$, $[P_a, P_b] = 0 = [P_a, P_{bc}]$,

$$[P_a, J_{bc}] = 2z (\eta_{arb} P_c - \frac{1}{3} \eta_{bc} P_a) + \frac{4}{3} e_{arb} P_{cm}$$

General Ansatz for the other commutators \rightarrow No solution for Jacobi identities (20 identities to be checked)

3.3) Extension to $(A)dS_3$

$$\nabla^2 V^a = -\sigma h^a h_b V^b, \quad \sigma = +1 \text{ for } AdS_3, \quad \sigma = -1 \text{ for } dS_3.$$

We can keep the action in the same form (*) as above

$$S = \int_{M_3} [\omega_a R^a(e) + e_a R^a(\omega) + \frac{2z}{3z} (\Omega_{ab} R^{ab}(E) + E_{ab} R^{ab}(\Omega))] \quad (*)$$

for the deformed curvatures

$$\begin{aligned} R^a(e) &= \nabla e^a + \lambda x_1 \varepsilon^{abc} h_b e_c + x_2 \varepsilon^{abc} h_b \omega_c + \lambda x_3 h_b E^{ab} + x_4 h_b \Omega^{ab}, \\ R^a(\omega) &= \nabla \omega^a + \lambda^2 x_5 \varepsilon^{abc} h_b \omega_c + \lambda x_6 \varepsilon^{abc} h_b \omega_c + \lambda^2 x_7 h_b E^{ab} + \lambda x_8 h_b \Omega^{ab}, \\ R^{aa}(E) &= \nabla E^{aa} + \lambda x_9 (h^a e^a - \frac{1}{3} \eta^{aa} h^b e_b) + x_{10} (h^a \omega^a - \frac{1}{3} \eta^{aa} h^b \omega_b) \\ &\quad + \lambda x_{11} h_b \varepsilon^{abc} E_c^a + x_{12} h_b \varepsilon^{abc} \Omega_c^a, \\ R^{aa}(\Omega) &= \nabla \Omega^{aa} + \lambda^2 x_{13} (h^a e^a - \frac{1}{3} \eta^{aa} h^b e_b) + \lambda x_{14} (h^a \omega^a - \frac{1}{3} \eta^{aa} h^b \omega_b) \\ &\quad + \lambda^2 x_{15} h_b \varepsilon^{abc} E_c^a + \lambda x_{16} h_b \varepsilon^{abc} \Omega_c^a. \end{aligned}$$

The corresponding gauge transformations being

$$\delta \begin{pmatrix} \lambda e^a \\ \omega^a \end{pmatrix} = \nabla \begin{pmatrix} \lambda \xi^a \\ \tilde{\Lambda}^a \end{pmatrix} + \lambda A \varepsilon^{abc} h_b \begin{pmatrix} \lambda \xi_c \\ \tilde{\Lambda}_c \end{pmatrix} + \lambda B h_b \begin{pmatrix} \lambda \xi^{ab} \\ \tilde{\alpha}^{ab} \end{pmatrix},$$

$$\delta \begin{pmatrix} \lambda E^{aa} \\ \Omega^{aa} \end{pmatrix} = \nabla \begin{pmatrix} \lambda \xi^{aa} \\ \tilde{\alpha}^{aa} \end{pmatrix} + \lambda C (h^a \delta_b^a - \frac{1}{3} \eta^{aa} h_b) \begin{pmatrix} \lambda \xi^b \\ \tilde{\Lambda}^b \end{pmatrix} + \lambda D \varepsilon^{abc} h_b \begin{pmatrix} \lambda \xi_c^a \\ \tilde{\alpha}_c^a \end{pmatrix},$$

with the numerical matrices explicitly given by

$$A = \begin{pmatrix} x_1 & x_2 \\ x_5 & x_6 \end{pmatrix}, \quad B = \begin{pmatrix} x_3 & x_4 \\ x_7 & x_8 \end{pmatrix}, \quad C = \begin{pmatrix} x_9 & x_{10} \\ x_{13} & x_{14} \end{pmatrix}, \quad D = \begin{pmatrix} x_{11} & x_{12} \\ x_{15} & x_{16} \end{pmatrix}.$$

