

# A new hyperbolic dispersive model for coastal waves

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# From Navier-Stokes to depth-averaged equations

Consider Navier-Stokes/ Euler equations of incompressible fluid

$$\begin{cases} \mathbf{div}(\mathbf{u}) = 0, & \text{(Continuity Eq)} \\ \frac{\partial \mathbf{u}}{\partial t} + \mathbf{div}(\mathbf{u} \otimes \mathbf{u}) = \mathbf{g} - \frac{1}{\rho} \mathbf{grad} p + \nu \mathbf{u}, & \text{(Momentum Eq)} \end{cases}$$

where  $\rho$ : density,  $\nu$ : kinematic viscosity,  $p$ : pressure, and  $\mathbf{g}$ : gravitational acceleration.

Numerical resolution is  
time-consuming

⇒

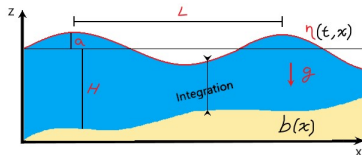
Integrating the equations over  
the depth

# Depth-averaged water waves models

$$\varepsilon = H/L \text{ (shallowness)}$$

$$\mu = a/H \text{ (nonlinearity)}$$

**BC. no-slip, kinematic, dynamic condition**



$$\begin{cases} \frac{\partial h}{\partial t} + \mathbf{div}(h\mathbf{U}) = 0, & \text{(Mass Eq)} \\ \frac{\partial h\mathbf{U}}{\partial t} + \mathbf{div}\left(h\mathbf{U} \otimes \mathbf{U} + \frac{gh^2}{2}\mathcal{I} + P_{NH}\mathcal{I}\right) = 0, & \text{(Momentum Eq)} \end{cases}$$

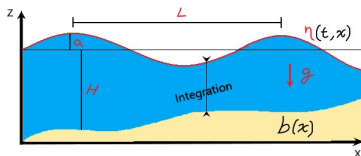
| model    | <b>NSWE</b> $\mathcal{O}(\varepsilon)$ | $\mathcal{O}(\varepsilon\mu)$ | <b>SGN</b> $\mathcal{O}(\varepsilon^2)$ |
|----------|--|-------------------------------|---|
| Pressure | $P_{NH} = 0$                           | <b>Boussinesq</b>             | $P_{NH} = h^2\ddot{h}/3$                |
| $\mu$    | no assump                              |                               | no assump                               |
| Type     | hyperbolic                             |                               | dispersive                              |

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| $\mu$    | no assump                              |                               | no assump                               |
| Type     | hyperbolic                             |                               | dispersive                              |

📖 Gavriluk&Favrie, **2017**; Escalante, **2019,2020**; Richard, **2021**

# Breaking wave: Energy dissipation

Energy dissipation due to breaking wave should be included in depth-averaged context.

Classic methods are:

- 1 Extra terms in the mass and/or the momentum equation to provide a necessary dissipation.

📖 Svendsen, **1984, 1996**; Zelt, **1991**; Schäffer et al., **1993**;  
Musumeci et al., **2005** etc.

- 2 Switching or hybrid methods (natural dissipation through the shock)

📖 Bonneton et al., **2011**; Tissier et al., **2012**; Kazolea et al., **2014**;  
Duran & Marche, **2015, 2017**

Both methods need a **breaking criterion** to determine when the wave breaks.

# New hyperbolic model for breaking waves

Objectives:

- 1 New hyperbolic model with cheaper numerical cost
- 2 Model which is capable to capture breaking phenomenon
- 3 Model with good dispersive properties

# Assumptions

Mimic large-eddy simulation (LES), decompose the velocity

$$\mathbf{u} = \bar{\mathbf{u}} + \overbrace{\text{small-scale turbulence}}^{\text{modeled by turbulent viscosity}}$$

$$\begin{array}{ccc}
 \text{SW eq.} & & \text{SGN eq.} \\
 \hline
 \bar{u}(t, x, z) = U(t, x) & + & u'(t, x, z) \\
 p = p_{Hydro} & + & p_{Nonhydro}
 \end{array}$$

Model of Kazakova & Richard

- $u'$  – the vertical variation of the horizontal velocity is arbitrary
- Hypothesis of weakly turbulent flow from Teshukov (2007):  
 $u' \approx O(\varepsilon)$
- The non-hydrostatic pressure is taken into account
- No surface tension and shear stress at the free surface

