# Towards a turnkey approach to unbiased Monte Carlo estimation of smooth functions of expectations 

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## Introduction

Joint work with Francesca R. Crucinio \& Sumeetpal S. Singh


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- a stream of IID random variables $X_{1}, X_{2}, \ldots$ with expectation $m$ and variance $\sigma^{2}$
generate unbiased estimates of $f(m)$.


## Taylor expansion

Taylor expansion of $f$ around some $x_{0}$ :

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\begin{aligned}
f(m) & =\sum_{k=0}^{\infty} \frac{f^{(k)}\left(x_{0}\right)}{k!}\left(m-x_{0}\right)^{k} \\
& =\sum_{k=0}^{\infty} \gamma_{k}\left(\frac{m}{x_{0}}-1\right)^{k}
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where $\gamma_{k}:=f^{(k)}\left(x_{0}\right) x_{0}^{k} / k!$.
Unbiased estimate for $\left(m / x_{0}-1\right)^{k}: \prod_{i=1}^{k}\left(X_{i} / x_{0}-1\right)$.

## A Taylor-based sum estimator

This suggests using a sum estimator (McLeish, 2011; Glynn and Rhee, 2014; Rhee and Glynn, 2015):

$$
\hat{f}=\sum_{k=0}^{R} \frac{\gamma_{k} U_{R, k}}{\mathbb{P}(R \geq k)}=\sum_{k=0}^{\infty} \gamma_{k} U_{R, k} \frac{\mathbf{1}\{R \geq k\}}{\mathbb{P}(R \geq k)}
$$

where $R$ takes values in $\mathbb{N}=\{0,1, \ldots\}$, and

$$
U_{r, k}=U_{k}=\prod_{i=1}^{k}\left(X_{i} / x_{0}-1\right)
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## Motivation I: Log and MLE

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For $f(x)=\log (x), \gamma_{k}=(-1)^{k-1} / k$ (sub-geometric).

## Motivation II: Reciprocal and un-normalised models

A model whose likelihood is of the form:

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p(y \mid \theta)=g(y, \theta) / Z(\theta)
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where $Z(\theta)$ is intractable.

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Often, unbiased estimates of $Z(\theta)$ are available, but we would like to estimate unbiasedly $1 / Z(\theta)$, e.g. to implement a pseudo-marginal MCMC sampler.
For $f(x)=1 / x, \gamma_{k}=(-1)^{k-1}$, which is also sub-geometric.

## Not a motivation: Exponential

Obviously

$$
\exp (x)=\exp \left(x_{0}\right) \times \sum_{k=0}^{\infty} \frac{\left(x-x_{0}\right)^{k}}{k!}
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has also many practical applications; however the decay of the coefficients is super-geometric, which leads to different considerations.

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See Papaspiliopoulos (2011).

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- sum of random variables (when estimates are computed sequentially)
- max of random variables (when estimates are computed in parallel)


## Theoretical properties

## Variance decomposition

$$
\operatorname{var}[\hat{f}]=\operatorname{var}[\mathbb{E}[\hat{f} \mid R]]+\mathbb{E}[\operatorname{var}[\hat{f} \mid R]]
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where:
the first term measures the variability induced by the random truncation.

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where:
the first term measures the variability induced by the random truncation.

- the second term measures the variability due to the $U_{r, k}$ ' $s$ (the unbiased estimates of $\left(m / x_{0}-1\right)^{k}$ ).


## Analysing the first term

$$
\mathbb{E}[\hat{f} \mid R=r]=\sum_{k=0}^{\infty} \gamma_{k} \frac{\mathbf{1}\{r \geq k\}}{\mathbb{P}(R \geq k)}\left(\frac{m}{x_{0}}-1\right)^{k} .
$$

Hence

$$
\begin{aligned}
& \operatorname{var}[\mathbb{E}[\hat{f} \mid R]]=\sum_{k=0}^{\infty} \gamma_{k}^{2}\left(\frac{m}{x_{0}}-1\right)^{2 k}\left(\frac{1}{\mathbb{P}(R \geq k)}-1\right) \\
& \quad+2 \sum_{k=0}^{\infty} \sum_{l=k+1}^{\infty} \gamma_{k} \gamma_{l}\left(\frac{m}{x_{0}}-1\right)^{k+l}\left(\frac{1}{\mathbb{P}(R \geq k)}-1\right)
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## Implications

These expressions suggest to take:

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- $x_{0}$ such that $\beta_{0}:=\left|m / x_{0}-1\right|<1$;
- $R \sim \operatorname{Geometric}(p)$, with $p<1-\beta_{0}$, so that $\mathbb{P}(R \geq k)>\beta_{0}^{2 k}$.


## Improving the $U_{r, k}$

Currently, we use the following unbiased estimate of $\left(m / x_{0}-1\right)^{k}$ :

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U_{r, k}=U_{k}=\prod_{i=1}^{k}\left(X_{i} / x_{0}-1\right)
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Computing $\hat{f}$ requires generating $X_{1}, \ldots, X_{R}$ in order to compute the last term $U_{R, R}$, but we use only the $k$ first inputs to estimate $\left(m / x_{0}-1\right)^{k}$. Seems inefficient.