The requirement of gauge invariance of the curvatures gives sixteen quadratic equations on the parameters x_i . In matrix form, they read

$$\begin{aligned} A^2 - \frac{5}{6} BC &= \sigma I, \\ \frac{1}{2} D^2 + CB &= 2\sigma I, \\ -\frac{3}{2} DC + CA &= 0, \\ -\frac{3}{2} BD + AB &= 0. \end{aligned}$$

A particularly simple solution is given by

$$A = \begin{pmatrix} 0 & 1 \\ \frac{3\sigma}{4} & 0 \end{pmatrix}, \quad B = \begin{pmatrix} 0 & 1 \\ \frac{3\sigma}{2} & 0 \end{pmatrix} = C, \quad D = \begin{pmatrix} 0 & 1 \\ \sigma & 0 \end{pmatrix}.$$

(It's not the only one)

Field redefinitions and flat limit

The redefined fields
$$\begin{pmatrix} \lambda e^a \\ \omega^a \end{pmatrix} = M \begin{pmatrix} \lambda e'^a \\ \omega'^a \end{pmatrix}, \quad \begin{pmatrix} \lambda E^{aa} \\ \Omega^{aa} \end{pmatrix} = N \begin{pmatrix} \lambda E'^{aa} \\ \Omega'^{aa} \end{pmatrix}$$

with redefined gauge parameters
$$\begin{pmatrix} \lambda \tilde{\gamma}^a \\ \tilde{\lambda}_a \end{pmatrix} = M \begin{pmatrix} \lambda \tilde{\gamma}'^a \\ \tilde{\lambda}'_a \end{pmatrix}, \quad \begin{pmatrix} \lambda \tilde{\gamma}^{aa} \\ \tilde{\lambda}'_{aa} \end{pmatrix} = N \begin{pmatrix} \lambda \tilde{\gamma}'^{aa} \\ \tilde{\lambda}'_{aa} \end{pmatrix}$$

where $M, N \in GL(2, \mathbb{R})$

will be related by the same transformation laws,

with $A' = M^{-1} A M$, $B' = M^{-1} B N$, $C' = N^{-1} C M$, $D' = N^{-1} D N$

↪ Two solutions of \square related by $GL(2, \mathbb{R}) \times GL(2, \mathbb{R})$ are regarded as equivalent.

Also, if (A, B, C, D) is a solution, then so is $(-A, -B, -C, -D)$.

Classification of the solutions

- Using $GL(2, \mathbb{R}) \times GL(2, \mathbb{R})$, the matrices (A, B, C, D) can be brought to one of

$$\begin{pmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{pmatrix}, \begin{pmatrix} \lambda & 1 \\ 0 & \lambda \end{pmatrix} \quad \text{or} \quad \begin{pmatrix} \mu & -\nu \\ \nu & \mu \end{pmatrix} \quad \text{all in } \text{Mat}(2, \mathbb{R}).$$

- A detailed analysis shows that there are **two** general classes of solutions:

1. The 4 matrices are real diagonal. This **requires** $\sigma = 1$, **AdS₃** background

2. The 4 matrices are all antisymmetric ($\mu = 0$).

↳ This **requires** $\sigma = -1$, **dS₃** background

In the flat case where formally $\sigma = 0$, we recover our previous results.

1. When the 4 matrices are diagonal, the fields (e^a, E^{aa}) and (ω^a, Ω^{aa})

form *two decoupled* systems, each noted (f^a, F^{aa}) , with gauge

transformations

$$\begin{cases} \delta f^a = \nabla \epsilon^a + \lambda a \varepsilon^{abc} h_b \epsilon_c + \lambda b h_b \epsilon^{ab}, \\ \delta F^{aa} = \nabla \epsilon^{aa} + \lambda c (h^a \delta_b^a - \frac{1}{3} \eta^{aa} h_b) \epsilon^b + \lambda d \varepsilon^{abc} h_b \epsilon_c^a, \end{cases}$$

$(a, b, c, d) \in \mathbb{R}^4$ constrained by

$$\begin{aligned} a^2 - \frac{5}{6} bc &= \sigma, & \frac{1}{2} d^2 + bc &= 2\sigma, \\ -\frac{3}{2} dc + ca &= 0, & -\frac{3}{2} bd + ab &= 0. \end{aligned}$$

There exist solutions only in AdS_3 ($\sigma=1$).