# Breaking waves model

Model derivation: equations for  $h, U, W$

**Dimensionless** equations  $\xrightarrow{\int \updownarrow}$   $\xrightarrow{O(\varepsilon^2)}$  + dissipation

Residual stress tensor is modeled by turbulent viscosity  $\nu_T$  and shear stress

Mass equation:

$$\frac{\partial \tilde{h}}{\partial \tilde{t}} + \frac{\partial \tilde{h} \tilde{U}}{\partial \tilde{x}} = 0$$

$Ox$ -Momentum equation:

$$\frac{\partial \tilde{h} \tilde{U}}{\partial \tilde{t}} + \frac{\partial}{\partial \tilde{x}} \left( \tilde{h} \tilde{U}^2 + \frac{\tilde{h}^2}{2} + \varepsilon^2 \tilde{h} \langle \tilde{u}'^2 \rangle + \varepsilon^2 \tilde{h} \langle \tilde{p}_N \rangle - \varepsilon^2 \boxed{2\nu_T \tilde{h} \frac{\partial \tilde{U}}{\partial \tilde{x}}} \right) = -\tilde{p}(b) \frac{\partial \tilde{b}}{\partial \tilde{x}}$$

$Oz$ -Momentum equation:

$$\frac{\partial \tilde{h} \tilde{W}}{\partial \tilde{t}} + \frac{\partial \tilde{h} \tilde{U} \tilde{W}}{\partial \tilde{x}} = \tilde{p}_N(b)$$


Defining  $\tilde{\varphi}$  (enstrophy),  $\tilde{W}$ , and  $\tilde{P}$

$$\tilde{\varphi} := \frac{\langle \tilde{u}'^2 \rangle}{\tilde{h}^2} \equiv \frac{1}{\tilde{h}^3} \int_{\tilde{b}}^{\tilde{\eta}} \tilde{u}'^2 d\tilde{z}, \quad \overbrace{\tilde{W} = \langle \tilde{w} \rangle, \tilde{P} = \langle \tilde{p}_N \rangle}^{\text{hyperbolic structure}}$$



# Breaking waves model

Model derivation: equations for  $P$  and  $\varphi$

Energy equation   $\longrightarrow O(\varepsilon^2)$

$$\frac{h^2}{2} \left( \frac{\partial h\varphi}{\partial t} + \frac{\partial hU\varphi}{\partial x} \right) + \frac{\partial h\langle e_a \rangle}{\partial t} + \frac{\partial hU\langle e_a \rangle}{\partial x}$$

$$= -h\langle P^r \rangle - \left( hP - 2\nu_T h \frac{\partial U}{\partial x} \right) \frac{\partial U}{\partial x} - 2 \left( P + 2\nu_T \frac{\partial U}{\partial x} \right) (W - \dot{b}),$$

Hyperbolicity admits slight compressibility in non-hydrostatic pressure!

where  $e_a$  is the acoustic energy and  $P^r$  is the energy transfer from large-scale turbulence to small-scale turbulence.

Postulate  $\langle e_a \rangle$  + decouple  $\longrightarrow$  equations for  $P$  and  $\varphi$

$$\frac{1}{h} \int_b^\eta e_a dz = \langle e_a \rangle = \frac{P^2}{2a_c^2}$$

where  $a_c$  is the constant sound velocity.

# Breaking waves model

Full system of equations

Under the mild slope condition

$$\frac{\partial h}{\partial t} + \frac{\partial hU}{\partial x} = 0$$

$$\frac{\partial hU}{\partial t} + \frac{\partial}{\partial x} \left( hU^2 + \frac{gh^2}{2} + h^3\varphi + hP \right) = \frac{\partial}{\partial x} \left( 2\nu_T h \frac{\partial U}{\partial x} \right) - gh \frac{\partial b}{\partial x}$$

$$\frac{\partial hW}{\partial t} + \frac{\partial hUW}{\partial x} = \frac{3}{2}P + 3\nu_T \frac{\partial U}{\partial x}$$

$$\frac{\partial hP}{\partial t} + \frac{\partial hUP}{\partial x} = -a_c^2 \left( h \frac{\partial U}{\partial x} + 2W \right)$$

$$\frac{\partial h\varphi}{\partial t} + \frac{\partial hU\varphi}{\partial x} = -\frac{2}{h} \langle P^r \rangle + \frac{4\nu_T}{h} \left( \frac{\partial U}{\partial x} \right)^2 - \frac{8\nu_T W}{h^2} \frac{\partial U}{\partial x}$$