## Cycling estimator

In order to use the whole sample, consider the following cycling estimator:

$$
\begin{aligned}
U_{r, k}^{\mathrm{C}}:=\frac{1}{r}\left[\prod_{i=1}^{k}\left(\frac{X_{i}}{x_{0}}-1\right)\right. & +\prod_{i=2}^{k+1}\left(\frac{X_{i}}{x_{0}}-1\right) \\
& \left.+\ldots+\left(\frac{X_{r}}{x_{0}}-1\right) \prod_{i=1}^{k-1}\left(\frac{X_{i}}{x_{0}}-1\right)\right]
\end{aligned}
$$

## Second term of the decomposition

For the cycling estimator, one has (under weak assumptions)

$$
\mathbb{E}\left[\operatorname{var}\left(\hat{f}^{\mathrm{C}} \mid R\right)\right]=\mathcal{O}(p \log (1 / p))
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- Average number of required inputs is $\mathbb{E}[R] \approx 1 / p$.
- We can have var $[\hat{f}] \rightarrow 0$ by taking $\mathbb{E}[R] \rightarrow+\infty$. (This is not the case for the simple estimator.)
- Up to log factor, standard Monte Carlo rate, i.e. $\operatorname{var}[f]=\mathcal{O}(\log \mathbb{E}[R] / \mathbb{E}[R])$.


## Without cycling

The simple estimator does not converge as $\mathbb{E}[R] \rightarrow+\infty$.

## Calibration of tuning parameters

## Tuning $x_{0}$

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$\Rightarrow$ pilot run, bootstrap to ensure this condition with high probability.

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Less of an issue with the cycling estimator, because work-normalised variance depends weakly on $p$.

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See paper.

Numerical experiments: log

## log-likelihood (and gradient) of a latent variable model

Model with data $y$, latent $z$, parameter $\theta$;

$$
p(y \mid \theta)=\int p(y \mid z, \theta) p(z \mid \theta) d z
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For a fixed $\theta$, importance sampling gives unbiased estimates of the likelihood:

$$
X_{i}=w_{i}=\frac{p\left(y \mid Z_{i}, \theta\right) p\left(Z_{i} \mid \theta\right)}{q\left(Z_{i}\right)}, \quad Z_{i} \sim q
$$

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To compute the MLE, use our approach to derive unbiased estimate of the log-likelihood and its gradient (stochastic gradient descent).

## Alternative approach: SUMO (Luo et al, 2021)

Consider biased (but consistent) IS estimate:

$$
\ell_{k}(\theta)=\log \left(\frac{1}{k} \sum_{i=1}^{k} w_{i}\right)
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The SUMO estimator is a sum estimator based on the series:

$$
\log p(y \mid \theta)=\mathbb{E}\left[\ell_{1}(\theta)\right]+\sum_{k=1}^{\infty} \mathbb{E}\left[\Delta_{k}\right], \quad \Delta_{k}=\ell_{k+1}(\theta)-\ell_{k}(\theta)
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Main issue: infinite variance.

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Adaptation of SUMO, truncation at $R=2^{K}$.

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Adaptation of SUMO, truncation at $R=2^{K}$.
Variance is infinite, but the random CPU time may have infinite variance (and has always heavy tails).

## Comparison on a toy model from Rob \& Cornish (2021)






Figure 1:


## Caption

Estimate vs CPU for an expected cost $C$ of 6 (top) and 96 (bottom) samples per data point. Dimension is $d=2$ (left) and $d=5$ (right). The vertical dashed line denotes the expected cost while the horizontal one denotes the true value of $\sum_{i=1}^{n} \log p\left(y_{i} \mid \theta\right)$.

## Independent component analysis (Allassonnière and Younes, 2012)

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y=\sum_{j=1}^{k} z_{j} a_{j}+\sigma \epsilon \quad \text { where }
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Aim is to estimate $\theta$ using SGD.

## Stochastic gradient descent

Given data $\left(y_{1}, \ldots, y_{n}\right)$, do gradient descent, where at east step, the gradient is replaced by an unbiased estimate of the gradient of a single term (chosen uniformly).

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A good illustration on the need for automation, i.e. at each iteration, the actual value of $m, \sigma^{2}$, and thus $x_{0}$ and $p$ must change.

## Estimated images



Numerical experiments: reciprocal

## Exponential random graph model



Figure 6: Florentine family business network

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- $s(y)$ is a collection of network statistics (number of edges, number of $k$-stars, etc.)
- $Z(\theta)$ is a sum over $2^{\binom{k}{2}}$ terms (intractable)


## Bayesian inference (and model choice)

Typically the dimension of $\theta$ is $2-3$, so even importance sampling could work reasonably well to approximate the posterior:

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Pseudo-marginal approach: replace $1 / Z(\theta)$ by an unbiased estimate.

## Details

For a fixed $\theta$, run a tempering SMC algorithm to obtain an unbiased estimate of $Z(\theta)$.

## Posterior approximation


(a) Simple

(a) Cycling

Figure 8: Bivariate weighted histograms approximating the posterior distributions obtained with the simple and the cycling estimator using $n=1024$ samples from proposal $q$.

## Cycling gives better performance II



Figure 9: ESS accross simulated $\theta_{j}$

## Conclusion

## Concluding remarks

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- No free lunch. Cannot work without pilot runs.
- Garbage in, garbage out: if the variance of the inputs is very large, the variance of our estimator will be large as well.


## Paper

Chopin N., Crucinio F.R. and S. S. Singh (2024). Towards a turnkey approach to unbiased Monte Carlo estimation of smooth functions of expectations, arxiv 2403.20313.