↳ There is a solution where the spin-2 and spin-3 sectors of the system (f^a, F^{aa})

do not mix: $a=1$, $b=0=c$, $d=\pm 2$ no free limit of single $SL(3, \mathbb{R})$ CS

↳ A more interesting solution mixes the two sectors (spin 2 and spin 3): $b \neq 0$, $c \neq 0$.

$$a = \frac{3}{2}, \quad b = 1, \quad c = \frac{3}{2}, \quad d = 1$$

When the 2 systems $(f_{(i)}^a, F_{(i)}^{aa})$ $i=1,2$ are considered simultaneously,

(e^a, E^{aa}) & (ω^a, Ω^{aa}) , we can combine the 2 solutions above.

Using the freedom $(a, b, c, d) \mapsto (-a, -b, -c, -d)$, there remain

- 2 solutions where the 2 systems mix spin 2 & spin 3:

$$A_1 = \frac{3}{2} \begin{pmatrix} 1 & 0 \\ 0 & \eta_1 \end{pmatrix}, \quad B_1 = \begin{pmatrix} 1 & 0 \\ 0 & \eta_1 \end{pmatrix}, \quad C_1 = \frac{3}{2} \begin{pmatrix} 1 & 0 \\ 0 & \eta_1 \end{pmatrix}, \quad D_1 = \begin{pmatrix} 1 & 0 \\ 0 & \eta_1 \end{pmatrix}, \quad \eta = \pm 1, \quad \sigma = +1,$$

and

- 4 solutions when only one system, say (e^a, E^{aa}) , mixes spin 2 & spin 3.

$$A_2 = \begin{pmatrix} \frac{3}{2} & 0 \\ 0 & \eta_1 \end{pmatrix}, \quad B_2 = \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}, \quad C_2 = \begin{pmatrix} \frac{3}{2} & 0 \\ 0 & 0 \end{pmatrix}, \quad D_2 = \begin{pmatrix} 1 & 0 \\ 0 & 2\eta_2 \end{pmatrix}, \quad \eta_i = \pm 1, \quad \sigma = +1.$$

(we exclude the cases where $B=0=C$)

2. Antisymmetric case The other solutions for the system of constraints for the matrices (A, B, C, D) are

$$A_3 = \frac{3}{2} \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}, \quad B_3 = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}, \quad C_3 = \frac{3}{2} \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}, \quad D_3 = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} \quad \sigma = -1 \mapsto dS_3.$$

Concl: 1. & 2. fully classify the solutions of the system of constraints on (A, B, C, D)

Rem: Using $(M, N) \in GL(2, \mathbb{R})$, the solution (A_1, B_1, C_1, D_1) with $\eta = -1$ in AdS_3

and the solution (A_3, B_3, C_3, D_3) in dS_3 can be brought in a unified form

$$A_0 = \begin{pmatrix} 0 & 1 \\ \frac{3\sigma}{4} & 0 \end{pmatrix}, \quad B_0 = \begin{pmatrix} 0 & 1 \\ \frac{3\sigma}{2} & 0 \end{pmatrix} = C_0, \quad D_0 = \begin{pmatrix} 0 & 1 \\ \sigma & 0 \end{pmatrix} \quad \text{where } \sigma = \pm 1.$$

[This form does not cover the case $\eta = +1$ of (A_1, B_1, C_1, D_1) , or (A_2, B_2, C_2, D_2)]

Actions in (A)dS₃

$$S[e^a, E^{aa}, \omega^a, \Omega^{aa}] = \frac{1}{2\lambda} \int_{M_3} \left[(\lambda e_a \ \omega_a) G \begin{pmatrix} \lambda R^a(e) \\ R^a(\omega) \end{pmatrix} + (\lambda E_{aa} \ \Omega_{aa}) H \begin{pmatrix} \lambda R^{aa}(E) \\ R^{aa}(\Omega) \end{pmatrix} \right]$$

where G & H non-degenerate and symmetric

• Gauge-invariance of S implies

$$A^T G - G A = 0, \quad G B + C^T H = 0, \quad D^T H - H D = 0,$$

where $G' = M^T G M$ and $H' = N^T H N$ equivalent to (G, H) .