# Breaking waves model

Full system of equations


Without turbulence and enstrophy  $\varphi$

$$\frac{\partial h}{\partial t} + \frac{\partial hU}{\partial x} = 0$$

$$\frac{\partial hU}{\partial t} + \frac{\partial}{\partial x} \left( hU^2 + \frac{gh^2}{2} + hP \right) = -gh \frac{\partial b}{\partial x}$$

$$\frac{\partial hW}{\partial t} + \frac{\partial hUW}{\partial x} = \frac{3}{2}P$$

$$\frac{\partial hP}{\partial t} + \frac{\partial hUP}{\partial x} = -a_c^2 \left( h \frac{\partial U}{\partial x} + 2W \right)$$

Hyperbolic model of the SGN equation developed by  Richard, **2021** in an incompressible context.

# Breaking waves model

Full system of equations

Acoustic sound velocity  $a_c \rightarrow \infty$

$$\frac{\partial h}{\partial t} + \frac{\partial hU}{\partial x} = 0$$

$$\frac{\partial hU}{\partial t} + \frac{\partial}{\partial x} \left( hU^2 + \frac{gh^2}{2} + h^3\varphi + \frac{h^2\ddot{h}}{3} \right) = \frac{\partial}{\partial x} \left( 4\nu_T h \frac{\partial U}{\partial x} \right) - gh \frac{\partial b}{\partial x}$$

$$\frac{\partial h\varphi}{\partial t} + \frac{\partial hU\varphi}{\partial x} = -\frac{2}{h} \langle P^r \rangle + \frac{8\nu_T}{h} \left( \frac{\partial U}{\partial x} \right)^2$$

Breaking wave model developed by 📖 Kazakova & Richard, **2019**.

Further without turbulence and enstrophy would reduce to SGN equation

$$\frac{\partial h}{\partial t} + \frac{\partial hU}{\partial x} = 0$$

$$\frac{\partial hU}{\partial t} + \frac{\partial}{\partial x} \left( hU^2 + \frac{gh^2}{2} + \frac{h^2\ddot{h}}{3} \right) = -gh \frac{\partial b}{\partial x}$$

# Hyperbolicity

The primitive form of the system has the Jacobian matrix

$$\begin{pmatrix} U & h & 0 & 0 & 0 \\ g + 3h\varphi + \frac{P}{h} & U & 0 & 1 & h^2 \\ 0 & 0 & U & 0 & 0 \\ 0 & a^2 & 0 & U & 0 \\ 0 & 0 & 0 & 0 & U \end{pmatrix}$$

The eigenvalues are

$$\lambda = U(\text{triple roots}), U \pm \sqrt{gh + 3h^2\varphi + P + a^2},$$

with the corresponding eigenvectors form a basis in  $\mathbb{R}^5$ . The model is hyperbolic if  $h > 0$ .

# Asymptotic dispersion relation to SGN model

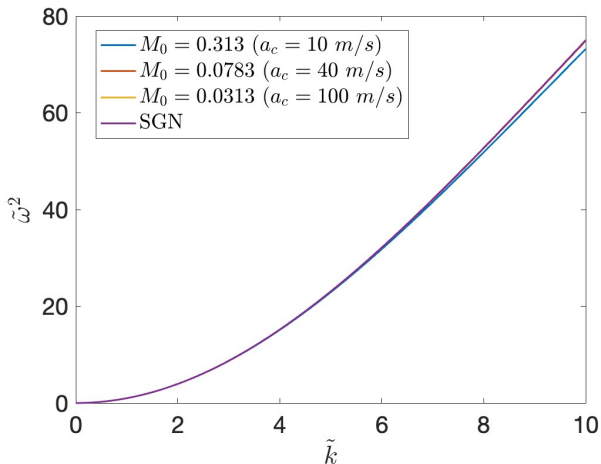
The dispersion relation of the model is

$$\frac{M_0^2}{3}\tilde{\omega}^4 - \tilde{\omega}^2 \left[ 1 + \frac{\tilde{k}^2}{3} (1 + M_0^2) \right] + \tilde{k}^2 = 0$$

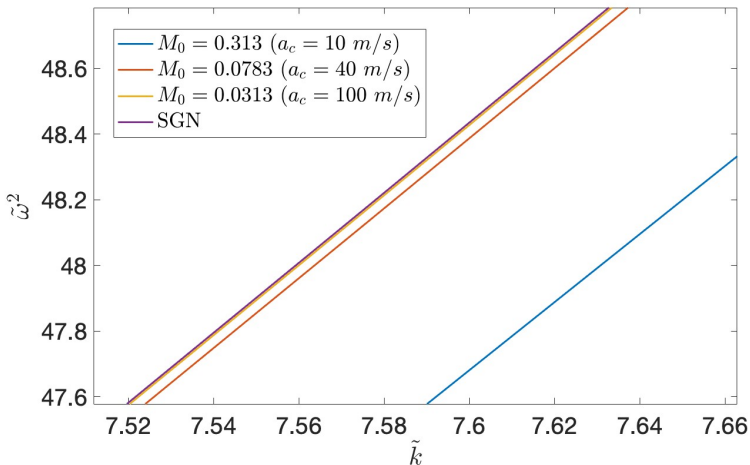
where  $M_0 = \sqrt{gh_0}/a_c$  is the Mach number at the reference state. As  $a_c \rightarrow \infty$ , the dispersion relation of the model approaches to that of SGN model

$$\tilde{\omega}^2 = \frac{\tilde{k}^2}{1 + \frac{\varepsilon^2 \tilde{k}^2}{3}}$$

# Asymptotic dispersion relation to SGN model



# Asymptotic dispersion relation to SGN model





# From energy dissipation to breaking criterion

Recall


$$\frac{\partial hU}{\partial t} + \frac{\partial}{\partial x} \left( hU^2 + \frac{gh^2}{2} + h^3\varphi + hP \right) = \frac{\partial}{\partial x} \left( 2\nu_T h \frac{\partial U}{\partial x} \right) - gh \frac{\partial b}{\partial x}$$

$$\frac{\partial hW}{\partial t} + \frac{\partial hUW}{\partial x} = \frac{3}{2}P + 3\nu_T \frac{\partial U}{\partial x}$$

$$\frac{\partial h\varphi}{\partial t} + \frac{\partial hU\varphi}{\partial x} = -\frac{2}{h} \langle P^r \rangle + \frac{4\nu_T}{h} \left( \frac{\partial U}{\partial x} \right)^2 - \frac{8\nu_T W}{h^2} \frac{\partial U}{\partial x}$$

Mean of dissipation  $\langle P^r \rangle$  and the turbulent viscosity  $\nu_T$  have the forms

$$\langle P^r \rangle = \frac{C_r}{2} h^2 \varphi^{3/2}, \quad \nu_T = \frac{h^2 \sqrt{\varphi}}{R},$$

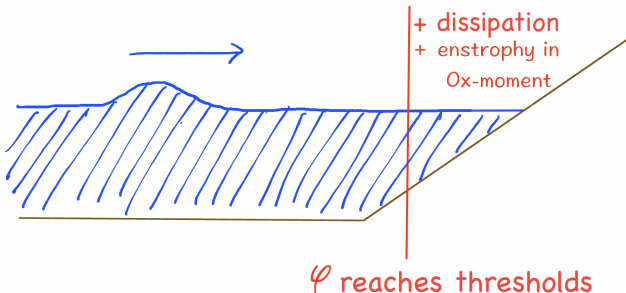
where  $C_r$  is a dimensionless quantity and  $R$  is an analogue of Reynold's number. (See  Kazakova & Richard, 2019)

# Breaking criterion explain

If there's NO criterion, we resolve the full system from the very beginning. **The dissipation is too significant for some cases.** Therefore, a **breaking criterion is needed.**

The enstrophy  $\varphi$  has definition similar to vorticity magnitude. Good for capturing the turbulence generated by the breaking.