Ⓐ In the solutions for (A, B, C, D) where they are *all diagonal*, G & H can also be taken diagonal.

A.1) When the system (f^a, F^{aa}) *does not* mix spin 2 & spin 3, we get

$$S[f^a, F^{aa}] = \frac{1}{2} \int_{M_3} (f_a R^a(f) \pm F_{aa} R^{aa}(F)) \quad \text{with} \quad R^a(f) = \nabla f^a + \lambda \epsilon^{abc} h_b f_c,$$

$$R^{aa}(F) = \nabla F^{aa} \pm 2\lambda \epsilon^{abc} h_b F_c^a.$$

A.2) When the system (f^a, F^{aa}) does mix spin 2 & spin 3, we get

with

$$S[f^a, F^{aa}] = \frac{1}{2} \int_{M_3} (f_a R^a(f) - \frac{2}{3} F_{aa} R^{aa}(F))$$

$$R^a(f) = \nabla f^a + \frac{3}{2} \lambda \varepsilon^{abc} h_b f_c + \lambda h_b F^{ab},$$

$$R^{aa}(F) = \nabla F^{aa} + \frac{3}{2} \lambda (h^a \delta_b^a - \frac{1}{3} \eta^{aa} h_b) f^b + \lambda \varepsilon^{abc} h_b F_c^a.$$

• Putting the two systems $(f_{(i)}^a, F_{(i)}^{aa})$ together, we find

$$G_1 = \begin{pmatrix} 1 & 0 \\ 0 & \tau \end{pmatrix}, \quad H_1 = -\frac{2}{3} \begin{pmatrix} 1 & 0 \\ 0 & \tau \end{pmatrix} \quad \text{for } (A_1, B_1, C_1, D_1)$$

where $\tau = \pm 1$ and both signs of η ,

and $G_2 = \begin{pmatrix} 1 & 0 \\ 0 & \tau_1 \end{pmatrix}$, $H_2 = \begin{pmatrix} -\frac{2}{3} & 0 \\ 0 & \tau_2 \end{pmatrix}$ for (A_2, B_2, C_2, D_2) , $\tau_i = \pm 1$.

Rem: Exotic kinetic terms $e de$ and $w dw$.

ⓑ In the case where (A_3, B_3, C_3, D_3) are antisymmetric, only in dS_3 ,

one uses the $GL(2, \mathbb{R}) \times GL(2, \mathbb{R})$ gauge

$$A_0 = \begin{pmatrix} 0 & 1 \\ \frac{3\sigma}{4} & 0 \end{pmatrix}, \quad B_0 = \begin{pmatrix} 0 & 1 \\ \frac{3\sigma}{2} & 0 \end{pmatrix} = C_0, \quad D_0 = \begin{pmatrix} 0 & 1 \\ \sigma & 0 \end{pmatrix}$$

and find $G_0 = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} = -H_0$. This brings $eR(\omega)$, $\omega R(e)$, $E R(\Omega)$ and $\Omega R(E)$.

Flat limits of the fixed equations

We showed that some solutions of the quadratic matrix-valued equations

$$A^2 - \frac{5}{6} BC = \sigma \mathbb{1}_2, \quad D^2 + 2CB = 4\sigma \mathbb{1}_2, \quad CA - \frac{3}{2} DC = 0, \quad AB - \frac{3}{2} BD = 0$$

for the 16 parameters x_i are in the $GL(2, \mathbb{R}) \times GL(2, \mathbb{R})$ orbit

of the following simple solution for both $\sigma = \pm 1$

$$A_0 = \begin{pmatrix} 0 & 1 \\ \frac{3\sigma}{4} & 0 \end{pmatrix}, \quad B_0 = \begin{pmatrix} 0 & 1 \\ \frac{3\sigma}{2} & 0 \end{pmatrix} = C_0, \quad D_0 = \begin{pmatrix} 0 & 1 \\ \sigma & 0 \end{pmatrix}.$$

In order to recover the flat limit, must

- 1) act with some appropriate $(M, N)_{x, z}$
- 2) send $\lambda \rightarrow 0$.

Matrices $(M, N)_{\gamma, z}$ are

$$M = \begin{pmatrix} \frac{3}{\sqrt{2}} \Delta & z \\ -\frac{9\sigma}{4} z & \frac{3}{\sqrt{2}} \Delta \end{pmatrix}, \quad N = \begin{pmatrix} 0 & 1 \\ \frac{3\sigma}{4} & 0 \end{pmatrix},$$

where Δ is the square root

$$\Delta = \sqrt{\gamma\sigma(2\gamma z^2 - 1)}.$$

Because the numerical matrices (A, B, C, D) are real and $\gamma = \pm 1$, extensions from flat to $(A)dS_3$ depend on values of z and γ .

- If $\gamma = +1$, we have $\Delta = \sqrt{\sigma z^2(2z^2 - 1)}$: the model can be extended to dS when $z^2 < 1/2$, to AdS for $z^2 > 1/2$, and to both when $z^2 = 1/2$. In particular, the original action of [1] corresponds to $z = -1$ and therefore can only be continued to AdS, not to dS.
- If $\gamma = -1$, we have $\Delta = \sqrt{\sigma z^2(2z^2 + 1)}$: these models can only be deformed to AdS.

Flat limits of the actions

$$\bullet \quad S[e^a, \omega^a, E^{ab}, \Omega^{ab}] = \frac{1}{2\lambda} \int_{(A)dS_3} \left[(\lambda e_a \omega_a) G \left(\begin{matrix} \lambda R^a(e) \\ R^a(\omega) \end{matrix} \right) + (\lambda E_{ab}, \Omega_{ab}) H \left(\begin{matrix} \lambda R^{ab}(E) \\ R^{ab}(\Omega) \end{matrix} \right) \right]$$

The terms $e R(\omega)$, $\omega R(e)$, $E R(\Omega)$ and $\Omega R(E)$ come with λ^0 .

The terms $\omega R(\omega)$ and $\Omega R(\Omega)$ come with λ^{-1} and diverge when $\lambda \rightarrow 0$

\Rightarrow should set $G_{22} = 0 = H_{22}$.

The terms $e R(e)$ and $E R(E) \rightarrow 0$ when $\lambda \rightarrow 0$.

To recover
$$S = \int_{M_3} \left[\omega_a R^a(e) + e_a R^a(\omega) + \frac{2z}{3z} (\Omega_{ab} R^{ab}(E) + E_{ab} R^{ab}(\Omega)) \right] \quad (*)$$

in the flat limit, one should have $G_{12} = G_{21} = 1$, $H_{12} = H_{21} = \frac{2z}{3z}$,
$$z = -\frac{2\gamma z}{3(3\gamma^2 - 2)}$$

on top of the constraints on (G, H) from gauge invariance.

- Remarkably, this selects only the following values for xz :

$$xz \in \left\{ -\frac{2}{3}, -\frac{2}{15}, \frac{2}{45}, \frac{2}{9} \right\} .$$

Of these values, only $xz = \frac{2}{9}$ is possible for both signs of σ .

The other 3 values of xz admit $\sigma = \pm 1$ only, i.e. AdS_3 .

- The higher dual of Fierz-Pauli has $xz = -\frac{2}{9}$, hence cannot be deformed to $(A)dS_3$.

- The value $xz = \frac{2}{9}$ can be reached from the case $(A_0, B_0, C_0, D_0, G_0, H_0)$ by

acting with $M = \begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix}$, $N = -z \begin{pmatrix} 3/2 & 0 \\ 0 & 2 \end{pmatrix}$