Numerical treatment of breaking:



# Breaking criteria

📖 Kazakova&Richard, 2019

$$\varphi_0 = \frac{g}{h_0} \tilde{\varphi}_0, \quad \tilde{\varphi}_0 = \begin{cases} \left(0.1 + \frac{0.031}{\mu_0}\right), & \mu_0 > 0.05 \\ 0, & \mu_0 < 0.05 \end{cases}$$

**Criterion: Activate once  $\tilde{\varphi} > \tilde{\varphi}_0$ .**

New criterion depends on the **local** dimensionless quantities

$$\tilde{\varphi}_1 = \frac{\varphi\eta}{g} > \alpha_1, \quad \tilde{\varphi}_2 = \frac{\varphi h}{g} > \alpha_2,$$

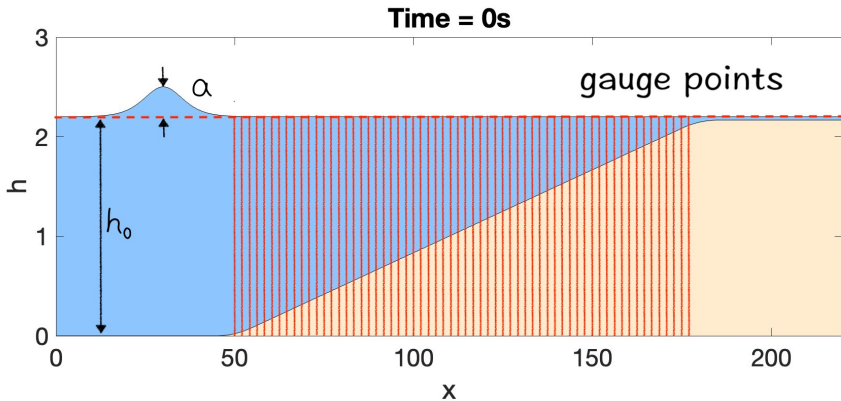
where  $\alpha_1 > \alpha_2$  are two thresholds for the activation of the breaking.

**Criterion: Activate once  $\tilde{\varphi}_1 > \alpha_1$  and deactivate when  $\tilde{\varphi}_2 > \alpha_2$ .**

**Note.** the new criterion now depends only on local variables/quantities!

# Experiment of Hsiao *et. al*, 2008

Gauge points of the Experiment 📖 Hsiao *et. al*, 2008



# Numerical Comparison: Hsiao Trial 41

Free surface and breaking criteria

In this scenario, we take trial 41 for example. The wave conditions are

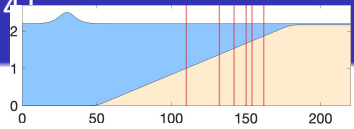
$$h_0 = 2.2 \text{ m}, \mu = 0.137$$

The numerical parameters we take

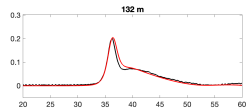
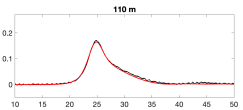
$$R = 1.7, \alpha_1 = 0.09, \alpha_2 = 0.005$$

# Numerical Comparison: Hsiao Trial 41

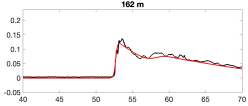
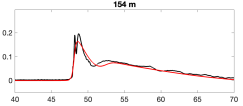
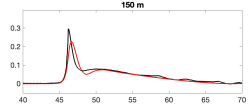
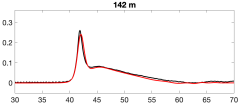
## Gauge points comparison



Amplitude



Breaking position:  
real:148m  
numerical:148.7m



Time series

# Numerical Comparison

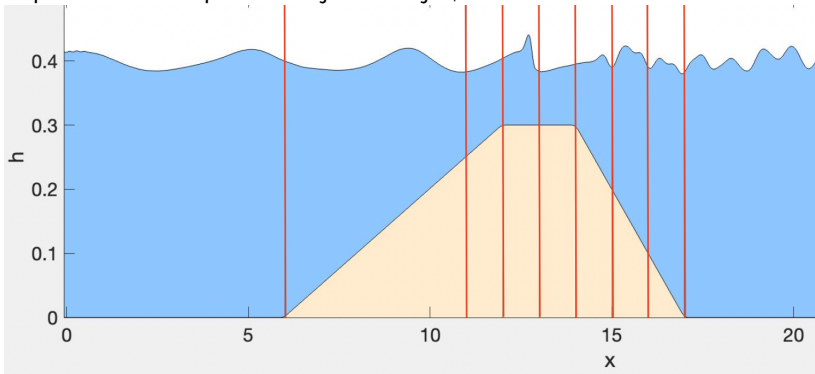
Deviation in position and amplitude of breaking point

| Trial   | Breaking position | Breaking amplitude |
|---------|-------------------|--------------------|
| 3       | -0.3/-0.7         | -0.0496/-0.0423    |
| 9       | 0.9/1             | -0.0341/-0.0345    |
| 14      | -0.4/0            | -0.101/-0.0983     |
| 15      | 0.9/1.4           | -0.0899/-0.0866    |
| 17      | 1.2/1.7           | -0.112/-0.1083     |
| 19      | 1.2/1.7           | -0.0978/-0.0942    |
| 21      | 2.4/1             | 0.0206/0.018       |
| 25      | 0.6/0.3           | 0.006/0.002        |
| 31      | 0.3/0.1           | -0.022/-0.027      |
| 37      | 0.4/0.4           | -0.0815/-0.082     |
| 41      | 0.7/0.9           | -0.1018/-0.1008    |
| 43      | 1.1/1.4           | -0.076/-0.074      |
| 49      | 0.4/-0.6          | -0.057/-0.057      |
| 54      | 0.6/0.3           | -0.101/-0.1064     |
| Average | 0.7143/0.6357     | -0.0641/-0.0637    |

Blue data is with the criteria of Kazakova & Richard that depends on initial global  $\mu_0$ . Red data is with new local breaking criteria.

# Experiments of Beji & Battjes, 1993

Experimental setup of  Beji & Battjes, 1993





# Numerical Comparison: Beji & Battjes SLS case

Free Surface and breaking criteria

In this scenario, we take Sinusoidal Long Spilling (SLS) wave for example. The wave conditions are

$$T = 2.5 \text{ s}, \quad a = 0.016 \text{ m}$$

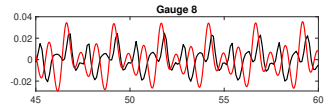
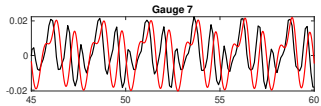
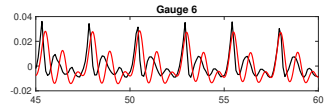
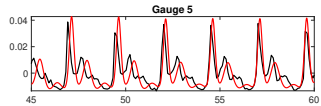
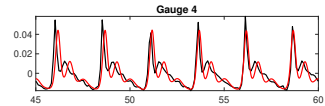
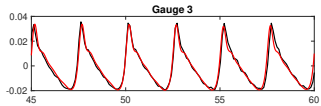
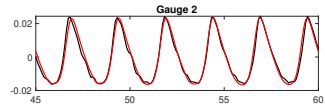
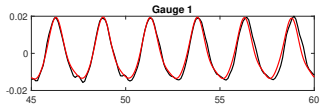
The numerical parameters we take

$$R = 7.5, \quad \alpha_1 = 0.01, \quad \alpha_2 = 0.005$$

# Numerical Comparison: Beji & Battjes SLS case


## Gauge points comparison

Amplitude ↑



Time series →

# Model with improved dispersive properties

Follow  Bonneton et al., **2011**, the idea is to use  $w$  at some height above the bottom as a variable instead of the average vertical velocity

$$\checkmark \quad w|_{z=b+\frac{\alpha}{2}h} \quad \times \quad \langle w \rangle$$

The choice of  $\alpha$  follows  Bonneton et al., **2011** with an optimal value

$$\alpha = 1.159$$

# Improved dispersion relation

Airy wave theory gives

$$\tilde{\omega}^2 = \tilde{k} \tanh(\tilde{k})$$

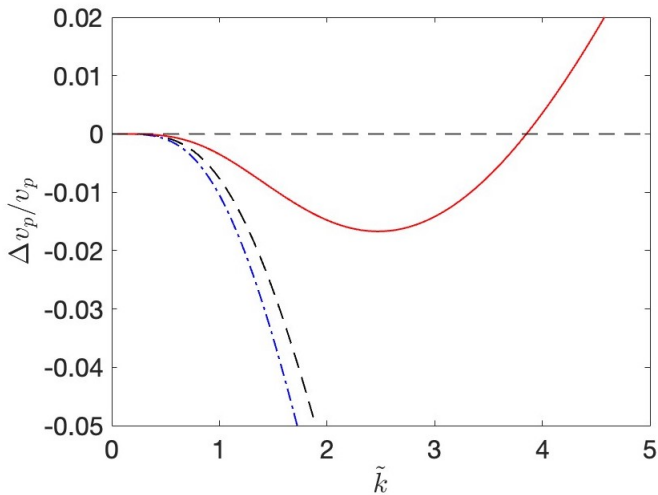
accurate for shallow water and deep water.