The other 3 values for αz are in the orbit of the hybrid system

$$A_2 = \begin{pmatrix} \frac{3}{2} & 0 \\ 0 & \eta_1 \end{pmatrix}, \quad B_2 = \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}, \quad C_2 = \begin{pmatrix} \frac{3}{2} & 0 \\ 0 & 0 \end{pmatrix}, \quad D_2 = \begin{pmatrix} 1 & 0 \\ 0 & 2\eta_2 \end{pmatrix}, \quad \eta_i = \pm 1, \quad \sigma = +1.$$

$$G_2 = \begin{pmatrix} 1 & 0 \\ 0 & \tau_1 \end{pmatrix}, \quad H_2 = \begin{pmatrix} -\frac{2}{3} & 0 \\ 0 & \tau_2 \end{pmatrix} \quad \text{with } \tau_1 = -1 \text{ and } \tau_2 = +1.$$

Conclusion: The one-parameter family of actions in flat space only admits deformations to (A) dS_3 for critical values of the product αz ,

$$\alpha z = -\frac{2\gamma z}{3(3\gamma^2 - 2)}.$$

④ Relation with quivers

Use spinor notation instead of vector $\psi(x, z)$. The one-forms can be grouped in

$$\Phi(y, x) = \sum_{N, i} \frac{1}{N!} y_{\alpha_1} \dots y_{\alpha_N} \Phi_i^{\alpha_1 \dots \alpha_N}(x)$$

$(e^{\alpha\alpha}, \omega^{\alpha\alpha}, E^{\alpha(\psi)}, \Omega^{\alpha(\psi)})$ in our case.

Field equations

$$\nabla \Phi = Q \Phi,$$

where

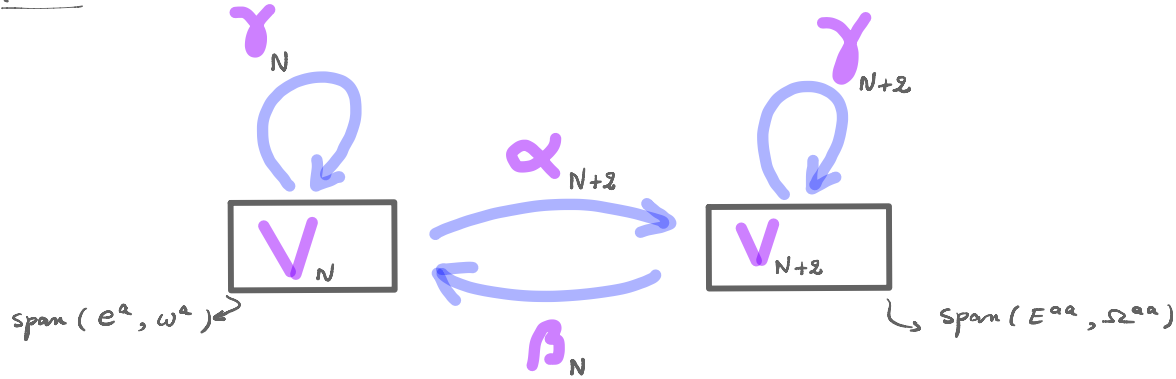
$$Q = \alpha(N) \hbar^{\alpha\alpha} y_\alpha y_\alpha + \beta(N) \hbar^{\alpha\alpha} \partial_\alpha \partial_\alpha + \gamma(N) \hbar^{\alpha\alpha} y_\alpha \partial_\alpha$$

For a topological system, $\mathcal{D} = \nabla - Q$ is nilpotent. This imposes constraints on

$$\alpha_N : V_{N-2} \rightarrow V_N, \quad \beta_N : V_{N+2} \rightarrow V_N, \quad \gamma_N : V_N \rightarrow V_N$$

Moreover, redefinitions $\Phi_N \rightarrow A_N \Phi_N$ by automorphisms.

Quiver



In AdS, one can use $GL_2 \times GL_2$

to reach $\alpha_{N+2} = \beta_N = \delta_N = \delta_{N+2} = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}$. It corresponds to (A_0, B_0, C_0, D_0) .

In flat space, $\beta_N = \delta_N = \delta_{N+2} = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}$ and $\alpha_{N+2} = \eta \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}$ 1-parameter.

• Constraints from nilpotency of \mathcal{D} .

Conclusions

- Strange higher-spin systems in flat space are associated with wild quivers .
- Classification of finite-dimensional representations of Poincaré algebra unknown (to us)
- Interactions were studied in the simplest $sp_{\mathbb{R}} 2 - sp_{\mathbb{R}} 3$ system