The dispersion relation of the model with improved dispersive properties is

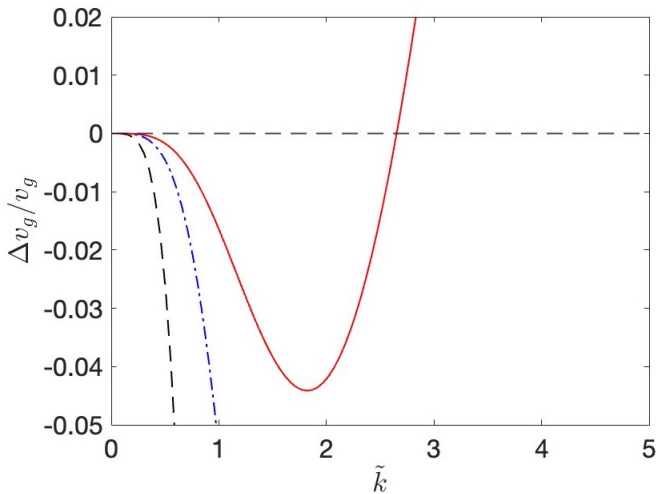
$$\frac{M_0^2}{3} \tilde{\omega}^4 - \tilde{\omega}^2 \left[ 1 + \frac{\tilde{k}^2}{3} \left( \alpha + \frac{2\alpha - 1}{\alpha} M_0^2 \right) \right] + \tilde{k}^2 \left[ 1 + \tilde{k}^2 \frac{\alpha - 1}{3} \left( 1 + \frac{M_0^2}{\alpha} \right) \right] = 0$$

where  $M_0 = \sqrt{gh_0}/a_c$  is the Mach number at the reference state.

# Improved dispersion relation



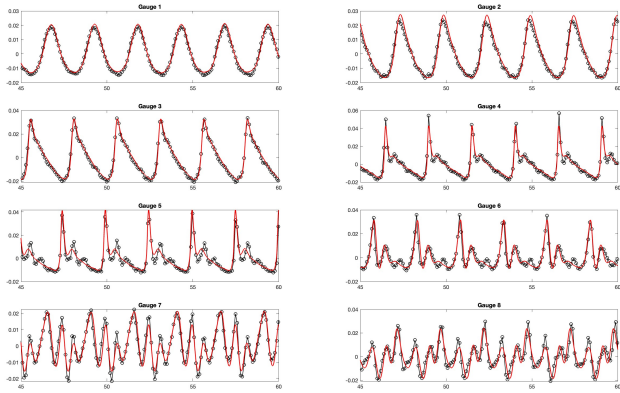
# Improved dispersion relation



# Numerical Comparison: Beji & Battjes SLS case

## Gauge points comparison

*Amplitude*



*Time series* →

# Numerical Comparison: Beji & Battjes Irregular wave

## Free Surface and breaking criteria

In this scenario, irregular waves are generated by JONSWAP spectrum, the breaker is of spilling type. The numerical parameters we take

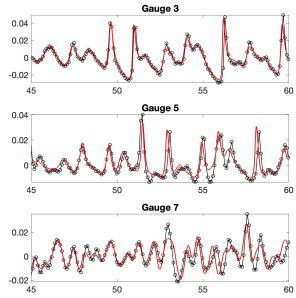
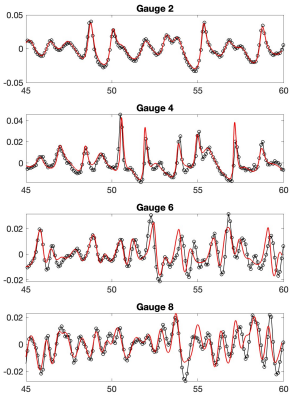
$$R = 7.5, \alpha_1 = 0.01, \alpha_2 = 0.005$$



# Numerical Comparison: Beji & Battjes Irregular wave

## Gauge points comparison

*Amplitude*



*Time series* →

# Conclusions & Perspectives

## Conclusions:

- Capable to capture breaking phenomenon
- Improved dispersive property
- Hyperbolic structure gives cheaper numerical cost
- Validated by the comparison to several experiments
- Local breaking criterion

## Perspectives:

- More stable numerical scheme can be implemented (A. Duran, in prep.)
- Sediment transport coupling (Julien Chauchat, LEGI)
- Implementation in TOLOSA (<https://tolosa-project.com>)

Merci de votre attention